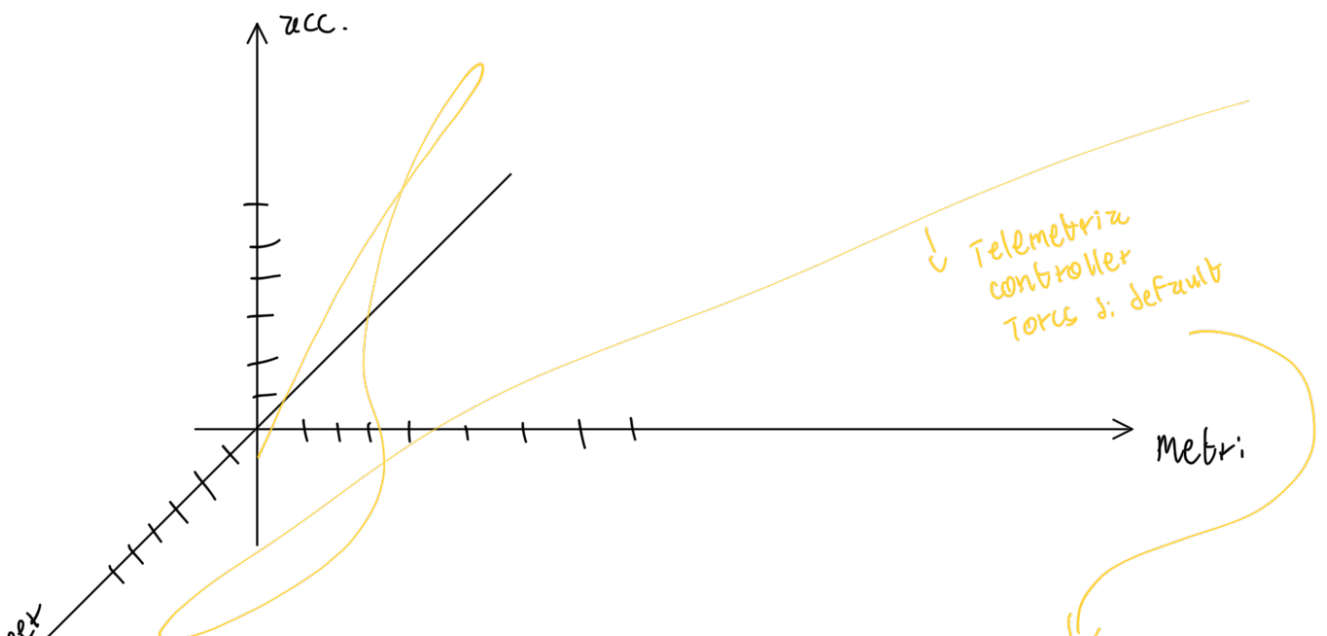
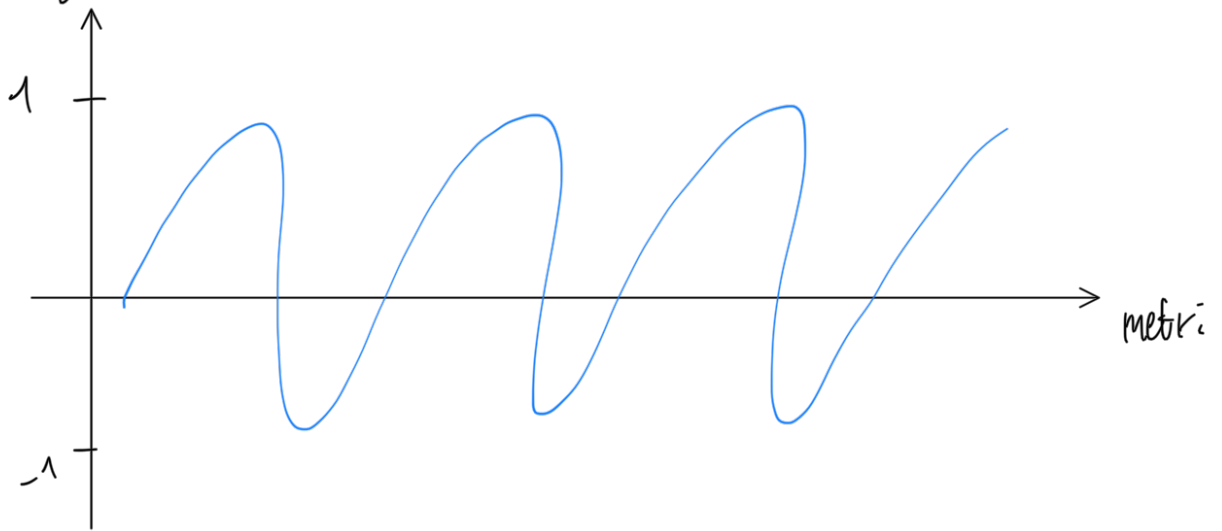
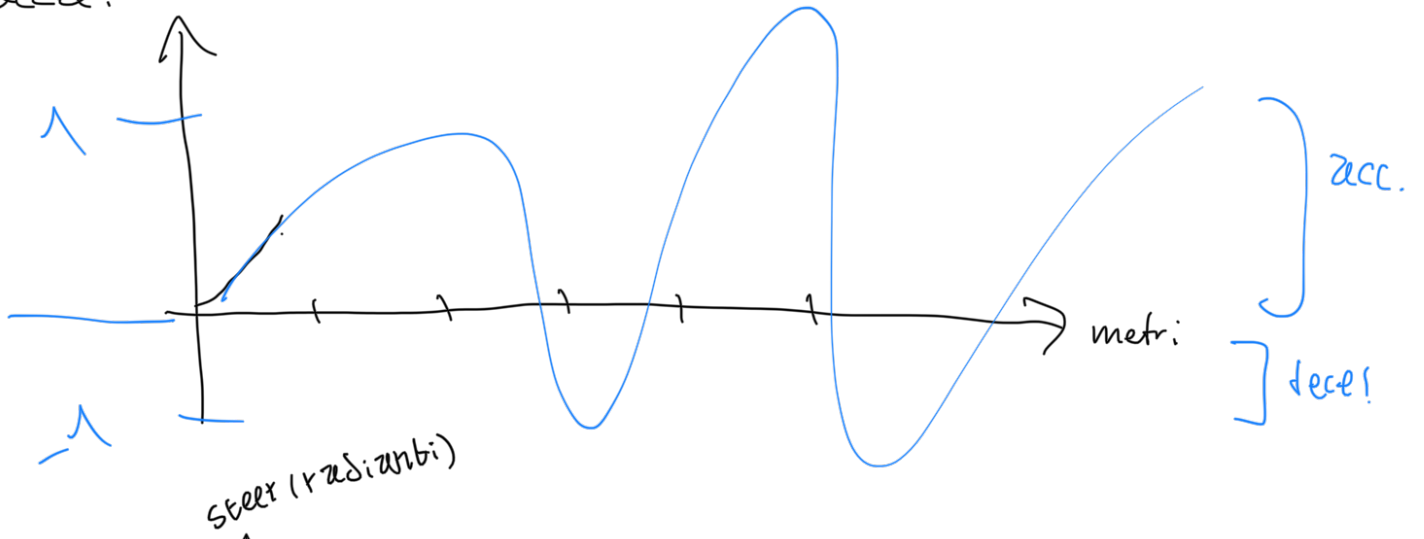


accel.



star

DFT in 3D \leftarrow start. point $\leftarrow \frac{1}{N} \sum \leftarrow$ vector < telemetrie >

ES

Fit. Function

$:= d_1$ gomme d_2 benzina
 d_3 tempo

Constraint.

- rimanere nel percorso
- finire il giro

Assunzioni:

- Single Agent
- No retro