

# **MAX**

# **APITZ-GROSSMAN**

***PRODUCT DESIGN MECHANICAL ENGINEERING PORTFOLIO 2025***



## 01 SALICO

- The world's first sea asparagus harvester.

## 02 SKYDIO

- X10 dock: electronics enclosure design.
- PT screw boss optimization.

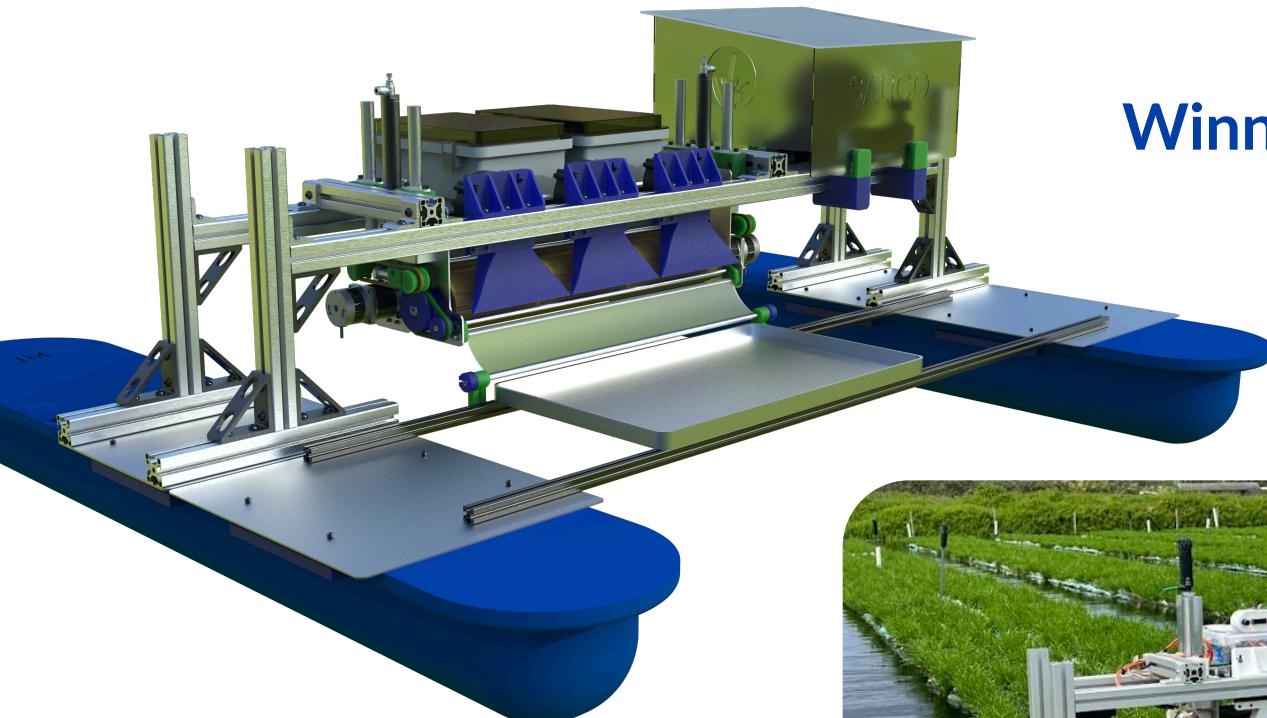
## 03 FORMLABS

- Form Wash: mounting arms rework.
- Form 4: cover damper testing and validation.

# PROJECT SALICO

Final Year Design Project

The world's first sea asparagus harvester.



Winner of Best Overall Project  
in Waterloo Mechatronics  
Engineering 2025



<https://salico-uw.github.io/>

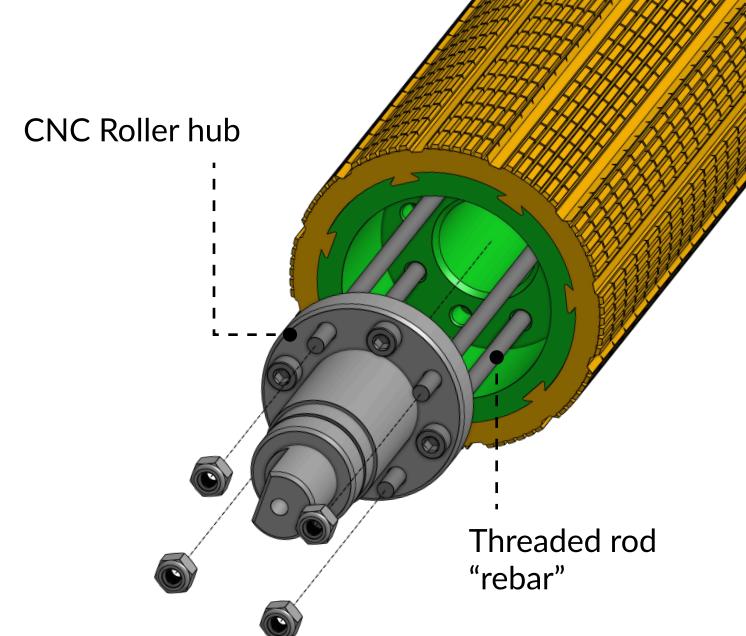
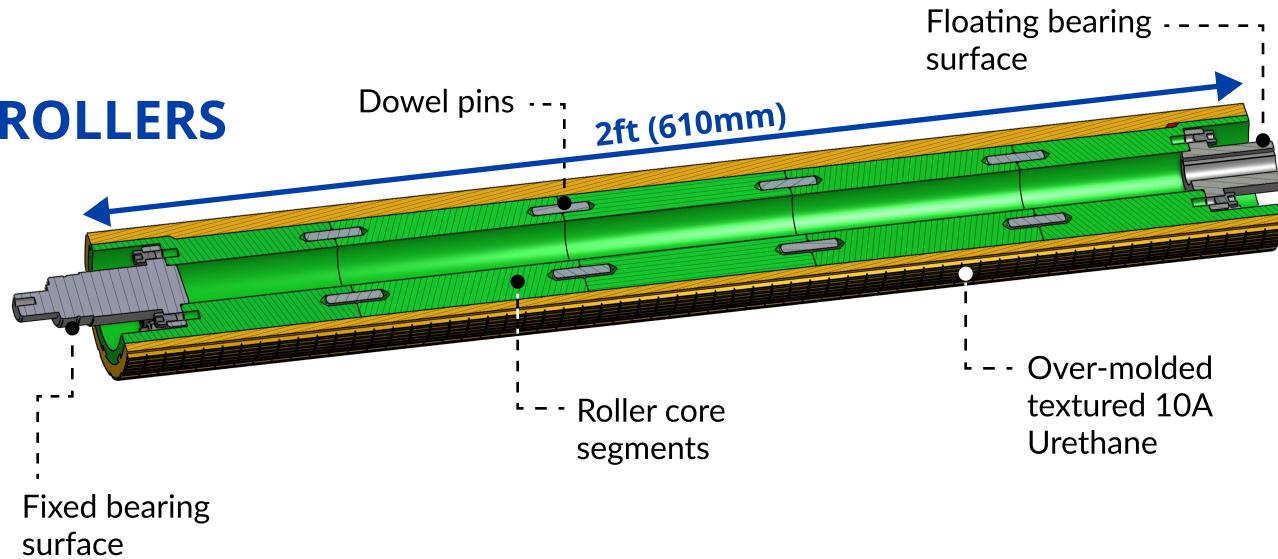
Salicornia, AKA sea asparagus, is a delicious and environmentally friendly salt water vegetable. No specific sea asparagus technology exists. Farms **struggle to scale** because of **manual labour**.

We make up a **5-person cross-functional team** of mechanical, electrical, firmware, and software engineers. My contributions included all the **mechanical design, prototyping, and assembly**.

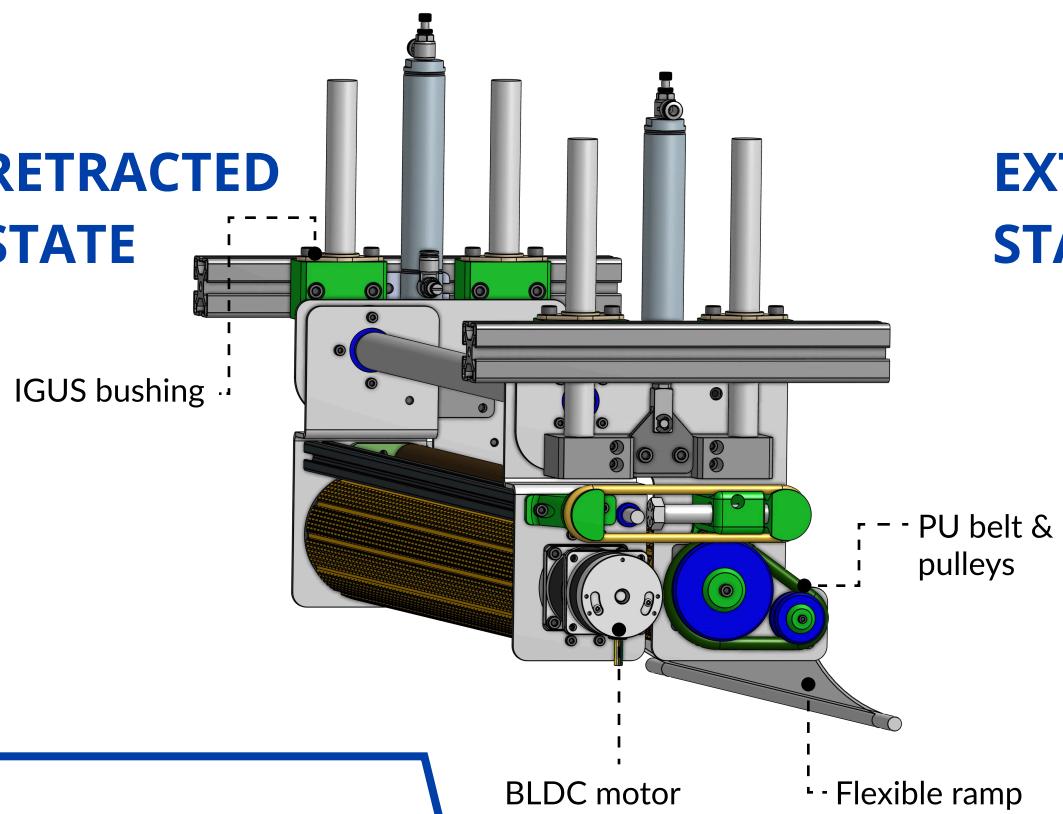
PROBLEM AND  
CONTRIBUTIONS

# DESIGN OVERVIEW

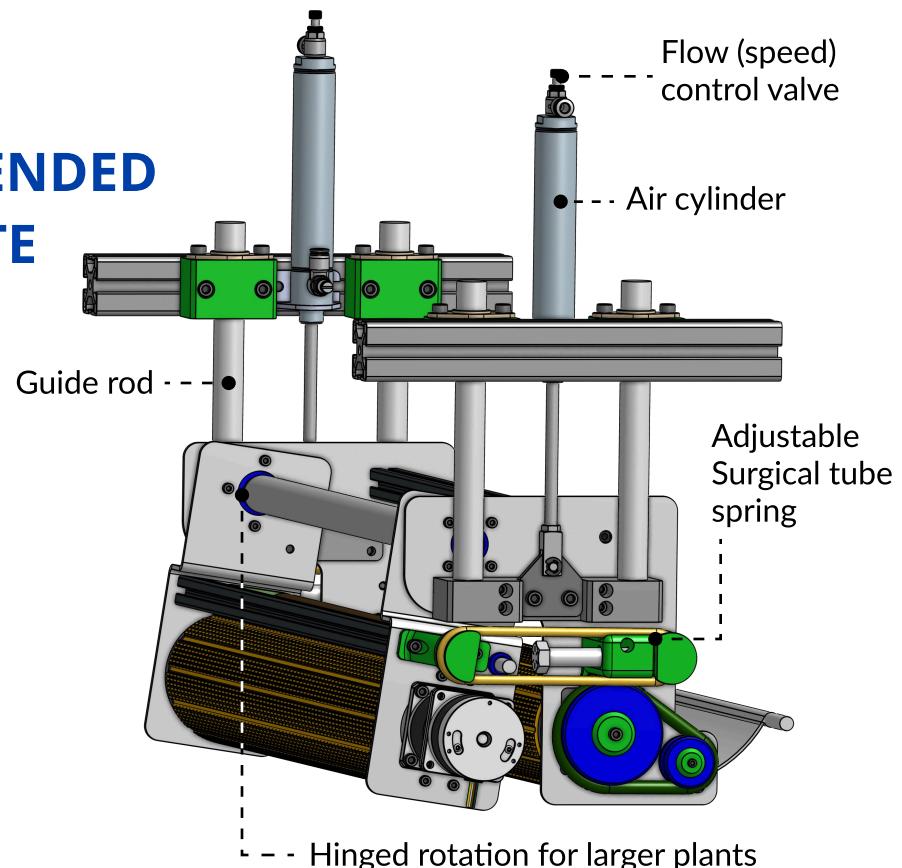
## ROLLERS



## RETRACTED STATE



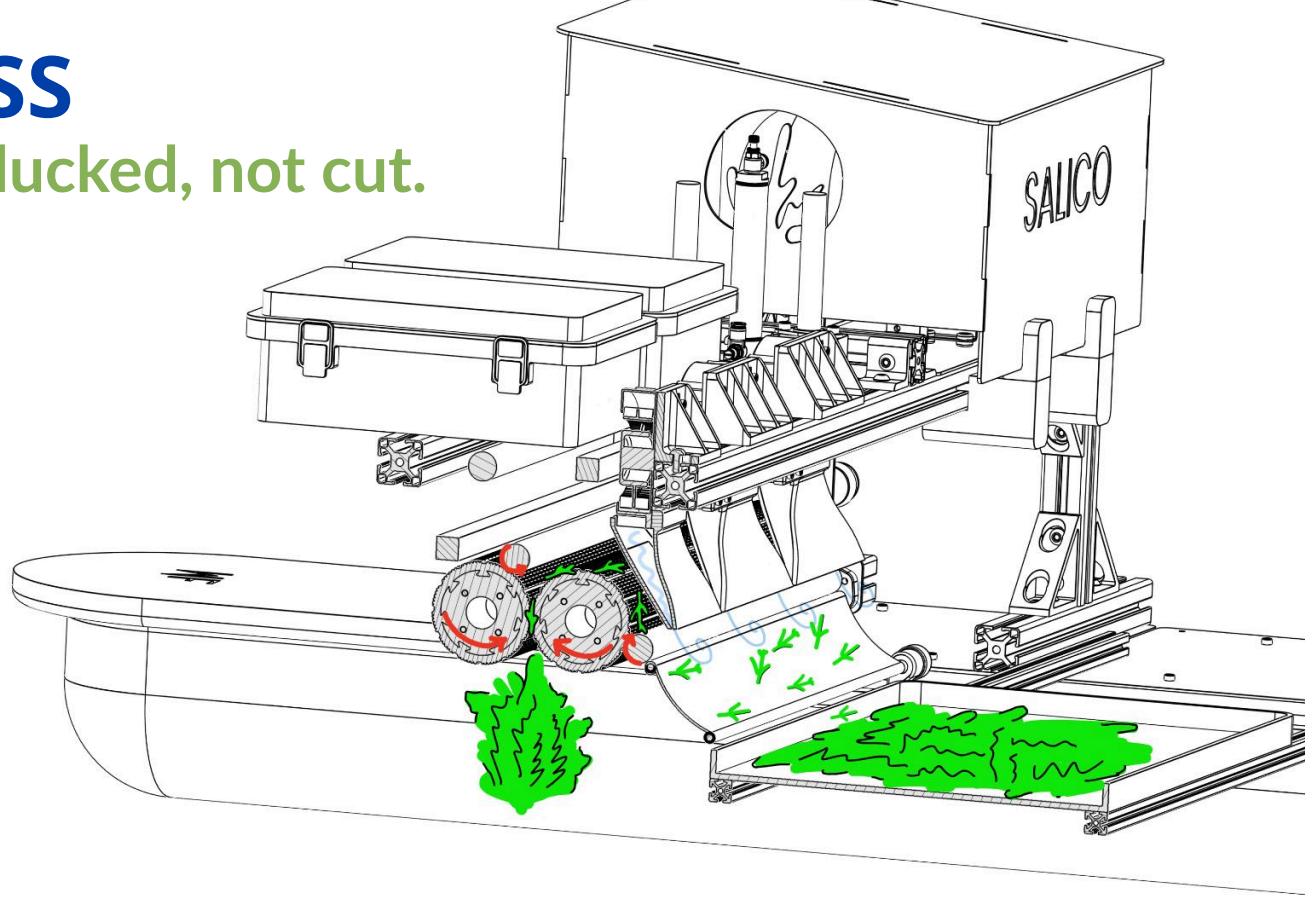
## EXTENDED STATE



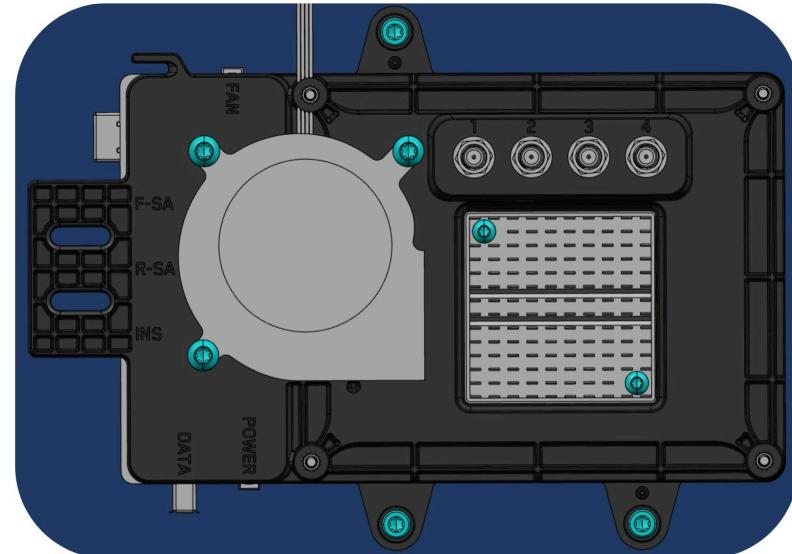
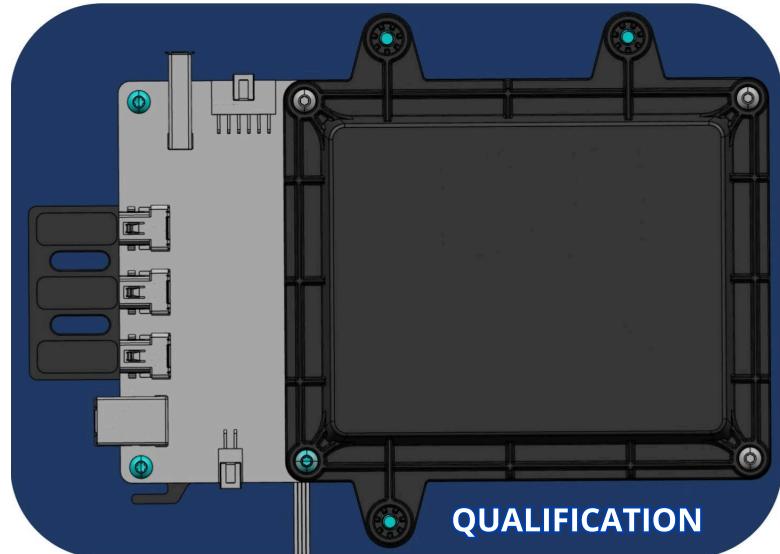
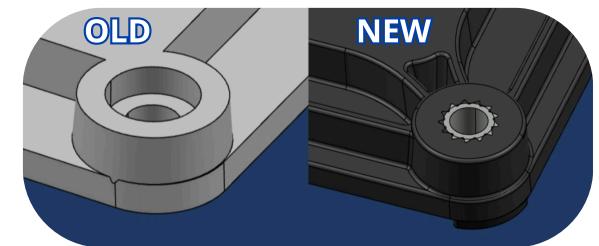
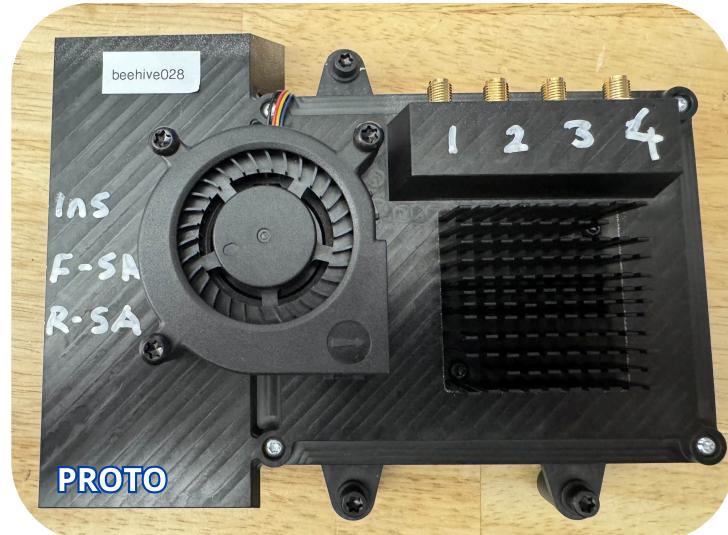
# HARVEST PROCESS

Sea asparagus must be plucked, not cut.

- Extend pistons while spinning rollers.
- Grasp plants between rollers.
- Lock the motors and retract pistons.
- Brushes powered by rollers direct the crops towards collection tray.
- Fans provide extra force to deposit harvest into collection tray.
- Move to next row, repeat.



### Skydio X10 dock: electronics enclosure design.

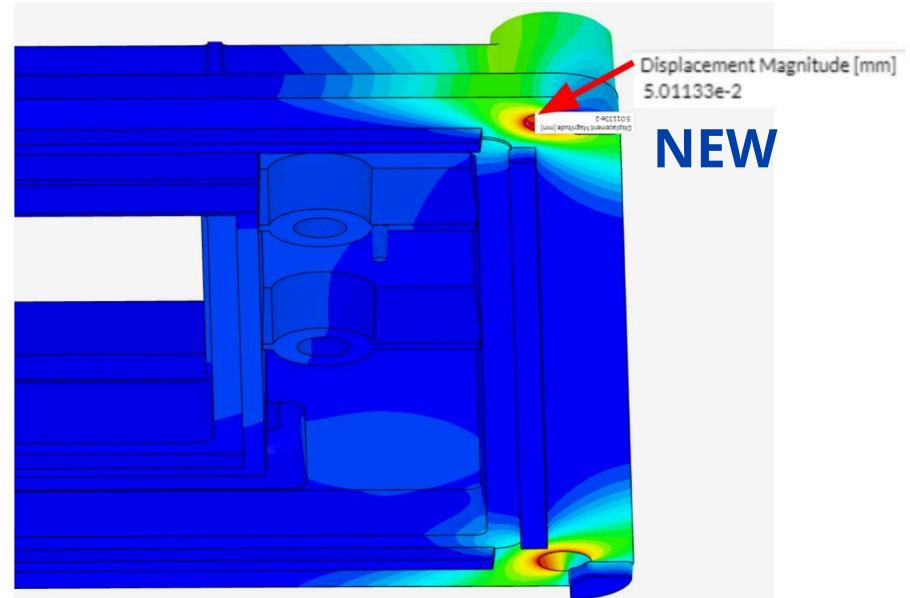
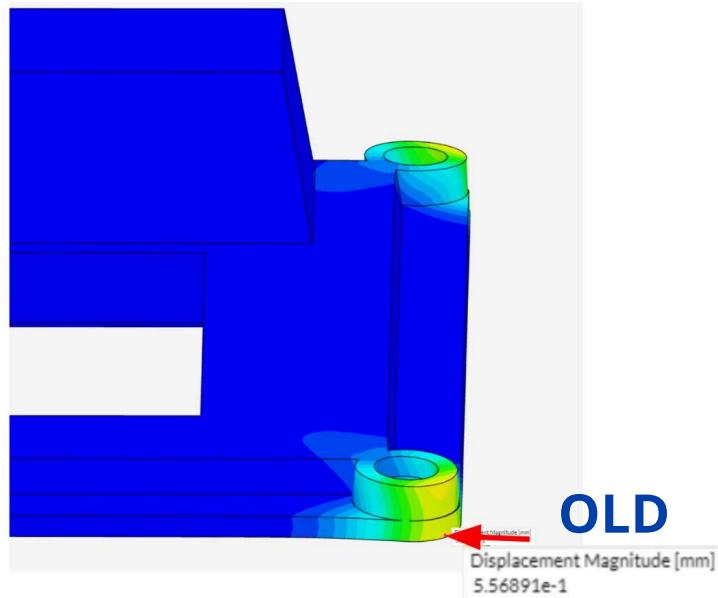
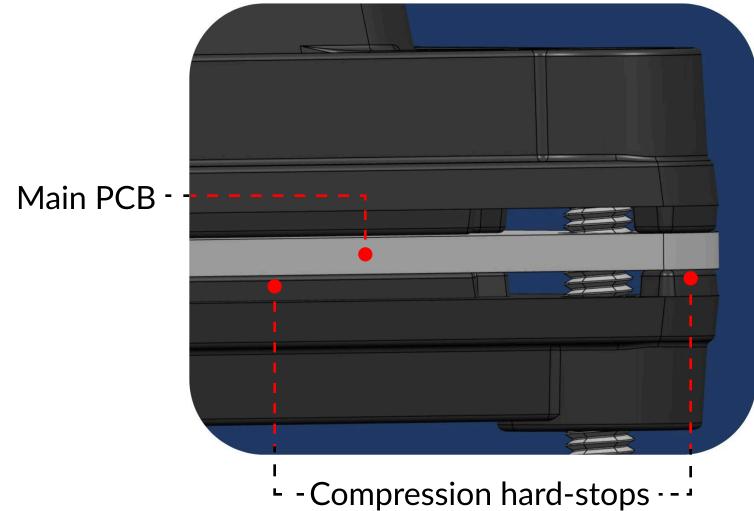
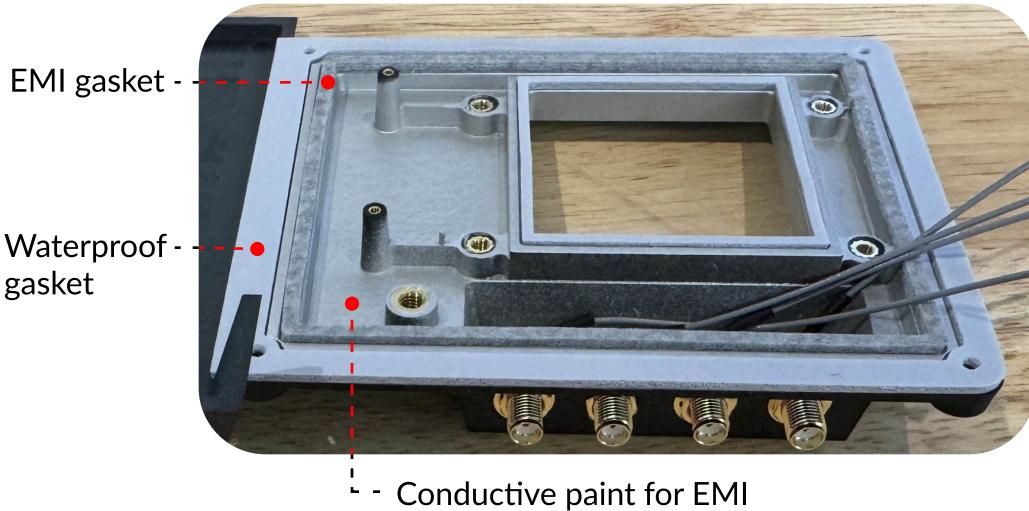


Moving from the **Prototype** to **Qualification** builds, there were a number of DFA, Rel, and manufacturing changes to be made.

## PROBLEM

# ENCLOSURE OVERVIEW 1

Hard-stops at all corners to control gasket compression distance. Ribs for rigidity.



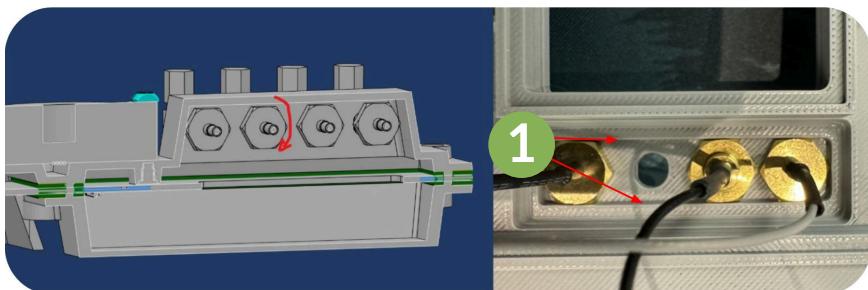
Owned all enclosure changes between Proto 2 and Qual 1 builds including the conversion from CNC to injection molding.

SOLUTION

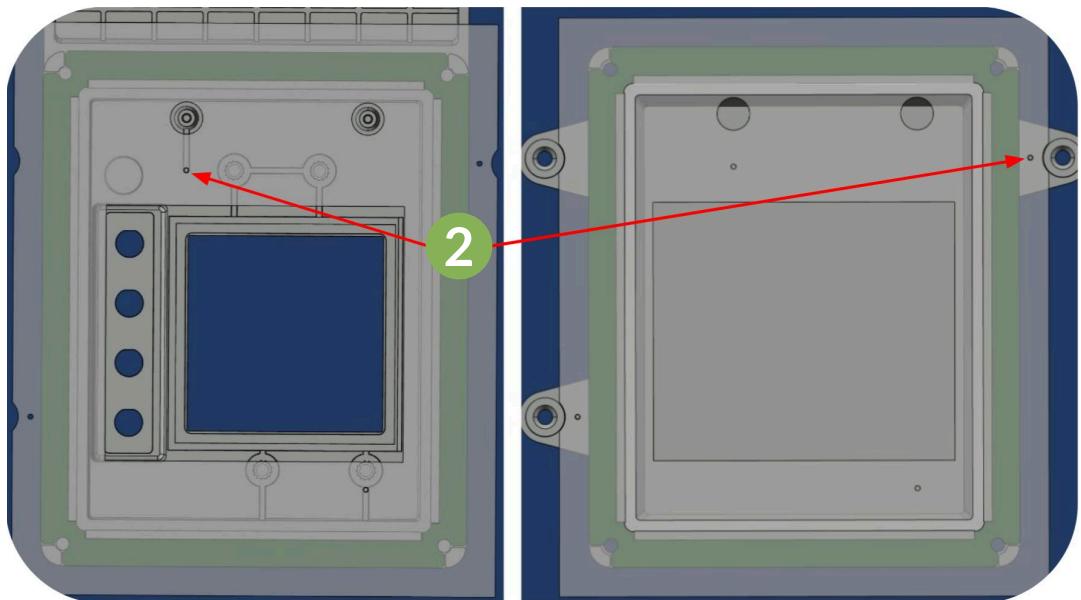
# ENCLOSURE OVERVIEW 2

DFA changes to fix issues discovered during the P2 build.

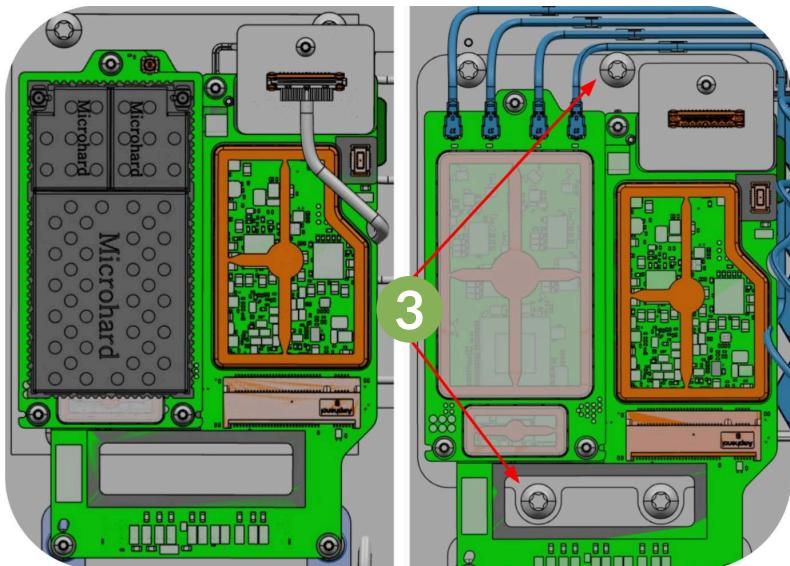
## HARD-STOPS FOR ANTENNAS



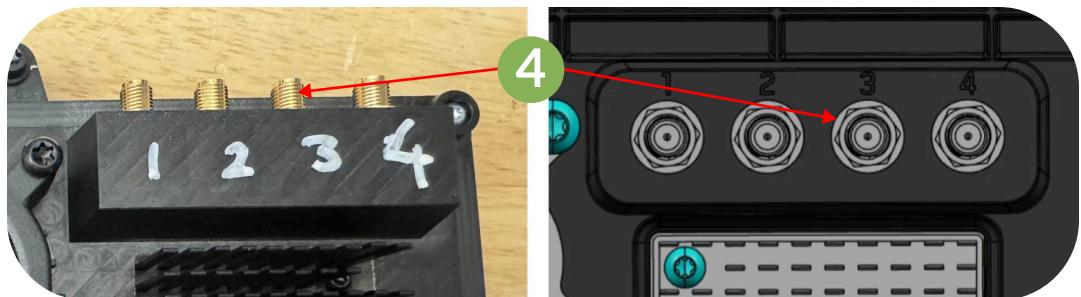
## ONE GASKET LINER FOR EVERYTHING



## FIXING BURIED SCREW ACCESS



## AVOIDING 90° ANTENNA ADAPTERS

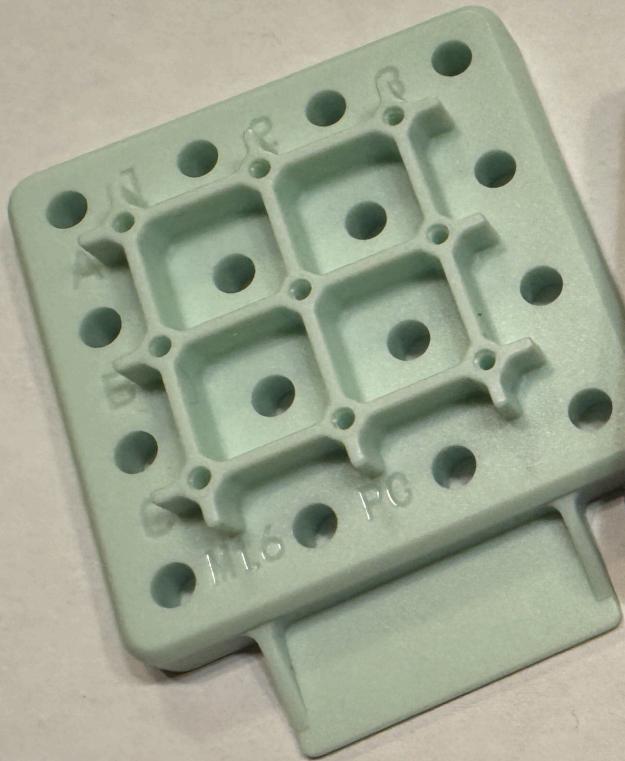


Owned all enclosure changes between Proto 2 and Qual 1 builds including the conversion from CNC to injection molding.

**SOLUTION**

## PT boss testing for M1.6 and M2 screws.

UNFILLED



CARBON FILLED



GLASS FILLED



PT screw bosses were **stripping** during assembly, **wasting time and money**. The team did not have **reliable PT boss guidelines**.

**PROBLEM**

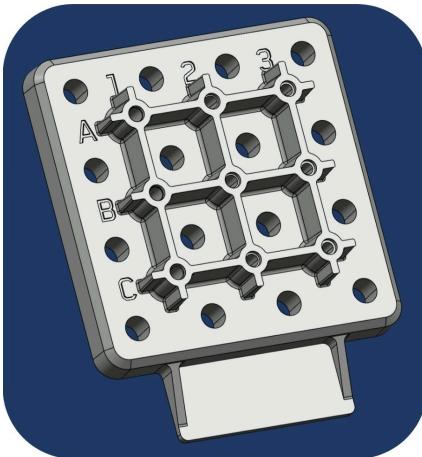
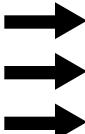
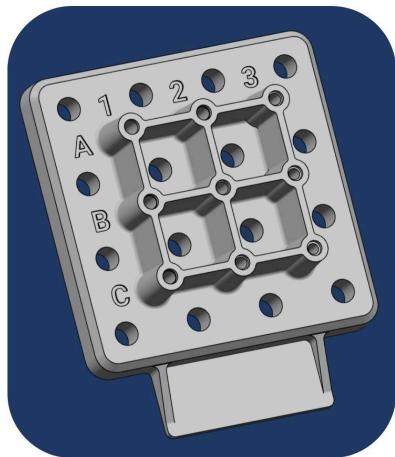
# PT SCREW OVERVIEW

9 boss geometries and 1620 screws were tested to determine the best design.

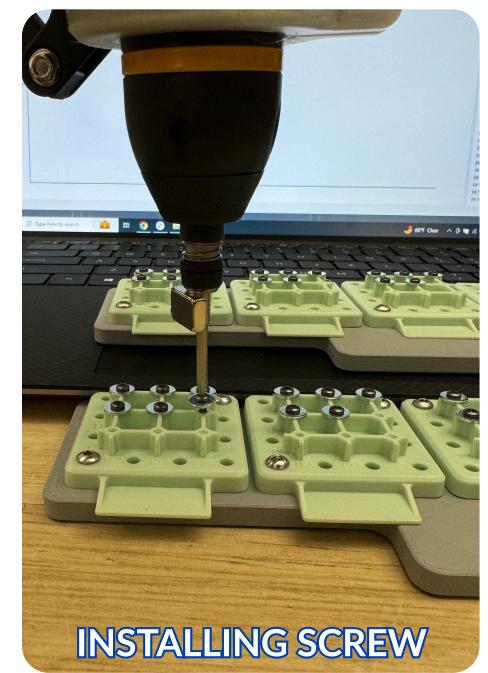
d = major diameter of screw	1		2		3	
	DRAFT	HOLE	DRAFT	HOLE	DRAFT	HOLE
A	2.0°	0.95 x d	2.0°	0.85 x d	2.0°	0.75 x d
B	1.5°	0.95 x d	1.5°	0.85 x d	1.5°	0.75 x d
C	1.0°	0.95 x d	1.0°	0.85 x d	1.0°	0.75 x d

BASELINE

## TOOL MODIFICATIONS



ASSEMBLING TRAYS



INSTALLING SCREW

## VARIABLES

Hole size: 3 levels

Draft angle: 3 levels

Material (PC): no fill, 20% CF, 20% GF

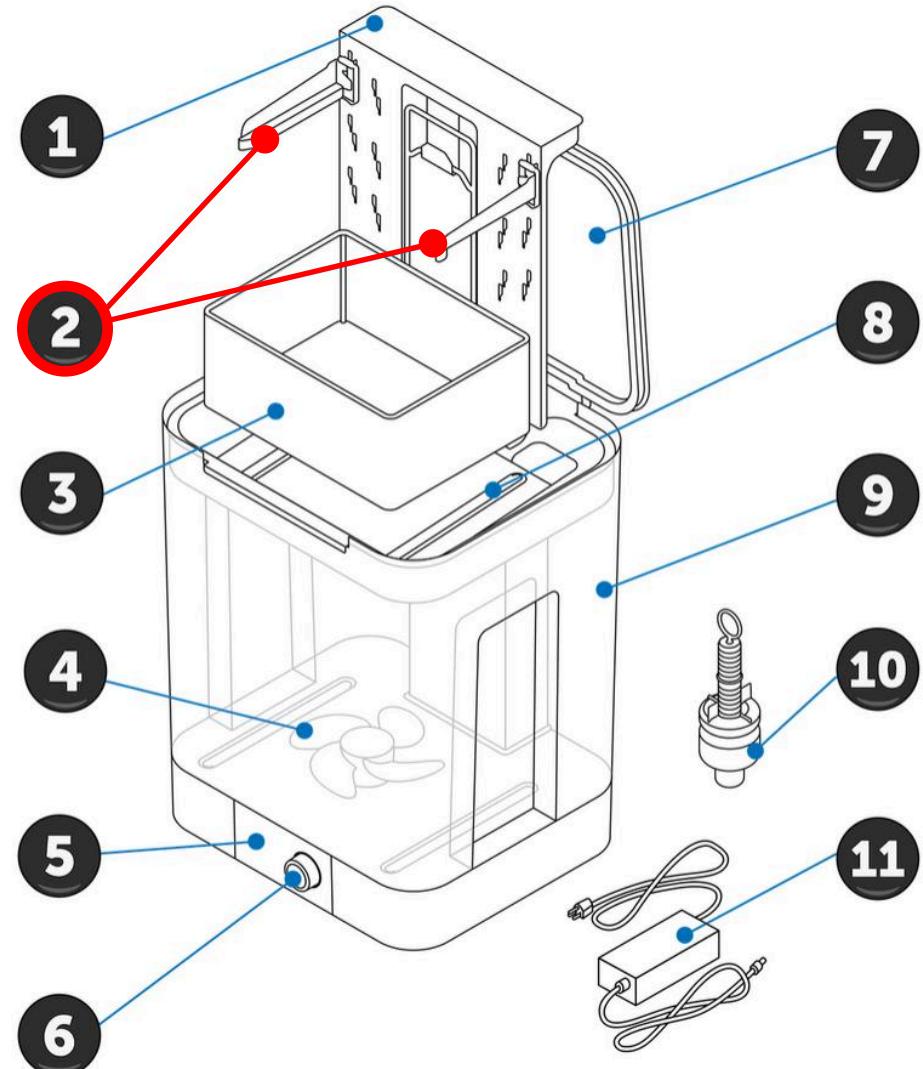
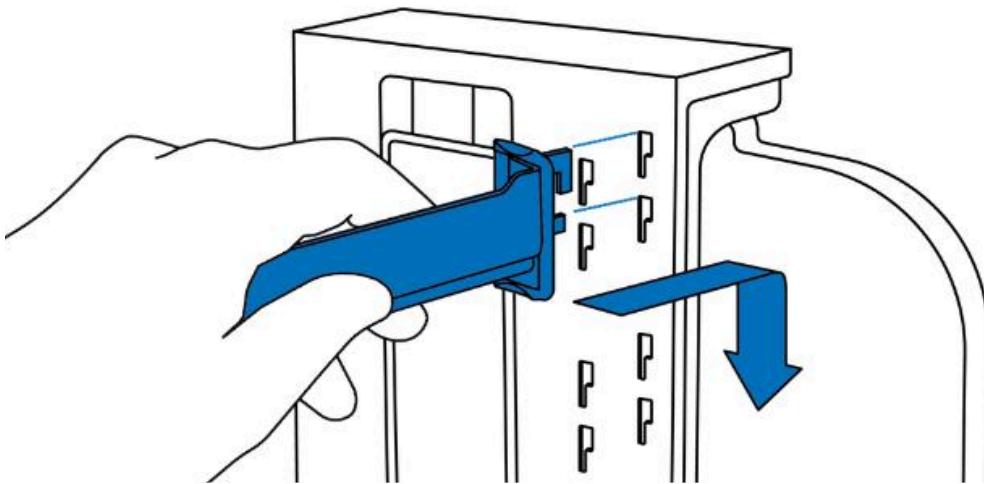
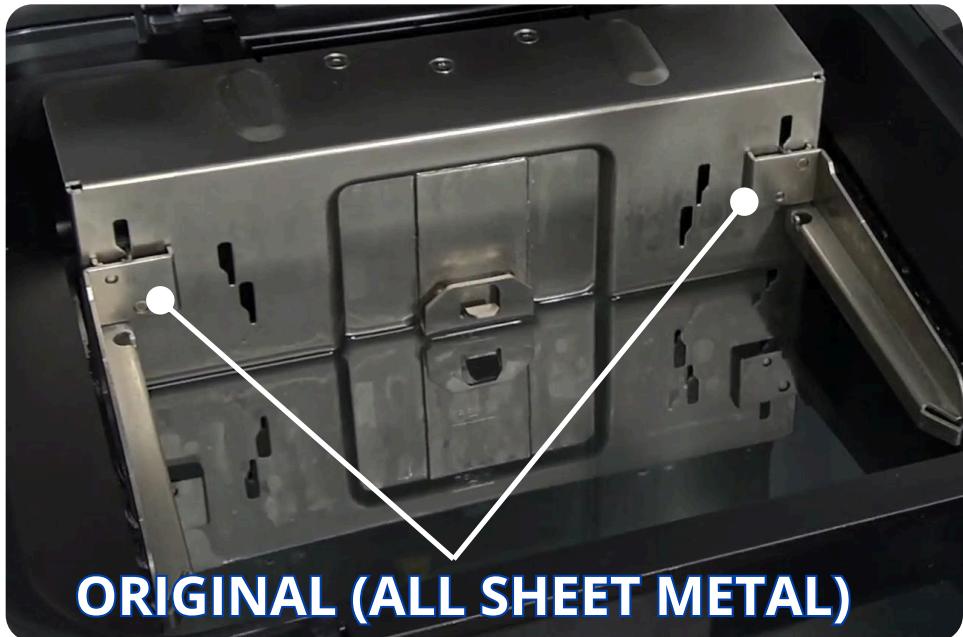
Tool RPM: 100, 150, 200

Screw size: M1.6, M2

Created a PT boss design guide for engineers to reference using the most common materials and screw sizes at Skydio.

SOLUTION

## Form Wash: Mounting arms rework.

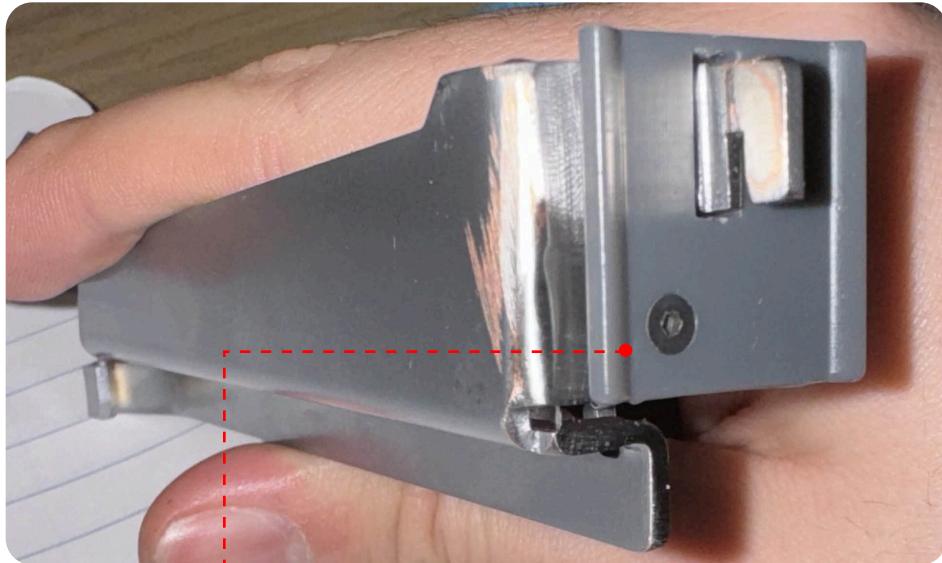


The Form Wash was shipping with inconsistent feeling mounting arms for the build plate. Tolerance issues caused excess friction.

**PROBLEM**

# MOUNTING ARM OVERVIEW

Exchanged sheet metal bends and welds for compliant polypropylene back plates.



3D printed tests -



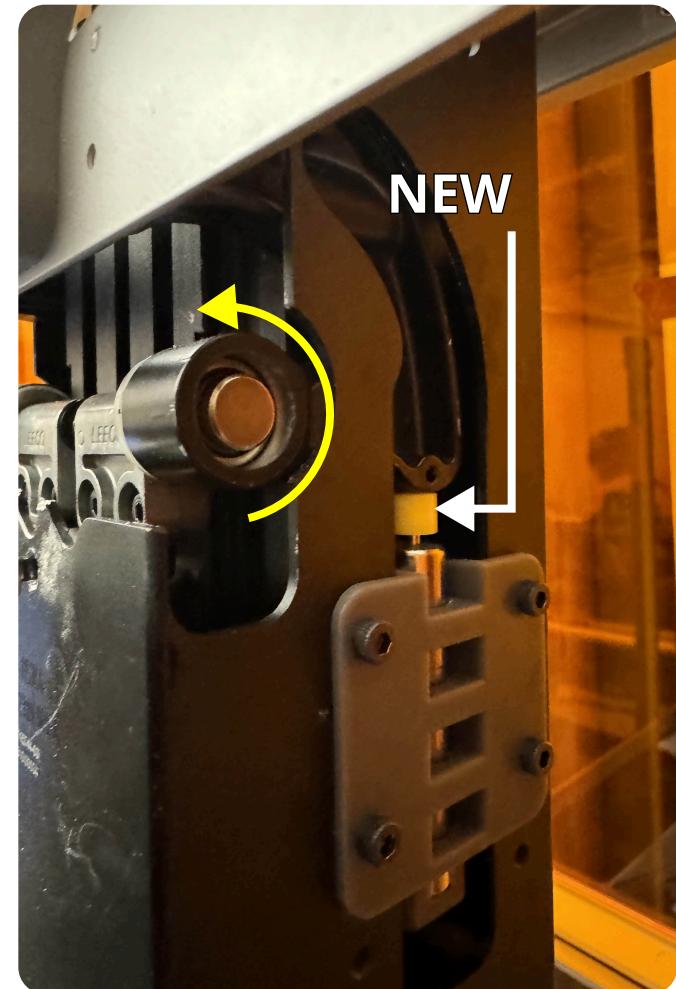
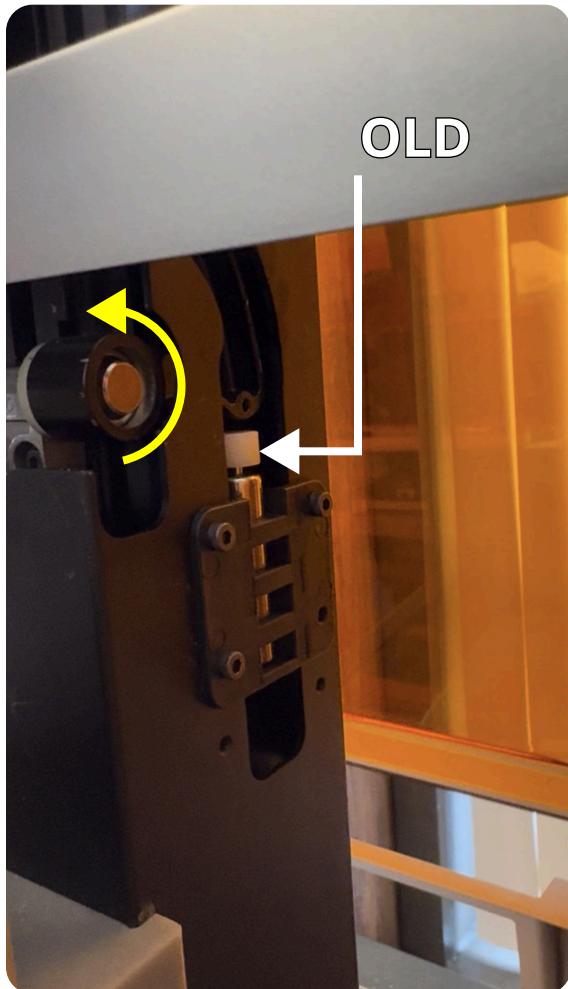
- Custom molds for testing (in-house)



Designed a drop-in replacement that saved money, decreased the tolerance stack, and improved the user experience.

**SOLUTION**

### Form 4: Cover damper testing and validation.



Dampers used for the Form 4 cover soft-close had last minute issues before launch. New dampers required validation.

**PROBLEM**

# COVER DAMPER OVERVIEW

## Cover damper test and validation rigs.

Air cylinder

Flow (speed) control valve

Cycle counter

Air manifold

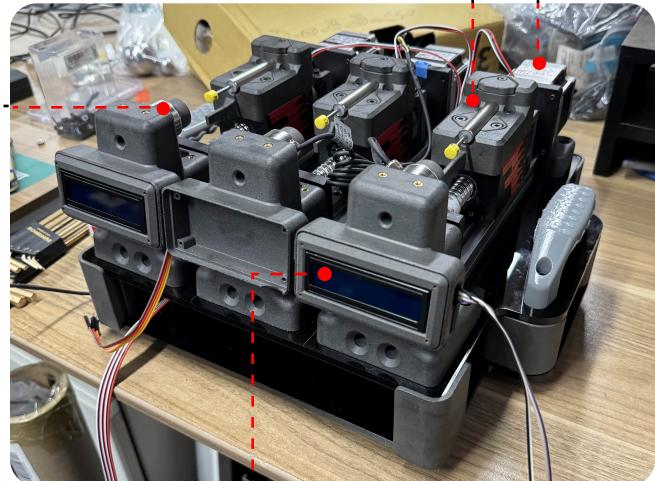


### PNEUMATIC LIFETIME TESTER

Mounted damper

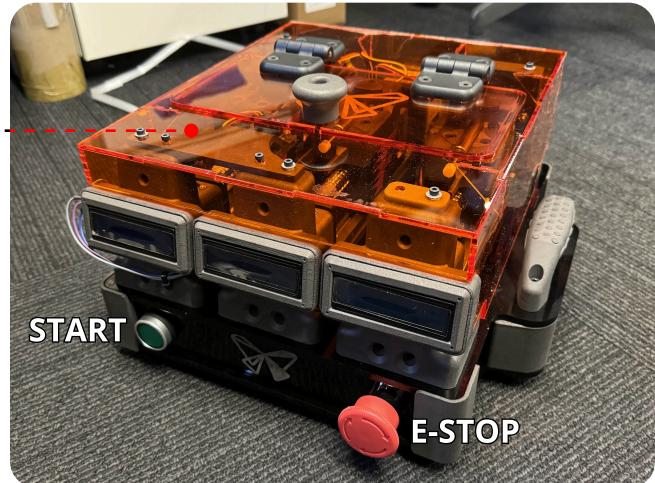
Magnetic damper mount --- Stepper motor

Load cell



LCD module

### FACTORY VALIDATION RIG



Safety enclosure with interlocks  
(power cut when door open)

Lifetime tested 150+ dampers to 10,000 cycles to confirm reliability. Created a rig to easily validate dampers on the line.

## SOLUTION