

Matthew Hutchinson

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Mechanical Engineer pursuing an M.S. at UCLA with a focus in Design, Robotics, and Manufacturing. Passionate about building control-driven systems at the intersection of biomechanics and automation. Skilled in Python, MATLAB, SolidWorks, and digital fabrication.

Education

UCLA Master of Science in Mechanical Engineering (DROM)	September 2025 - June 2026
Bionic Systems Engineering, Soft Robotics, Data Science, Advanced Robotics (planned), Compliant Mechanism Design (planned), Reinforcement Learning (planned)	
UCLA Bachelor of Science in Mechanical Engineering	September 2022 - June 2024
Robotics (Kinematics, Dynamics, & Control), Rapid Prototyping & Manufacturing, Mechanism Design, Manufacturing, Data Structures & Algorithms, C++, Python	

Work Experience

UCLA Engineering MakerSpace	April 2024 – July 2024
Digital Fabrication Artist	
• Designed 3D-layered art pieces using laser cutters, 3D printers, and hand tools (acrylic, wood, paper)	
• Led student workshops on fabrication techniques and digital tools (Illustrator, Fusion 360)	
• Mentored 30+ students on design thinking and hands-on prototyping	
UCLA DevX	September 2022 – June 2024
Autonomous Rover Developer	
• Designed and built an autonomous rover for street navigation and disk transport, featuring a rack-and-pinion scooper arm and crank-based lift for elevated drop-off	
• Programmed drive and control systems using Python, OpenCV (line detection), and PID loops on Raspberry Pi and Arduino	
• Validated system on ramped obstacle course achieving accurate object delivery and path tracking	

Robotic Arm For Automated Fiber Placement	March 2024 – June 2024
Member	
• Designed impedance controller for robotic roller to regulate force during composite fiber layup	
• Maintained target force of $50 \pm 10\text{N}$ while minimizing lateral loads and ensuring structural integrity	
• Generated fiber deposition trajectories using Bezier surface intersections	
• Simulated full system in PyDrake and validated control logic through bench tests	

NASA Langley Research Center	August 2022 – August 2022
Intern, AAM Safety Team	
• Investigated safety and airspace challenges for Advanced Air Mobility (AAM) and eVTOL aircraft • Proposed a conceptual detect-and-avoid (DAA) system using neural networks and multi-sensor fusion for eVTOL aircraft • Explored urban air mobility use cases and integration barriers for AAM systems • Delivered a conceptual safety assurance framework to NASA engineers and researchers	
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Skills: Data Science/Machine Learning, MATLAB, Python, SolidWorks

Hobbies: Acrobatics, Cooking, Digital fabrication, Motorcycles, Yoga