

ML.init(0): Dive into PyTorch

A Beginner's Guide to AI & ML Exploration!

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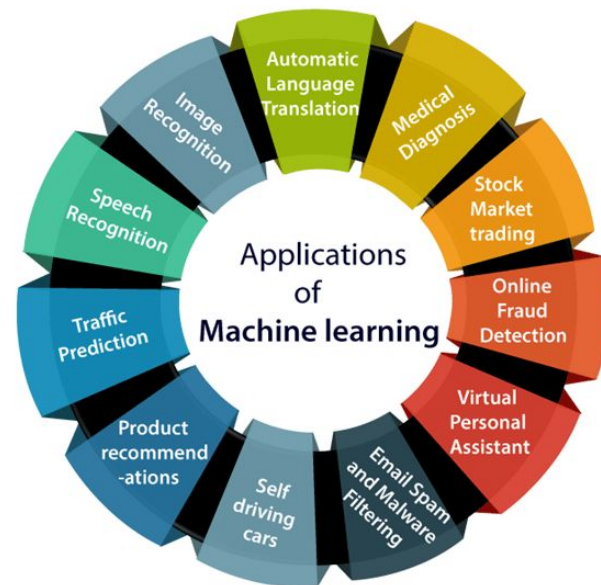
Objectives

- Set up a machine learning project in PyTorch
- Train and test a machine learning (ML) model
- Run inferences using the trained model



What is PyTorch?

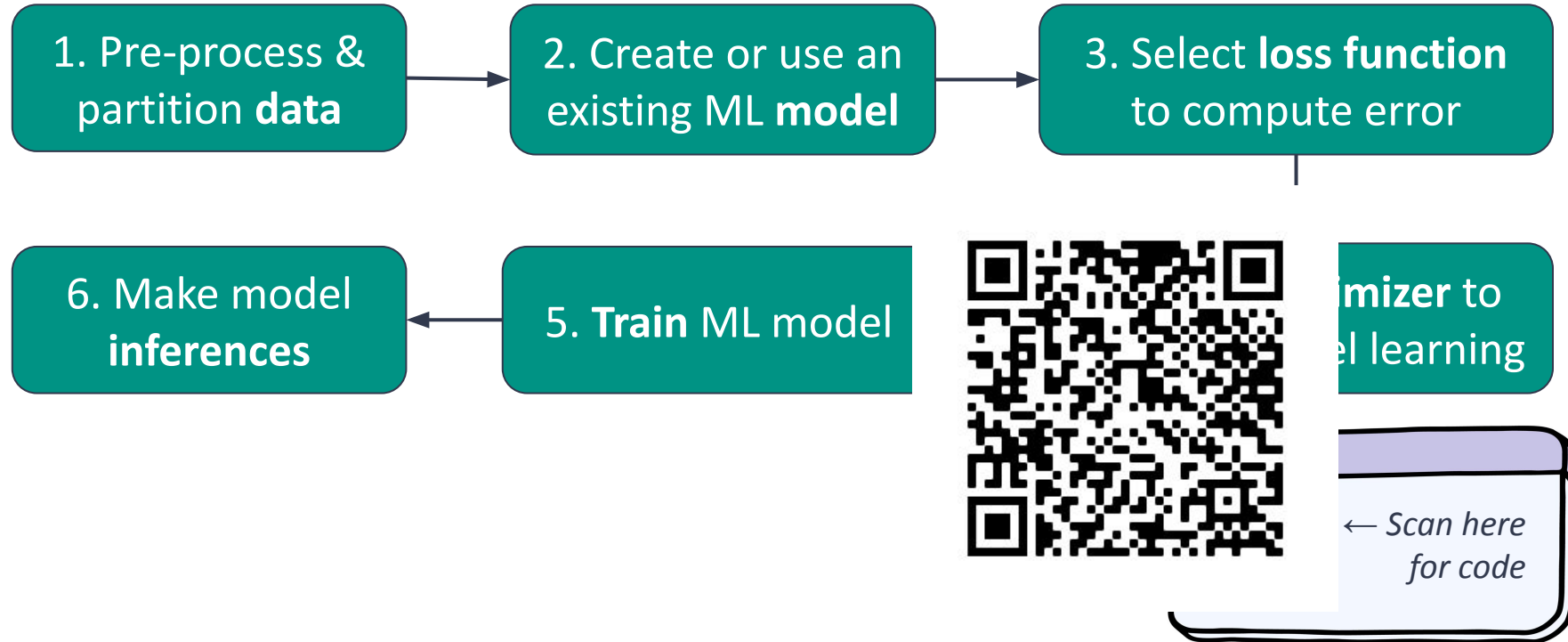
- Open-source deep learning library for Python
- Mainly used by data scientists for R&D
- Tensor computation, great for GPU use
- **Important modules:** autograd, optim, nn



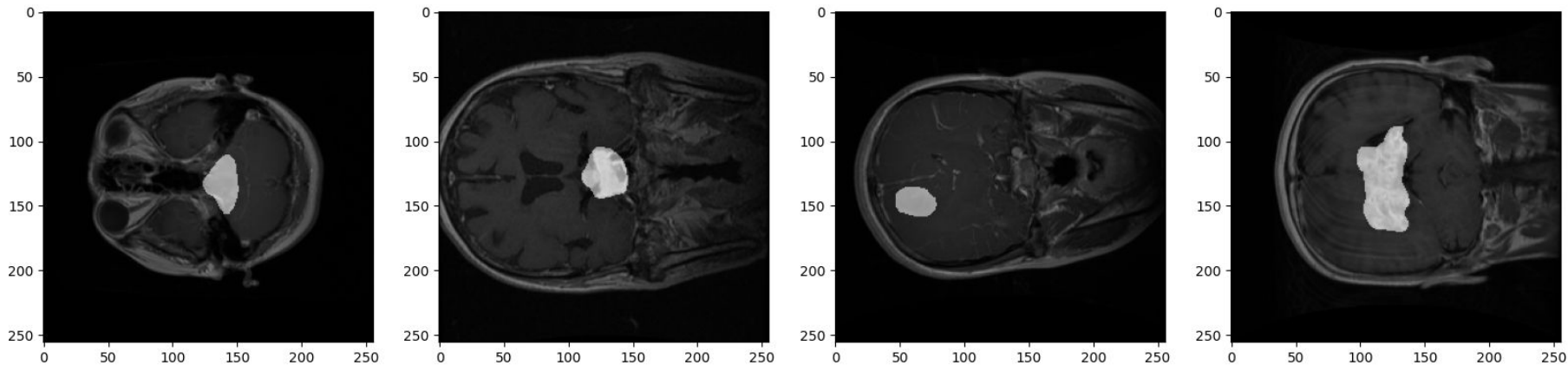
How does it compare with TensorFlow?

PyTorch	TensorFlow
<ul style="list-style-type: none">● Pythonic implementation; APIs easier to write, understand and debug● Flexible for experimentation, prototyping and data visualisation● Rapidly expanding community	<ul style="list-style-type: none">● Mature, extensive documentation with a large, established community● Optimised for production deployment● Compatible with existing frameworks and industry standards

AI research project workflow



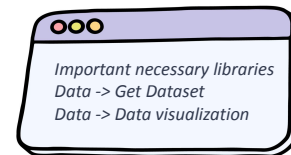
Example: Brain Tumor Segmentation



- 3064 T1 MRI slices from 233 patients
- Three brain tumor types:
 - Meningioma
 - Glioma
 - Pituitary tumor

Cheng (2017). Brain tumor dataset. figshare. Dataset.

<https://doi.org/10.6084/m9.figshare.1512427.v5>

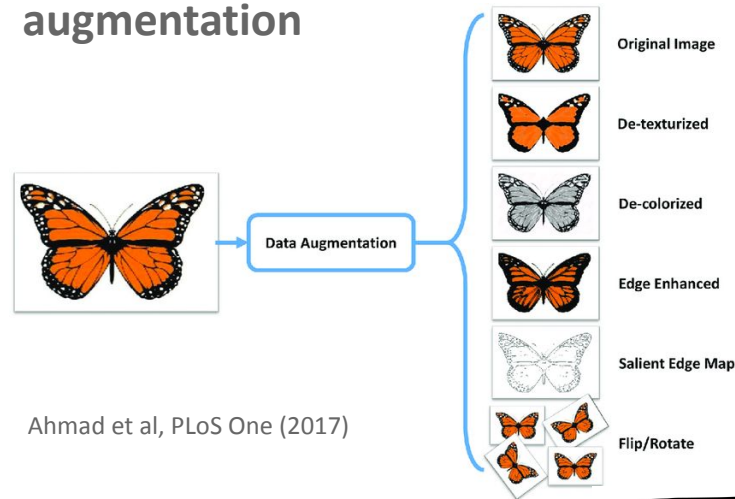


1. Data

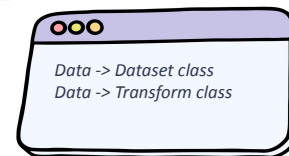
Pre-process data using the **Transform** class

- Numpy arrays \rightarrow Tensor (*torch.from_numpy*)
 - Tensor designed to work with GPU acceleration and backpropagation
- Resize image

Can also enlarge dataset by **data augmentation**



Ahmad et al, PLoS One (2017)



1. Data

```
class Resize(object):
    """Resize the image and mask.

    Args:
        output_size (tuple or int): Desired output size. If tuple, output is
            matched to output_size. If int, smaller of image edges is matched
            to output_size keeping aspect ratio the same.

    """

    def __init__(self, output_size):
        assert isinstance(output_size, (int, tuple))
        self.output_size = output_size

    def __call__(self, sample):
        image = sample['image']
        mask = sample['mask']

        h, w = image.shape[:2]
        if isinstance(self.output_size, int):
            if h > w:
                new_h, new_w = self.output_size * h / w, self.output_size
            else:
                new_h, new_w = self.output_size, self.output_size * w / h
        else:
            new_h, new_w = self.output_size

        new_h, new_w = int(new_h), int(new_w)

        image = transform.resize(image, (new_h, new_w)) * 255.0
        image = np.stack((image,) * 3, axis=-1)
        mask = transform.resize(mask, (new_h, new_w)) * 255.0
        mask = np.expand_dims(mask, axis=-1)

        sample['image'] = image
        sample['mask'] = mask

    return sample

    aset):
    """

    ot_dir, transform=None):

    ing): Directory with all the images.
    llable, optional): Optional transform to be applied
    le.

    oot_dir
    listdir(self.root_dir)
    transform

    mages)

    idx):
    r(idx):
    ist())

    h.join(self.root_dir, self.image
    filename, 'r').get('cjdاتا')
    'image')[()]
    tumorMask')[()]

    : image, 'mask': mask}

    :
    .transform(sample)
```

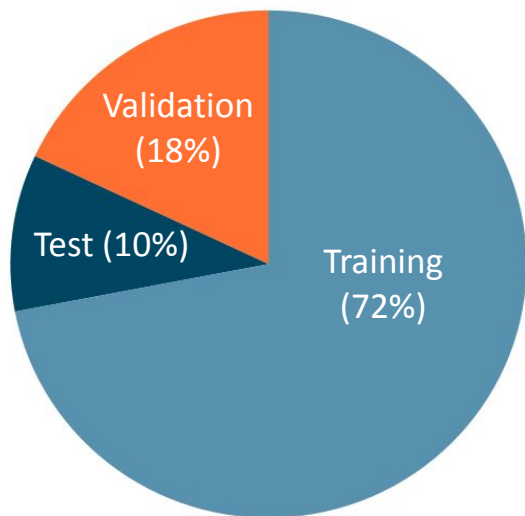
```
class ToTensor(object):
    """Convert ndarrays to Tensors."""

    def __call__(self, sample):
        # swap color axis because
        # numpy image: H x W x C
        # torch image: C x H x W
        image = sample['image'].transpose((2, 0, 1))
        mask = sample['mask'].transpose((2, 0, 1))
        sample['image'] = torch.from_numpy(image)
        sample['mask'] = torch.from_numpy(mask)

    return sample
```


1. Data

Split dataset and **save**
to respective folders



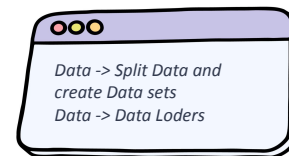
Load data with DataLoader

- *Batching*: Optimises memory usage
- *Shuffling*: Avoid learning patterns
- *Parallel loading*: Speeds up training

```
# Training data
train_dataloader = DataLoader(
    train_dataset, batch_size= 4, num_workers=2, shuffle=True)

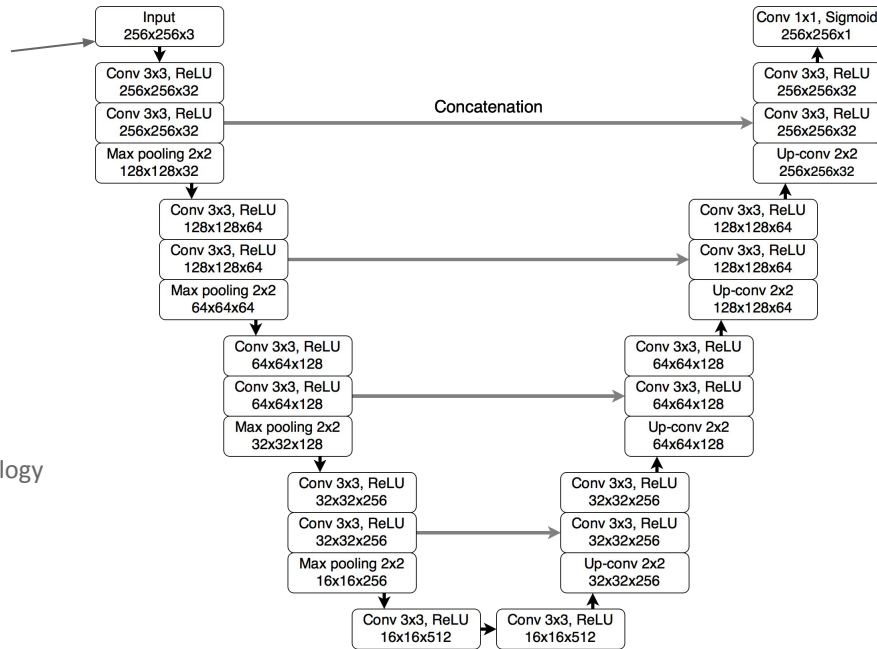
# Test data
test_dataloader = DataLoader(
    test_dataset, batch_size= 4, num_workers=2, shuffle=False)

# Validation data
val_dataloader = DataLoader(
    val_dataset, batch_size= 4, num_workers=2, shuffle=False)
```



2. Model

Three-channel
MRI slice



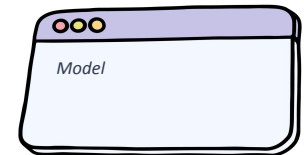
Single-channel
probability map of
abnormal regions

U-Net model

(developed specifically for
segmenting abnormalities
from brain MRI)

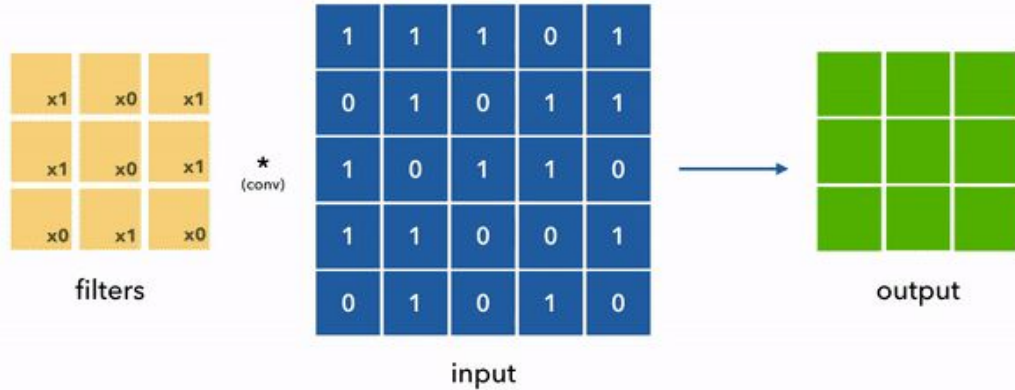
Buda et al, Computers in Biology
and Medicine (2019)

```
model = torch.hub.load('mateuszbuda/brain-segmentation-pytorch', 'unet',
    in_channels=3, out_channels=1, init_features=32, pretrained=True)
```

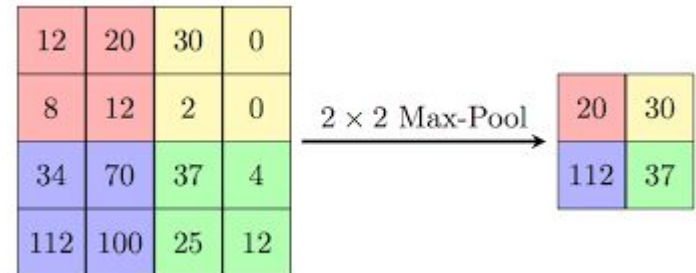


Building blocks

Convolution



Max Pooling



3. Loss

- Quantify how well our model predictions **perform** v.s. ground truth
- Model **learns by reducing** the loss function
- Improve model's predictive ability by **minimising** the loss function
- **Choice** of loss function is important

3. Loss

DICE score

Accurate boundary localisation



Binary Cross-Entropy (BCE)

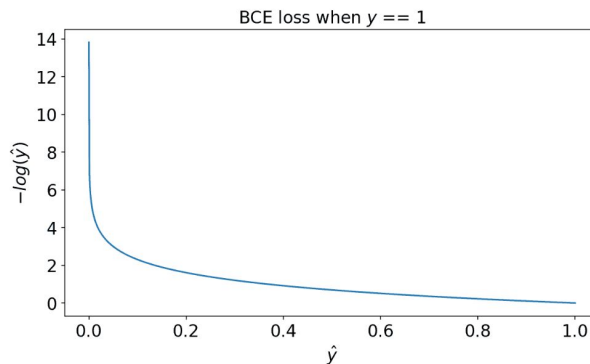
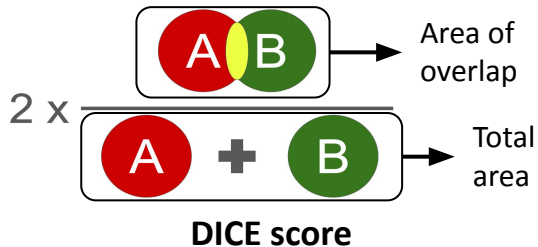
Measures pixel-wise similarity
between predicted & target mask



BCE Dice Loss

Accurate object localisation &
overall segmentation accuracy

A = Prediction B = Ground truth (target)



```
def bce_dice_loss(inputs, target):
    dicescore = dice_loss(inputs, target)
    bcescore = nn.BCELoss()
    bceloss = bcescore(inputs, target)

    return bceloss + dicescore
```

Balanced approach for image segmentation



4. Optimizer

- Optimizer **updates the value of weights** using the gradient from loss.backward to **minimize loss**
 - Gradient = change in loss function w.r.t. weight of model
 - Gradient $\rightarrow 0$: minimise loss, achieve **optimal model configuration**
- Lr scheduler to update learning rate depending on the training behaviour

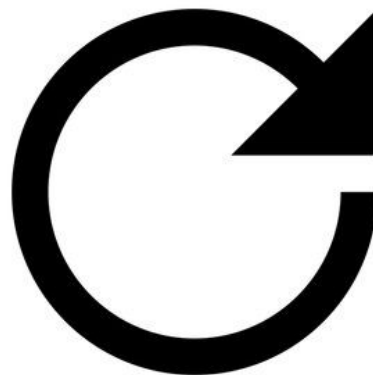
```
optimizer = AdamW(model.parameters(), 0.1)  
scheduler = lr_scheduler.StepLR(optimizer, step_size=5, gamma=0.5)
```



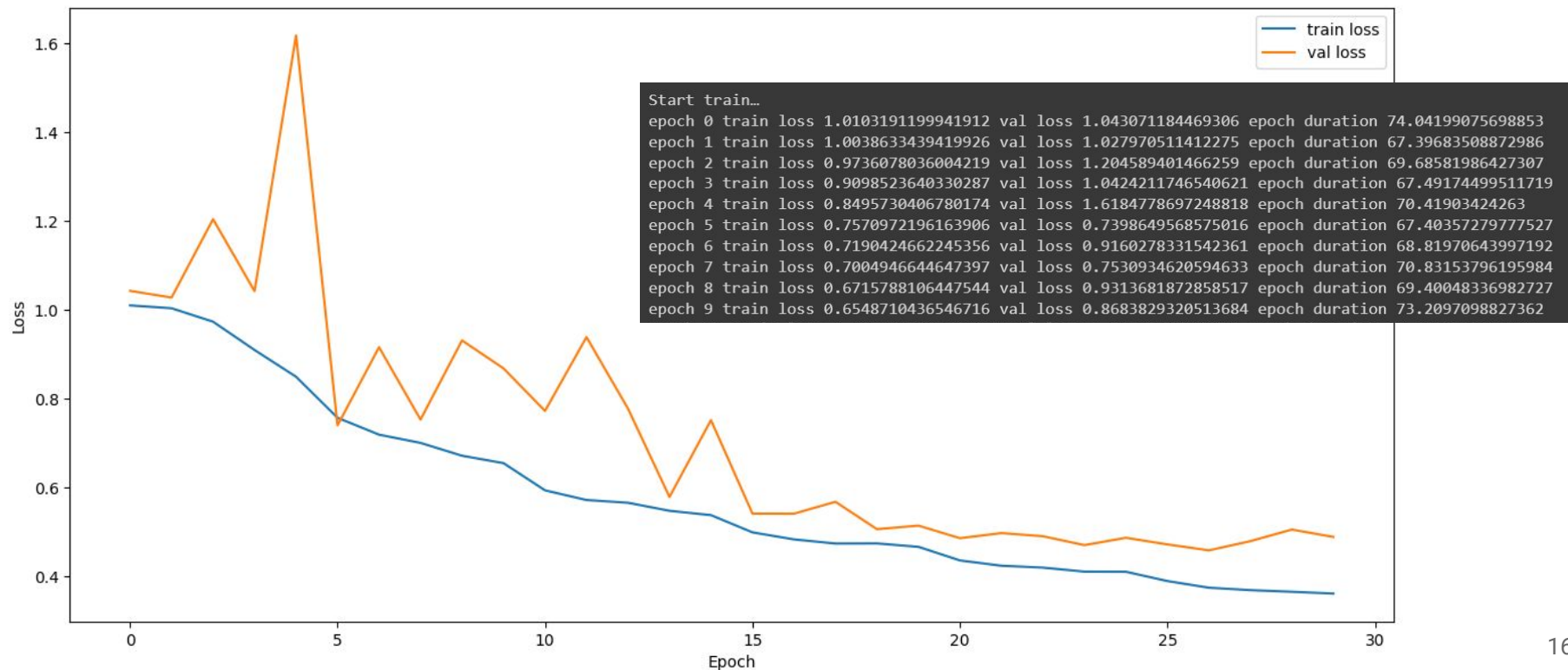
5. Training

Training loop:

- Train
 - Predict
 - Compute loss
 - Optimize
- Validate
 - Predict
 - Compute loss
- Save best model
- Adjust learning rate
- Repeat



5. Training

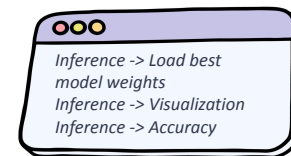


6. Inference

- **Save & load** models
- Use **best model weights** to segment tumours (test set)

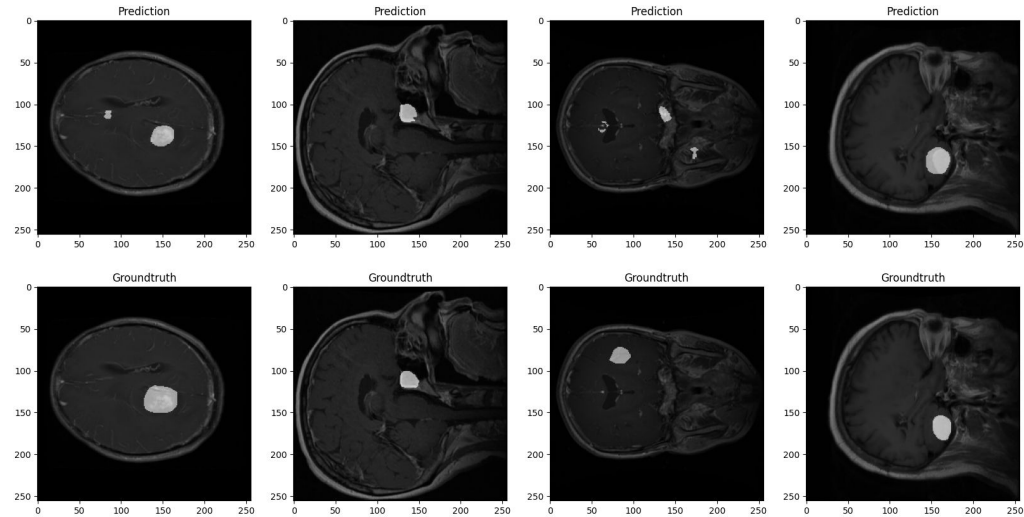
```
if curr_loss_val < best_loss_val:  
    best_loss_val = curr_loss_val  
    torch.save(model.state_dict(), r'/content/best_model.pth')
```

```
checkpoint = torch.load(  
    '/content/best_model.pth', map_location=torch.device('cpu'))  
model.load_state_dict(checkpoint)
```



6. Inference

- Save & load models
- Use best model weights to segment tumours (test set)
- **Visualize** predicted and ground truth images
- Compute **model accuracy** using test cases



```
[27] # Test set
      acc_test = compute_acc(test_dataloader, model)
      print(f'Accuracy on the train set is {acc_test}')
```

Accuracy on the train set is 0.6898969995913493

Inference -> Load best
model weights
Inference -> Visualization
Inference -> Accuracy

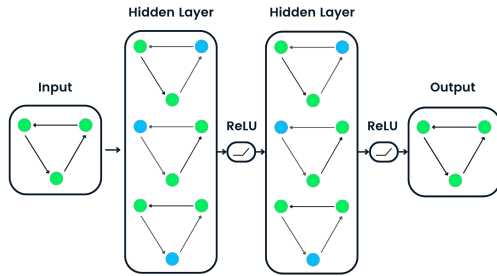
Summary

- **Learnt** how to **set up** a machine learning project in PyTorch
- **Trained** and **tested** a machine learning model to perform brain tumour **segmentation**
- Performed **inferences** with the trained model

Now, let's head over to the code!

What's next?

Graph Convolution Network



Diffusion Models

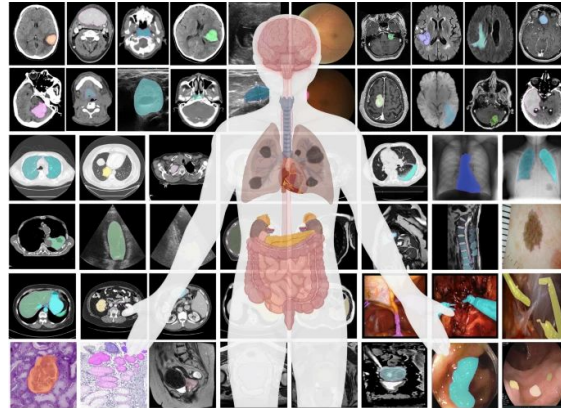


Article | [Open access](#) | Published: 22 January 2024

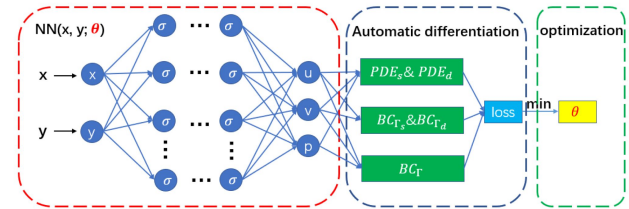
Segment anything in medical images

[Jun Ma](#), [Yuting He](#), [Feifei Li](#), [Lin Han](#), [Chenyu You](#) & [Bo Wang](#)

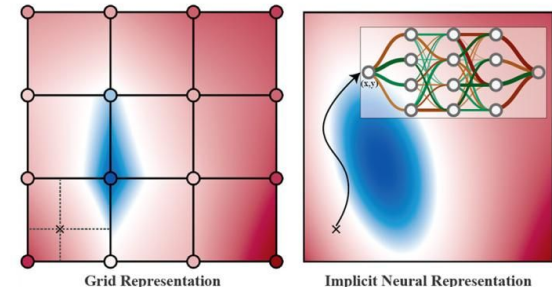
Nature Communications **15**, Article number: 654 (2024) | [Cite this article](#)



Physics-Informed Neural Networks (PINNs)



Neural Implicit Representation (NIR)



ML.init() team



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If you're interested to use ML in your work, or are just curious:
feel free to reach out for a chat!