```
restart;
  with(LinearAlgebra):
\rightarrow Dmat := proc(se, pars)
   local DD1, i, j;
   description "Form the derivative matrix";
   with(LinearAlgebra):
   DD1 := Matrix(1..Dimension(pars), 1..Dimension(se)):
   for i from 1 to Dimension(pars) do
       for j from 1 to Dimension(se) do
           DD1[i, j] := diff(se[j], pars[i])
       end do
   end do:
   DD1;
   end proc:
\gt Estpar := \mathbf{proc}(DD1, pars, ret)
   local r, d, alphapre, alpha, PDE, FF, i, j, ans;
   description "Finds the estimable set of parameters for derivative matrix DD1. If ret = 1 returns
       alpha, PDEs, estimable parameter combinations. Otherwise returns estimable parameter
       combinations":
   with(LinearAlgebra) :
   r := Rank(DD1); d := Dimension(pars) - r:
   alphapre := NullSpace(Transpose(DD1)) : \alpha := Matrix(d, Dimension(pars)) : PDE :=
        Vector(d):
   FF := f(seq(pars[i], i=1 ..Dimension(pars))):
   for i from 1 to d do
         \alpha[i, 1..Dimension(pars)] := alphapre[i]:
         PDE[i] := add(diff(FF, pars[j]) \cdot \alpha[i, j], j = 1 ... Dimension(pars)):
   end do:
   if ret = 1 then
           ans := \langle pdsolve(\{seq(PDE[i] = 0, i = 1..d)\}), \{alpha\}, \{PDE\} \rangle:
   else
          ans := pdsolve(\{seq(PDE[i] = 0, i = 1..d)\}):
   end if:
   ans:
   end proc:
C := \langle \langle h[t] \cdot r[t] | 0 | 0 | 0 | 0 | 0 \rangle, \langle 0 | h[t] \cdot r[t] | 0 | 0 | 0 | 0 \rangle, \langle 0 | 0 | h[t] \cdot r[t] | 0 | 0 | 0 \rangle, \langle 0 | 0 | h[t] \cdot r[t] | 0 \rangle
       |0\rangle, \langle 0|0| 0| 0| h[t] \cdot r[t] |0\rangle, \langle 0| 0|0| 0| 0| h[t] \cdot r[t] \rangle;
   A := \langle \langle 0|f[t-1]|f[t-1]|f[t-1]|f[t-1]|f[t-1]\rangle, \langle (1-h[t-1]) \cdot s[t-1]|0|0|0|0|0\rangle,
        [-1]) \cdot s[t-1]|0|0\rangle, \langle 0|0|0|0|(1-h[t-1]) \cdot s[t-1]|0\rangle\rangle; xI := \langle N[1,1], N[1,2], N[1,1]\rangle
       3], N[1, 4], N[1, 5], N[1, 6]\rangle;
```

$$C := \begin{bmatrix} h_t r_t & 0 & 0 & 0 & 0 & 0 \\ 0 & h_t r_t & 0 & 0 & 0 & 0 \\ 0 & 0 & h_t r_t & 0 & 0 & 0 \\ 0 & 0 & 0 & h_t r_t & 0 & 0 \\ 0 & 0 & 0 & 0 & h_t r_t & 0 \\ 0 & 0 & 0 & 0 & 0 & h_t r_t \end{bmatrix}$$

$$A := \left[\left[0, f_{t-1}, f_{t-1}, f_{t-1}, f_{t-1}, f_{t-1}, f_{t-1} \right], \right.$$

$$\left[\left(1 - h_{t-1} \right) s_{t-1}, 0, 0, 0, 0, 0 \right], \\
\left[0, \left(1 - h_{t-1} \right) s_{t-1}, 0, 0, 0, 0 \right], \\
\left[0, 0, \left(1 - h_{t-1} \right) s_{t-1}, 0, 0, 0 \right], \\
\left[0, 0, 0, \left(1 - h_{t-1} \right) s_{t-1}, 0, 0 \right], \\
\left[0, 0, 0, 0, \left(1 - h_{t-1} \right) s_{t-1}, 0 \right] \right]$$

$$xI := \begin{bmatrix} N_{1, 1} \\ N_{1, 2} \\ N_{1, 3} \\ N_{1, 4} \\ N_{1, 5} \\ N_{1, 6} \end{bmatrix}$$
 (1)

> $xt := \langle x[t, 1], x[t, 2], x[t, 3], x[t, 4], x[t, 5], x[t, 6] \rangle;$

$$xt := \begin{bmatrix} x_{t, 1} \\ x_{t, 2} \\ x_{t, 3} \\ x_{t, 4} \\ x_{t, 5} \\ x_{t, 6} \end{bmatrix}$$
 (2)

$$A := \langle \langle 0 | f[t-1] | f[t-1] | f[t-1] \rangle, \langle (1-h[t-1]) \cdot s[t-1] | 0 | 0 \rangle, \langle 0 | (1-h[t-1]) \cdot s[t-1] | 0 | 0 \rangle, \langle 0 | 0 | (1-h[t-1]) \cdot s[t-1] | 0 \rangle \rangle; xI := \langle N[1,1], N[1,2], N[1,3], N[1,4] \rangle;$$

$$C := \left[\begin{array}{cccc} h_t r_t & 0 & 0 & 0 \\ 0 & h_t r_t & 0 & 0 \\ 0 & 0 & h_t r_t & 0 \\ 0 & 0 & 0 & h_t r_t \end{array} \right]$$

$$A := \begin{bmatrix} 0 & f_{t-1} & f_{t-1} & f_{t-1} \\ (1-h_{t-1}) s_{t-1} & 0 & 0 & 0 \\ 0 & (1-h_{t-1}) s_{t-1} & 0 & 0 \\ 0 & 0 & (1-h_{t-1}) s_{t-1} & 0 \end{bmatrix}$$

$$xI := \begin{bmatrix} N_{1, 1} \\ N_{1, 2} \\ N_{1, 3} \\ N_{1, 4} \end{bmatrix}$$
(3)

- # Components of the exhaustive summary
- \rightarrow kappa11 := MatrixMatrixMultiply(eval(C, t=1), x1);

$$\kappa II := \begin{bmatrix} h_1 r_1 N_{1, 1} \\ h_1 r_1 N_{1, 2} \\ h_1 r_1 N_{1, 3} \\ h_1 r_1 N_{1, 4} \end{bmatrix}$$

$$(4)$$

$$\kappa 12 := \begin{bmatrix}
r_2 h_2 \left(f_1 N_{1, 2} + f_1 N_{1, 3} + f_1 N_{1, 4} \right) \\
r_2 h_2 \left(1 - h_1 \right) s_1 N_{1, 1} \\
r_2 h_2 \left(1 - h_1 \right) s_1 N_{1, 2} \\
r_2 h_2 \left(1 - h_1 \right) s_1 N_{1, 3}
\end{bmatrix}$$
(5)

- \rightarrow kappa13 := MatrixMatrixMultiply(eval(C, t = 3), MatrixMatrixMultiply(eval(A, t = 3), MatrixMatrixMultiply(eval(A, t=2), x1));

$$\kappa I3 := \begin{bmatrix}
r_3 h_3 \left(f_2 \left(1 - h_1 \right) s_1 N_{1, 1} + f_2 \left(1 - h_1 \right) s_1 N_{1, 2} + f_2 \left(1 - h_1 \right) s_1 N_{1, 3} \right) \\
r_3 h_3 \left(1 - h_2 \right) s_2 \left(f_1 N_{1, 2} + f_1 N_{1, 3} + f_1 N_{1, 4} \right) \\
r_3 h_3 \left(1 - h_2 \right) s_2 \left(1 - h_1 \right) s_1 N_{1, 1} \\
r_3 h_3 \left(1 - h_2 \right) s_2 \left(1 - h_1 \right) s_1 N_{1, 2}
\end{bmatrix}$$
(6)

- $> \#C_3A_4A_3A_2x_1$
- > kappa14 := MatrixMatrixMultiply(eval(C, t = 4), MatrixMatrixMultiply(eval(A, t = 4), MatrixMatrixMultiply(eval(A, t = 3), MatrixMatrixMultiply(eval(A, t = 2), x1))));

$$\kappa I4 := \left[\left[r_4 h_4 \left(f_3 \left(1 - h_2 \right) s_2 \left(f_1 N_{1, 2} + f_1 N_{1, 3} + f_1 N_{1, 4} \right) + f_3 \left(1 - h_2 \right) s_2 \left(1 - h_1 \right) s_1 N_{1, 1} \right. \right. \\
+ f_3 \left(1 - h_2 \right) s_2 \left(1 - h_1 \right) s_1 N_{1, 2} \right], \\
\left[r_4 h_4 \left(1 - h_3 \right) s_3 \left(f_2 \left(1 - h_1 \right) s_1 N_{1, 1} + f_2 \left(1 - h_1 \right) s_1 N_{1, 2} + f_2 \left(1 - h_1 \right) s_1 N_{1, 3} \right) \right], \\
\left[r_4 h_4 \left(1 - h_3 \right) s_3 \left(1 - h_2 \right) s_2 \left(f_1 N_{1, 2} + f_1 N_{1, 3} + f_1 N_{1, 4} \right) \right], \\
\left[r_4 h_4 \left(1 - h_3 \right) s_3 \left(1 - h_2 \right) s_2 \left(1 - h_1 \right) s_1 N_{1, 1} \right] \right]$$

- # Building exhaustive summary up one component at a time
- $\rightarrow kappa1 := \langle kappa11 \rangle;$

$$\kappa I := \begin{bmatrix} h_1 \, r_1 \, N_{1, \, 1} \\ h_1 \, r_1 \, N_{1, \, 2} \\ h_1 \, r_1 \, N_{1, \, 3} \\ h_1 \, r_1 \, N_{1, \, 4} \end{bmatrix} \tag{8}$$

> indets(kappa1) $\{N_{1,1}, N_{1,2}, N_{1,3}, N_{1,4}, h_1, r_1\}$ (9)

 $\rightarrow pars1 := \langle h_1, r_1 \rangle;$

$$pars1 := \begin{bmatrix} h_1 \\ r_1 \end{bmatrix}$$
 (10)

 $\rightarrow D1 := Dmat(convert(kappa1, Vector), pars1);$

$$D1 := \begin{bmatrix} r_1 N_{1, 1} & r_1 N_{1, 2} & r_1 N_{1, 3} & r_1 N_{1, 4} \\ h_1 N_{1, 1} & h_1 N_{1, 2} & h_1 N_{1, 3} & h_1 N_{1, 4} \end{bmatrix}$$

$$(11)$$

> nopars := Dimension(pars1); rr := Rank(D1); d := Dimension(pars1) - rr;nopars := 2

$$rr := 1$$

$$d := 1$$
(12)

= > Estpar(D1, pars1, 0);

$$\{f(h_1, r_1) = FI(r_1 h_1)\}$$
 (13)

= $\langle kappa1 := \langle kappa11, kappa12 \rangle;$

$$\kappa I := \begin{bmatrix}
h_1 r_1 N_{1, 1} \\
h_1 r_1 N_{1, 2} \\
h_1 r_1 N_{1, 3} \\
h_1 r_1 N_{1, 4} \\
r_2 h_2 (f_1 N_{1, 2} + f_1 N_{1, 3} + f_1 N_{1, 4}) \\
r_2 h_2 (1 - h_1) s_1 N_{1, 1} \\
r_2 h_2 (1 - h_1) s_1 N_{1, 2} \\
r_2 h_2 (1 - h_1) s_1 N_{1, 3}
\end{bmatrix}$$
(14)

> indets(kappa1)

$$\{N_{1,1}, N_{1,2}, N_{1,3}, N_{1,4}, f_1, h_1, h_2, r_1, r_2, s_1\}$$
 (15)

 $\{N_{1, 1}, \dots, pars1 := \langle f_1, h_1, h_2, r_1, r_2, s_1 \rangle;$

$$pars1 := \begin{bmatrix} f_1 \\ h_1 \\ h_2 \\ r_1 \\ r_2 \\ s_1 \end{bmatrix} \tag{16}$$

> D1 := Dmat(convert(kappa1, Vector), pars1); $D1 := [[0, 0, 0, 0, r_2 h_2 (N_{1, 2} + N_{1, 3} + N_{1, 4}), 0, 0, 0],$ $[r_1 N_{1, 1}, r_1 N_{1, 2}, r_1 N_{1, 3}, r_1 N_{1, 4}, 0, -r_2 h_2 s_1 N_{1, 1}, -r_2 h_2 s_1 N_{1, 2}, -r_2 h_2 s_1 N_{1, 3}],$ $[0, 0, 0, 0, r_2 (f_1 N_{1, 2} + f_1 N_{1, 3} + f_1 N_{1, 4}), r_2 (1 - h_1) s_1 N_{1, 1}, r_2 (1 - h_1) s_1 N_{1, 2}, r_2 (1 - h_1) s_1 N_{1, 3}],$ $[h_1 N_{1, 1}, h_1 N_{1, 2}, h_1 N_{1, 3}, h_1 N_{1, 4}, 0, 0, 0, 0],$ $[0, 0, 0, 0, h_2 (f_1 N_{1, 2} + f_1 N_{1, 3} + f_1 N_{1, 4}), h_2 (1 - h_1) s_1 N_{1, 1}, h_2 (1 - h_1) s_1 N_{1, 2},$ $h_2 (1 - h_1) s_1 N_{1, 3}],$ $[0, 0, 0, 0, 0, r_2 h_2 (1 - h_1) N_{1, 1}, r_2 h_2 (1 - h_1) N_{1, 2}, r_2 h_2 (1 - h_1) N_{1, 3}]]$

> nopars := Dimension(pars1); rr := Rank(D1); d := Dimension(pars1) - rr; nopars := 6rr := 3

$$rr := 3$$

$$d := 3$$
(18)

> *Estpar*(*D1*, *pars1*, 0);

(19)

$$\left\{ f(f_1, h_1, h_2, r_1, r_2, s_1) = _F I\left(r_1 h_1, r_2 f_1 h_2, \frac{s_1(h_1 - 1)}{f_1}\right) \right\}$$
 (19)

 \rightarrow kappa1 := $\langle kappa11, kappa12, kappa13 \rangle$;

$$h_{1} r_{1} N_{1, 1}
h_{1} r_{1} N_{1, 2}
h_{1} r_{1} N_{1, 3}
h_{1} r_{1} N_{1, 4}
r_{2} h_{2} (f_{1} N_{1, 2} + f_{1} N_{1, 3} + f_{1} N_{1, 4})
r_{2} h_{2} (1 - h_{1}) s_{1} N_{1, 1}
r_{2} h_{2} (1 - h_{1}) s_{1} N_{1, 2}
r_{2} h_{2} (1 - h_{1}) s_{1} N_{1, 3}
r_{3} h_{3} (f_{2} (1 - h_{1}) s_{1} N_{1, 1} + f_{2} (1 - h_{1}) s_{1} N_{1, 2} + f_{2} (1 - h_{1}) s_{1} N_{1, 3})
r_{3} h_{3} (1 - h_{2}) s_{2} (f_{1} N_{1, 2} + f_{1} N_{1, 3} + f_{1} N_{1, 4})
\vdots$$
(20)

12 × 1 Matrix

> indets(kappa1)

$$\{N_{1,1}, N_{1,2}, N_{1,3}, N_{1,4}, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2\}$$
 (21)

- > $pars1 := \langle f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2 \rangle$:
- $\triangleright D1 := Dmat(convert(kappa1, Vector), pars1)$:
- > nopars := Dimension(pars1); rr := Rank(D1); d := Dimension(pars1) rr;nopars := 10

$$rr := 5$$

$$d := 5$$
(22)

> Estpar(D1, pars1, 0);

$$\left\{ f\left(f_{1}, f_{2}, h_{1}, h_{2}, h_{3}, r_{1}, r_{2}, r_{3}, s_{1}, s_{2}\right) = FI\left(r_{1} h_{1}, r_{2} f_{1} h_{2}, r_{3} h_{3} f_{2} f_{1}, \frac{s_{1} \left(h_{1} - 1\right)}{f_{1}}, \frac{s_{2} \left(-1 + h_{2}\right)}{f_{2}}\right) \right\}$$

$$\frac{s_{2} \left(-1 + h_{2}\right)}{f_{2}}\right)$$
(23)

⊳ # Clear pattern

> #Estimable parameter combinations are $r_1 h_1$, $r_2 h_2 f_1$, $r_3 h_3 f_1 f_2$, ..., $r_n h_n f_1 f_2 ... f_n$, $\frac{s_1 \left(1 - h_1\right)}{f_1}$,

$$\frac{s_2(1-h_2)}{f_2},...,\frac{s_{n-1}(1-h_{n-1})}{f_{n-1}}$$

 $pp := 4 \cdot n - 2$

$$pp := 4 n - 2 \tag{24}$$

>
$$rr := 2 \cdot n - 1$$

 $rr := 2 n - 1$ (25)
> $dd := pp - rr$;

dd := 2 n - 1(26)

- > # Apply extension Theomrem in two directions
- > # First involves adding extra age classes this would be a "trivual" application of the extension theorem as you add new exhaustive summary terms, but no new parameters. Note it is not completely straightforward, as model is parameter redundant. Would need to first reparameterise in terms of estimable parameter combinations. You can easily show that each additional terms can be written in terms of the estimable parameter combinations - and rest follows from this fact.
- > # Second involves adding extra years. This would be more complicated, but still involves reparamerising in terms of the estimable parameter combinations.
- # Hunter Survey data
- $kappa2 := \langle r[1] \cdot a[1], r[2] \cdot a[2], r[3] \cdot a[3] \rangle;$

$$\kappa 2 := \begin{bmatrix} r_1 \, a_1 \\ r_2 \, a_2 \\ r_3 \, a_3 \end{bmatrix} \tag{27}$$

> $pars2 := \langle r[1], r[2], r[3] \rangle;$

$$pars2 := \begin{bmatrix} r_1 \\ r_2 \\ r_3 \end{bmatrix}$$
 (28)

 $\rightarrow D2 := Dmat(kappa2, pars2);$

$$D2 := \begin{bmatrix} a_1 & 0 & 0 \\ 0 & a_2 & 0 \\ 0 & 0 & a_3 \end{bmatrix}$$
 (29)

> nopars := Dimension(pars2); rr := Rank(D2); d := Dimension(pars2) - rr;nopars := 3

$$rr := 3$$

$$d := 0$$
(30)

Radio Tracking data

>
$$kappa3 := \langle h[1] \cdot v[1], (1 - h[1]) \cdot (1 - s[1]) \cdot v[1], h[2] \cdot v[2], (1 - h[2]) \cdot (1 - s[2]) \cdot v[2], h[3] \cdot v[3], (1 - h[3]) \cdot (1 - s[3]) \cdot v[3] \rangle;$$

$$\kappa_3 := \begin{bmatrix}
h_1 v_1 \\
(1 - h_1) (1 - s_1) v_1 \\
h_2 v_2 \\
(1 - h_2) (1 - s_2) v_2 \\
h_3 v_3 \\
(1 - h_3) (1 - s_3) v_3
\end{bmatrix}$$
(31)

$$pars3 := \begin{bmatrix} h_1 \\ h_2 \\ h_3 \\ s_1 \\ s_2 \\ s_3 \end{bmatrix}$$

$$(32)$$

> D3 := Dmat(kappa3, pars3);

$$D3 := \begin{bmatrix} v_1 & -(1-s_1) & v_1 & 0 & 0 & 0 & 0 \\ 0 & 0 & v_2 & -(1-s_2) & v_2 & 0 & 0 \\ 0 & 0 & 0 & 0 & v_3 & -(1-s_3) & v_3 \\ 0 & -(1-h_1) & v_1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -(1-h_2) & v_2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -(1-h_3) & v_3 \end{bmatrix}$$

$$(33)$$

> nopars := Dimension(pars3); rr := Rank(D3); d := Dimension(pars3) - rr;nopars := 6

$$rr := 6$$

$$d := 0$$
(34)

- # Considering different combinations of data sets:
- $kappajoin := convert(\langle kappa1, kappa2 \rangle, Vector)$:
- > indets(kappajoin)

$$\left\{N_{1,1}, N_{1,2}, N_{1,3}, N_{1,4}, a_1, a_2, a_3, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2\right\} \tag{35}$$

- Djoin := Dmat(kappajoin, pars):
- > nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) rr;nopars := 10

```
rr := 8
                                                            d := 2
                                                                                                                                   (36)
> Estpar(Djoin, pars, 0);

\left\{ f\left(f_{1}, f_{2}, h_{1}, h_{2}, h_{3}, r_{1}, r_{2}, r_{3}, s_{1}, s_{2}\right) = FI\left(h_{1}, f_{1} h_{2}, f_{2} h_{3} f_{1}, r_{1}, r_{2}, r_{3}, \frac{s_{1}}{f_{1}}, -\frac{s_{2} \left(-1 + h_{2}\right)}{f_{2}}\right) \right\}

                                                                                                                                   (37)
                                                                                                                                   (38)
(39)
  > dd := pp - rr; 
                                                        dd := n - 1
                                                                                                                                   (40)
    kappajoin := convert(\langle kappa1, kappa3 \rangle, Vector):
 > indets(kappajoin)
                     \{N_{1,1},N_{1,2},N_{1,3},N_{1,4},f_1,f_2,h_1,h_2,h_3,r_1,r_2,r_3,s_1,s_2,s_3,v_1,v_2,v_3\}
                                                                                                                                   (41)
> pars := \langle f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3 \rangle:
\triangleright Djoin := Dmat(kappajoin, pars):
 > nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) - rr;
                                                       nopars := 11
                                                          rr := 11
                                                            d := 0
                                                                                                                                   (42)
\triangleright kappajoin := convert(\langle kappa2, kappa3\rangle, Vector):
 > indets(kappajoin)
                                 \{a_1, a_2, a_3, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3, v_1, v_2, v_3\}
                                                                                                                                   (43)
 > pars := \langle h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3 \rangle:
\rightarrow Djoin := Dmat(kappajoin, pars):
 > nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) - rr;
                                                        nopars := 9
                                                           rr := 9
                                                            d := 0
                                                                                                                                   (44)
\blacktriangleright kappajoin \coloneqq convert(\langle kappa1, kappa2, kappa3\rangle, Vector):
 > indets(kappajoin)
               \{N_{1-1}, N_{1-2}, N_{1-3}, N_{1-4}, a_1, a_2, a_3, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3, v_1, v_2, v_3\}
                                                                                                                                   (45)
 > pars := \langle f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3 \rangle:
\triangleright Djoin := Dmat(kappajoin, pars):
 > nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) - rr;
                                                       nopars := 11
                                                          rr := 11
                                                            d := 0
                                                                                                                                   (46)
```