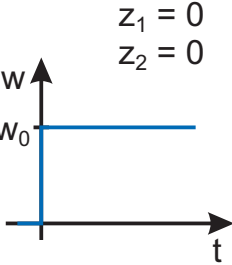
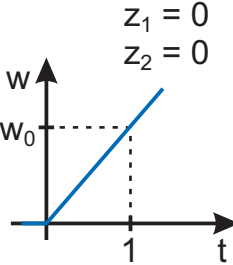
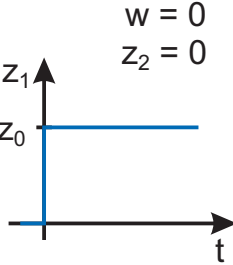
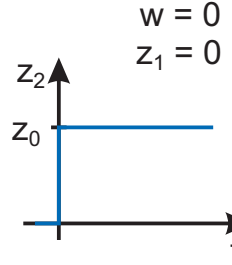


Regler $G_R(s)$		Regelstrecke $G_S(s)$	Bleibende Regeldifferenz e_∞ für			
						
P	K_P	P-Typ entsprechend $K_S \cdot \frac{1+ \dots}{1+ \dots}$	$\frac{1}{1+K_P K_S} \cdot w_0$	∞	$\frac{-K_S}{1+K_P K_S} \cdot z_0$	$\frac{-1}{1+K_P K_S} \cdot z_0$
I	$\frac{K_I}{s}$		0	$\frac{1}{K_I K_S} \cdot w_0$	0	0
PI	$K_P + \frac{K_I}{s}$		0	$\frac{1}{K_I K_S} \cdot w_0$	0	0
I_2	$\frac{K_I}{s^2}$		0	0	0	0
P	K_P	I-Typ entsprechend $\frac{K_S}{s} \cdot \frac{1+ \dots}{1+ \dots}$	0	$\frac{1}{K_P K_S} \cdot w_0$	$\frac{-1}{K_P} \cdot z_0$	0
I	$\frac{K_I}{s}$		0	0	0	0
PI	$K_P + \frac{K_I}{s}$		0	0	0	0