```
# Identifiability of Elk using 2 state model
   restart;
> with(LinearAlgebra):
> Dmat := proc(se, pars)
   local DD1, i, j;
   description "Form the derivative matrix";
   with(LinearAlgebra) :
   DD1 := Matrix(1..Dimension(pars), 1..Dimension(se)):
   for i from 1 to Dimension(pars) do
       for j from 1 to Dimension(se) do
            DD1[i, j] := diff(se[j], pars[i])
        end do
    end do:
   DD1:
    end proc:
\gt Estpar := proc(DD1, pars, ret)
   local r, d, alphapre, alpha, PDE, FF, i, j, ans;
   description "Finds the estimable set of parameters for derivative matrix DD1. If ret = 1 returns
        alpha, PDEs, estimable parameter combinations. Otherwise returns estimable parameter
        combinations";
   with(LinearAlgebra) :
   r := Rank(DD1); d := Dimension(pars) - r:
   alphapre := NullSpace(Transpose(DD1)) : \alpha := Matrix(d, Dimension(pars)) : PDE :=
         Vector(d):
   FF := f(seq(pars[i], i = 1 .. Dimension(pars))):
   for i from 1 to d do
          \alpha[i, 1..Dimension(pars)] := alphapre[i]:
          PDE[i] := add(diff(FF, pars[i]) \cdot \alpha[i, j], j = 1 .. Dimension(pars)):
   end do:
    if ret = 1 then
            ans := \langle pdsolve(\{seq(PDE[i] = 0, i = 1 ... d)\}), \{alpha\}, \{PDE\} \rangle:
    else
           ans := pdsolve(\{seq(PDE[i] = 0, i = 1..d)\}):
    end if:
    ans:
   end proc:
\succ C := \langle \langle h[t] \cdot r[t] | 0 \rangle, \langle 0 | h[t] \cdot r[t] \rangle \rangle;
    A := \langle \langle 0 | f[t-1] \rangle, \langle (1-h[t-1]) \cdot s[t-1] | (1-h[t-1]) \cdot s[t-1] \rangle \rangle;
   x1 := \langle N[1, 1], N[1, 2] \rangle;
                            C := \begin{bmatrix} h_t r_t & 0 \\ 0 & h_t r_t \end{bmatrix}
A := \begin{bmatrix} 0 & f_{t-1} \\ (1 - h_{t-1}) s_{t-1} & (1 - h_{t-1}) s_{t-1} \end{bmatrix}
```

$$xI := \begin{bmatrix} N_{1, 1} \\ N_{1, 2} \end{bmatrix}$$
 (1)

Components of the exhaustive summary

 $+ C_1 x_1$

> kappa11 := MatrixMatrixMultiply(eval(C, t=1), x1)

$$\kappa II := \begin{bmatrix} h_1 r_1 N_{1, 1} \\ h_1 r_1 N_{1, 2} \end{bmatrix}$$
 (2)

> # $C_2A_2x_1$

> kappa12 := MatrixMatrixMultiply(eval(C, t=2), MatrixMatrixMultiply(eval(A, t=2), x1));

$$\kappa 12 := \begin{bmatrix} h_2 r_2 f_1 N_{1, 2} \\ h_2 r_2 ((1 - h_1) s_1 N_{1, 1} + (1 - h_1) s_1 N_{1, 2}) \end{bmatrix}$$
(3)

= > #C₃A₃A₂x₁

> kappa13 := MatrixMatrixMultiply(eval(C, t=3), MatrixMatrixMultiply(eval(A, t=3), MatrixMatrixMultiply(eval(A, t=2), x1)));

$$\kappa I3 := \begin{bmatrix} h_3 r_3 f_2 \left(\left(1 - h_1 \right) s_1 N_{1, 1} + \left(1 - h_1 \right) s_1 N_{1, 2} \right) \\ h_3 r_3 \left(\left(1 - h_2 \right) s_2 f_1 N_{1, 2} + \left(1 - h_2 \right) s_2 \left(\left(1 - h_1 \right) s_1 N_{1, 1} + \left(1 - h_1 \right) s_1 N_{1, 2} \right) \end{bmatrix}$$

$$(4)$$

 $\rightarrow #C_3A_4A_3A_2x_1$

> kappa14 := MatrixMatrixMultiply(eval(C, t = 4), MatrixMatrixMultiply(eval(A, t = 4), MatrixMatrixMultiply(eval(A, t = 3), MatrixMatrixMultiply(eval(A, t = 2), x1))));

$$\kappa I4 := \left[\left[h_4 r_4 f_3 \left(\left(1 - h_2 \right) s_2 f_1 N_{1, 2} + \left(1 - h_2 \right) s_2 \left(\left(1 - h_1 \right) s_1 N_{1, 1} + \left(1 - h_1 \right) s_1 N_{1, 2} \right) \right], \quad (5)$$

$$\left[h_4 r_4 \left(\left(1 - h_3 \right) s_3 f_2 \left(\left(1 - h_1 \right) s_1 N_{1, 1} + \left(1 - h_1 \right) s_1 N_{1, 2} \right) + \left(1 - h_3 \right) s_3 \left(\left(1 - h_2 \right) s_2 f_1 N_{1, 2} + \left(1 - h_2 \right) s_2 \left(\left(1 - h_1 \right) s_1 N_{1, 1} + \left(1 - h_1 \right) s_1 N_{1, 2} \right) \right) \right] \right]$$

> # Building exhaustive summary up one component at a time

 \rightarrow kappa1 := $\langle kappa11 \rangle$;

$$\kappa l := \begin{bmatrix} h_1 r_1 N_{1, 1} \\ h_1 r_1 N_{1, 2} \end{bmatrix}$$
 (6)

= > indets(kappa1)

$$\{N_{1,1}, N_{1,2}, h_1, r_1\} \tag{7}$$

 $\rightarrow pars1 := \langle h_1, r_1 \rangle;$

$$pars1 := \begin{bmatrix} h_1 \\ r_1 \end{bmatrix}$$
 (8)

 $\triangleright D1 := Dmat(convert(kappa1, Vector), pars1);$

$$D1 := \begin{bmatrix} r_1 N_{1, 1} & r_1 N_{1, 2} \\ h_1 N_{1, 1} & h_1 N_{1, 2} \end{bmatrix}$$
 (9)

> nopars := Dimension(pars1); rr := Rank(D1); d := Dimension(pars1) - rr;nopars := 2

$$rr := 1$$

$$d := 1$$
(10)

$$\{f(h_1, r_1) = FI(r_1 h_1)\}$$
 (11)

* Estpar(D1, pars1, 0); $\{f(h_1, r_1) = F1(r_1 h_1)\}$ * kappa1 := $\langle kappa11, kappa12 \rangle$;

$$\kappa I := \begin{bmatrix}
h_1 r_1 N_{1, 1} \\
h_1 r_1 N_{1, 2} \\
h_2 r_2 f_1 N_{1, 2} \\
h_2 r_2 ((1 - h_1) s_1 N_{1, 1} + (1 - h_1) s_1 N_{1, 2})
\end{bmatrix}$$
(12)

$$\{N_{1,1}, N_{1,2}, f_1, h_1, h_2, r_1, r_2, s_1\}$$
(13)

 $\begin{cases} N_{1,\;1},N_{1,\;2},f_1,h_1,h_2,r_1,r_2,s_1 \end{cases}$ $= \begin{cases} N_{1,\;1},N_{1,\;2},f_1,h_1,h_2,r_1,r_2,s_1 \end{cases};$

$$pars1 := \begin{bmatrix} f_1 \\ h_1 \\ h_2 \\ r_1 \\ r_2 \\ s_1 \end{bmatrix} \tag{14}$$

 $\rightarrow D1 := Dmat(convert(kappa1, Vector), pars1);$

$$DI := Dmat(convert(kappa1, Vector), pars1);$$

$$DI := \begin{bmatrix} 0 & 0 & h_2 r_2 N_{1,2} & 0 \\ r_1 N_{1,1} & r_1 N_{1,2} & 0 & h_2 r_2 \left(-s_1 N_{1,1} - s_1 N_{1,2} \right) \\ 0 & 0 & r_2 f_1 N_{1,2} & r_2 \left(\left(1 - h_1 \right) s_1 N_{1,1} + \left(1 - h_1 \right) s_1 N_{1,2} \right) \\ h_1 N_{1,1} & h_1 N_{1,2} & 0 & 0 \\ 0 & 0 & h_2 f_1 N_{1,2} & h_2 \left(\left(1 - h_1 \right) s_1 N_{1,1} + \left(1 - h_1 \right) s_1 N_{1,2} \right) \\ 0 & 0 & 0 & h_2 r_2 \left(\left(1 - h_1 \right) N_{1,1} + \left(1 - h_1 \right) N_{1,2} \right) \end{bmatrix}$$

$$(15)$$

> nopars := Dimension(pars1); rr := Rank(D1); d := Dimension(pars1) - rr;nopars := 6rr := 3

> # Need to first reparameterise in terms of estimable parameter combinations - then apply extension theorem

Hunter Survey data

> $kappa2 := \langle r[1] \cdot a[1], r[2] \cdot a[2], r[3] \cdot a[3] \rangle;$

$$\kappa 2 := \begin{bmatrix} r_1 a_1 \\ r_2 a_2 \\ r_3 a_3 \end{bmatrix}$$
 (25)

 $\rightarrow pars2 := \langle r[1], r[2], r[3] \rangle;$

$$pars2 := \begin{bmatrix} r_1 \\ r_2 \\ r_3 \end{bmatrix} \tag{26}$$

 $\rightarrow D2 := Dmat(kappa2, pars2);$

$$D2 := \begin{bmatrix} a_1 & 0 & 0 \\ 0 & a_2 & 0 \\ 0 & 0 & a_3 \end{bmatrix}$$
 (27)

> nopars := Dimension(pars2); rr := Rank(D2); d := Dimension(pars2) - rr;

$$nopars := 3$$

$$rr := 3$$

$$d := 0$$
(28)

Radio Tracking data

> $kappa3 := \langle h[1] \cdot v[1], (1 - h[1]) \cdot (1 - s[1]) \cdot v[1], h[2] \cdot v[2], (1 - h[2]) \cdot (1 - s[2]) \cdot v[2], h[3] \cdot v[3], (1 - h[3]) \cdot (1 - s[3]) \cdot v[3] \rangle;$

$$\kappa_{3} := \begin{bmatrix}
h_{1} v_{1} \\
(1 - h_{1}) (1 - s_{1}) v_{1} \\
h_{2} v_{2} \\
(1 - h_{2}) (1 - s_{2}) v_{2} \\
h_{3} v_{3} \\
(1 - h_{3}) (1 - s_{3}) v_{3}
\end{bmatrix}$$
(29)

> $pars3 := \langle h_1, h_2, h_3, s_1, s_2, s_3 \rangle;$

$$pars3 := \begin{bmatrix} h_1 \\ h_2 \\ h_3 \\ s_1 \\ s_2 \\ s_3 \end{bmatrix}$$

$$(30)$$

 $\rightarrow D3 := Dmat(kappa3, pars3);$

$$D3 := \begin{bmatrix} v_1 & -(1-s_1) & v_1 & 0 & 0 & 0 & 0 \\ 0 & 0 & v_2 & -(1-s_2) & v_2 & 0 & 0 \\ 0 & 0 & 0 & 0 & v_3 & -(1-s_3) & v_3 \\ 0 & -(1-h_1) & v_1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -(1-h_2) & v_2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -(1-h_3) & v_3 \end{bmatrix}$$

$$(31)$$

> nopars := Dimension(pars3); rr := Rank(D3); d := Dimension(pars3) - rr;nopars := 6

$$rr := 6$$

$$d := 0$$
(32)

- # Considering different combinations of data sets:
 - $kappajoin := convert(\langle kappa1, kappa2 \rangle, Vector) :$
- > indets(kappajoin)

$$\{N_{1,1}, N_{1,2}, a_1, a_2, a_3, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2\}$$
(33)

- > $pars := \langle f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2 \rangle$:
- \triangleright Djoin := Dmat(kappajoin, pars):
- > nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) rr;nopars := 10

$$rr \coloneqq 8$$

$$d := 2 \tag{34}$$

$$pp := 4 n - 2 \tag{36}$$

$$rr \coloneqq 3 \ n - 1 \tag{37}$$

```
dd := n - 1
                                                                                                                                      (38)
    kappajoin := convert(\langle kappa1, kappa3 \rangle, Vector):
    indets(kappajoin)
                             \{N_{1-1}, N_{1-2}, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3, v_1, v_2, v_3\}
                                                                                                                                      (39)
    pars := \langle f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3 \rangle:
    Djoin := Dmat(kappajoin, pars):
 \rightarrow nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) - rr;
                                                         nopars := 11
                                                            rr := 11
                                                             d := 0
                                                                                                                                      (40)
    kappajoin := convert(\langle kappa2, kappa3 \rangle, Vector):
 > indets(kappajoin)
                                  \{a_1, a_2, a_3, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3, v_1, v_2, v_3\}
                                                                                                                                      (41)
    pars := \langle h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3 \rangle:
\square Djoin := Dmat(kappajoin, pars):
 \rightarrow nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) - rr;
                                                         nopars := 9
                                                             rr := 9
                                                             d := 0
                                                                                                                                      (42)
\rightarrow kappajoin := convert(\langle kappa1, kappa2, kappa3\rangle, Vector):
 > indets(kappajoin)
                       \{N_{1-1}, N_{1-2}, a_1, a_2, a_3, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3, v_1, v_2, v_3\}
                                                                                                                                      (43)
 > pars := \langle f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3 \rangle:
\triangleright Djoin := Dmat(kappajoin, pars):
 > nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) - rr;
                                                         nopars := 11
                                                            rr := 11
                                                             d := 0
                                                                                                                                      (44)
     # Identifiability of Elk using 2 state model - assuming starting values unknown
 \succ C := \langle \langle h[t] \cdot r[t] | 0 \rangle, \langle 0 | h[t] \cdot r[t] \rangle \rangle;
     A := \langle \langle 0 | f[t-1] \rangle, \langle (1-h[t-1]) \cdot s[t-1] | (1-h[t-1]) \cdot s[t-1] \rangle \rangle;
      xI := \langle N[1, 1], N[1, 2] \rangle;
                                                   C := \left[ \begin{array}{cc} h_t r_t & 0 \\ 0 & h_t r_t \end{array} \right]
                                  A := \begin{bmatrix} 0 & f_{t-1} \\ (1-h_{t-1}) s_{t-1} & (1-h_{t-1}) s_{t-1} \end{bmatrix}
```

(45)

$$xI := \begin{bmatrix} N_{1, 1} \\ N_{1, 2} \end{bmatrix}$$
 (45)

#` Components of the exhaustive summary

 $+ C_1 x_1$

> kappa11 := MatrixMatrixMultiply(eval(C, t=1), x1);

$$\kappa II := \begin{bmatrix} h_1 r_1 N_{1, 1} \\ h_1 r_1 N_{1, 2} \end{bmatrix}$$
 (46)

> $\#``C_2A_2x_1$

> kappa12 := MatrixMatrixMultiply(eval(C, t=2), MatrixMatrixMultiply(eval(A, t=2), x1));

$$\kappa I2 := \begin{bmatrix} h_2 r_2 f_1 N_{1, 2} \\ h_2 r_2 ((1 - h_1) s_1 N_{1, 1} + (1 - h_1) s_1 N_{1, 2}) \end{bmatrix}$$

$$(47)$$

= > #C₃A₃A₂x₁

> kappa13 := MatrixMatrixMultiply(eval(C, t=3), MatrixMatrixMultiply(eval(A, t=3), MatrixMatrixMultiply(eval(A, t=2), x1)));

$$\kappa I3 := \begin{bmatrix} h_3 r_3 f_2 \left(\left(1 - h_1 \right) s_1 N_{1, 1} + \left(1 - h_1 \right) s_1 N_{1, 2} \right) \\ h_3 r_3 \left(\left(1 - h_2 \right) s_2 f_1 N_{1, 2} + \left(1 - h_2 \right) s_2 \left(\left(1 - h_1 \right) s_1 N_{1, 1} + \left(1 - h_1 \right) s_1 N_{1, 2} \right) \end{bmatrix}$$

$$(48)$$

 $\rightarrow #C_3A_4A_3A_2x_1$

> kappa14 := MatrixMatrixMultiply(eval(C, t = 4), MatrixMatrixMultiply(eval(A, t = 4), MatrixMatrixMultiply(eval(A, t = 3), MatrixMatrixMultiply(eval(A, t = 2), x1))));

$$\kappa I4 := \left[\left[h_4 r_4 f_3 \left((1 - h_2) s_2 f_1 N_{1, 2} + (1 - h_2) s_2 \left((1 - h_1) s_1 N_{1, 1} + (1 - h_1) s_1 N_{1, 2} \right) \right], \quad (49)$$

$$\left[h_4 r_4 \left((1 - h_3) s_3 f_2 \left((1 - h_1) s_1 N_{1, 1} + (1 - h_1) s_1 N_{1, 2} \right) + (1 - h_3) s_3 \left((1 - h_2) s_2 f_1 N_{1, 2} + (1 - h_2) s_2 \left((1 - h_1) s_1 N_{1, 1} + (1 - h_1) s_1 N_{1, 2} \right) \right) \right] \right]$$

Building exhaustive summary up one component at a time

 \rightarrow kappa1 := $\langle kappa11 \rangle$;

$$\kappa I := \begin{bmatrix} h_1 r_1 N_{1, 1} \\ h_1 r_1 N_{1, 2} \end{bmatrix}$$
 (50)

> indets(kappa1)

$$\{N_{1,1}, N_{1,2}, h_1, r_1\}$$
 (51)

 \rightarrow pars $1 := \langle N_{1, 1}, N_{1, 2}, h_1, r_1 \rangle;$

(52)

$$pars1 := \begin{bmatrix} N_{1, 1} \\ N_{1, 2} \\ h_{1} \\ r_{1} \end{bmatrix}$$
 (52)

 \rightarrow D1 := Dmat(convert(kappa1, Vector), pars1);

$$DI := \begin{bmatrix} r_1 h_1 & 0 \\ 0 & r_1 h_1 \\ r_1 N_{1, 1} & r_1 N_{1, 2} \\ h_1 N_{1, 1} & h_1 N_{1, 2} \end{bmatrix}$$
 (53)

> nopars := Dimension(pars1); rr := Rank(D1); d := Dimension(pars1) - rr;nopars := 4

$$rr := 2$$

$$d := 2$$
(54)

> *Estpar*(*D1*, *pars1*, 0);

$$\left\{ f(N_{1,1}, N_{1,2}, h_1, r_1) = _F I\left(\frac{N_{1,2}}{N_{1,1}}, h_1 r_1 N_{1,1}\right) \right\}$$
 (55)

 \rightarrow kappa1 := $\langle kappa11, kappa12 \rangle$;

$$\kappa I := \begin{bmatrix}
h_1 \, r_1 \, N_{1, \, 1} \\
h_1 \, r_1 \, N_{1, \, 2} \\
h_2 \, r_2 \, f_1 \, N_{1, \, 2} \\
h_2 \, r_2 \, \left(\left(1 - h_1 \right) \, s_1 \, N_{1, \, 1} + \left(1 - h_1 \right) \, s_1 \, N_{1, \, 2} \right)
\end{bmatrix}$$
(56)

> indets(kappa1)

$$\left\{N_{1,1}, N_{1,2}, f_1, h_1, h_2, r_1, r_2, s_1\right\} \tag{57}$$

> $pars1 := \langle N_{1,1}, N_{1,2}, f_1, h_1, h_2, r_1, r_2, s_1 \rangle;$

(58)

$$pars1 := \begin{bmatrix} N_{1, 1} \\ N_{1, 2} \\ f_{1} \\ h_{1} \\ h_{2} \\ r_{1} \\ r_{2} \\ s_{1} \end{bmatrix}$$
 (58)

$$DI := Dmat(convert(kappa1, Vector), pars1);$$

$$DI := \begin{bmatrix} r_1 h_1 & 0 & 0 & h_2 r_2 (1 - h_1) s_1 \\ 0 & r_1 h_1 & h_2 r_2 f_1 & h_2 r_2 (1 - h_1) s_1 \\ 0 & 0 & h_2 r_2 N_{1,2} & 0 \\ \\ r_1 N_{1,1} & r_1 N_{1,2} & 0 & h_2 r_2 (-N_{1,1} s_1 - N_{1,2} s_1) \\ 0 & 0 & r_2 f_1 N_{1,2} & r_2 ((1 - h_1) s_1 N_{1,1} + (1 - h_1) s_1 N_{1,2}) \\ h_1 N_{1,1} & h_1 N_{1,2} & 0 & 0 \\ 0 & 0 & h_2 f_1 N_{1,2} & h_2 ((1 - h_1) s_1 N_{1,1} + (1 - h_1) s_1 N_{1,2}) \\ 0 & 0 & 0 & h_2 r_2 ((1 - h_1) N_{1,1} + (1 - h_1) N_{1,2}) \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{S} \text{propaga} := Dimension(pars1) : rr := Pank(D1) : d := Dimension(pars1) = rr.} \end{bmatrix}$$

> nopars := Dimension(pars1); rr := Rank(D1); d := Dimension(pars1) − rr;nopars := 8

$$rr := 4$$

$$d := 4$$
(60)

> *Estpar*(*D1*, *pars1*, 0);

$$\left\{ f\left(N_{1,1}, N_{1,2}, f_1, h_1, h_2, r_1, r_2, s_1\right) = FI\left(\frac{N_{1,2}}{N_{1,1}}, h_1 r_1 N_{1,1}, h_2 r_2 f_1 N_{1,1}, \frac{s_1 (h_1 - 1)}{f_1}\right) \right\}$$
(61)

> $kappa1 := \langle kappa11, kappa12, kappa13 \rangle;$

>
$$indets(kappa1)$$
 $\{N_{1,1}, N_{1,2}, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2\}$ (63)

pars $l := \langle N_{1,1}, N_{1,2}, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2 \rangle$:

 $\triangleright D1 := Dmat(convert(kappa1, Vector), pars1) :$

> nopars := Dimension(pars1); rr := Rank(D1); d := Dimension(pars1) - rr;nopars := 12

$$rr := 6$$

$$d := 6$$
(64)

$$\left\{ f\left(N_{1, 1}, N_{1, 2}, f_{1}, f_{2}, h_{1}, h_{2}, h_{3}, r_{1}, r_{2}, r_{3}, s_{1}, s_{2}\right) = _{F}I\left(\frac{N_{1, 2}}{N_{1, 1}}, h_{1} r_{1} N_{1, 1}, h_{2} r_{2} f_{1} N_{1, 1}, h_{2} r_{2} f_{1} N_{1, 1}, h_{3} r_{2} f_{1} N_{1, 1}, h_{4} r_{5} f_{1} N_{1, 1}, h_{5} r_{5} f_{1$$

> # Clear pattern

> #Estimable parameter combinations are $\frac{N_{1,\,2}}{N_{1,\,1}}$, $r_1\,h_1N_{1,\,1}$, $r_2h_2f_1N_{1,\,1}$, $r_3h_3f_1f_2N_{1,\,1}$,, $r_nh_nf_1f_2$...

$$f_n N_{1, 1}, \frac{s_1 (1-h_1)}{f_1}, \frac{s_2 (1-h_2)}{f_2}, ..., \frac{s_{n-1} (1-h_{n-1})}{f_{n-1}}$$

$$pp := 4 n \tag{66}$$

$$rr \coloneqq 2 n \tag{67}$$

$$dd := 2 n \tag{68}$$

> # Apply extension Theomrem:

> # Need to first reparameterise in terms of estimable parameter combinations - then apply extension theorem

Hunter Survey data $kappa2 := \langle r[1] \cdot a[1], r[2] \cdot a[2], r[3] \cdot a[3] \rangle;$

$$\kappa 2 := \begin{bmatrix} r_1 \, a_1 \\ r_2 \, a_2 \\ r_3 \, a_3 \end{bmatrix} \tag{69}$$

> $pars2 := \langle r[1], r[2], r[3] \rangle;$

$$pars2 := \begin{bmatrix} r_1 \\ r_2 \\ r_3 \end{bmatrix} \tag{70}$$

D2 := Dmat(kappa2, pars2);

$$D2 := \begin{bmatrix} a_1 & 0 & 0 \\ 0 & a_2 & 0 \\ 0 & 0 & a_3 \end{bmatrix}$$
 (71)

> nopars := Dimension(pars2); rr := Rank(D2); d := Dimension(pars2) - rr;nopars := 3

$$rr := 3$$

$$d := 0$$
(72)

> # Radio Tracking data

> $kappa3 := \langle h[1] \cdot v[1], (1 - h[1]) \cdot (1 - s[1]) \cdot v[1], h[2] \cdot v[2], (1 - h[2]) \cdot (1 - s[2]) \cdot v[2], h[3] \cdot v[3], (1 - h[3]) \cdot (1 - s[3]) \cdot v[3] \rangle;$

$$\kappa 3 := \begin{bmatrix}
h_1 v_1 \\
(1 - h_1) (1 - s_1) v_1 \\
h_2 v_2 \\
(1 - h_2) (1 - s_2) v_2 \\
h_3 v_3 \\
(1 - h_3) (1 - s_3) v_3
\end{bmatrix}$$
(73)

> $pars3 := \langle h_1, h_2, h_3, s_1, s_2, s_3 \rangle$

$$pars3 := \begin{bmatrix} h_1 \\ h_2 \\ h_3 \\ s_1 \\ s_2 \\ s_3 \end{bmatrix}$$
 (74)

> D3 := Dmat(kappa3, pars3);

(75)

$$D3 := \begin{bmatrix} v_1 & -(1-s_1) v_1 & 0 & 0 & 0 & 0 \\ 0 & 0 & v_2 & -(1-s_2) v_2 & 0 & 0 \\ 0 & 0 & 0 & 0 & v_3 & -(1-s_3) v_3 \\ 0 & -(1-h_1) v_1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -(1-h_2) v_2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -(1-h_3) v_3 \end{bmatrix}$$
 (75)

> nopars := Dimension(pars3); rr := Rank(D3); d := Dimension(pars3) - rr;nopars := 6

$$rr := 6$$

$$d := 0$$
(76)

- > # Considering different combinations of data sets:
- \rightarrow kappajoin := convert(\langle kappa1, kappa2\rangle, Vector):
- > indets(kappajoin)

$$\{N_{1,1}, N_{1,2}, a_1, a_2, a_3, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2\}$$
(77)

- \rightarrow pars := $\langle N_{1,1}, N_{1,2}, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2 \rangle$:
- \triangleright Djoin := Dmat(kappajoin, pars):
- > nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) rr;nopars := 12

$$rr := 9$$

$$d := 3$$
(78)

> Estpar(Djoin, pars, 0);

$$\begin{cases}
f(N_{1,1}, N_{1,2}, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2) = FI\left(h_1 N_{1,1}, \frac{N_{1,2}}{N_{1,1}}, f_1 h_2 N_{1,1}, N_{1,1} h_3 f_2 f_1, r_1, \frac{N_{1,2}}{N_{1,1}}, f_1 h_2 N_{1,1}, N_{1,1} h_3 f_2 f_1, r_1, \frac{N_{1,2}}{N_{1,1}}, f_1 h_2 N_{1,1}, \frac{N_{1,2}}{N_{1,1}}, f_1 h_2 N_{1,1}, \frac{N_{1,2}}{N_{1,1}}, \frac{N_{1,2}}{N_{1,2}}, \frac{N_{$$

$$r_2, r_3, -\frac{s_1(h_1-1)}{f_1}, -\frac{s_2(-1+h_2)}{f_2}$$

 $pp := 4 \cdot n$

$$pp \coloneqq 4 \, n \tag{80}$$

 $rr := 3 \cdot n$

$$rr \coloneqq 3 n$$
 (81)

$$dd := n$$
 (82)

- \rightarrow kappajoin := convert($\langle kappa1, kappa3 \rangle$, Vector):
- > indets(kappajoin)

$$\{N_{1,1}, N_{1,2}, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3, v_1, v_2, v_3\}$$
(83)

- > $pars := \langle N_{1,1}, N_{1,2}, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3 \rangle$:
- \rightarrow Djoin := Dmat(kappajoin, pars):
- > nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) rr;

```
nopars := 13
                                                       rr := 12
                                                        d := 1
                                                                                                                            (84)
   kappajoin := convert(\langle kappa2, kappa3 \rangle, Vector):
   indets(kappajoin)
                              \left\{a_{1}, a_{2}, a_{3}, h_{1}, h_{2}, h_{3}, r_{1}, r_{2}, r_{3}, s_{1}, s_{2}, s_{3}, v_{1}, v_{2}, v_{3}\right\}
                                                                                                                            (85)
   pars := \langle h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3 \rangle:
   Djoin := Dmat(kappajoin, pars):
> nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) − rr;
                                                    nopars := 9
                                                       rr := 9
                                                        d := 0
                                                                                                                            (86)
   kappajoin := convert(\langle kappa1, kappa2, kappa3 \rangle, Vector):
   indets(kappajoin)
                    \{N_{1,1}, N_{1,2}, a_1, a_2, a_3, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3, v_1, v_2, v_3\}
                                                                                                                            (87)
   pars := \langle N_{1,1}, N_{1,2}, f_1, f_2, h_1, h_2, h_3, r_1, r_2, r_3, s_1, s_2, s_3 \rangle :
   Djoin := Dmat(kappajoin, pars):
> nopars := Dimension(pars); rr := Rank(Djoin); d := Dimension(pars) - rr;
                                                   nopars := 13
                                                       rr := 13
                                                        d := 0
                                                                                                                            (88)
```