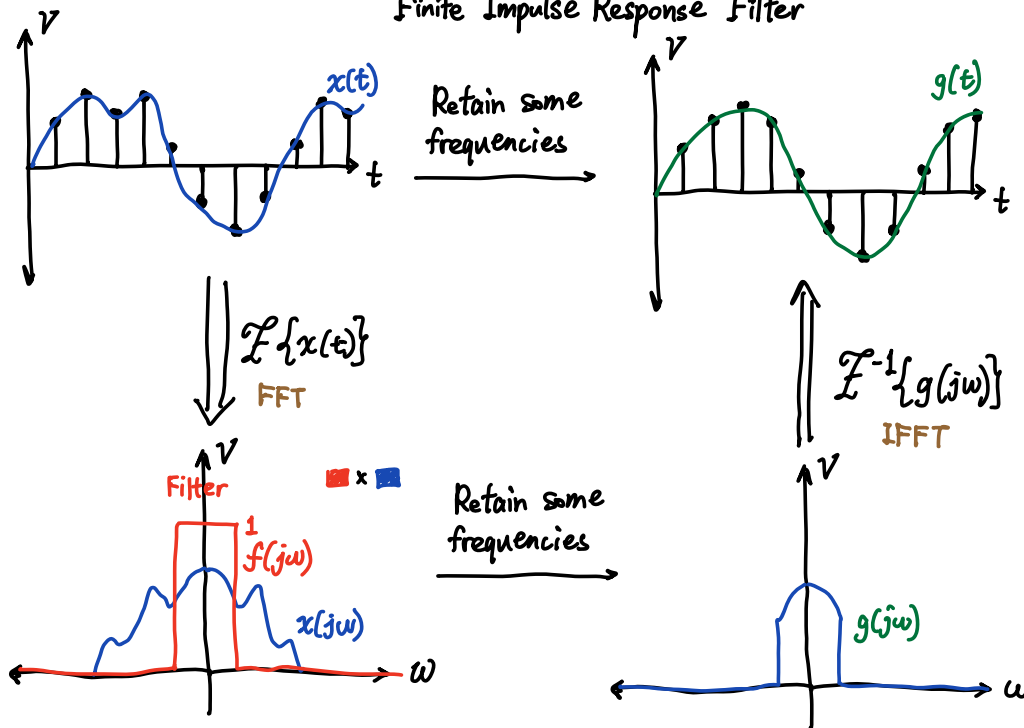
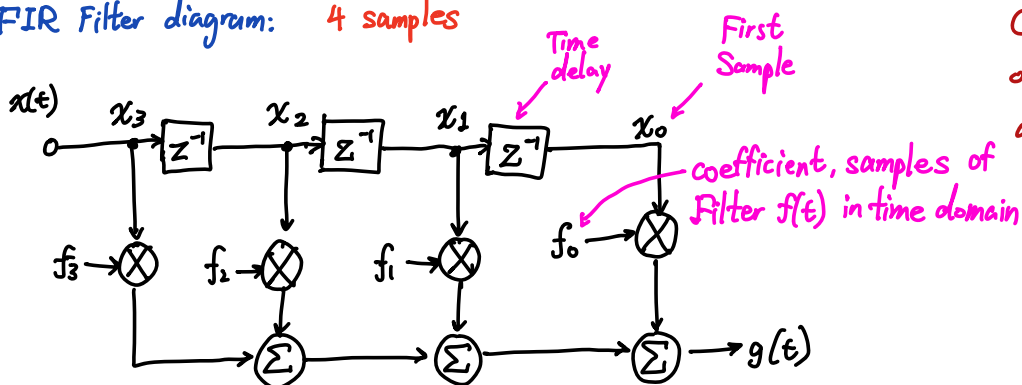


Finite Impulse Response Filter



FIR Filter diagram: 4 samples



Convolution: Multiplication of one signal by another and the integrating that product.

Because number of f_i is finite, filter can't be ideal. (Trade passband ripple vs. roll off slope)

$$y[n] = \sum_{k=0}^N b_k x[n-k] \quad H(z) = \sum_{k=0}^N b_k z^{-k} = b_0 \cdot \prod_{k=1}^N (1 - c_k z^{-1}) \quad \text{Only pole at } z=0.$$

$$h[n] = \begin{cases} b_n, & 0 \leq n \leq N \\ 0, & \text{otherwise} \end{cases}$$

Optimize RMSE or Maximum Error: $H(e^{j\omega}) \Leftrightarrow H_d(e^{j\omega})$
This class

FIR can have arbitrary magnitude/phase response, can obtain linear phase.

PIR pseudocode:

Load coefficient

while core_enable is True:

 If reset is active:

 reset x

 End if

 for $i=63, i>0, i=i-1$:

$x[i]=x[i-1]$

 end for

 If input_end is not active:

$x[0]=d_{in}$

 End if

 Else:

$x[0]=0$

 for $i=63, i\geq 0, i=i-1$:

$sum += b[63-i] \cdot x[i]$

 end for

 output sum

 If x is empty AND input_end is active:

 core_enable = False

 End if

End while

