

# Parallel Port for Altera DE-Series Boards

For Quartus II 13.0

### 1 Core Overview

The Parallel Port IP core provides a simple interface for general purpose I/O. This is a version of the Altera's *PIO Core* adapted for use with Altera's DE-series boards.

# 2 Functional Description

The Parallel Port IP core can provide up to 32 I/O ports. It captures data on its inputs and drives data to its outputs, which provides easy communication with user logic and external devices. Some example uses include:

- Controlling LEDs
- Acquiring data from switches
- Controlling display devices

# 3 Instantiating the Core in Qsys Builder

Designers use the Parallel Port IP core's configuration wizard in Qsys to specify the features. The following describes the available options, shown in Figure 1.

- **DE-series boards** allows users to specify the target board.
- Create custom parallel port allows users to select between using one of the presets or create a custom parallel port.
- Presets
  - I/0 device allows users to select a preset I/O device.
  - LEDs color allows users to specify a set of LEDs that are present of some DE-series boards.
  - Seven Segment Digits allows users to specify a set of 7-segment displays when more than four are present on the selected DE-series board.
  - Expansion Header allows users to specify expansion headers that are present on some DE-series boards.
- Basic Settings (Presets) This section is only visible for preset parallel ports and it shows the data width and port direction for the selected preset configuration.

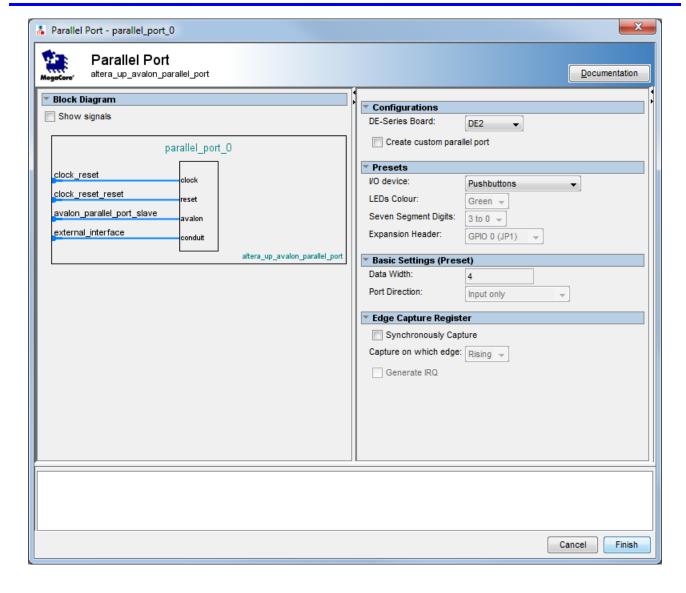


Figure 1. Parallel port's Qsys wizard.

- Basic Settings This section is only visible for custom parallel ports.
  - Data Width The width of the parallel port can be set to any integer value between 1 and 32.
  - Port Direction You can set the parallel port's direction to one of the options shown in Table 1.
- Edge Capture Register
  - Synchronously Capture Enables the edge capture register.
  - Capture on which Edge allows users to select the type of edge to capture. This can either be rising edge, falling edge or both edges.
  - Generate IRQ allows users to enable interrupts, so that an IRQ will be asserted when an edge is captured.

Table 1. Direction Settings	
Setting	Description
Bidirectional (tristate) ports	In this mode, each parallel port bit can either be used as
	input or output, and the direction of each bit is individ-
	ually selectable.
Input ports only	In this mode the parallel port can only capture input.
Output ports only	In this mode the parallel port can only drive output.

# **Software Programming Model**

# **Register Map**

The Parallel Port IP core can have up to four registers, as shown in Table 2. These registers have a configurable data width, n, which is set through the Qsys component wizard.

Not all of these registers are generated in a given parallel port interface. For example, the Direction register is included only when a bidirectional interface is specified.

Table 2. Parallel Port register map					
Offset in bytes	Register name		Read/Write	Bits $(n-1)\dots 0$	
0	data	Input	R	Data value currently on Parallel Port inputs.	
		Output	W	New value to drive on Parallel Port outputs.	
4	direction		R/W	Individual direction control for each I/O port.	
				A value of 0 sets the direction to input; 1 sets	
				the direction to output.	
8	interruptmask		R/W	IRQ enable/disable for each input port. Set-	
				ting a bit to 1 enables interrupts for the corre-	
				sponding port.	
12	edgecapture		R/W	Edge detection for each input port.	

Notes on Table 2:

- (1) This register may not exist, depending on the hardware configuration. If a register is not present, reading the register returns an undefined value, and writing the register has no effect.
- (2) Writing any value to edgecapture clears all bits to 0.

#### 4.1.1 **Data Register**

This register holds the *n* bits of data that are transferred between the Parallel Port interface and the Nios II processor. It can be implemented as an input, output, or a bidirectional register.

Reading from the data register returns the value present at the input ports and/or the last data written to an output

Writing to the data register stores the value to a register that drives the output ports. If the core is configured in input-only mode, writing to data register has no effect. In bidirectional mode, the registered value appears on an output port only when the corresponding bit in the direction register is set to 1 (output).

### 4.1.2 Direction Register

The *direction* register is enabled only when the Parallel Port is set to bidirectional, and is used to specify data transfer direction for each bit. When bit *n* in the *direction* register is set to 1, the corresponding bit of the *data* register is set to be output. When it si set to 0, the corresponding port bit is set as input, and is held at high-impedance state until driven by an outside source. In the case, when the *direction* register does not exist, reading it returns an undefined value, writing the *direction* register has no effect.

After reset, all bits of the *direction* register are 0, so that all bidirectional I/O ports are configured as inputs.

# 4.1.3 Interruptmask Register

The *interruptmask* register only exists when the hardware is configured to generate IRQs. Setting a bit in the *interruptmask* register to 1 enables interrupts for the corresponding bit in the parallel port's *edgecapture* register. If the core cannot generate IRQs, reading the *interruptmask* register returns an undefined value, and writing to the *interruptmask* register has no effect.

After reset, all bits of interruptmask are zero, so that interrupts are disabled for all bits.

## 4.1.4 Edgecapture Register

When the parallel port is configured to detect edges, the *edgecapture* register is created to indicate on which bit(s) of the port an edge has occurred. If bit n in the *edgecapture* register is set to 1 whenever an edge is detected on input port n.

The type of edge(s) to detect is specified in hardware at system generation time. The *edgecapture* register only exists when the hardware is configured to capture edges. An Avalon-MM master peripheral can read the *edgecapture* register to determine if an edge has occurred on any of the parallel input bits. If the core is not configured to capture edges, reading from the *edgecapture* register returns an undefined value, and writing to edgecapture has no effect.

## 4.2 Programming with the Parallel Ports

The Parallel Port core is packaged with C-language device drivers accessible through the hardware abstraction layer (HAL). These functions implement basic operations for the Parallel Port.

To use the functions, the C code must include the statement:

```
#include "altera_up_avalon_parallel_port.h"
```

#### 4.2.1 alt\_up\_parallel\_port\_open\_dev

**Prototype:** alt\_up\_parallel\_port\_dev\* alt\_up\_parallel\_port\_open\_dev(const

char \*name)

Include: <altera\_up\_avalon\_parallel\_port.h>

**Parameters:** name – the parallel port name. For example, if the parallel port name in

Qsys is "green\_leds", then *name* should be "/dev/green\_leds"

**Returns:** The corresponding device structure, or NULL if the device is not found.

**Description:** Open the parallel port device specified by *name*.

# 4.2.2 alt\_up\_parallel\_port\_read\_data

Prototype: unsigned int alt\_up\_parallel\_port\_read\_data(

alt\_up\_parallel\_port\_dev \*parallel\_port)

**Returns:** data – The data read for the parallel port.

**Description:** Read from the data register of the parallel port.

# 4.2.3 alt\_up\_parallel\_port\_write\_data

Prototype: void alt\_up\_parallel\_port\_write\_data(alt\_up\_parallel\_port\_dev

\*parallel\_port, unsigned data)

data – The data to be written to the parallel port.

**Description:** Write to the data register of the parallel port.

## 4.2.4 alt\_up\_parallel\_port\_read\_direction

Prototype: unsigned int alt\_up\_parallel\_port\_read\_direction(

alt\_up\_parallel\_port\_dev \*parallel\_port)

Include: <altera\_up\_avalon\_parallel\_port.h>
Parameters: parallel\_port - struct for the parallel port device.
Returns: direction - The direction read for the parallel port.

Description: Read from the direction register of the parallel port.

#### 4.2.5 alt\_up\_parallel\_port\_set\_port\_direction

Prototype: void alt\_up\_parallel\_port\_set\_port\_direction(

alt\_up\_parallel\_port\_dev \*parallel\_port,

unsigned direction)

**Description:** Set the direction register of the parallel port.

#### 4.2.6 alt\_up\_parallel\_port\_set\_all\_bits\_to\_input

Prototype: void alt\_up\_parallel\_port\_set\_all\_bits\_to\_input(

alt\_up\_parallel\_port\_dev \*parallel\_port)

## 4.2.7 alt\_up\_parallel\_port\_set\_all\_bits\_to\_output

Prototype: void alt\_up\_parallel\_port\_set\_all\_bits\_to\_output(

alt\_up\_parallel\_port\_dev \*parallel\_port)

#### 4.2.8 alt\_up\_parallel\_port\_set\_bit\_to\_input

Prototype: void alt\_up\_parallel\_port\_set\_bit\_to\_input(

alt\_up\_parallel\_port\_dev \*parallel\_port,

unsigned int bit)

Include: <altera\_up\_avalon\_parallel\_port.h>

**Parameters:** parallel\_port – struct for the parallel port device.

bit – The bit of the parallel port to be set as an input.

**Description:** Set the direction of one bit of the parallel port to be input.

# 4.2.9 alt\_up\_parallel\_port\_set\_bit\_to\_output

Prototype: void alt\_up\_parallel\_port\_set\_bit\_to\_output(

alt up parallel port dev \*parallel port,

unsigned int bit)

Include: <altera\_up\_avalon\_parallel\_port.h>

**Parameters:** parallel\_port - struct for the parallel port device.

bit – The bit of the parallel port to be set as an output.

**Description:** Set the direction of one bit of the parallel port to be output.

### 4.2.10 alt\_up\_parallel\_port\_read\_interrupt\_mask

Prototype: unsigned int alt\_up\_parallel\_port\_read\_interrupt\_mask(

alt\_up\_parallel\_port\_dev \*parallel\_port)

Include: <altera\_up\_avalon\_parallel\_port.h>
Parameters: parallel\_port - struct for the parallel port device.

Returns: data - The current interrupt mask of the parallel port.

Description: Read from the interrupt mask register of the parallel port.

#### 4.2.11 alt\_up\_parallel\_port\_set\_interrupt\_mask

Prototype: void alt\_up\_parallel\_port\_set\_interrupt\_mask(

alt\_up\_parallel\_port\_dev \*parallel\_port,

unsigned mask)

mask – The interrupt mask to be set in the parallel port.

**Description:** Set the interrupt mask register of the parallel port.

# 4.2.12 alt\_up\_parallel\_port\_read\_edge\_capture

Prototype: unsigned int alt\_up\_parallel\_port\_read\_edge\_capture(

alt\_up\_parallel\_port\_dev \*parallel\_port)

# 4.2.13 alt\_up\_parallel\_port\_read\_interrupt\_pending

Prototype: unsigned int alt\_up\_parallel\_port\_read\_interrupt\_pending(

alt\_up\_parallel\_port\_dev \*parallel\_port)

Include: <altera\_up\_avalon\_parallel\_port.h>
Parameters: parallel\_port - struct for the parallel port device.

Returns: pending - The interrupt pending bit field of the parallel port.

Parameters: pending - The interrupt pending bit field of the parallel port.

**Description:** Read interrupt pending information of the parallel port.

# 5 Appendix

The Parallel Port IP core differs from the PIO Core in the following ways:

- The Parallel Port core provides presets for ease of use with the simple I/Os on the DE-series boards, such as the LEDs and Switches.
- The PIO core provides an fourth direction option, named "Both input and output ports".
- The bit set/clear option of the PIO core is not available in the Parallel Port core.
- The Parallel Port core allows for edge-sensitive interrupts, while the PIO Core additionally allows for level-sensitive interrupts.
- For the Parallel Port core, the edge capture register is cleared when that register is read.
- The PIO core provides extra simulation support.
- The Parallel Port IP core includes device drivers that can be accessed by HAL.