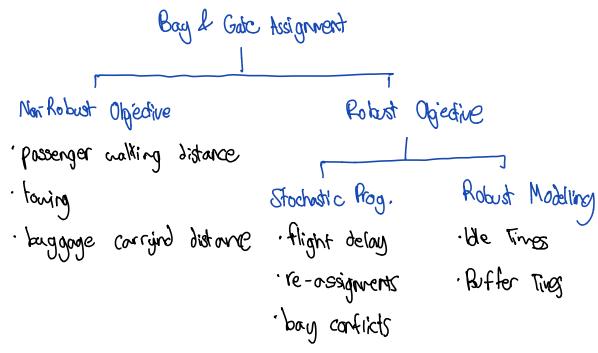
Topic -> Robust Scheduling for the Bay and Gate Assignment Bay: Parking stand of the aircraft

Gate: Position where passengers board the plane

Sensitivity analysed for vovious delay cases Four ophlimization objectives:

- 1. Minimization of aircraft repositioning
- 2. Maximization of airline preferences
- 3. Maximization of passenger transport distance
- 4. Maximizing the robustness of the schedule

Static Mode) is. Stochastic Model



Optimization Methods: Primal-Phal Simplex, LD Relaxation & Branch and Bound Stakeholders: Passengers, Airlines, Airport/Ground Personnel Specific Airport Gate Constraints

Bay Assignment -> Gate Assignment

reduce index of control variables

extra terms in objective value

Bay Model

Objective Function (JKIA Oriented)

- 1. Min: Passenger Walking Distance => (Peparture & Arrival)

 z1 = Exp Know Pi x Xilk x Oternik

 i=0 K=1
- 2. Airline Preferences

 22 = 5 5 Xi, x > PREF i, x
 i-0 x-1
- 3. Penalty Value for Aircraft Repositioning 24 = XZ1 + BZz + (U+V+W). J.Z3

Preference: 2 > 3 > 1

Pecision Variables: Binary Xi, [i=Flight, j=Buy]
Constraints

Single tive-slot construint (one flight per bay)

Xix + Xixx &1

Bay Comphance Constraint

BC(i) = Eman Yik=1 Yik

Single Bay per Aircraft Constraint

Prevent Double Scheduling Flights

Long Stay Flights are separated into (Arrival, Parting, Departure)

SB(i) = \(\frac{k}{x} \) \(\frac{

Only for departing flights

Non-Dosnetic or "Full" Donestic: F(;): Exx; x = 1

Long Stay Donestic: F(i): Entry Xi, x + Exi-1,x 21