

CSE 13s Spring 2021
 Assignment 5:
 Hamming Codes
 Design Document

Prelab:

1.

error		row in H^T (0-index)
MSB	0000	LSB \Rightarrow HAM_OK
	0001	\rightarrow 4
	0010	\rightarrow 5
	0011	\rightarrow HAM_Err
	0100	\rightarrow 6
	0101	\rightarrow HAM_Err
	0110	\rightarrow HAM_Err
	0111	\rightarrow 3
	1000	\rightarrow 7
	1001	\rightarrow HAM_Err
	1010	\rightarrow HAM_Err
	1011	\rightarrow 2
	1100	\rightarrow HAM_Err
	1101	\rightarrow 1
	1110	\rightarrow 0
	1111	\rightarrow HAM_Err

2.

a.

2.)

$$a.) \begin{array}{cc} 1110 & 0011 \\ p_3 p_2 p_1 p_0 & p_3 p_2 p_1 p_0 \end{array}$$

$$p_0 = \overline{D_1} \wedge D_2 \wedge D_3 \quad \begin{array}{c} 0 \\ 1 \end{array}$$

$$= 1 \wedge 0 \wedge 0 = 1 \neq p_0$$

$$p_1 = D_0 \wedge \overline{D_2} \wedge D_3$$

$$= 1 \wedge 0 \wedge 0 = 1 = p_1$$

$$p_2 = D_0 \wedge \overline{D_1} \wedge D_3$$

$$= 1 \wedge 1 \wedge 0 = 0 = p_2 \neq 1$$

$$p_3 = D_0 \wedge \overline{D_1} \wedge \overline{D_2}$$

$$= 1 \wedge 1 \wedge 0 = 0 = p_3 \neq 1$$

• All errors occurs because of D_1

So it has to be flipped

to 0

$$\text{Correct} = \underbrace{1110}_p \quad \underbrace{0001}_p$$

b.

$$6.) \quad 1101 \ 1000_2$$

$$P_0 = D_1 \wedge D_2 \wedge D_3 \quad P_0 = 1$$

$$= 0 \wedge 0 \wedge 1 = 1 \equiv P_0$$

$$+ P_1 = D_0 \wedge D_2 \wedge D_3 \quad P_1 = 0$$

$$= 0 \wedge 0 \wedge 1 = 1 \neq P_1$$

$$P_2 = D_0 \wedge D_1 \wedge D_3 \quad P_2 = 1$$

$$= 0 \wedge 0 \wedge 1 = 1 \equiv P_2$$

$$+ P_3 = D_0 \wedge D_1 \wedge D_2 \quad P_3 = 1$$

$$= 0 \wedge 0 \wedge 0 = 0 \neq P_3$$

• This is not correctable because both P_1 & P_3 are wrong, and they have D_0 and D_2 in common. But P_2 & P_0 is correct so no possible replacement.

Description:

For this assignment, I will be implementing hamming codes, encoding and decoding them. It used to counteract noisy interference, because transferring data through a noisy communication channel is prone to errors. This is done by adding extra information to our data which allows us to perform error checking, and request that the sender retransmit any data that was incorrect. In addition, not only detect errors but we can also correct them. This technique is called forward error correction (FEC).

TOP LEVEL:

Encode:

```
encode{
    opt = 0;
    output = stdout;
    input = stdin;
    C = 0;

    while ((opt = getopt(argc, argv, OPTIONS)) != -1) { //program argument
        parser.
        switch (opt) {
            case 'h':
                //print message
                exit(1);
                break;
            case 'i': input = fopen(optarg, "rb"); break;
            case 'o': output = fopen(optarg, "wb"); break;
        }
    }

    //create Generator Matrix G
    while ((c = fgetc(input)) != EOF){
        //read byte
        //encode top nibble
        //put it in the output
    }
}
```

```

        //encode bottom nibble
        //put it in the output
    }

    //close program
    //delete G bit matrix
    //close input and output
    //return successful exit
}

```

Decode:

```

decode(int argc, char **argv) {
    opt = 0;
    output = stdout;
    input = stdin;
    verbose = false;
    C = 0x0;

    while ((opt = getopt(argc, argv, OPTIONS)) != -1) { //program argument
        parser.
        switch (opt) {
            case 'h':
                //print message
                exit(1);
                break;
            case 'i': input = fopen(optarg, "rb"); break;
            case 'o': output = fopen(optarg, "wb"); break;
            case 'v': verbose = true; break;
        }
    }

    //create Generator Matrix H 4x8

    while ((byte = fgetc(input)) != EOF){

```

```

        //read byte
        //decode byte

        //check return HAM type and add it to its corresponding counter
        //read byte
        //decode byte
        //check return HAM type and add it to its corresponding counter

        //combine both msg values together and push it to output

    }
    if (verbose){
        printf("PRINT DATA \n");
    }
    //close program
    //delete H bit matrix
    //close input and output files
    //return successful exit
}

```

BitVector:

```

BitVector *bv_create(uint32_t length){
    //create bitvector
    assert(v); //check if it created
    v.length = length;
    v.vector = calloc((length/8) + length%8 * 8, sizeof(uint8_t));
    if (v.vector){
        free(v);
        v = NULL;
        return NULL;
    }
    return v;
}

```

```

bv_delete(BitVector **v){
    assert(*v);
    assert((*v).vector);
    free((*v).vector);
    free(*v);
    return;
}
bv_length(BitVector *v){
    return v.length;
}
bv_set_bit(BitVector *v, i){
    v.vector[i/8] |= (0x1<<(i%8));//or to set
    return;
}
bv_clr_bit(BitVector *v, i){
    v.vector[i/8] &= ~(0x1<<(i%8));//or to set
    return;
}
bv_xor_bit(BitVector *v, i, bit){
    v.vector[i/8] ^= (bit<<(i%8));//xor to set
    return;
}
bv_get_bit(BitVector *v, i){
    return (v.vector[i/8]&(0x1 <<(i%8)))>>(i%8);
}
bv_print(BitVector *v){
    for (i = v.length; i >= 0 ;i--){
        printf(bv_get_bit(v,i));
    }
    printf("\n");
    return;
}

```

BitMatrix:

```
BitMatrix *bm_create(rows, cols) {
    BitMatrix *m = (BitMatrix *) calloc(1, sizeof(BitMatrix));
    //check if m worked
    m->rows = rows;
    m->cols = cols;
    m->vector = bv_create(rows * cols);
    //check if m->vector worked
    return m;
}

bm_delete(BitMatrix **m) {
    //check if m exists
    bv_delete(&(*m)->vector);
    free(*m);
    *m = NULL;
    return;
}

bm_rows(BitMatrix *m) {
    //check if m exists
    return m->rows;
}

bm_cols(BitMatrix *m) {
    //check if m exists
    return m->cols;
}

bm_set_bit(BitMatrix *m, uint32_t r, uint32_t c) {
    //check if m exists
    bv_set_bit(m->vector, (r * m->cols) + c);
}

bm_clr_bit(BitMatrix *m, uint32_t r, uint32_t c) {
    //check if m exists
    bv_clr_bit(m->vector, (r * m->cols) + c);
}
```



```

bm_get_bit(BitMatrix *m, uint32_t r, uint32_t c) {
    //check if m exists
    return bv_get_bit(m->vector, (r * m->cols) + c);
}

BitMatrix *bm_from_data(uint8_t byte, uint32_t length) {
    BitMatrix *c = bm_create(1, length);
    for loop through length {
        if (byte & (1 << i)) {
            bm_set_bit(c, 0, i);
        } else {
            bm_clr_bit(c, 0, i);
        }
    }
    return c;
}

bm_to_data(BitMatrix *m) {
    //check if m exists
    //start at c = 0
    for loop through the cols) {
        c |= (bm_get_bit(m, 0, i) << i; //shift to its corresponding position
    }
    return c;
}

BitMatrix *bm_multiply(BitMatrix *A, BitMatrix *B) {
    BitMatrix *C = bm_create(bm_rows(A), bm_cols(B));
    //rows in a{
    //cols in B{
        val = 0;
        //a cols{
            val ^= bm_get_bit(A, i, k) & bm_get_bit(B, k, j);
        }
        if (val % 2) { //mod 2
            bm_set_bit(C, i, j);
        }
    }
}
return C;

```

```

}

bm_print(BitMatrix *m) {
    for (loop through rows) {
        for (loops through cols) {
            printf("%u ", bm_get_bit(m, i, j));
        }
        //print new line
    }
}

```

Hamming:

```

lookup[16] = { HAM_OK, 4, 5, HAM_ERR, 6, HAM_ERR, HAM_ERR, 3, 7,
HAM_ERR, HAM_ERR, 2, HAM_ERR, 1, 0, HAM_ERR };
encode(G, msg){
    //c = bm_from_data(msg,4)
    //code = bm_multiply c,G
    //f = bm_to_data(code)
    //remove all bm and free them
    Return f
}
Decode (Ht, code, msg){
    BitMatrix *c = bm_from_data(code, 8);
    //bm_print(c);
    BitMatrix *err = bm_multiply(c, Ht);
    errormsg = bm_to_data(err);
    //loopup(errormsg)
    //If ham ok
        // msg = c
        //return HAM_OK
    //Else if ham_error
        //msg = c
        //return HAM_ERR
    //else
        //flip bitmatrix c at location lookup(errormsg)
        //msg = c
        //return HAM_CORRECT
}

```

Design Process:

1. In the beginning I was trying to implement a 2d bit matrix but I learned that it was wrong and I need to make a 1d matrix which acts as a 2d matrix which I found interesting and a lot easier than the method I was trying to implement.
2. I had a hard time with decode in the beginning because I wasn't aware I had to read two bytes at a time since encodes multiplied original space by two since it combined a nibble with another nibble which contains information to figure out the original message if an error occurs. I think this method of encoding and decoding might be a bit efficient since multiplying the original message by 2 in order to prevent information loss during transfer. I hope there is a better method out there since it doesn't seem to be too good in my opinion.

What I learned:

1. I learned how to manipulate bits in c and implement a bit matrix and learned how to implement a bit matrix multiplication.
2. I learned what a hamming code is and the use of it is.
3. I learned what entropy is.

Resources Used:

- Asgn5.pdf
- asgn5Design by William Santosa from Piazza
- Example_design.pdf found in CSE 13s Discord.