THE UNIVERSITY OF HONG KONG

COMP3259: Principles of Programming Languages

Tutorial 8

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1 Introduction

This tutorial aims at providing students with experience in writing interpreters and type checkers with first-class functions and recursion. In addition, we will introduce writing interpreters in a monadic way.

2 A Language with Recursive Functions

We now continue to improve SNH by supporting recursive definitions. For example, you may want to write a Fibonacci function as follows:

```
var fib = function(x: Int) {
  if (x == 0) 0;
  else if (x == 1) 1;
  else fib(x-1) + fib(x-2)
};
fib(10)
```

Recall that the code for evaluating non-recursive variable declarations is:

```
evaluate (Decl x e body) env =
  let newEnv = (x, evaluate e env) : env
  in evaluate body newEnv
```

The declared variable **x** itself is not in the environment so it cannot be used in **e**. We can add support for recursion in SNH with the help of recursion in Haskell. By using a *circular program*, the change to variable declarations is minimal:

```
evaluate (Decl x e body) env =
    -- when evaluating `e`, use `newEnv` instead of `env`
    let newEnv = (x, evaluate e newEnv) : env
    in evaluate body newEnv
```

Similarly, when type checking a variable declaration, we don't know the type of x that may be recursively used in e:

```
tcheck (Decl x e body) env = do
  t <- tcheck e env
  tcheck body ((x, t) : env)</pre>
```

Unfortunately, the same trick doesn't apply here because it leads to an endless loop. To remedy this, one simple way is to give extra information to the type checker. Therefore, we slightly alter the syntax of variable declarations, that is, we require every variable to be explicitly typed. For example, fib now becomes:

```
var fib: Int -> Int = function(x: Int) {
  if (x == 0) 0;
  else if (x == 1) 1;
  else fib(x-1) + fib(x-2)
};
fib(10)
```

Here we specify the type of fib as Int -> Int. It may seem tedious to write types for non-recursive declarations, but it makes type checking recursive functions much easier.

How are variable declarations type checked then? The answer is that we assume the variable have the specified type and then check whether the definition is consistent with this assumption. In the case of fib, we assume it have type Int -> Int in the typing environment, and then call tcheck e. Since the result is indeed Int -> Int, it type checks.

Question 1. Fix type checking Decl in the file TypeCheck.hs.

Now you can recompile SNH and test if demo.txt can type check.

Question 2. In Tutorial 7, we built a stack machine called K. Does the K machine support recursive definitions? If so, show the evaluation derivation of fib(2); if not, modify the implementation to support recursion.

3 Monads

Let's take a closer look at monads and understand why they can be useful. In functional programming (Haskell in particular), monads are used as a *design pattern*. This means that monads offer a reusable solution to a commonly occurring problem. The abstraction of monads reduces boilerplate code in Haskell programming. We are going to see several monads and how they can be used to model errors.

3.1 A Navigation Language

Suppose that we have a very small language which simulates movements in a plane. We may define the current location as a pair of coordinates:

```
type Loc = (Int, Int) -- (x, y)
```

We want to define three functions (up, down, and left), which represent safe movements within the plane. By "safe" we mean that only non-negative coordinates are allowed after movements. It should be clear that, in functional programming, we would like to have total functions. Thus, we want potential errors to be reflected in the type system, rather than take the risk of blowing up the program at run time.

Let's first consider the following (possibly unsafe) definitions:

```
up :: Loc -> Loc -- increases y by 1
down :: Loc -> Loc -- decreases y by 1
left :: Loc -> Loc -- decreases x by 1
```

Judged by their names and type signatures, the defintion of up should be correct: no matter what valid location is passed, it will always return another valid location. However, down and left are error-prone: for some valid locations taken as input, they may produce invalid locations. For instance, down (3, 0) will produce the invalid location (3, -1). Therefore, we want down and left to return errors in those cases. Here are three possible options for down:

```
down1 :: Loc -> Maybe Loc
down2 :: Loc -> List Loc
down3 :: Loc -> Either String Loc
```

All the three implementations are trying to convey the same information. In case the movement is invalid, down1 returns Nothing; down2 returns an empty list; down3 returns Left err (where err is the error message). Otherwise, down1 returns Just v; down2 returns [v] (a singleton list); down3 returns Right v.

Then we can write a sample program that composes left, down, and an extra update. Note that we have to constantly check errors:

```
update :: (Int -> Int) -> (Int -> Int) -> Loc -> Loc
update f g (x, y) | f x \geq 0 && g y \geq 0 = (f x, g y)
                 | otherwise
                                       = (x, y)
ex1 :: Loc -> Maybe Loc
ex1 loc = case left1 loc of
           Nothing -> Nothing
           Just loc' -> case down1 loc' of
                          Nothing -> Nothing
                          Just loc'' -> Just $ update (+1) (+1) loc''
ex2 :: Loc -> List Loc
ex2 loc = case left2 loc of
                      -> Nil
           Nil
           Cons loc' _ -> case down2 loc' of
                            Nil -> Nil
                            Cons loc'' _ -> singleton $ update (+1) (+1) loc''
ex3 :: Loc -> Either String Loc
ex3 loc = case left3 loc of
           Left err -> Left err
           Right loc' -> case down3 loc' of
                           Left err' -> Left err'
                           Right loc'' -> Right $ update (+1) (+1) loc''
```

As you can witness, this kind of code is extremely tedious to write. Furthermore, no matter which option we choose, the code looks remarkably similar. This motivates the need for a new design pattern. The most common solution amongst functional programmers is probably monads.

3.2 Introducing Monads

Monads are data structures that support two primitive operators: return (pure) and bind. Haskell models them as a type class, which can be thought as an interface that requires every member of it to implement the two operators:

```
class Monad m where
  return :: a -> m a
  (>>=) :: m a -> (a -> m b) -> m b
```

The latter (bind is denoted as >>= in Haskell) serves the purpose of sequencing; while the former injects a value into a monad. The benefit of using a monad is that constant checking for corner cases is no longer visible to the programmer.

We can declare all three types (i.e. Maybe, List, and Either String) as monads by define the two primitive operators. You should have tried to implement bind for Either in Assignment 1. It is important for you to understand what is happening under the hood for the other two cases. For example, the Maybe monad is implemented as:

We define two functions: return a and ma >>= a2mb. The first function, given a value of any type, injects it into the monad by applying the Just constructor to it. The second function, given a computation which is already inside the monad (i.e. a term of type Maybe a) and a continuation in case the evaluation is successful, performs pattern matching and applies the continuation only when the first computation succeeds. Therefore, error checking is hidden behind the >>= operator. In fact, our previous example ex1 was no more than a sequence of these checks, followed by an injection of an application of the update function. It means that we can write less verbose code to express equivalent logic:

This pattern is so common in Haskell that there is a special syntax for it. The same program can be written with the *do-notation*:

Here, do is a keyword indicating that the inner block is running inside a monad. Each occurrence of <- is translated to a use of >>=. Finally, return remains unchanged. This notation is reminiscent of some form of imperative programming.

Question 3. Complete the definitions of ex2do and ex3do using the do-notation.

3.3 Parametrization of Monads

Though we have already written neat monadic code, we can still add a final degree of abstraction. Since we went through the trouble of defining safe operators for all the three monads, we can now easily offer programmers the opportunity to choose their preferred ones!

The idea is that we define a new function that runs our language inside any monad, as long as it provides the basic constructs. Thus, the example can be parametrized by the type of monads:

```
exM :: Monad m => (Loc -> m Loc) -> (Loc -> m Loc) -> (Loc -> m Loc)
-> Loc -> m Loc
exM up down left loc = undefined
```

The first three parameters are the base constructs: up, down, and left. The forth parameter is the input location. Notice that even though we are free to choose a Monad and its implementation for the basic operators, we can not mix different monads together. We can choose to call exM with up1, down1, and left1, but not with nonsensical combinations like up1, down2, and left3. For example, the following program instantiates exM with the Either String monad:

```
exEither :: Loc -> Either String Loc
exEither = exM up3 down3 left3
```

Question 4. Complete the definition of exM using the do-notation, whose logic is equivalent to ex1do, ex2do, or ex3do.

The evaluators we wrote in previous lectures and tutorials can also be simplified by monads and do-notation. Try to find some of them and refactor by yourself!