# CHRISTOS N. MAVRIDIS

© (+1) 301·405·3374 · ★ https://mavridischristos.github.io/ · ★ mavridis@umd.edu 2239 A.V. Williams Building, University of Maryland, College Park, MD 20742, USA

### Research Interests:

Theoretical: Control Theory, Optimization, Machine Learning.

Applied: Robotics, Multi-Agent Systems, Intelligent Transportation Systems, Communication Networks, Healthcare.

#### **EDUCATION**

# University of Maryland, College Park

2021

Ph.D., Electrical and Computer Engineering

Advisor: Prof. John S. Baras

· Ph.D. Thesis: "Learning Latent Representations and Intrinsic Laws of Complex Systems".

# University of Maryland, College Park

2021

M.S., Electrical and Computer Engineering

## National Technical University of Athens, Greece

2017

Diploma (5 years) in Electrical and Computer Engineering

Advisor: Prof. Kostas J. Kyriakopoulos

· Diploma Thesis: "EEG and EMG Signals in Neuro-Robotic Systems".

#### RESEARCH EXPERIENCE

## Institute for Systems Research & ARC Lab, UMD

August 2017 - December 2021

Graduate Research Assistant

University of Maryland, College Park, MD

- · Research Focus: Machine Learning Theory, Optimization, Systems and Control Theory, Multi-Agent Systems, Robotics.
- · Research Advisor: John S. Baras, Distinguished University Professor and Chair in Systems Engineering.

# System Sciences Lab, Palo Alto Research Center (PARC)

May 2019 - August 2019

Palo Alto, CA

- · Research Focus: Control of Networked Systems, Mean-field Game Theory.
- · Supervisors: Ion Matei and Johan de Kleer.

## Math & Algorithms Research Group, Nokia Bell Labs Research Intern

June 2018 - August 2018

Murray Hill, NJ

- $\cdot$  Research Focus: Information Theory for Feature Extraction and Machine Learning Applications.
- · Supervisor: Iraj Saniee, Head, Math & Algorithms Research Group.

# Control Systems Lab

Research Intern

August 2015 - June 2017

Undergraduate Research Assistant

Mechanical Eng. Dept., NTUA, Athens, Greece

- · Research Focus: System Identification, Machine Learning, Adaptive Control, Human-Robot Collaboration, EEG & EMG Signal Processing, Brain-Robot Interfaces, Robot Control.
- · Advisor: Kostas J. Kyriakopoulos, Professor of Robotics, Mechatronics and Control.

# TEACHING EXPERIENCE

#### Graduate Teaching Assistant

Fall 2020, Spring 2021

Dept. of Electrical and Computer Engineering

University of Maryland, College Park, MD

- · Spring 2021: ENEE 436 (Foundations of Machine Learning), Prof. Behtash Babadi.
- · Fall 2020: ENEE 660 (Systems Theory), Prof. John S. Baras.

#### **Guest Lecturer**

Spring 2018 - Spring 2021

Dept. of Electrical and Computer Engineering

University of Maryland, College Park, MD

· ENEE436 (Foundations of Machine Learning), ENEE660 (Systems Theory), ENSE622 (System Trade-off Analysis, Modeling, and Simulation).

#### **PUBLICATIONS**

## Journal Papers

- · <u>Christos N. Mavridis</u>, John S. Baras, Online Deterministic Annealing for Classification and Clustering, IEEE Transactions on Neural Networks and Learning Systems (TNNLS) [to appear, arXiv:2102.05836].
- · <u>Christos N. Mavridis</u>, Amoolya Tirumalai, John S. Baras, Learning Swarm Interaction Dynamics from Density Evolution, IEEE Transactions on Control of Network Systems (TCNS) [to appear, arXiv:2112.02675].
- · <u>Christos N. Mavridis</u>, John S. Baras, Annealing Optimization for Progressive Learning with Stochastic Approximation, Transactions on Automatic Control (TAC) [under review].
- · Amoolya Tirumalai, <u>Christos N. Mavridis</u>, John S. Baras, Weak Solutions to an Euler Alignment System with Singular Interactions in a Bounded Domain, SIAM Journal on Mathematical Analysis (SIMA) [under review, arXiv:2111.05361].
- · <u>Christos N. Mavridis</u>, John S. Baras, Towards the One Learning Algorithm Hypothesis: A System-theoretic Approach, SIAM Journal on Mathematics of Data Science (SIMODS) [under review, arXiv:2112.02256].
- · <u>Christos N. Mavridis</u>, John S. Baras, Universal Machine Learning Architectures Inspired by the One Learning Algorithm Hypothesis, Proceedings of the National Academy of Sciences (PNAS) [under review].

# Peer-Reviewed Conference Papers

- · Faizan M. Tariq, Nilesh Suriyarachchi, <u>Christos N. Mavridis</u>, John S. Baras, Autonomous Vehicle Overtaking in a Bidirectional Mixed-Traffic Setting, 2022 American Control Conference (ACC) [under review].
- · <u>Christos N. Mavridis</u>, Nilesh Suriyarachchi, John S. Baras, Maximum-Entropy Progressive State Aggregation for Reinforcement Learning, IEEE Conference on Decision and Control (CDC), 2021.
- · <u>Christos N. Mavridis</u>, John S. Baras, Progressive Graph Partitioning Based on Information Diffusion, IEEE Conference on Decision and Control (CDC), 2021.
- · Nilesh Suriyarachchi, Faizan M. Tariq, <u>Christos N. Mavridis</u>, John S. Baras, Real-Time Priority-Based Cooperative Highway Merging for Heterogeneous Autonomous Traffic, IEEE International Conference on Intelligent Transportation Systems (ITSC), 2021. (Best Student Paper Award)
- · <u>Christos N. Mavridis</u>, John S. Baras, Vector Quantization for Adaptive State Aggregation in Reinforcement Learning, American Control Conference (ACC), 2021.
- · <u>Christos N. Mavridis</u>, Nilesh Suriyarachchi, John S. Baras, Detection of Dynamically Changing Leaders in Complex Swarms from Observed Dynamic Data, Conference on Decision and Game Theory for Security (GameSec), 2020.
- · <u>Christos N. Mavridis</u>, Amoolya Tirumalai, John S. Baras, Learning Interaction Dynamics from Particle Trajectories and Density Evolution, IEEE Conference on Decision and Control (CDC), 2020.
- · <u>Christos N. Mavridis</u>, Amoolya Tirumalai, John S. Baras, Ion Matei, Semi-linear Poisson-mediated Flocking in a Cucker-Smale Model, International Symposium on Mathematical Theory of Networks and Systems (MTNS), 2020.
- · <u>Christos N. Mavridis</u>, John Baras, Kostas Kyriakopoulos, A Human-Robot Interface based on Surface Electroencephalographic Sensors, International Conference on Intelligent Robots and Systems (IROS), 2020.
- · <u>Christos N. Mavridis</u>, John S. Baras, Convergence of Stochastic Vector Quantization and Learning Vector Quantization with Bregman Divergences, IFAC World Congress, 2020.
- · <u>Christos N. Mavridis</u>, Constantinos Vrohidis, John S. Baras, Kostas J. Kyriakopoulos, Robot Navigation Under MITL Constraints Using Time-Dependent Vector Field Based Control, IEEE Conference on Decision and Control (CDC), 2019.
- · Ion Matei, <u>Christos N. Mavridis</u>, John S. Baras, Maksym Zhenirovskyy, Inferring Particle Interaction Physical Models and Their Dynamical Properties, IEEE Conference on Decision and Control (CDC), 2019.
- · <u>Christos N. Mavridis</u>, Konstantinos Alevizos, Charalampos P. Bechlioulis, Kostas J. Kyriakopoulos, Human-robot collaboration based on robust motion intention estimation with prescribed performance, European Control Conference (ECC), 2018.

### OPEN-SOURCE SOFTWARE

## Online Deterministic Annealing (ODA)

https://github.com/MauridisChristos/OnlineDeterministicAnnealing

· "A progressively-growing competitive-learning neural network architecture with inherent interpretability, robustness, and regularization properties. ODA is based on the principles of vector quantization and annealing optimization, and is trained with a gradient-free stochastic approximation algorithm. Applications include online unsupervised and supervised learning, adaptive graph partitioning, swarm leader detection, and reinforcement learning".

#### PATENTS

### Patent No.: US 11,188,617 B2

· Iraj Saniee, <u>Christos Mavridis</u>, "Method and network node for internet-of-things (IoT) feature selection for storage and computation" (Current Assignee: Nokia Technologies Oy).

#### RESEARCH PROJECTS

### Northrop Grumman Corporation Grant

"Neuromorphic Signal Processing: From Analytics for Deep Learning to Cortex-on-a-Chip" Spring 2020 - Spring 2021

· Lead research, developed theory and algorithms, performed computations, prepared reports and presentations.

# DARPA Artificial Intelligence Research Associate Program (AIRA)

Agreement No. HR00111990027

"Learning Intrinsically Composable Laws of Complex Autonomous Collectives"

Spring 2018 - Spring 2019

· Lead research and communication, developed theory and algorithms, performed computations, prepared bi-monthly reports and presentations, contributed to conceptualization and writing of project extension proposal.

# ONR Science of Autonomy Program

Grant N00014-17-1-2622

"Intelligent and Learning Autonomous Systems: Composability and Correctness"

Fall 2017 - Spring 2022

· Lead research, developed theory and algorithms, performed computations, prepared reports and presentations.

#### HONORS & AWARDS

- · Best Student Paper Award ( $1^{st}$  place), IEEE ITSC (2021).
- · ISR Outstanding Systems Engineering Graduate Student Award, UMD (2021).
- · Ann G. Wylie Dissertation Fellowship [\$15,000], UMD (2021).
- · Future Faculty Program Fellowship, A. James Clark School of Engineering, UMD (2021).
- · Graduate School's Outstanding Research Assistant Award, A. James Clark School of Engineering, UMD (2020-21).
- · Gerontelis Foundation Scholarship [\$5,000], MA (2018).
- · Qualcomm Innovation Fellowship US Finalist, San Diego, CA (2018).
- · A. James Clark School of Engineering Distinguished Graduate Fellowship [\$15,000], UMD (2017).
- · "Great Moment for Education" student excellence award [€1,000], EFG Eurobank, Greece (2010).

### INVITED TALKS

· "Learning Latent Representations and Intrinsic Laws of Complex Systems", Maryland Robotics Center, UMD, October 2021.

### PROFESSIONAL & VOLUNTARY SERVICE

- · Scholarly peer reviewer: CDC, ACC, ITSC, ICRA, IROS, DCDS-B, ECC, ABB.
- · Member, ECE Graduate Student Association Board, UMD.
- · Member, Management Committee, 24th IEEE MED Conference, Athens, Greece.

# SOFTWARE SKILLS

Languages Python, C++, C, Bash (Unix Shell), HTML/CSS, Matlab.

Tools PyTorch, ROS/Gazebo, Wolfram Mathematica, Gurobi Optimizer, Latex, Git.

Christos Mavridis Last updated: 12/2021