Deep Learning

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Expected Outcomes

- How to create MLP/CNN-LSTM model
- How to train a deep learning model by Pytorch

Pytorch

https://pytorch.org/

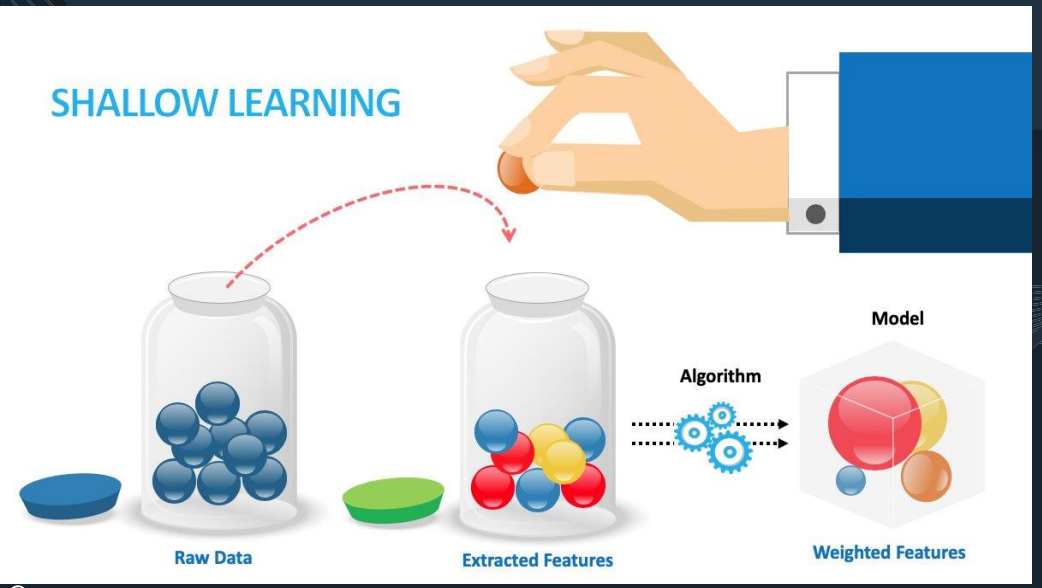
NOTE: Latest PyTorch requires Python 3.9 or later.

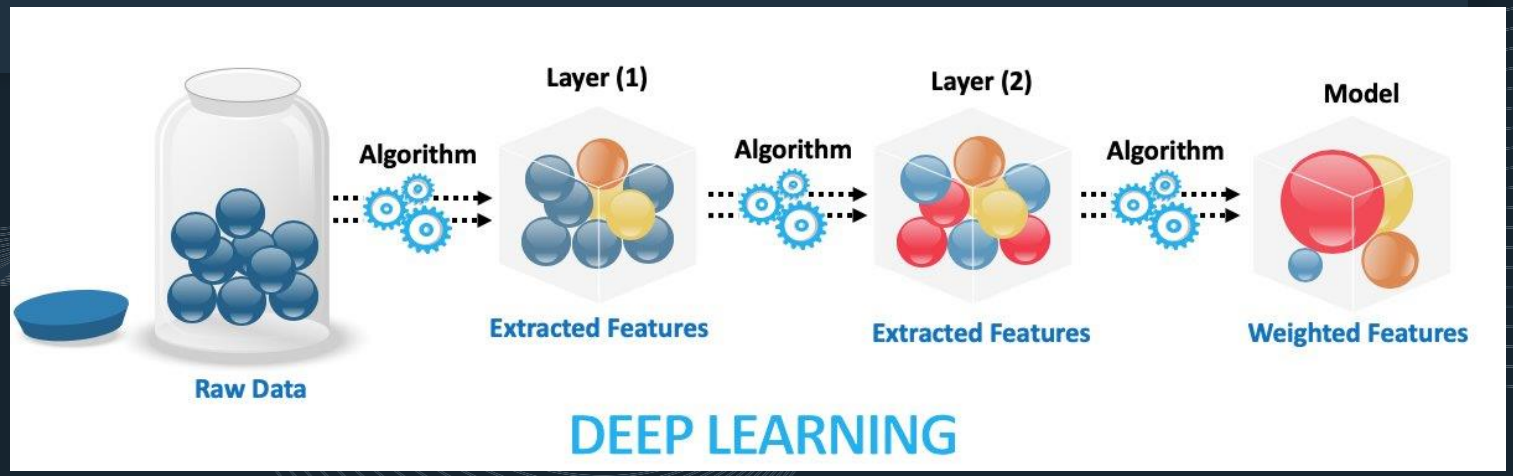
PyTorch Build	Stable (2.6.0)			Preview (Nightly)	
Your OS	Linux		Mac	Windows	
Package	Conda	Pip		LibTorch	Source
Language	Python			C++ / Java	
Compute Platform	CUDA 11.8	CUDA 12.4	CUDA 12.6	~~ROCm 6.2.4~~	CPU
Run this Command:	`pip3 install torch torchvision torchaudio`				

differences

Shallow Learning: we extract features from the channels across the entire s liding window. So each sliding window is transformed into 2 features (for example, the mean total acceleration and the mean total angular speed)

Deep Learning: we do not extract features but give the whole data of the sli ding window at once. That is, 32*2 (64) values. The deep neural network is s upposed to learn features from the “raw” data. And deep learning model also have a much higher parameter and complexity

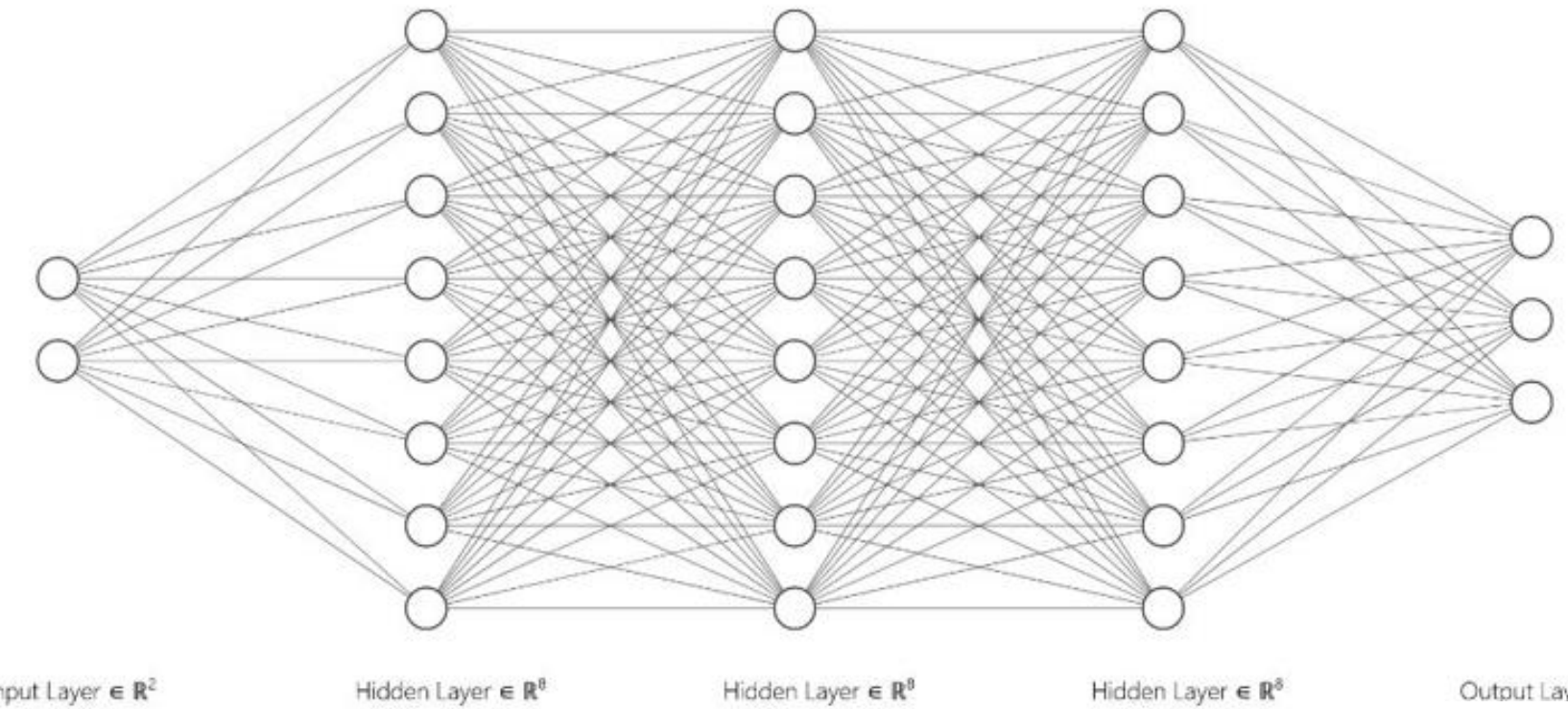


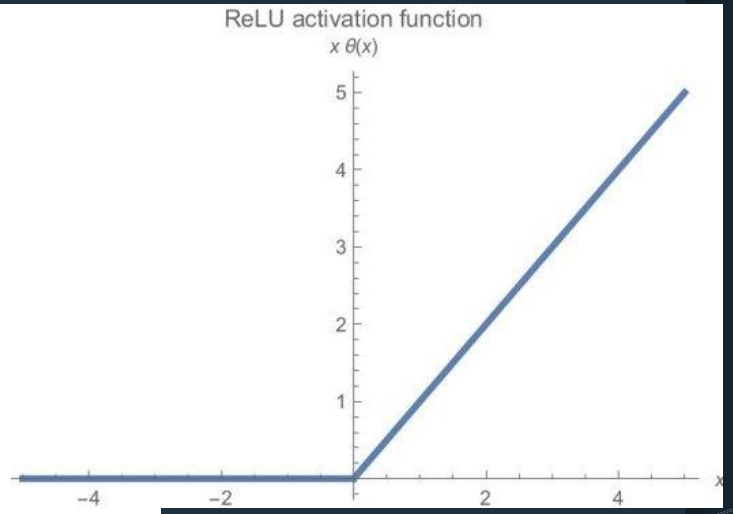


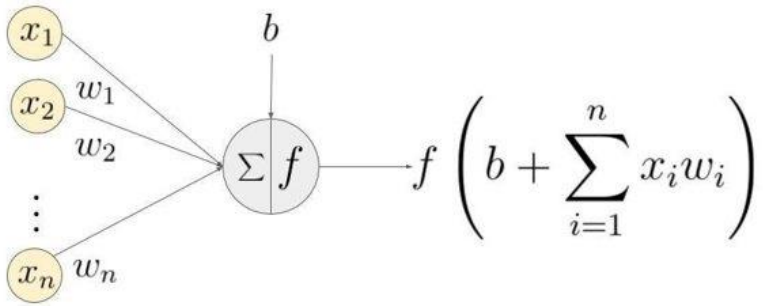
Steps for training Deep learning model

- **STEP 1.** We define the number of layers and their neurons.
- **STEP 2.** We initialize the weights and biases.
- **STEP 3.** We choose an optimizer, loss function, and learning rate. These three things will work together to gradually change the weights.
- **STEP 4.** We start the learning (training or optimization).
- **STEP 5.** The training ends according to certain criteria

Multi-layer perceptron (MLP)

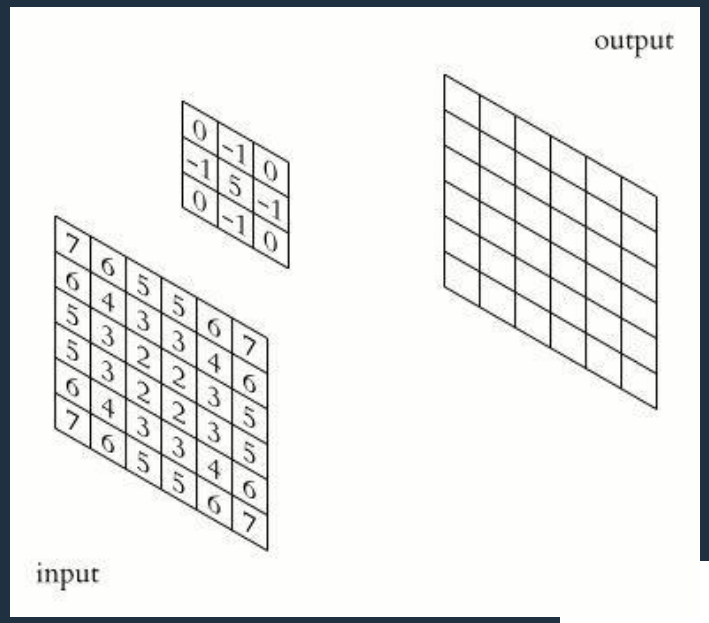


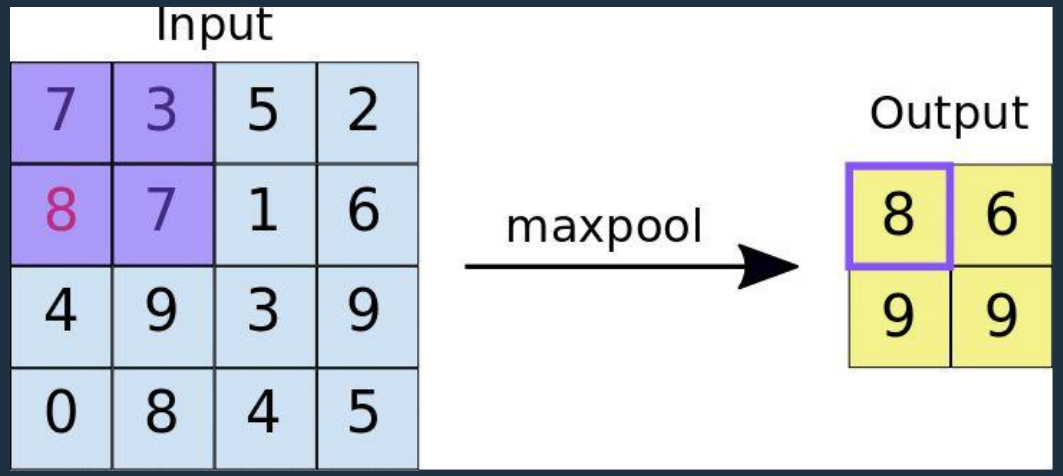


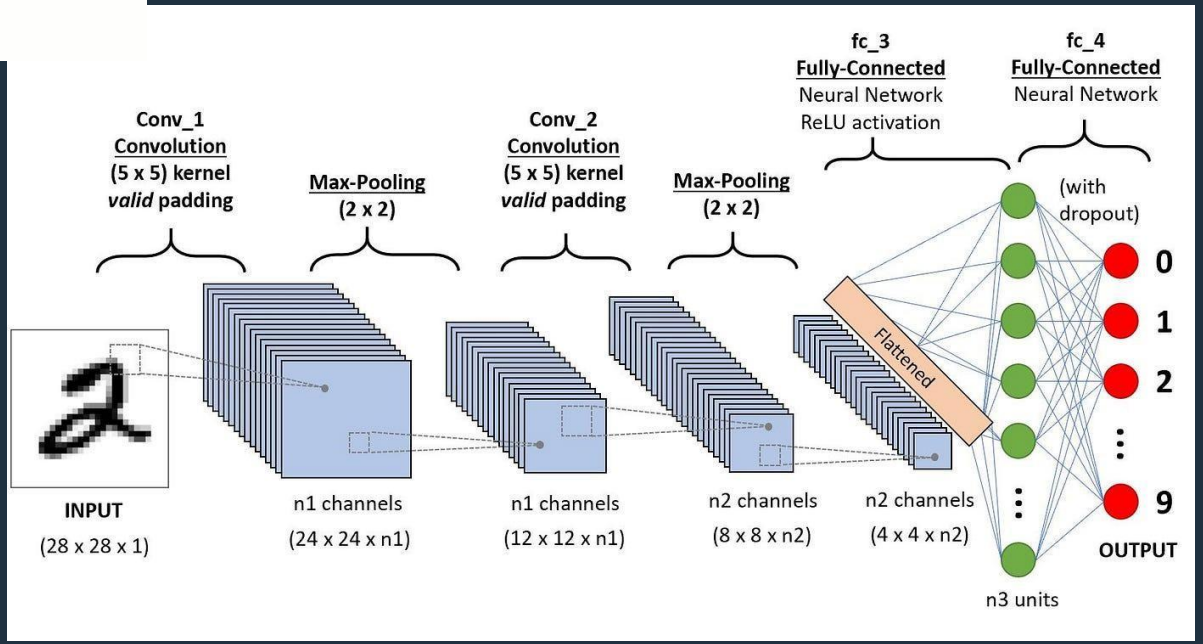


An example of a neuron showing the input (x_1 - x_n), their corresponding weights (w_1 - w_n), a bias (b) and the activation function f applied to the weighted sum of the inputs.

Convolutional Neural Network (CNN)



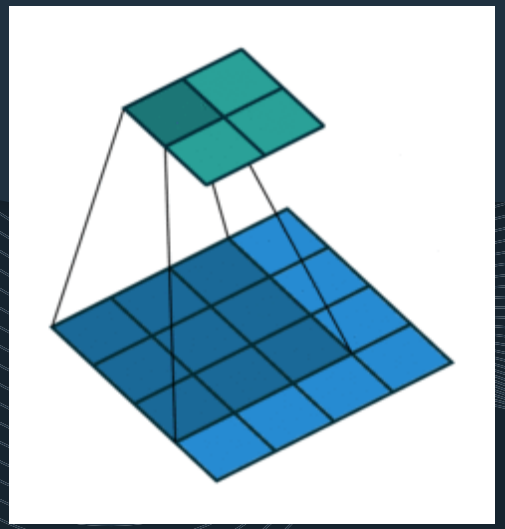




Convolutional Neural Network (CNN)

Kenel size = (3,3)

Stride=(1,1)
Padding=0



Stride=(2,2)
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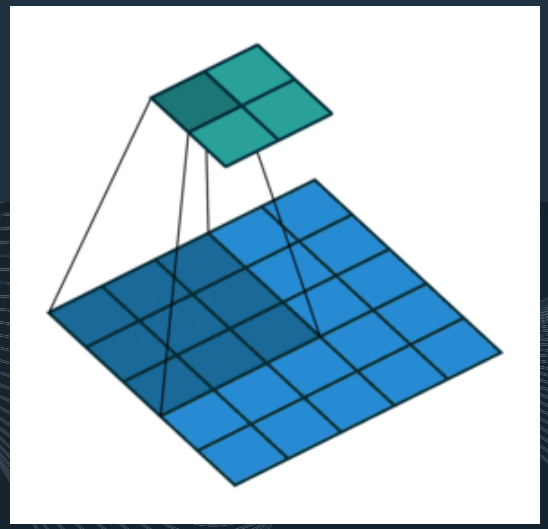

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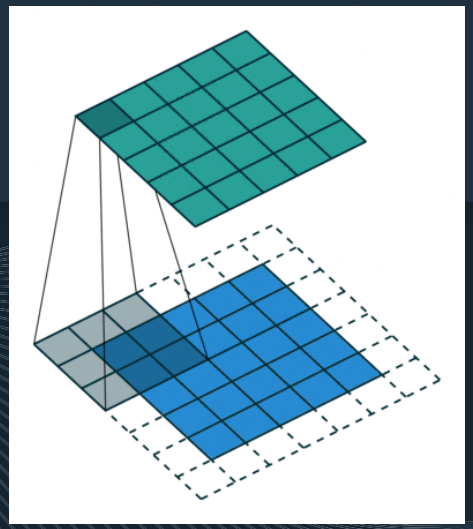

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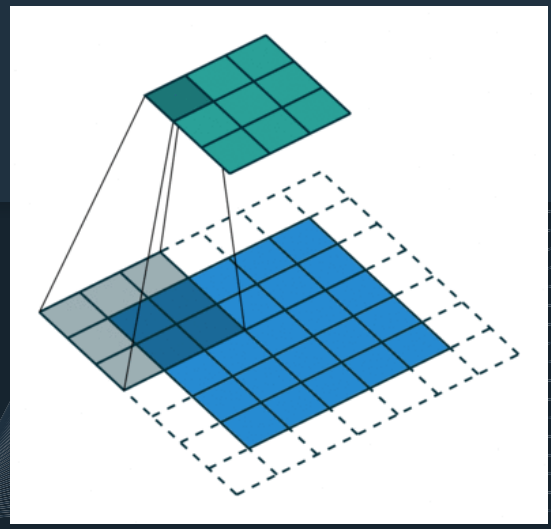
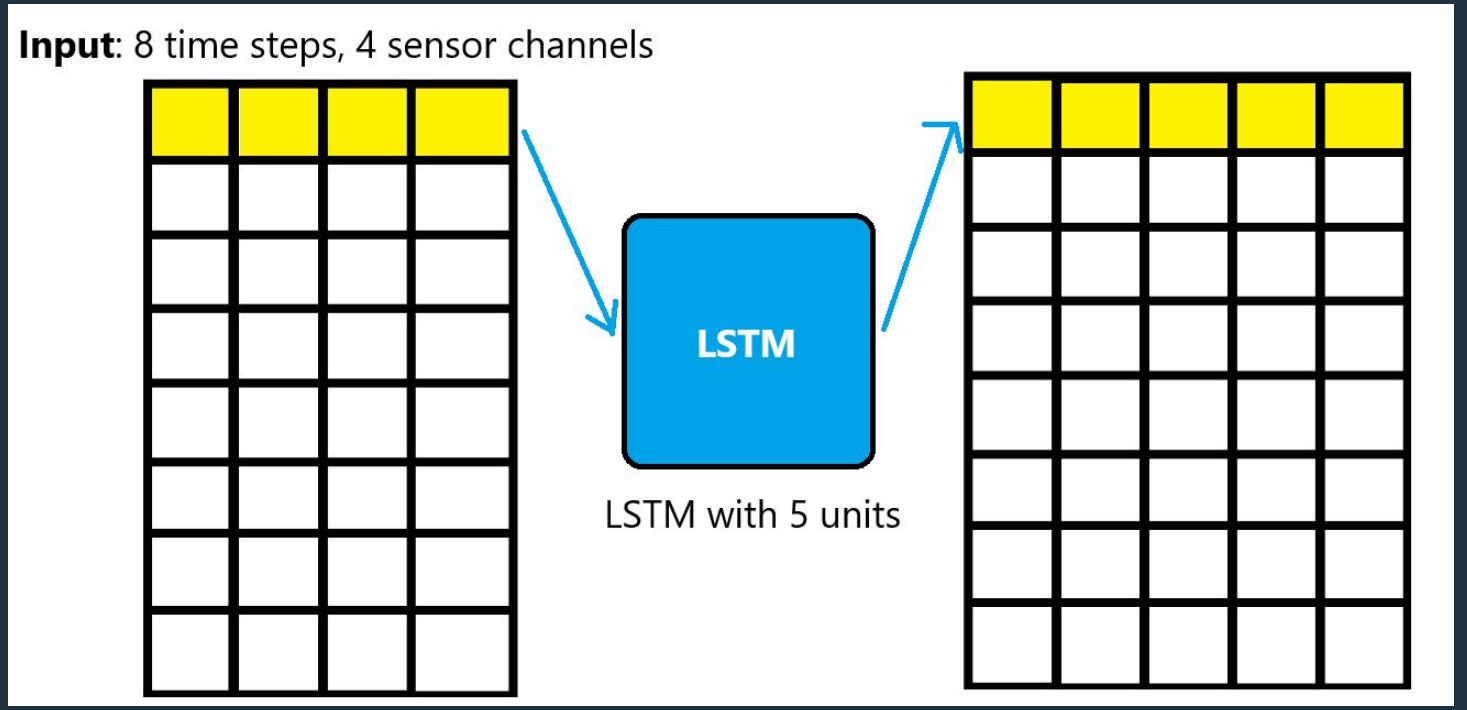


- LSTMs (Long Short-Term Memory): for temporal relationship
- An LSTM layer processes the input (time-series data) step by step. Step *n* depends on all previous steps.

  Input size:(batch_size, 8, 4)
  Input gate, forget gate, output gate
  Output size: (batch_size, 5), the last hidden state from LSTM(batch_size, 8, 5)



Summary

1. How to receive data from Arduino

2. How to pre-processing data

3. Different classification model: shallow learning methods

4. Model deployment: real-time prediction

5. Deep learning

Next lecture and tutorial: Q&A