A

The beam will experience the highest moment of x on the point furthest away from the wall because it is an extremity and it doesn't have a wall creating a force in the opposite direction in this location

B

Given that the beam is symmetric along the y axis, the center x-coordinate will be at $\frac{b}{2}$

$$y_c = \frac{\sum yA}{\sum A}$$

$$= \frac{2\frac{b}{2}(bt) + t(2t(b-2t))}{2bt + 2t(b-2t)}$$

Since
$$t^n$$
 0 when n , $t(2t$ and $4t^2$ > 1 $(b$ $= 0$ $-2t$ $)) = 0$

$$egin{aligned} y_c &= rac{b^2 t}{2bt + 2tb} \ &= rac{b^2 t}{4tb} = rac{b}{4} \end{aligned}$$

This has been proven with the following code:

```
In [183]:
```

```
import numpy as np
import sympy as spy
b, t, M \times y = spy.symbols('b t M \times y')
left arm = \{'x': t, 'y': b, 'x_c': t/2, 'y_c': b/2\}
center_beam = {'x': b-2*t, 'y': 2*t, 'x_c': b/2, 'y_c': t}
right arm = {'x': t, 'y': b, 'x c': b-(t/2), 'y c': b/2}
y c = (left arm['y c'] * left arm['x'] * left_arm['y'] + center_beam['y_c'] * center_bea
m['x'] * center_beam['y'] + right_arm['y_c'] * right_arm['x'] * right_arm['y'])/(left_ar
m['x'] * left arm['y'] + center beam['x'] * center beam['y'] + right arm['x'] * right ar
m['y'])
x c = (left_arm['x_c'] * left_arm['x'] * left_arm['y'] + center_beam['x_c'] * center_bea
m['x'] * center_beam['y'] + right_arm['x_c'] * right_arm['x'] * right_arm['y'])/(left_ar
m['x'] * left_arm['y'] + center_beam['x'] * center_beam['y'] + right_arm['x'] * right_ar
m['y'])
x c, y c = spy.expand(x c), spy.expand(y c)
for m in range(2, 5):
   x_c = x_c.subs(t**m, 0)
   y c = y c.subs(t**m, 0)
x_c, y_c = x_c.subs(t**2, 0), y_c.subs(t**2, 0)
print(f'x_c={x_c}' , f'y_c={y_c}')
```

$$x c=b/2 y c=b/4$$

```
In [184]:
I xx 1 = (1/12) * right arm['x'] * right arm['y']**3 + right arm['x'] * right arm['y'] *
(right arm['y c'] - y c)**2
I xx 2 = (1/12) * center beam['x'] * center beam['y']**3 + center beam['x'] * center bea
m['y'] * (center beam['y c'] - y c)**2
I \times X = (1/12) * left arm['x'] * left arm['y'] * * 1 + left arm['x'] * left arm['y'] * (left arm['y'] * (left arm['y'] * (left arm['x'] * (l
ft arm['y c'] - y c)**2
I xx = I xx 1 + I xx_2 + I_xx_3
I yy 1 = (1/12) * right arm['y'] * right arm['x']**3 + right arm['y'] * right arm['x'] *
(right arm['x c'] - x c) **2
I yy 2 = (1/12) * center beam['y'] * center beam['x']**3 + center beam['y'] * center beam
m['x'] * (center beam['x c'] - x c)**2
I yy 3 = (1/12)^{\frac{1}{x}} left arm['y']^{\frac{1}{x}} left arm['x']^{**3} + left arm['y'] * left arm['x'] * (left)
ft arm['x c'] - x c) **2
I_yy = I_yy_1 + I_yy_2 + I_yy_3
I xy 1 = right arm['x'] * right arm['y'] * (right arm['y c'] - y c) * (right arm['x c']
- x c)
I_xy_2 = center_beam['x'] * center_beam['y'] * (center_beam['y_c'] - y c) * (center_beam['y'] * (center_beam['y'] * (center_beam['y'] - y c) * (center_beam['y'] * (center_beam['y'] * (center_beam['y'] - y c) * (center_beam['y'] * (center_beam['y'] + center_beam['y'] * (center_beam['y'] - y c) * (center_beam['y'] + center_beam['y'] + center['y'] + center['
 ['x c'] - x c)
I_xy_3 = left_arm['x'] * left_arm['y'] * (left_arm['y_c'] - y_c) * (left_arm['x c'] - x_c')
I xy = I xy 1 + I xy 2 + I xy 3
I xx, I yy, I xy = spy.expand(I xx), spy.expand(I yy), spy.expand(I xy)
for m in range (2, 5):
              I_xx = I_xx.subs(t**m, 0)
              I yy = I yy.subs(t**m, 0)
              I xy = I xy.subs(t**m, 0)
print(f'I xx={I xx}', f'I yy={I yy}', f'I xy={I xy}')
I xx=0.41666666666667*b**3*t I yy=0.66666666666667*b**3*t I xy=0
In [185]:
sigma z = M x/I xx * y
sigma z
Out[185]:
2.4M_xy
```

D

 h^3t

The points at which the stress whill be the largest are the ones with the highest y, regardless of their x positions. This means that both top corners will experience the same stress along the corners further away from the wall