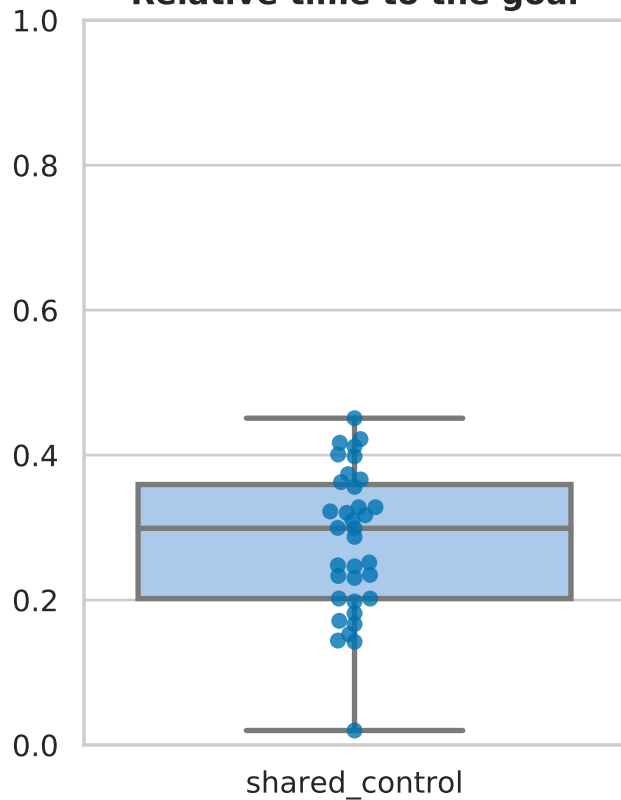


Relative time to the goal



Relative path length to the goal

