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Real-Time Automatic Gain Control for Singing Voice Applications

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1. Motivation
2. Algorithm
3. Optimization
4. Results
5. Future Implementations



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Motivation

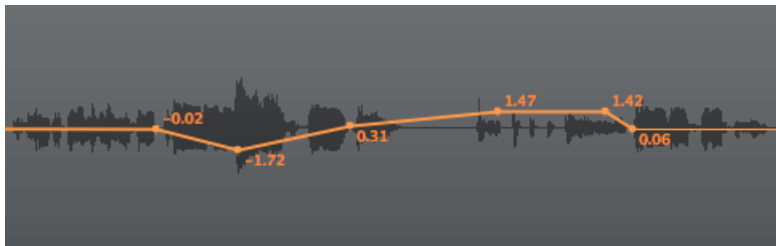




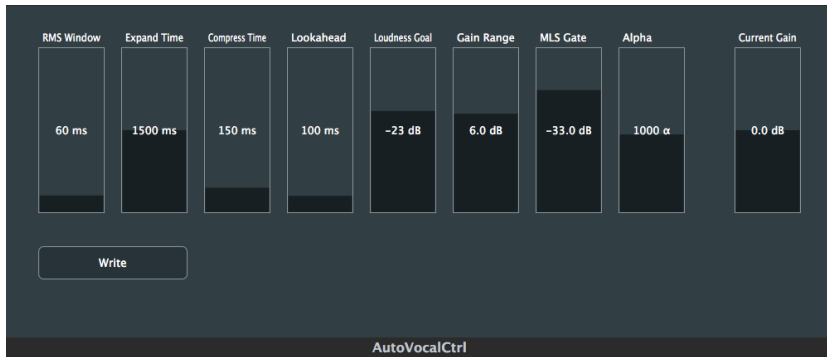
- compressor to fast



- compressor to fast ■ factor in human perception



- compressor to fast
- factor in human perception
- save time





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Signal Processing

Algorithm

2. Algorithm

2.1 Filter

2.2 RMS

2.2.1 Time Coefficients

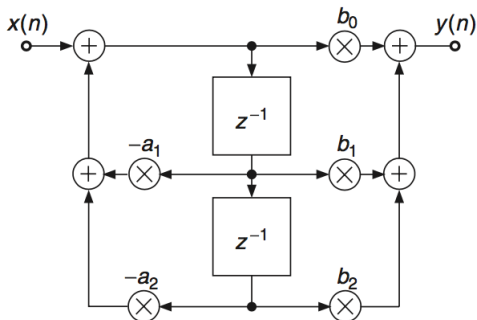
2.3 Gate

2.4 Gain

2.4.1 Loudness Goal Adaption

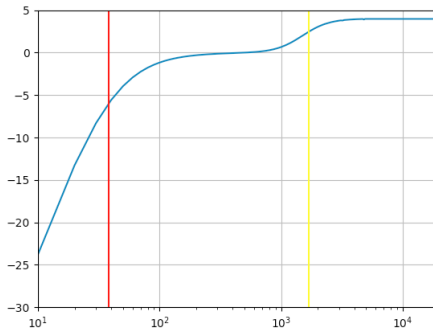
2.4.2 Write Automation

2.5 Lookahead



[1]

[1] Figure from DAFX: Digital Audio Effects by Udo Zolzer.



- lowcut (38 Hz), highshelf (1681 Hz)^[2]

^[2] from Recommendation ITU-R BS.1770-4.

Root Mean Square (RMS):

```
void AutoVocalCtrlAudioProcessor::updateRMS(int channel)
{
    rms[channel] = (1. - rmsCo) * rms[channel] +
        rmsCo * (filterSample[channel] * filterSample[channel]);
}
```

[3]

Time Constants:

```
float AutoVocalCtrlAudioProcessor::getTimeConstant(float ms)
{
    if (ms > 0.f)
        return 1.f - exp(-2.2*(1./currentSampleRate)/(ms/1000.));
    else
        return 1.f;
}
```

[2]

[3] Based on Book: Digital Audio Signal Processing by Udo Zolzer.



Algorithm: Gain

```
void AutoVocalCtrlAudioProcessor::updateGain(int channel)
{
    const double g = *loudnessGoal - mls[channel];
    const double co = g < gain[channel] ? compressTCo : expandTCo;
    gain[channel] = clipRange.clipValue((1 - co) * gain[channel] + co * g);
    updateAutomation();
    ...
}
```

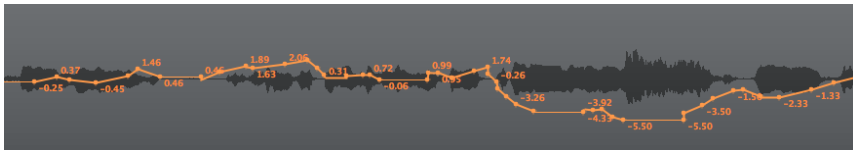
Algorithm: Gain: Loudness Goal Adaption

```

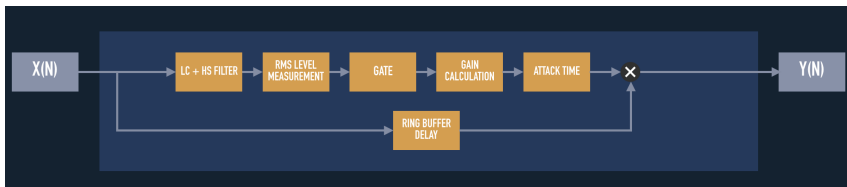
void AutoVocalCtrlAudioProcessor::updateGain(int channel)
{
    ...
    alphaGain[channel] = (1 - alphaCo) * alphaGain[channel] + alphaCo * gain[channel];
    if (channel == getTotalNumInputChannels() - 1)
    {
        ...
        updateLoudnessGoal();
    }
}

```


Algorithm: Gain: Write Automation



per ringbuffer





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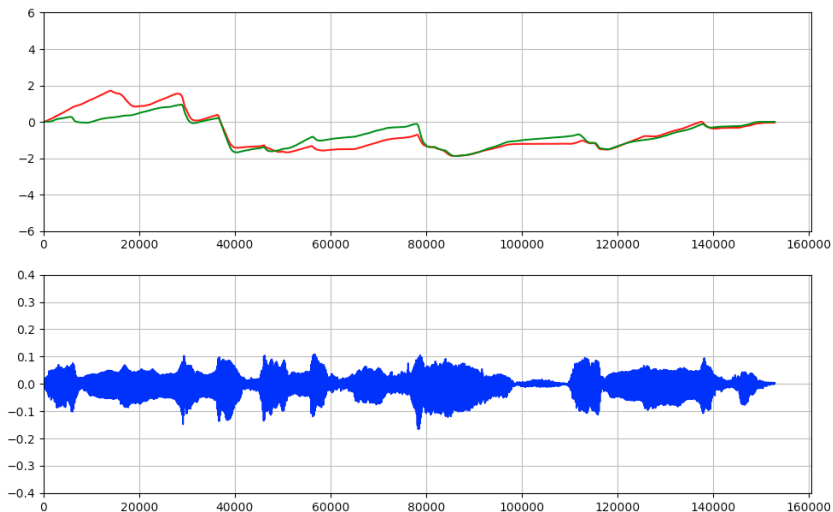


Signal Processing

Optimization

```
...
res = optmze.brute(compareGainCurve, bnds, full_output=True, finish=optmze.fmin)
...
res = optmze.minimize(compareGainCurve, x0, bounds=bnds, options={'disp': True, 'eps': 0.5})
...
x1 = np.array([-28.22, 5.65, 110.14, 2044.41, -33.94, 0.])
...
```

Optimization: Results





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Signal Processing

Results



■ Original: 

■ Gain Control: 





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Signal Processing

Future Implementations

Future Implementations

- side chain backtrack
- offline loudness goal calculation
- set parameters → simplify UI
- improve writing of automation
- idle time?
- wet / dry?

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