

#### Nils Heine

# Real-Time Automatic Gain Control for Singing Voice Applications

University of Hamburg Department of Informatics March 20, 2018

- 1. Motivation
- 2. Algorithm
- 3. Optimization
- 4. Results
- 5. Future Implementations



### **Motivation**



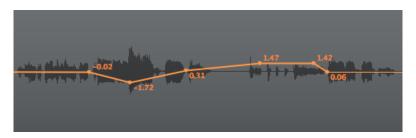




compressor to fast



■ compressor to fast ■ factor in human perception



■ compressor to fast ■ factor in human perception ■ save time

## Dummy UI



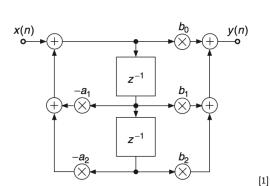


SP Signal Processing

### **Algorithm**



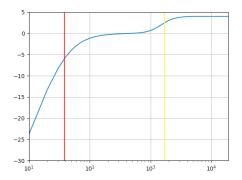
- 2. Algorithm
  - 2.1 Filter
  - 2.2 RMS
    - 2.2.1 Time Coefficients
  - 2.3 Gate
  - 2.4 Gain
    - 2.4.1 Loudness Goal Adaption
    - 2.4.2 Write Automation
  - 2.5 Lookahead



-1

11 This is the short title Short Name

 $<sup>\</sup>ensuremath{^{[1]}}$  Figure from DAFX: Digital Audio Effects by Udo Zoelzer.



■ lowcut (38 Hz), highshelf (1681 Hz)<sup>[2]</sup>

<sup>[2]</sup> from Recommendation ITU-R BS.1770-4.



### Root Mean Square (RMS):

#### Time Constants:

```
\label{eq:float_angle} \begin{cases} \mbox{float MutoVocalCtrlAudioProcessor::getTimeConstant(float ms)} \\ \{ & \mbox{if } (ms>0.f) \\ & \mbox{return } 1.f - \exp(-2.2*(1./\mbox{currentSampleRate})/(ms/1000.)); \\ & \mbox{else} \\ & \mbox{return } 1.f; \\ \} \end{cases}
```

[2]

 $<sup>\</sup>begin{tabular}{ll} [3] \\ \hline \end{tabular}$  Based on Book: Digital Audio Signal Processing by Udo Zoelzer.





```
void AutoVocalCtrlAudioProcessor::updateGain(int channel)
{
    const double g = *loudnessGoal - mls[channel];
    const double co = g < gain[channel] ? compressTCo:expandTCo;
    gain[channel] = clipRange.clipValue((1 - co) * gain[channel] + co * g);
    updateAutomation();
...</pre>
```



# Algorithm: Gain: Loudness Goal Adaption





# Algorithm: Gain: Write Automation







# Algorithm: Lookahead



per ringbuffer





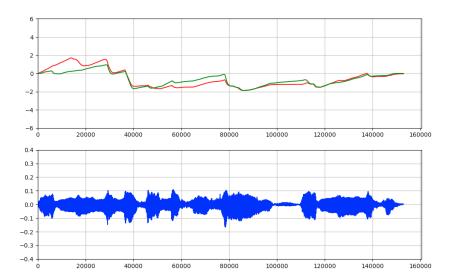
### **Optimization**

```
... res = optmze.brute(compareGainCurve, bnds, full_output=True, finish=optmze.fmin) ... res = optmze.minimize(compareGainCurve, x0, bounds=bnds, options={'disp': True, 'eps': 0.5}) ... x1 = np.array([-28.22, 5.65, 110.14, 2044.41, -33.94, 0.])
```



# Optimization: Results







### Results









- Original: O
- Gain Control:





### **Future Implementations**

### Future Implementations



- side chain backtrack
- offline loudness goal calculation
- set parameters → simplify UI
- improve writing of automation
- idle time?
- wet / dry?

- 1. Motivation
- 2. Algorithm
- 3. Optimization
- 4. Results
- 5. Future Implementations