## APPENDX: SMC Package Tutorial

As a part of our project we have written an R package, SMC, which is mostly written in C++ using the Rcpp/RcppArmadillo package. In this tutorial we provide an overview of the different algorithms implemented in the SMC package. For a description of the algorithms used within this tutorial, we refer the reader to the primary report.

The algorithms within SMC have been written in order to conduct analysis on data which can be modelled by a Stochastic Volatility Model (SVM):

$$X_t = \alpha X_{t-1} + \epsilon_t, \quad \epsilon \sim \mathcal{N}(0, 1) \tag{1}$$

$$Y_t = \beta \exp(X_t/2)\zeta_t, \quad \zeta_t \sim \mathcal{N}(0,1)$$
 (2)

We start by defining our model parameters  $\theta = (\alpha, \beta, \sigma)$  and generating synthetic data from the associated SVM.

## 2 -1.5648786 -1.0726622 ## 3 -0.9949148 0.3077198 ## 4 -1.4801125 -0.2607910 ## 5 -1.9113543 -0.3422655 ## 6 -2.2165251 -0.3295994

Figure 1 shows a plot of the data generated using SMC::stochastic\_volatility(). One can clearly see that the volatility of the observations, represented by the grey points, decreases as the states decrease. In practice we do not have access to the unknown states  $x_{0:t}$ , however we can estimate them through the use of the Bootstrap Partcile Filter (BSF) and the Auxiliary Particle Filter.

## Bootstrap MSE: 854.2543 ## Auxiliary MSE: 766.7677

Figure 2 shows the filtered states plotted against the true synthetic states. In this context there does not seem to be a huge difference in performance. We have of course taken for granted that we know the true model parameters used to generate the data. In practice we often must estimate the model parameters from the data. Working in the offline setting, we can do this using a Pseudo-Marginal Metropolis Hastings

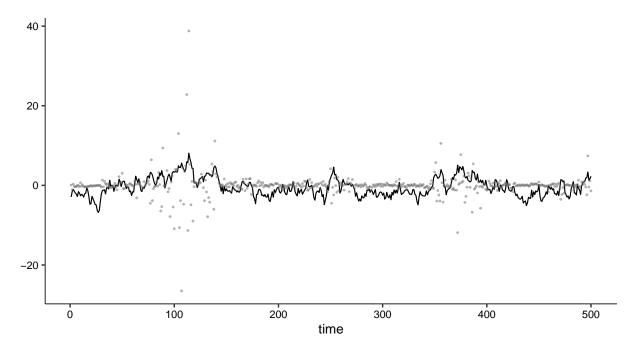


Figure 1: Synthetic data generated according to the Stochastic Volatility model with model parameters theta = (0.91, 1, 1).

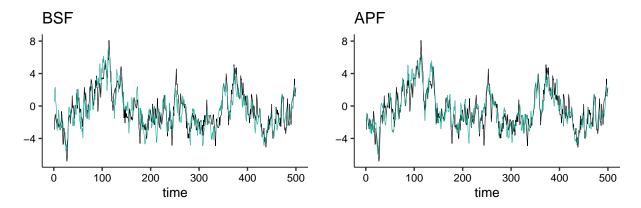


Figure 2: Results of running running the BSF and APF on the synthetic data. The true states are given by the solid black line, and the filtered states are given by the dark green line.

(PMMH) algorithm. In short, one can use the above particle filters to approximate the marinal likelihood of the observations

$$\hat{P}_N(y_{0:t}|\boldsymbol{\theta}) \approx p(y_{0:t}|\boldsymbol{\theta}). \tag{3}$$

We can incorporate this approximation into the Metropolis Hastings algorithm, and use it to accept/reject proposed values. For further details of this algorithm we once again refer the reader to the main report.

There are two versions of PMMH algorithm implemented within the SMC package. The first, pmmh1, estimates parameters  $\alpha$  and  $\sigma$  only, using the prior/proposal

$$p(\alpha) = \text{Beta}(6, \frac{6}{0.8} - 6), \quad q(\alpha^* | \alpha) = \text{Beta}(100, \frac{100}{\alpha} - 100)$$
 (4)

$$p(\sigma) = \operatorname{Gamma}(5, \frac{0.5}{5}), \quad q(\sigma^* | \sigma) = \operatorname{Beta}(200, \frac{\sigma}{200}). \tag{5}$$

The second, pmmh2 estimates all three parameters  $\theta = (\alpha, \beta, \sigma)$  and uses the prior

$$p(\alpha) = \text{Trunc-Normal}_{(-1,1)}(0.9, 0.5) \tag{6}$$

$$p(\beta) = p(\sigma) = \text{Gamma}(2, 2)$$
 (7)

with the proposal

$$q(\theta^*|\theta) = \mathcal{N}(\theta, \sigma_{\text{Drop}} \mathbf{I}). \tag{8}$$

Since all of the parameters are bounded ( $\sigma$  and  $\beta$  must be positive;  $\|\alpha\| < 1$ ), we have applied reflection at each of their respective boundaries. This ensures proposals are only ever in pheasible regions. In this tutorial we will show the use of pmmh2:

## ## Acceptance rate: 23.92761%

The acceptance rate should ideally be around 23.4%. Let's examine the trace plots:

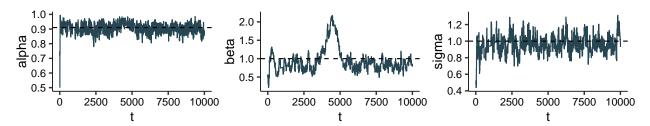
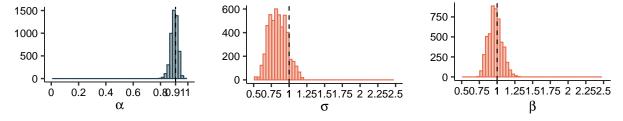


Figure 3: Trace plots for each model parameter; generated using pmmh2().

The trace plots indicate that each parameters has converged to its stationary regime. The ACF plots should also decay to 0 (here we take a burn in of 500 iterations).

And finally we can plot a histogram of the approximated posterior samples:



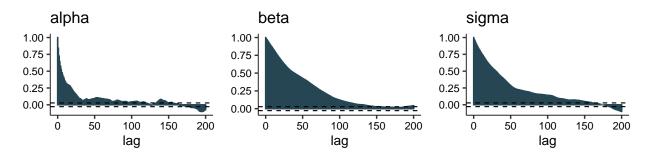


Figure 4: ACF plots for each model parameter; generated using pmmh2().