A Combinatorial Perspective on Theta Structures Applications in Superglue

Max DUPARC

EPFL

SQIparty at Lleida: May 15, 2025

The challenge of Isogeny Based Cryptography



Figure: An outsider perspective on current Isogeny Based Cryptography

You can get a practical understanding of HD varieties & isogenies without scheme theory !

- ▶ Can infer most interesting properties from *theta structures*.
- Is it simpler?
 - ▶ NO!
 - ▶ More accessible. (Just ugly linear algebra).
- You should get a good toolbox to use Kani's Lemma:



You can get a practical understanding of HD varieties & isogenies without scheme theory !

- ▶ Can infer most interesting properties from *theta structures*.
 - Is it simpler?
 - ▶ NO !!
 - ▶ More accessible. (Just ugly linear algebra).
 - You should get a good toolbox to use Kani's Lemma:



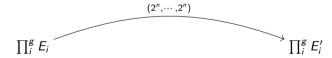
You can get a practical understanding of HD varieties & isogenies without scheme theory!

- ▶ Can infer most interesting properties from *theta structures*.
 - Is it simpler?
 - ► NO !!
 - ▶ More accessible. (Just ugly linear algebra).
 - You should get a good toolbox to use Kani's Lemma:



You can get a practical understanding of HD varieties & isogenies without scheme theory !

- ▶ Can infer most interesting properties from *theta structures*.
- Is it simpler?
 - ► NO !!
 - ▶ More accessible. (Just ugly linear algebra).
- You should get a good toolbox to use Kani's Lemma:



You can get a practical understanding of HD varieties & isogenies without scheme theory !

- ▶ Can infer most interesting properties from *theta structures*.
- Is it simpler?
 - ► NO !!
 - ▶ More accessible. (Just ugly linear algebra).
- You should get a good toolbox to use Kani's Lemma:

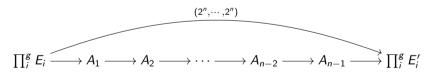


Table of Contents

Constructing theta structures

Exploring theta structures

Exploiting theta structures: Superglue

Reminder: Elliptic curves

Definition (Elliptic curve)

An *elliptic curve* E is an abelian variety of dimension 1 given by the zeros locus of a homogeneous polynomial.

$$E: zy^2 = x^3 + Ax^2z + xz^2 = x(x - \alpha z)(x - \alpha^{-1}z)$$

We have that $E[N] \cong \mathbb{Z}_N^2$ and their exists a non-degenerate, bilinear, and alternating Weil pairing

$$e_N: E[N] \times E[N] \longrightarrow \mathbb{S}^1$$

- non-degenerate: $\exists P, Q \text{ s.t. } e_N(P,Q) \neq 1$
- bilinear: $e_N(P_1 + P_2, Q) = e_N(P_1, Q) \cdot e_N(P_2, Q)$
- alternating: $e_N(P,Q) = e_N(Q,P)^{-1}$

Reminder: Elliptic curves

Definition (Elliptic curve)

An *elliptic curve* E is an abelian variety of dimension 1 given by the zeros locus of a homogeneous polynomial.

$$E: zy^2 = x^3 + Ax^2z + xz^2 = x(x - \alpha z)(x - \alpha^{-1}z)$$

We have that $E[N] \cong \mathbb{Z}_N^2$ and their exists a non-degenerate, bilinear, and alternating Weil pairing.

$$e_{N}: E[N] \times E[N] \longrightarrow \mathbb{S}^{1}$$

- non-degenerate: $\exists P, Q \text{ s.t. } e_N(P,Q) \neq 1$
- bilinear: $e_N(P_1 + P_2, Q) = e_N(P_1, Q) \cdot e_N(P_2, Q)$
- alternating: $e_N(P,Q) = e_N(Q,P)^{-1}$

Definition (Abelian variety)

An Abelian variety A of dimension g given by the zeros locus of some homogeneous polynomials.

We have that $A[N]\cong \mathbb{Z}_N^{2g}$ and their is a *non-degenerate*, bilinear, and alternating Weil pairing

$$e_N:A[N]\times A[N]\longrightarrow \mathbb{S}^2$$

Weil Pairing is no longer trivia

• A symplectic structure of A[N] is an isomorphism $\pi:A[N]\cong\mathbb{Z}_N^g\times\mathbb{Z}_N^g$ compatible with the Weil pairing.

$$\pi(P) = (x_P, \widehat{x_P})$$
 and $e_N(P, Q) = \omega^{(\widehat{x_Q} \cdot x_P) - (\widehat{x_P} \cdot x_Q)}$

with ω is a primitive N-th root of unity.

Definition (Symplectic basis)

A symplectic basis of A[N] is a basis $\{S_1,...,S_g,T_1,...,T_g\}$ such that

$$e_N(S_i, S_i) = e_N(T_i, T_i) = 1, \quad e_N(S_i, T_i) = \omega^{\delta_i}$$

Definition (Abelian variety)

An Abelian variety A of dimension g given by the zeros locus of some homogeneous polynomials. We have that $A[N] \cong \mathbb{Z}_N^{2g}$ and their is a non-degenerate, bilinear, and alternating Weil pairing.

$$e_{\mathcal{N}}:A[\mathcal{N}]\times A[\mathcal{N}]\longrightarrow \mathbb{S}^1$$

- Weil Pairing is no longer trivial.
- A symplectic structure of A[N] is an isomorphism $\pi:A[N]\cong\mathbb{Z}_N^g\times\mathbb{Z}_N^g$ compatible with the Weil pairing.

$$\pi(P) = (x_P, \widehat{x_P})$$
 and $e_N(P, Q) = \omega^{(\widehat{x_Q} \cdot x_P) - (\widehat{x_P} \cdot x_Q)}$

with ω is a primitive N-th root of unity.

Definition (Symplectic basis)

A symplectic basis of A[N] is a basis $\{S_1,...,S_g,T_1,...,T_g\}$ such that

$$e_N(S_i, S_i) = e_N(T_i, T_i) = 1, \quad e_N(S_i, T_i) = \omega^{\delta_i}$$

Definition (Abelian variety)

An Abelian variety A of dimension g given by the zeros locus of some homogeneous polynomials. We have that $A[N] \cong \mathbb{Z}_N^{2g}$ and their is a non-degenerate, bilinear, and alternating Weil pairing.

$$e_{N}:A[N]\times A[N]\longrightarrow \mathbb{S}^{1}$$

- ▶ Weil Pairing is no longer trivial.
- A symplectic structure of A[N] is an isomorphism $\pi:A[N]\cong\mathbb{Z}_N^g\times\mathbb{Z}_N^g$ compatible with the Weil pairing.

$$\pi(P)=(x_P,\widehat{x_P})$$
 and $e_N(P,Q)=\omega^{(\widehat{x_Q}\cdot x_P)-(\widehat{x_P}\cdot x_Q)}$

with ω is a primitive N-th root of unity.

Definition (Symplectic basis)

A symplectic basis of A[N] is a basis $\{S_1,...,S_g,T_1,...,T_g\}$ such that

$$e_N(S_i, S_i) = e_N(T_i, T_i) = 1, \quad e_N(S_i, T_i) = \omega^{\delta_i}$$

Definition (Abelian variety)

An Abelian variety A of dimension g given by the zeros locus of some homogeneous polynomials. We have that $A[N] \cong \mathbb{Z}_N^{2g}$ and their is a non-degenerate, bilinear, and alternating Weil pairing.

$$e_{N}:A[N]\times A[N]\longrightarrow \mathbb{S}^{1}$$

- Weil Pairing is no longer trivial.
- A symplectic structure of A[N] is an isomorphism $\pi:A[N]\cong \mathbb{Z}_N^{\mathfrak{g}}\times \widehat{\mathbb{Z}_N^{\mathfrak{g}}}$ compatible with the Weil pairing.

$$\pi(P) = (x_P, \widehat{x_P})$$
 and $e_N(P, Q) = \omega^{(\widehat{x_Q} \cdot x_P) - (\widehat{x_P} \cdot x_Q)}$

with ω is a primitive N-th root of unity.

Definition (Symplectic basis

A symplectic basis of A[N] is a basis $\{S_1,...,S_g,T_1,...,T_g\}$ such that

$$e_N(S_i, S_j) = e_N(T_i, T_j) = 1, \quad e_N(S_i, T_j) = \omega^{\delta_i}$$

Definition (Abelian variety)

An Abelian variety A of dimension g given by the zeros locus of some homogeneous polynomials. We have that $A[N] \cong \mathbb{Z}_N^{2g}$ and their is a non-degenerate, bilinear, and alternating Weil pairing.

$$e_{N}:A[N]\times A[N]\longrightarrow \mathbb{S}^{1}$$

- ▶ Weil Pairing is no longer trivial.
- A symplectic structure of A[N] is an isomorphism $\pi:A[N]\cong \mathbb{Z}_N^{\mathfrak{g}}\times \widehat{\mathbb{Z}_N^{\mathfrak{g}}}$ compatible with the Weil pairing.

$$\pi(P) = (x_P, \widehat{x_P})$$
 and $e_N(P, Q) = \omega^{(\widehat{x_Q} \cdot x_P) - (\widehat{x_P} \cdot x_Q)}$

with ω is a primitive N-th root of unity.

Definition (Symplectic basis)

A symplectic basis of A[N] is a basis $\{S_1,...,S_g,T_1,...,T_g\}$ such that:

$$e_N(S_i, S_i) = e_N(T_i, T_i) = 1, \quad e_N(S_i, T_i) = \omega^{\delta_{ij}}$$

Definition (Theta structure)

Let A be an Abelian variety of dimension g. A (level 2 symmetric) theta structure is a morphism into the Kummer variety \mathcal{K}_A :

$$\theta^A: A_{/\pm 1} \longrightarrow \mathcal{K}_A \subseteq \mathbb{P}^{2^g-1}$$

that is compatible with a symplectic basis on A[2]: For all $X \in A[2]$ with $\pi(X) = (x, \hat{x})$:

$$\theta_i^A(P+X) = (-1)^{\widehat{x}\cdot i}\theta_{i+x}^A(P)$$

- $\theta^A(0)$ the theta null point characterises A up to isomorphism.
- Several valid solutions for one symplectic basis over A[2].
 - [Mum66] Fix one when considering symplectic basis over A[4].

Definition (Theta structure)

Let A be an Abelian variety of dimension g. A (level 2 symmetric) theta structure is a morphism into the Kummer variety \mathcal{K}_A :

$$\theta^A: A_{/\pm 1} \longrightarrow \mathcal{K}_A \subseteq \mathbb{P}^{2^g-1}$$

that is compatible with a symplectic basis on A[2]: For all $X \in A[2]$ with $\pi(X) = (x, \widehat{x})$:

$$\theta_i^A(P+X) = (-1)^{\widehat{x}\cdot i}\theta_{i+x}^A(P)$$

- $\theta^A(0)$ the theta null point characterises A up to isomorphism.
- Several valid solutions for one symplectic basis over A[2].
 - [Mum66] Fix one when considering symplectic basis over A[4].

Definition (Theta structure)

Let A be an Abelian variety of dimension g. A (level 2 symmetric) theta structure is a morphism into the $Kummer\ variety\ \mathcal{K}_A$:

$$\theta^A: A_{/\pm 1} \longrightarrow \mathcal{K}_A \subseteq \mathbb{P}^{2^g-1}$$

that is compatible with a symplectic basis on A[2]: For all $X \in A[2]$ with $\pi(X) = (x, \widehat{x})$:

$$\theta_i^A(P+X) = (-1)^{\widehat{x}\cdot i}\theta_{i+x}^A(P)$$

- $\theta^A(0)$ the theta null point characterises A up to isomorphism.
- Several valid solutions for one symplectic basis over A[2]
 - [Mum66] Fix one when considering symplectic basis over A[4].

Definition (Theta structure)

Let A be an Abelian variety of dimension g. A (level 2 symmetric) theta structure is a morphism into the Kummer variety \mathcal{K}_A :

$$\theta^A: A_{/\pm 1} \longrightarrow \mathcal{K}_A \subseteq \mathbb{P}^{2^g-1}$$

that is compatible with a symplectic basis on A[2]: For all $X \in A[2]$ with $\pi(X) = (x, \widehat{x})$:

$$\theta_i^A(P+X) = (-1)^{\widehat{X}\cdot i}\theta_{i+x}^A(P)$$

- $\theta^A(0)$ the theta null point characterises A up to isomorphism.
- Several valid solutions for one symplectic basis over A[2].
 - [Mum66] Fix one when considering symplectic basis over A[4].

Definition (Symmetric elements)

Given $T \in E[4]$, we define the symmetric element \mathfrak{g}_T as the symmetry such that $\mathfrak{g}_T \cdot {x_T \choose z_T} = {x_T \choose z_T}$.

$$\forall X \in E, \ X + [2]T = \mathfrak{g}_T \cdot X$$

Let $\langle S, T \rangle$ be a (symplectic) basis of E[4]. Let $\theta_i(P) = \theta_i \cdot \binom{x_P}{x_O}$:

$$heta_i$$
 such that $\left\{egin{array}{ll} heta_i\cdot \mathfrak{g}_{\mathcal{T}} &= (-1)^i heta_i \ heta_i\cdot \mathfrak{g}_{\mathcal{S}} &= heta_{i+1} \end{array}
ight. \implies \left\{egin{array}{ll} heta_0 &= [\mathfrak{g}_0+\mathfrak{g}_{\mathcal{T}}]_0, \ heta_1 &= heta_0\cdot \mathfrak{g}_{\mathcal{S}} \end{array}
ight.$

Definition (Symmetric elements)

Given $T \in E[4]$, we define the symmetric element \mathfrak{g}_T as the symmetry such that $\mathfrak{g}_T \cdot {x_T \choose z_T} = {x_T \choose z_T}$.

$$\forall X \in E, \ X + [2]T = \mathfrak{g}_T \cdot X$$

Let $\langle S, T \rangle$ be a (symplectic) basis of E[4]. Let $\theta_i(P) = \theta_i \cdot \binom{x_P}{z_O}$

$$heta_i$$
 such that $\left\{egin{array}{ll} heta_i\cdot \mathfrak{g}_{\mathcal{T}} &= (-1)^i heta_i \ heta_i\cdot \mathfrak{g}_{\mathcal{S}} &= heta_{i+1} \end{array}
ight. \implies \left\{egin{array}{ll} heta_0 &= [\mathfrak{g}_0+\mathfrak{g}_{\mathcal{T}}]_0, \ heta_1 &= heta_0\cdot \mathfrak{g}_{\mathcal{S}} \end{array}
ight.$

Definition (Symmetric elements)

Given $T \in E[4]$, we define the symmetric element \mathfrak{g}_T as the symmetry such that $\mathfrak{g}_T \cdot {x_T \choose z_T} = {x_T \choose z_T}$.

$$\forall X \in E, X + [2]T = \mathfrak{g}_T \cdot X$$

Let $\langle S, T \rangle$ be a (symplectic) basis of E[4]. Let $\theta_i(P) = \theta_i \cdot {x_P \choose z_O}$:

$$heta_i$$
 such that $\left\{egin{array}{ll} heta_i\cdot \mathfrak{g}_{\mathcal{T}} &= (-1)^i heta_i \ heta_i\cdot \mathfrak{g}_{\mathcal{S}} &= heta_{i+1} \end{array}
ight. \implies \left\{egin{array}{ll} heta_0 &= [\mathfrak{g}_0+\mathfrak{g}_{\mathcal{T}}]_{0,-} \ heta_1 &= heta_0\cdot \mathfrak{g}_{\mathcal{S}} \end{array}
ight.$

Definition (Symmetric elements)

Given $T \in E[4]$, we define the symmetric element \mathfrak{g}_T as the symmetry such that $\mathfrak{g}_T \cdot {x_T \choose z_T} = {x_T \choose z_T}$.

$$\forall X \in E, X + [2]T = \mathfrak{g}_T \cdot X$$

Let $\langle S, T \rangle$ be a (symplectic) basis of E[4]. Let $\theta_i(P) = \theta_i \cdot {\binom{x_P}{x_O}}$:

$$heta_i$$
 such that $\left\{ egin{array}{ll} heta_i \cdot \mathfrak{g}_{\mathcal{T}} &= (-1)^i heta_i \ heta_i \cdot \mathfrak{g}_{\mathcal{S}} &= heta_{i+1} \end{array}
ight. \implies \left\{ egin{array}{ll} heta_0 &= [\mathfrak{g}_0 + \mathfrak{g}_{\mathcal{T}}]_{0,-} \ heta_1 &= heta_0 \cdot \mathfrak{g}_{\mathcal{S}} \end{array}
ight.$

- You can generalise symmetric element to $\prod_{i=1}^g E_i$ using tensor product.
 - ullet Ex: For $\langle S_1, S_2
 angle \oplus \langle T_1, T_2
 angle = (E_1 imes E_2)[4]$

$$\theta_{i} \text{ such that } \begin{cases} \begin{array}{l} \theta_{i} \cdot \mathfrak{g}_{\mathcal{T}_{1}} &= (-1)^{01 \cdot i} \theta_{i} \\ \theta_{i} \cdot \mathfrak{g}_{\mathcal{T}_{2}} &= (-1)^{10 \cdot i} \theta_{i} \\ \theta_{i} \cdot \mathfrak{g}_{S_{1}} &= \theta_{i+01} \\ \theta_{i} \cdot \mathfrak{g}_{S_{2}} &= \theta_{i+10} \end{array} \Longrightarrow \begin{cases} \begin{array}{l} \theta_{00} &= [(\mathfrak{g}_{0} + \mathfrak{g}_{\mathcal{T}_{1}})(\mathfrak{g}_{0} + \mathfrak{g}_{\mathcal{T}_{2}})]_{0,-} \\ \theta_{01} &= \theta_{00} \cdot \mathfrak{g}_{S_{1}} \\ \theta_{10} &= \theta_{00} \cdot \mathfrak{g}_{S_{2}} \\ \theta_{11} &= \theta_{01} \cdot \mathfrak{g}_{S_{2}} \end{array} \end{cases}$$

with $\mathfrak{g}_P=\mathfrak{g}_{P_1}\otimes\mathfrak{g}_{P_2}$

- Symmetric elements have a structure inherited from Pauli's X, Y, Z matrices.
 - Anti-commutativity: $q_{x} \cdot q_{y} = -q_{y}q_{y}$
 - Quaternionic structure: $g_X \cdot g_Y = \pm i \cdot g_{X+Y}$

- You can generalise symmetric element to $\prod_{i=1}^g E_i$ using tensor product.
 - Ex: For $\langle S_1, S_2 \rangle \oplus \langle T_1, T_2 \rangle = (E_1 \times E_2)[4]$

$$\theta_{i} \text{ such that } \begin{cases} \begin{array}{ll} \theta_{i} \cdot \mathfrak{g}_{\mathcal{T}_{1}} &= (-1)^{01 \cdot i} \theta_{i} \\ \theta_{i} \cdot \mathfrak{g}_{\mathcal{T}_{2}} &= (-1)^{10 \cdot i} \theta_{i} \\ \theta_{i} \cdot \mathfrak{g}_{S_{1}} &= \theta_{i+01} \\ \theta_{i} \cdot \mathfrak{g}_{S_{2}} &= \theta_{i+10} \end{array} \implies \begin{cases} \begin{array}{ll} \theta_{00} &= [(\mathfrak{g}_{0} + \mathfrak{g}_{\mathcal{T}_{1}})(\mathfrak{g}_{0} + \mathfrak{g}_{\mathcal{T}_{2}})]_{0,-} \\ \theta_{01} &= \theta_{00} \cdot \mathfrak{g}_{S_{1}} \\ \theta_{10} &= \theta_{00} \cdot \mathfrak{g}_{S_{2}} \\ \theta_{11} &= \theta_{01} \cdot \mathfrak{g}_{S_{2}} \end{array} \end{cases}$$

with $\mathfrak{g}_P=\mathfrak{g}_{P_1}\otimes\mathfrak{g}_{P_2}$

- Symmetric elements have a structure inherited from Pauli's X, Y, Z matrices.
 - Anti-commutativity: $q_{x} \cdot q_{y} = -q_{y}q_{x}$
 - Quaternionic structure: $g_X \cdot g_Y = \pm i \cdot g_{X+Y}$

- You can generalise symmetric element to $\prod_{i=1}^g E_i$ using tensor product.
 - Ex: For $\langle S_1, S_2 \rangle \oplus \langle T_1, T_2 \rangle = (E_1 \times E_2)[4]$

$$\theta_{i} \text{ such that } \begin{cases} \theta_{i} \cdot \mathfrak{g}_{\mathcal{T}_{1}} &= (-1)^{01 \cdot i} \theta_{i} \\ \theta_{i} \cdot \mathfrak{g}_{\mathcal{T}_{2}} &= (-1)^{10 \cdot i} \theta_{i} \\ \theta_{i} \cdot \mathfrak{g}_{S_{1}} &= \theta_{i+01} \\ \theta_{i} \cdot \mathfrak{g}_{S_{2}} &= \theta_{i+10} \end{cases} \implies \begin{cases} \theta_{00} &= [(\mathfrak{g}_{0} + \mathfrak{g}_{\mathcal{T}_{1}})(\mathfrak{g}_{0} + \mathfrak{g}_{\mathcal{T}_{2}})]_{0,-} \\ \theta_{01} &= \theta_{00} \cdot \mathfrak{g}_{S_{1}} \\ \theta_{10} &= \theta_{00} \cdot \mathfrak{g}_{S_{2}} \\ \theta_{11} &= \theta_{01} \cdot \mathfrak{g}_{S_{2}} \end{cases}$$

with $\mathfrak{g}_P = \mathfrak{g}_{P_1} \otimes \mathfrak{g}_{P_2}$

- Symmetric elements have a structure inherited from Pauli's X, Y, Z matrices.
 - Anti-commutativity: $g_X \cdot g_Y = -g_Y g_X$
 - Quaternionic structure: $g_X \cdot g_Y = \pm \mathbf{i} \cdot g_{X+Y}$

- You can generalise symmetric element to $\prod_{i=1}^g E_i$ using tensor product.
 - Ex: For $\langle S_1, S_2 \rangle \oplus \langle T_1, T_2 \rangle = (E_1 \times E_2)[4]$

$$\theta_{i} \text{ such that } \begin{cases} \theta_{i} \cdot \mathfrak{g}_{\mathcal{T}_{1}} &= (-1)^{01 \cdot i} \theta_{i} \\ \theta_{i} \cdot \mathfrak{g}_{\mathcal{T}_{2}} &= (-1)^{10 \cdot i} \theta_{i} \\ \theta_{i} \cdot \mathfrak{g}_{S_{1}} &= \theta_{i+01} \\ \theta_{i} \cdot \mathfrak{g}_{S_{2}} &= \theta_{i+10} \end{cases} \implies \begin{cases} \theta_{00} &= [(\mathfrak{g}_{0} + \mathfrak{g}_{\mathcal{T}_{1}})(\mathfrak{g}_{0} + \mathfrak{g}_{\mathcal{T}_{2}})]_{0,-} \\ \theta_{01} &= \theta_{00} \cdot \mathfrak{g}_{S_{1}} \\ \theta_{10} &= \theta_{00} \cdot \mathfrak{g}_{S_{2}} \\ \theta_{11} &= \theta_{01} \cdot \mathfrak{g}_{S_{2}} \end{cases}$$

with $\mathfrak{g}_P = \mathfrak{g}_{P_1} \otimes \mathfrak{g}_{P_2}$

- Symmetric elements have a structure inherited from Pauli's X, Y, Z matrices.
 - Anti-commutativity: $g_X \cdot g_Y = -g_Y g_X$
 - Quaternionic structure: $\mathfrak{q}_X \cdot \mathfrak{q}_Y = \pm \mathbf{i} \cdot \mathfrak{q}_{X+Y}$

Structure of E[4]

$$(1:1) (1:-1)$$

$$(a+b:a-b) (0:1) = C (a+ib:a-ib)$$

$$(a^2+b^2:a^2-b^2) \to (1:0) \leftarrow (a^2-b^2:a^2+b^2)$$

$$(a-b:a+b) (a-ib:a+ib)$$

Figure: Structure of E[4] over the Kummer line.

$$\mathfrak{g}_{(1:\pm 1)} = \pm X$$

$$\mathfrak{g}_{(a\pm b:a\mp b)} = \pm \frac{1}{2ab} ((a^2 + b^2)Z - \mathbf{i}(a^2 - b^2)Y)$$

$$\mathfrak{g}_{(a\pm ib:a\mp ib)} = \mp \frac{1}{2ab} (\mathbf{i}(a^2 - b^2)Z + (a^2 + b^2)Y)$$

Structure of E[4]

$$(1:1) (1:-1)$$

$$(a+b:a-b) (0:1) = C (a+ib:a-ib)$$

$$(a^2+b^2:a^2-b^2) \to (1:0) \leftarrow (a^2-b^2:a^2+b^2)$$

$$(a-b:a+b) (a-ib:a+ib)$$

Figure: Structure of E[4] over the Kummer line.

$$\begin{split} \mathfrak{g}_{(1:\pm 1)} &= \pm X \\ \mathfrak{g}_{(a\pm b:a\mp b)} &= \pm \frac{1}{2ab} \big((a^2+b^2)Z - \mathbf{i}(a^2-b^2)Y \big) \\ \mathfrak{g}_{(a\pm ib:a\mp ib)} &= \mp \frac{1}{2ab} \big(\mathbf{i}(a^2-b^2)Z + (a^2+b^2)Y \big) \end{split}$$

Lookup table for theta structure on EC

$$\mathcal{B}_{1} = \langle (a+b:a-b), (1:1) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{1}} = \begin{pmatrix} b & b \\ a & -a \end{pmatrix}$$

$$\mathcal{B}_{2} = \langle (a+b:a-b), (1:-1) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{2}} = \begin{pmatrix} a & -a \\ b & b \end{pmatrix} = \text{the theta model}$$

$$\mathcal{B}_{3} = \langle (1:1), (a+b:a-b) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{3}} = \begin{pmatrix} a+b & b-a \\ b-a & a+b \end{pmatrix}$$

$$\mathcal{B}_{4} = \langle (1:-1), (a+b:a-b) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{4}} = \begin{pmatrix} a+b & b-a \\ a-b & -a-b \end{pmatrix}$$

$$\mathcal{B}_{5} = \langle (a+b:a-b), (a+\mathbf{i}b:a-\mathbf{i}b) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{5}} = \begin{pmatrix} a+b & -(a-b) \\ -\mathbf{i}(a-b) & \mathbf{i}(a+b) \end{pmatrix}$$

$$\mathcal{B}_{6} = \langle (a+b:a-b), (a-\mathbf{i}b:a+\mathbf{i}b) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{6}} = \begin{pmatrix} a+b & -(a-b) \\ -\mathbf{i}(a-b) & -\mathbf{i}(a+b) \end{pmatrix}$$

Table: List of the change of basis matrix of the different theta structures depending on the basis of E[4].

$$\mathcal{B}_3 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \mathcal{B}_1 \iff \theta^{\mathcal{B}_3} = \mathcal{H}(\theta^{\mathcal{B}_1}) = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \cdot \theta^{\mathcal{B}_1}$$

 DUPARC (EPFL)
 Superglue
 May 15, 2025
 11/22

Lookup table for theta structure on EC

$$\mathcal{B}_{1} = \langle (a+b:a-b), (1:1) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{1}} = \begin{pmatrix} b & b \\ a & -a \end{pmatrix}$$

$$\mathcal{B}_{2} = \langle (a+b:a-b), (1:-1) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{2}} = \begin{pmatrix} a & -a \\ b & b \end{pmatrix} = \text{the theta model}$$

$$\mathcal{B}_{3} = \langle (1:1), (a+b:a-b) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{3}} = \begin{pmatrix} a+b & b-a \\ b-a & a+b \end{pmatrix}$$

$$\mathcal{B}_{4} = \langle (1:-1), (a+b:a-b) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{4}} = \begin{pmatrix} a+b & b-a \\ a-b & -a-b \end{pmatrix}$$

$$\mathcal{B}_{5} = \langle (a+b:a-b), (a+\mathbf{i}b:a-\mathbf{i}b) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{5}} = \begin{pmatrix} a+b & -(a-b) \\ -\mathbf{i}(a-b) & \mathbf{i}(a+b) \end{pmatrix}$$

$$\mathcal{B}_{6} = \langle (a+b:a-b), (a-\mathbf{i}b:a+\mathbf{i}b) \rangle \qquad \Longrightarrow \qquad \theta^{\mathcal{B}_{6}} = \begin{pmatrix} a+b & -(a-b) \\ -\mathbf{i}(a-b) & -\mathbf{i}(a+b) \end{pmatrix}$$

Table: List of the change of basis matrix of the different theta structures depending on the basis of E[4].

$$\mathcal{B}_3 = egin{pmatrix} 0 & 1 \ 1 & 0 \end{pmatrix} \cdot \mathcal{B}_1 \iff heta^{\mathcal{B}_3} = \mathcal{H}(heta^{\mathcal{B}_1}) = egin{pmatrix} 1 & 1 \ 1 & -1 \end{pmatrix} \cdot heta^{\mathcal{B}_1}$$

DUPARC (EPFL) Superglue May 15, 2025 11/22

Table of Contents

- Constructing theta structures
- Exploring theta structures

Exploiting theta structures: Superglue

Theta structure²

• Theta structure have a lot of self-similarities:

$$P \in A[2] \implies \theta_i^A(P) = (-1)^{\widehat{\mathbf{x}} \cdot i} \theta_{i+x}^A(0) \text{ with } \pi(P) = (\mathbf{x}, \widehat{\mathbf{x}})$$

$$P \in A[4] \implies \theta^A(P)$$
 is fixed by the action of [2]

		T_1	T_2	$T_1 + T_2$
		(x:0:y:0)	(x:y:0:0)	(x:0:0:y)
S_1	(x:x:y:y)	(x:ix:y:iy)	(x:x:y:-y)	(x:ix:y:-iy)
S_2	(x:y:x:y)	(x:y:x:-y)	(x:y:ix:-iy)	(x:y:-ix:iy)
$S_1 + S_2$	(x:y:y:x)	(x:y:-iy:ix)	(x:y:iy:ix)	(x:y:-y:x)

Table: Structure of $\theta^A(P)$ depending on the position of $[2]P \in A[2]$

Theta structure²

• Theta structure have a lot of .self-similarities:

$$P \in A[2] \implies \theta_i^A(P) = (-1)^{\widehat{x} \cdot i} \theta_{i+x}^A(0) \text{ with } \pi(P) = (x, \widehat{x})$$

$$P \in A[4] \implies \theta^A(P)$$
 is fixed by the action of [2] F

		T_1	T_2	$T_1 + T_2$
		(x:0:y:0)	(x:y:0:0)	(x:0:0:y)
S_1	(x:x:y:y)	(x:ix:y:iy)	(x:x:y:-y)	(x:ix:y:-iy)
S_2	(x:y:x:y)	(x:y:x:-y)	(x:y:ix:-iy)	(x:y:-ix:iy)
$S_1 + S_2$	(x:y:y:x)	(x:y:-iy:ix)	(x:y:iy:ix)	(x:y:-y:x)

Table: Structure of $\theta^A(P)$ depending on the position of $[2]P \in A[2]$

Theta structure²

• Theta structure have a lot of .self-similarities:

$$P \in A[2] \implies \theta_i^A(P) = (-1)^{\widehat{x} \cdot i} \theta_{i+x}^A(0) \text{ with } \pi(P) = (x, \widehat{x})$$

$$P \in A[4] \implies \theta^A(P)$$
 is fixed by the action of $[2]P$

Table: Structure of $\theta^A(P)$ depending on the position of $[2]P \in A[2]$

Riemann positions

Theorem: Riemann positions

Let $P_1, \dots, P_4 \in \mathbb{F}_q$ such that $\sum P_i = [2]P$ and $P'_i = P - P_i$. Then,

$$\mathcal{H}\Big(\theta^{A}(P_1)\odot\theta^{A}(P_2)\Big)\odot\mathcal{H}\Big(\theta^{A}(P_3)\odot\theta^{A}(P_4)\Big)=\mathcal{H}\Big(\theta^{A}(P_1')\odot\theta^{A}(P_2')\Big)\odot\mathcal{H}\Big(\theta^{A}(P_3')\odot\theta^{A}(P_4')\Big)$$

• It is a differential addition mechanism:

$$\mathcal{H}\left(heta^A(P+Q)\odot heta^A(P-Q)
ight)\odot\mathcal{H}\left(heta^A(0)^{\odot 2}
ight)=\mathcal{H}\left(heta^A(P)^{\odot 2}
ight)\odot\mathcal{H}\left(heta^A(Q)^{\odot 2}
ight)$$

• It is a triple addition mechanism:

$$\mathcal{H}\left(\theta^{A}(P+Q+R)\odot\theta^{A}(P)\right)\odot\mathcal{H}\left(\theta^{A}(Q)\odot\theta^{A}(R)\right)=\mathcal{H}\left(\theta^{A}(0)\odot\theta^{A}(Q+R)\right)\odot\mathcal{H}\left(\theta^{A}(P+R)\odot\theta^{A}(P+Q)\right)$$

Riemann positions

Theorem: Riemann positions

Let $P_1, \dots, P_4 \in \mathbb{F}_q$ such that $\sum P_i = [2]P$ and $P'_i = P - P_i$. Then,

$$\mathcal{H}\Big(\theta^{A}(P_1)\odot\theta^{A}(P_2)\Big)\odot\mathcal{H}\Big(\theta^{A}(P_3)\odot\theta^{A}(P_4)\Big)=\mathcal{H}\Big(\theta^{A}(P_1')\odot\theta^{A}(P_2')\Big)\odot\mathcal{H}\Big(\theta^{A}(P_3')\odot\theta^{A}(P_4')\Big)$$

• It is a differential addition mechanism:

$$\mathcal{H}\left(\theta^A(P+Q)\odot\theta^A(P-Q)\right)\odot\mathcal{H}\left(\theta^A(0)^{\odot 2}\right)=\mathcal{H}\left(\theta^A(P)^{\odot 2}\right)\odot\mathcal{H}\left(\theta^A(Q)^{\odot 2}\right)$$

• It is a triple addition mechanism:

 $\mathcal{H}\left(\theta^{A}(P+Q+R)\odot\theta^{A}(P)\right)\odot\mathcal{H}\left(\theta^{A}(Q)\odot\theta^{A}(R)\right)=\mathcal{H}\left(\theta^{A}(0)\odot\theta^{A}(Q+R)\right)\odot\mathcal{H}\left(\theta^{A}(P+R)\odot\theta^{A}(P+Q)\right)$

Riemann positions

Theorem: Riemann positions

Let $P_1, \dots, P_4 \in \mathbb{F}_q$ such that $\sum P_i = [2]P$ and $P'_i = P - P_i$. Then,

$$\mathcal{H}\Big(\theta^{A}(P_1)\odot\theta^{A}(P_2)\Big)\odot\mathcal{H}\Big(\theta^{A}(P_3)\odot\theta^{A}(P_4)\Big)=\mathcal{H}\Big(\theta^{A}(P_1')\odot\theta^{A}(P_2')\Big)\odot\mathcal{H}\Big(\theta^{A}(P_3')\odot\theta^{A}(P_4')\Big)$$

• It is a differential addition mechanism:

$$\mathcal{H}\left(\theta^A(P+Q)\odot\theta^A(P-Q)\right)\odot\mathcal{H}\left(\theta^A(0)^{\odot 2}\right)=\mathcal{H}\left(\theta^A(P)^{\odot 2}\right)\odot\mathcal{H}\left(\theta^A(Q)^{\odot 2}\right)$$

• It is a triple addition mechanism:

$$\mathcal{H}\left(\theta^{A}(P+Q+R)\odot\theta^{A}(P)\right)\odot\mathcal{H}\left(\theta^{A}(Q)\odot\theta^{A}(R)\right)=\mathcal{H}\left(\theta^{A}(0)\odot\theta^{A}(Q+R)\right)\odot\mathcal{H}\left(\theta^{A}(P+R)\odot\theta^{A}(P+Q)\right)$$

Riemann positions

Theorem: Riemann positions

Let $P_1, \dots, P_4 \in \mathbb{F}_q$ such that $\sum P_i = [2]P$ and $P'_i = P - P_i$. Then,

$$\mathcal{H}\Big(\theta^{A}(P_1)\odot\theta^{A}(P_2)\Big)\odot\mathcal{H}\Big(\theta^{A}(P_3)\odot\theta^{A}(P_4)\Big)=\mathcal{H}\Big(\theta^{A}(P_1')\odot\theta^{A}(P_2')\Big)\odot\mathcal{H}\Big(\theta^{A}(P_3')\odot\theta^{A}(P_4')\Big)$$

• It is a differential addition mechanism:

$$\mathcal{H}\left(\theta^A(P+Q)\odot\theta^A(P-Q)\right)\odot\mathcal{H}\left(\theta^A(0)^{\odot 2}\right)=\mathcal{H}\left(\theta^A(P)^{\odot 2}\right)\odot\mathcal{H}\left(\theta^A(Q)^{\odot 2}\right)$$

• It is a triple addition mechanism:

$$\mathcal{H}\left(\theta^{A}(P+Q+R)\odot\theta^{A}(P)\right)\odot\mathcal{H}\left(\theta^{A}(Q)\odot\theta^{A}(R)\right)=\mathcal{H}\left(\theta^{A}(0)\odot\theta^{A}(Q+R)\right)\odot\mathcal{H}\left(\theta^{A}(P+R)\odot\theta^{A}(P+Q)\right)$$

Theorem: Duplication Formula

g times

Let $K = \langle T_1, \cdots, T_g \rangle \subset A[2]$ and $\Phi : A \to B$ the $(2, \cdots, 2)$ isogeny with $\ker(\Phi) = K$. We then have the *Duplication Formula*:

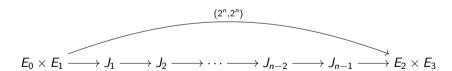
$$\mathcal{H}\Big(\theta^A\big(P+Q\big)\odot\theta^A\big(P-Q\big)\Big)=\widetilde{\theta}^B\big(\Phi(P)\big)\odot\widetilde{\theta}^B\big(\Phi(Q)\big)$$



Theorem: Duplication Formula

Let $K = \langle T_1, \cdots, T_g \rangle \subset A[2]$ and $\Phi : A \to B$ the $(2, \cdots, 2)$ isogeny with $\ker(\Phi) = K$. We then have the *Duplication Formula*:

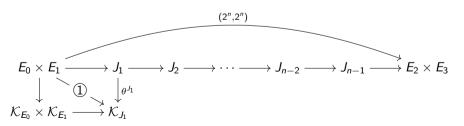
$$\mathcal{H}\Big(\theta^A\big(P+Q\big)\odot\theta^A\big(P-Q\big)\Big)=\widetilde{\theta}^B\big(\Phi(P)\big)\odot\widetilde{\theta}^B\big(\Phi(Q)\big)$$



Theorem: Duplication Formula

Let $K = \langle T_1, \cdots, T_g \rangle \subset A[2]$ and $\Phi : A \to B$ the $(2, \cdots, 2)$ isogeny with $\ker(\Phi) = K$. We then have the *Duplication Formula*:

$$\mathcal{H}\Big(\theta^A\big(P+Q\big)\odot\theta^A\big(P-Q\big)\Big)=\widetilde{\theta}^B\big(\Phi(P)\big)\odot\widetilde{\theta}^B\big(\Phi(Q)\big)$$

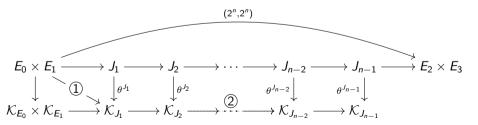


Theorem: Duplication Formula

g times

Let $K = \langle T_1, \cdots, T_g \rangle \subset A[2]$ and $\Phi : A \to B$ the $(2, \cdots, 2)$ isogeny with $\ker(\Phi) = K$. We then have the *Duplication Formula*:

$$\mathcal{H}\Big(\theta^A\big(P+Q\big)\odot\theta^A\big(P-Q\big)\Big)=\widetilde{\theta}^B\big(\Phi(P)\big)\odot\widetilde{\theta}^B\big(\Phi(Q)\big)$$



Theorem: Duplication Formula

g times

Let $K = \langle T_1, \cdots, T_g \rangle \subset A[2]$ and $\Phi : A \to B$ the $(2, \cdots, 2)$ isogeny with $\ker(\Phi) = K$. We then have the *Duplication Formula*:

$$\mathcal{H}\Big(\theta^A\big(P+Q\big)\odot\theta^A\big(P-Q\big)\Big)=\widetilde{\theta}^B\big(\Phi(P)\big)\odot\widetilde{\theta}^B\big(\Phi(Q)\big)$$

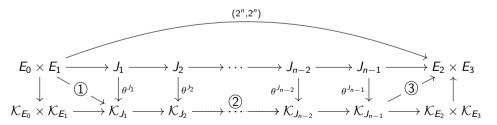


Table of Contents

Constructing theta structures

Exploring theta structures

3 Exploiting theta structures: Superglue

$$\Phi: \textit{E}_{1} \times \textit{E}_{2} \rightarrow \textit{J}_{1}$$

$$\mathcal{H}\Big(\theta^{\mathsf{E}_1\times\mathsf{E}_2}(P+Q)\odot\theta^{\mathsf{E}_1\times\mathsf{E}_2}(P-Q)\Big)=\widetilde{\theta}^{J_1}\big(\Phi(P)\big)\odot\widetilde{\theta}^{J_1}\big(\Phi(Q)$$

$$\Phi: E_1 \times E_2 \rightarrow J_1$$

$$\mathcal{H}\Big(heta^{ extsf{E}_1 imes extsf{E}_2}(P+Q)\odot heta^{ extsf{E}_1 imes extsf{E}_2}(P-Q)\Big)=\widetilde{ heta}^{J_1}ig(\Phi(P)ig)\odot\widetilde{ heta}^{J_1}ig(\Phi(Q)ig)$$

$$\Phi: E_1 \times E_2 \rightarrow J_1$$

$$\mathcal{H}\Big(\theta^{\mathsf{E}_1 \times \mathsf{E}_2}(P+Q) \odot \theta^{\mathsf{E}_1 \times \mathsf{E}_2}(P-Q)\Big) = \widetilde{\theta}^{J_1}\big(\Phi(P)\big) \odot \widetilde{\theta}^{J_1}\big(\Phi(Q)\big)$$

$$\theta^{E_1 \times E_2}(X) = \mathbf{M}(X_1 \otimes X_2) = \begin{pmatrix} \mathbf{M}_{0,0} & \mathbf{M}_{0,1} & \mathbf{M}_{0,2} & \mathbf{M}_{0,3} \\ \mathbf{M}_{1,0} & \mathbf{M}_{1,1} & \mathbf{M}_{1,2} & \mathbf{M}_{1,3} \\ \mathbf{M}_{2,0} & \mathbf{M}_{2,1} & \mathbf{M}_{2,2} & \mathbf{M}_{2,3} \\ \mathbf{M}_{3,0} & \mathbf{M}_{3,1} & \mathbf{M}_{3,2} & \mathbf{M}_{3,3} \end{pmatrix} \begin{pmatrix} x_1 x_2 \\ x_1 z_2 \\ z_1 x_2 \\ z_1 z_2 \end{pmatrix}$$

• How many components of M do we need to compute Φ ?

$$\Phi: E_1 \times E_2 \rightarrow J_1$$

$$\mathcal{H}\Big(heta^{ extsf{E}_1 imes extsf{E}_2}(P+Q)\odot heta^{ extsf{E}_1 imes extsf{E}_2}(P-Q)\Big)=\widetilde{ heta}^{J_1}ig(\Phi(P)ig)\odot\widetilde{ heta}^{J_1}ig(\Phi(Q)ig)$$

$$\theta^{E_1 \times E_2}(X) = \mathbf{M}(X_1 \otimes X_2) = \begin{pmatrix} \mathbf{M}_{0,0} & \mathbf{M}_{0,1} & \mathbf{M}_{0,2} & \mathbf{M}_{0,3} \\ \mathbf{M}_{1,0} & \mathbf{M}_{1,1} & \mathbf{M}_{1,2} & \mathbf{M}_{1,3} \\ \mathbf{M}_{2,0} & \mathbf{M}_{2,1} & \mathbf{M}_{2,2} & \mathbf{M}_{2,3} \\ \mathbf{M}_{3,0} & \mathbf{M}_{3,1} & \mathbf{M}_{3,2} & \mathbf{M}_{3,3} \end{pmatrix}$$

- Answer: 6.33 !
- Done by using the self-similarities of theta structure.

$$\Phi: E_1 \times E_2 \rightarrow J_1$$

$$\mathcal{H}\Big(\theta^{E_1\times E_2}(P+Q)\odot\theta^{E_1\times E_2}(P-Q)\Big)=\widetilde{\theta}^{J_1}\big(\Phi(P)\big)\odot\widetilde{\theta}^{J_1}\big(\Phi(Q)\big)$$

$$\theta^{{\mathcal E}_1\times{\mathcal E}_2}(P+Q)\odot\theta^{{\mathcal E}_1\times{\mathcal E}_2}(P-Q)=\left({\mathbf M}\cdot(P^1_\oplus\otimes P^2_\oplus)\right)\odot\left({\mathbf M}\cdot(P^1_\ominus\otimes P^2_\ominus)\right)$$

$$egin{aligned} \Phi: E_1 imes E_2 &
ightarrow J_1 \ &\mathcal{H}\Big(heta^{E_1 imes E_2}(P+Q) \odot heta^{E_1 imes E_2}(P-Q)\Big) = \widetilde{ heta}^{J_1}ig(\Phi(P)ig) \odot \widetilde{ heta}^{J_1}ig(\Phi(Q)ig) \ & heta^{E_1 imes E_2}(P+Q) \odot heta^{E_1 imes E_2}(P-Q) = ig(\mathbf{M} ec{u}ig)^{\odot 2} - ig(\mathbf{M} ec{v}\Big)^{\odot 2} \ & ext{} ec{u} = egin{pmatrix} u_1 u_2 + v_1 v_2 \\ u_1 w_2 \\ w_1 u_2 \\ w_1 w_2 \\ w_1 w_2 \\ 0 \end{pmatrix} \quad ec{v} = egin{pmatrix} v_1 u_2 + u_1 v_2 \\ v_1 w_2 \\ w_1 v_2 \\ 0 \\ 0 \end{pmatrix} \end{aligned}$$

Using $(u_i \mp v_i : w_i) = P_i \pm Q_i$.

$$\begin{split} \mathcal{H}\Big(\theta^{E_1\times E_2}(P+Q)\odot\theta^{E_1\times E_2}(P-Q)\Big) &= \widetilde{\theta}^{J_1}\big(\Phi(P)\big)\odot\widetilde{\theta}^{J_1}\big(\Phi(Q)\big) \\ \theta^{E_1\times E_2}(P+Q)\odot\theta^{E_1\times E_2}(P-Q) &= [\mathbf{M}_0\mathbf{M}_0](u_1^2-v_1^2)(u_2^2-v_2^2) + [\mathbf{M}_1\mathbf{M}_1]w_2^2(u_1^2-v_1^2) \\ &+ [\mathbf{M}_2\mathbf{M}_2]w_1^2(u_2^2-v_2^2) + [\mathbf{M}_3\mathbf{M}_3]w_1^2w_2^2 \\ &+ 2[\mathbf{M}_0\mathbf{M}_1]u_2w_2(u_1^2-v_1^2) + 2[\mathbf{M}_2\mathbf{M}_3]u_2w_2w_1^2 \end{split}$$

 $\Phi: E_1 \times E_2 \to J_1$

Using $(u_i \mp v_i : w_i) = P_i \pm Q_i$.

 $+2[\mathbf{M}_{0}\mathbf{M}_{3}+\mathbf{M}_{1}\mathbf{M}_{2}]u_{1}u_{2}w_{1}w_{2}$ $+2[\mathbf{M}_{0}\mathbf{M}_{3}-\mathbf{M}_{1}\mathbf{M}_{2}]v_{1}v_{2}w_{1}w_{2}$

 $+2[\mathbf{M}_0\mathbf{M}_2]u_1w_1(u_2^2-v_2^2)+2[\mathbf{M}_1\mathbf{M}_3]u_1w_1w_2^2$

$$\begin{split} \Phi : E_1 \times E_2 &\to J_1 \\ \mathcal{H} \Big(\theta^{E_1 \times E_2} (P + Q) \odot \theta^{E_1 \times E_2} (P - Q) \Big) = \widetilde{\theta}^{J_1} \big(\Phi(P) \big) \odot \widetilde{\theta}^{J_1} \big(\Phi(Q) \big) \\ \mathcal{H} \left(\theta^{E_1 \times E_2} (P + Q) \odot \theta^{E_1 \times E_2} (P - Q) \right) &= [\widetilde{\mathbf{M}_0} \widetilde{\mathbf{M}_0}] (u_1^2 - v_1^2) (u_2^2 - v_2^2) + [\widetilde{\mathbf{M}_1} \widetilde{\mathbf{M}_1}] w_2^2 (u_1^2 - v_1^2) \\ &+ [\widetilde{\mathbf{M}_2} \mathbf{M}_2] w_1^2 (u_2^2 - v_2^2) + [\widetilde{\mathbf{M}_3} \widetilde{\mathbf{M}_3}] w_1^2 w_2^2 \\ &+ 2 [\widetilde{\mathbf{M}_0} \widetilde{\mathbf{M}_1}] u_2 w_2 (u_1^2 - v_1^2) + 2 [\widetilde{\mathbf{M}_2} \widetilde{\mathbf{M}_3}] u_2 w_2 w_1^2 \\ &+ 2 [\widetilde{\mathbf{M}_0} \widetilde{\mathbf{M}_2}] u_1 w_1 (u_2^2 - v_2^2) + 2 [\widetilde{\mathbf{M}_1} \widetilde{\mathbf{M}_3}] u_1 w_1 w_2^2 \\ &+ 2 [\widetilde{\mathbf{M}_0} \widetilde{\mathbf{M}_3} + \widetilde{\mathbf{M}_1} \widetilde{\mathbf{M}_2}] u_1 u_2 w_1 w_2 \\ &+ 2 [\widetilde{\mathbf{M}_0} \widetilde{\mathbf{M}_3} - \widetilde{\mathbf{M}_1} \widetilde{\mathbf{M}_2}] v_1 v_2 w_1 w_2 \end{split}$$

Using $(u_i \mp v_i : w_i) = P_i \pm Q_i$.

- $\mathbf{M}_i = \theta^{E_1 \times E_2} (C^{\delta_{10 \cdot i}} \otimes C^{\delta_{01 \cdot i}})$ with C = (0:1).
- $\mathbf{M}_i \mathbf{M}_j$ are couples of points in $J_1[4]$.
- Using the self-similarities of theta structures
 - Of the 10 couples of points, we only need 4
 - Of those 4, at least 2 are sparse
 - The rest is retrieved from the position of $C \in \ker(\Phi)$
- 9 cases yielding 9 distinct set of equations.

- $\mathbf{M}_i = \theta^{E_1 \times E_2} (C^{\delta_{10 \cdot i}} \otimes C^{\delta_{01 \cdot i}})$ with C = (0:1).
- M_iM_j are couples of points in $J_1[4]$.
- Using the self-similarities of theta structures:
 - Of the 10 couples of points, we only need 4.
 - Of those 4, at least 2 are sparse.
 - The rest is retrieved from the position of $C \in \ker(\Phi)$.
- 9 cases yielding 9 distinct set of equations.

- $\mathbf{M}_i = \theta^{E_1 \times E_2} (C^{\delta_{10 \cdot i}} \otimes C^{\delta_{01 \cdot i}})$ with C = (0:1).
- M_iM_j are couples of points in $J_1[4]$.
- Using the self-similarities of theta structures:
 - Of the 10 couples of points, we only need 4.
 - Of those 4, at least 2 are sparse.
 - The rest is retrieved from the position of $C \in \ker(\Phi)$.
- 9 cases yielding 9 distinct set of equations.

- $\mathbf{M}_i = \theta^{E_1 \times E_2} (C^{\delta_{10 \cdot i}} \otimes C^{\delta_{01 \cdot i}})$ with C = (0:1).
- $\mathbf{M}_i \mathbf{M}_j$ are couples of points in $J_1[4]$.
- Using the self-similarities of theta structures:
 - Of the 10 couples of points, we only need 4.
 - Of those 4, at least 2 are sparse.
 - The rest is retrieved from the position of $C \in \ker(\Phi)$.
- 9 cases yielding 9 distinct set of equations.

Superglue formulae (Type I)

Theorem: Superglue in position 01

Let $\theta^{E_1 \times E_2}$ be a theta structure induced by the symplectic basis of $\langle (0, C), (C, 0) \rangle \oplus \langle (C, \alpha), (\beta, C) \rangle$ with **M** its change of basis matrix. For any $P, Q \in E_1 \times E_2$ we have that

$$\mathcal{H}(\theta^{E_1 imes E_2}(P+Q) \odot \theta^{E_1 imes E_2}(P-Q)) =$$

$$\begin{split} &[\widetilde{\mathsf{M}_0}\widetilde{\mathsf{M}_0}](u_1^2-v_1^2)(u_2^2-v_2^2) + [\widetilde{\mathsf{M}_1}\widetilde{\mathsf{M}_1}]w_2^2(u_1^2-v_1^2) + [\widetilde{\mathsf{M}_2}\widetilde{\mathsf{M}_2}]w_1^2(u_2^2-v_2^2) + [\widetilde{\mathsf{M}_3}\widetilde{\mathsf{M}_3}]w_1^2w_2^2 \\ &+ 2[\widetilde{\mathsf{M}_0}\widetilde{\mathsf{M}_1}]u_2w_2(u_1^2-v_1^2) + 2[\widetilde{\mathsf{M}_2}\widetilde{\mathsf{M}_3}]u_2w_2w_1^2 \\ &+ 2[\widetilde{\mathsf{M}_0}\widetilde{\mathsf{M}_2}]u_1w_1(u_2^2-v_2^2) + 2[\widetilde{\mathsf{M}_1}\widetilde{\mathsf{M}_3}]u_1w_1w_2^2 \\ &+ 2[\widetilde{\mathsf{M}_0}\widetilde{\mathsf{M}_3} + \widetilde{\mathsf{M}_1}\widetilde{\mathsf{M}_2}]u_1u_2w_1w_2 + 2[\widetilde{\mathsf{M}_0}\widetilde{\mathsf{M}_3} - \widetilde{\mathsf{M}_1}\widetilde{\mathsf{M}_2}]v_1v_2w_1w_2 \end{split}$$

Superglue formulae (Type I)

Theorem: Superglue in position 01

Let $\theta^{E_1 \times E_2}$ be a theta structure induced by the symplectic basis of $\langle (0, C), (C, 0) \rangle \oplus \langle (C, \alpha), (\beta, C) \rangle$ with **M** its change of basis matrix. For any $P, Q \in E_1 \times E_2$ we have that

$$\mathcal{H}(\theta^{E_1 imes E_2}(P+Q) \odot \theta^{E_1 imes E_2}(P-Q)) =$$

$$\begin{pmatrix} \mathbf{M}_{1,0}^2 + \mathbf{M}_{2,0}^2 \\ \mathbf{M}_{0,0}^2 - \mathbf{M}_{1,0}^2 \\ \mathbf{M}_{0,0}^2 - \mathbf{M}_{2,0}^2 \end{pmatrix} \odot \begin{pmatrix} (u_1^2 - v_1^2 + w_1^2)(u_2^2 - v_2^2 + w_2^2) \\ (u_1^2 - v_1^2 + w_1^2)(u_2^2 - v_2^2 - w_2^2) \\ (u_1^2 - v_1^2 - w_1^2)(u_2^2 - v_2^2 + w_2^2) \end{pmatrix} + 2u_2w_2 \begin{pmatrix} \mathbf{M}_{0,0}\mathbf{M}_{0,1} + \mathbf{M}_{0,2}\mathbf{M}_{0,3} \\ \mathbf{M}_{0,0}\mathbf{M}_{0,1} - \mathbf{M}_{0,2}\mathbf{M}_{0,3} \end{pmatrix} \odot \begin{pmatrix} u_1^2 - v_1^2 + w_1^2 \\ 0 \\ u_1^2 - v_1^2 - w_1^2 \end{pmatrix} + 2u_1w_1 \begin{pmatrix} \mathbf{M}_{0,0}\mathbf{M}_{0,2} + \mathbf{M}_{0,1}\mathbf{M}_{0,3} \\ \mathbf{M}_{0,0}\mathbf{M}_{0,2} - \mathbf{M}_{0,1}\mathbf{M}_{0,3} \\ 0 \\ 0 \end{pmatrix} \odot \begin{pmatrix} u_2^2 - v_2^2 + w_2^2 \\ u_2^2 - v_2^2 - w_2^2 \\ 0 \\ 0 \\ 0 \end{pmatrix} + 4w_1w_2 \begin{pmatrix} \mathbf{M}_{0,0}\mathbf{M}_{0,3} + \mathbf{M}_{0,1}\mathbf{M}_{0,3} \\ 0 \\ 0 \\ \mathbf{M}_{0,0}\mathbf{M}_{0,3} - \mathbf{M}_{0,1}\mathbf{M}_{0,3} \end{pmatrix} \odot \begin{pmatrix} u_1^2 - v_1^2 + w_1^2 \\ 0 \\ 0 \\ v_1v_2 \end{pmatrix}$$

Algorithms	Classic gluing	Superglue	
ThetaChangeOfBasis	113 M $+ 8$ S $+ 1$ I $+ 49$ a	37M + 7S + 34a	
GluingCodomain	$167 \mathbf{M} + 16 \mathbf{S} + 1 \mathbf{I} + 105 \mathbf{a}$	98 M $+ 19$ S $+ 94$ a	
GluingEval	$40\mathbf{M} + 8\mathbf{S} + 44\mathbf{a}$	27M + 2S + 24a	
GluingEvalSpecial	23M + 4S + 28a	20M + 4S + 20a	

- Also works on quadratic twist
- Should generalises to dimension g (only 3g distinct cases to handle¹)
- ▶ Open question: Is it interesting for generic (2,2) isogenies ?

Algorithms	Classic gluing	Superglue	
ThetaChangeOfBasis	113 M $+ 8$ S $+ 1$ I $+ 49$ a	37M + 7S + 34a	
GluingCodomain	$167 \mathbf{M} + 16 \mathbf{S} + 1 \mathbf{I} + 105 \mathbf{a}$	98 M $+ 19$ S $+ 94$ a	
GluingEval	$40\mathbf{M} + 8\mathbf{S} + 44\mathbf{a}$	27M + 2S + 24a	
GluingEvalSpecial	23M + 4S + 28a	20M + 4S + 20a	

- Also works on quadratic twist.
- Should generalises to dimension g (only 3^g distinct cases to handle¹).
- ▶ Open question: Is it interesting for generic (2,2) isogenies ?

 $^{^{1}+}$ endless fun in debugging

Algorithms	Classic gluing	Superglue	
ThetaChangeOfBasis	113 M $+ 8$ S $+ 1$ I $+ 49$ a	37M + 7S + 34a	
GluingCodomain	167 M $+ 16$ S $+ 1$ I $+ 105$ a	98 M $+ 19$ S $+ 94$ a	
GluingEval	40 M $+$ 8 S $+$ 44 a	27M + 2S + 24a	
GluingEvalSpecial	23M + 4S + 28a	20M + 4S + 20a	

- Also works on quadratic twist.
- Should generalises to dimension g (only 3^g distinct cases to handle¹).
- ▶ Open question: Is it interesting for generic (2,2) isogenies?

¹+ endless fun in debugging.

Algorithms	Classic gluing	Superglue	
ThetaChangeOfBasis	113 M $+ 8$ S $+ 1$ I $+ 49$ a	37M + 7S + 34a	
GluingCodomain	167 M $+ 16$ S $+ 1$ I $+ 105$ a	98 M $+ 19$ S $+ 94$ a	
GluingEval	40 M $+$ 8 S $+$ 44 a	27M + 2S + 24a	
GluingEvalSpecial	23M + 4S + 28a	20M + 4S + 20a	

- Also works on quadratic twist.
- Should generalises to dimension g (only 3^g distinct cases to handle¹).
- ▶ Open question: Is it interesting for generic (2,2) isogenies ?

¹+ endless fun in debugging.

The end

$$\begin{pmatrix} \mathbf{M}_{1,0}^2 + \mathbf{M}_{2,0}^2 \\ \mathbf{M}_{0,0}^2 - \mathbf{M}_{1,0}^2 \\ \mathbf{M}_{0,0}^2 - \mathbf{M}_{2,0}^2 \end{pmatrix} \odot \begin{pmatrix} (u_1^2 - v_1^2 - w_1^2)(u_2^2 - v_2^2 + w_2^2) \\ (u_1^2 - v_1^2 + w_1^2)(u_2^2 - v_2^2 - w_2^2) \\ (u_1^2 - v_1^2 + w_1^2)(u_2^2 - v_2^2 + w_2^2) \end{pmatrix} + 2u_2w_2 \begin{pmatrix} \mathbf{M}_{0,0}\mathbf{M}_{0,1} - \mathbf{M}_{0,2}\mathbf{M}_{0,3} \\ \mathbf{M}_{0,0}\mathbf{M}_{0,1} + \mathbf{M}_{0,2}\mathbf{M}_{0,3} \end{pmatrix} \odot \begin{pmatrix} u_1^2 - v_1^2 - w_1^2 \\ 0 \\ u_1^2 - v_1^2 + w_1^2 \end{pmatrix} + 2u_1w_1 \begin{pmatrix} \mathbf{M}_{0,0}\mathbf{M}_{0,2} - \mathbf{M}_{0,1}\mathbf{M}_{0,3} \\ \mathbf{M}_{0,0}\mathbf{M}_{0,2} - \mathbf{M}_{0,1}\mathbf{M}_{0,3} \\ 0 \end{pmatrix} \odot \begin{pmatrix} u_2^2 - v_2^2 - w_2^2 \\ u_2^2 - v_2^2 + w_2^2 \end{pmatrix} + 4w_1w_2 \begin{pmatrix} \mathbf{0} \\ \mathbf{M}_{0,0}\mathbf{M}_{0,3} + \mathbf{M}_{0,1}\mathbf{M}_{0,3} \\ \mathbf{M}_{0,0}\mathbf{M}_{0,3} - \mathbf{M}_{0,1}\mathbf{M}_{0,3} \end{pmatrix} \odot \begin{pmatrix} \mathbf{0} \\ 0 \\ u_1u_2 \\ v_1v_2 \end{pmatrix}$$

HD isogenies are fun!!

Thank you for your attention!

eprint 2025/736.

Type II formulae (position 00)

Theorem: Superglue in position 00

Let $\theta^{E_1 \times E_2}$ be the theta structure induced by the symplectic basis of $\langle (0,\beta), (C,0) \rangle \oplus \langle (C,C), (\alpha,\beta) \rangle$ with **M** its change of basis matrix. For any $P, Q \in E_1 \times E_2$ we have that

$$\mathcal{H}(\theta^{E_1 \times E_2}(P+Q) \odot \theta^{E_1 \times E_2}(P-Q)) =$$

$$\begin{pmatrix} \mathbf{M_{1,0}}^2 + \mathbf{M_{2,0}}^2 \\ \mathbf{M_{0,0}}^2 - \mathbf{M_{1,0}}^2 \\ \mathbf{M_{0,0}}^2 - \mathbf{M_{2,0}}^2 \end{pmatrix} \odot \begin{pmatrix} (u_1^2 - v_1^2 + w_1^2)(u_2^2 - v_2^2 + w_2^2) \\ (u_1^2 - v_1^2 + w_1^2)(u_2^2 - v_2^2 + w_2^2) \\ (u_1^2 - v_1^2 - w_1^2)(u_2^2 - v_2^2 - w_2^2) \end{pmatrix} \\ + 2u_2w_2 \begin{pmatrix} \mathbf{M_{0,0}M_{0,1} + M_{1,0}M_{1,1}} \\ \mathbf{M_{0,0}M_{0,1} - M_{1,0}M_{1,1}} \\ 0 \\ 0 \end{pmatrix} \odot \begin{pmatrix} u_1^2 - v_1^2 + w_1^2 \\ u_1^2 - v_1^2 + w_1^2 \\ 0 \\ 0 \end{pmatrix} \\ + (-1)^{\mathbf{M_{0,1}} = -\mathbf{M_{0,2}}} \begin{pmatrix} \mathbf{M_{0,0}M_{0,1} - M_{1,0}M_{1,1}} \\ 2u_1w_1 \begin{pmatrix} \mathbf{M_{0,0}M_{0,1} - M_{1,0}M_{1,1}} \\ \mathbf{M_{0,0}M_{0,1} + M_{1,0}M_{1,1}} \\ 0 \\ 0 \end{pmatrix} \odot \begin{pmatrix} u_2^2 - v_2^2 + w_2^2 \\ u_2^2 - v_2^2 + w_2^2 \\ u_2^2 - v_2^2 + w_2^2 \\ 0 \\ 0 \end{pmatrix} \\ + 4w_1w_2 \begin{pmatrix} \mathbf{M_{0,0}}^2 - \mathbf{M_{1,0}}^2 \\ \mathbf{M_{1,0}}^2 + \mathbf{M_{2,0}}^2 \\ \mathbf{M_{1,0}}^2 + \mathbf{M_{2,0}}^2 \\ 0 \\ v_1v_2 \end{pmatrix} \odot \begin{pmatrix} u_1u_2 \\ u_1u_2 \\ 0 \\ v_1v_2 \end{pmatrix} \end{pmatrix}$$

columns	theta points		columns	dual theta points
M_0M_0	$\theta^{E_1 \times E_2}(0,0) \theta^{E_1 \times E_2}(0,0)$	\iff	$\widetilde{M_0}\widetilde{M_0}$	$\widetilde{ heta}^{J_1}(\Phi(0,0))\widetilde{ heta}^{J_1}(\Phi(0,0))$
M_1M_1	$\theta^{E_1 \times E_2}(0,C)\theta^{E_1 \times E_2}(0,C)$	\iff	$\widetilde{M_1M_1}$	$\widetilde{ heta}^{J_1}(\Phi(0,0))\widetilde{ heta}^{J_1}(\Phi(0,\mathcal{C}))$
M_2M_2	$\theta^{E_1 \times E_2}(C,0)\theta^{E_1 \times E_2}(C,0)$	\iff	$\widetilde{M_2M_2}$	$\widetilde{ heta}^{J_1}(\Phi(0,0))\widetilde{ heta}^{J_1}(\Phi(\mathcal{C},0))$
M_3M_3	$\theta^{E_1 \times E_2}(C,C)\theta^{E_1 \times E_2}(C,C)$	\iff	$\widetilde{M_3M_3}$	$\widetilde{ heta}^{J_1}(\Phi(0,0))\widetilde{ heta}^{J_1}(\Phi({ extsf{C}},{ extsf{C}}))$
M_0M_1	$\theta^{E_1 \times E_2}(0,0) \theta^{E_1 \times E_2}(0,C)$	\iff	$\widetilde{M_0M_1}$	$\widetilde{ heta}^{J_1}(\Phi(0,C'))\widetilde{ heta}^{J_1}(\Phi(0,C'))$
M_2M_3	$\theta^{E_1 \times E_2}(C,0)\theta^{E_1 \times E_2}(C,C)$	\iff	$\widetilde{M_2M_3}$	$\widetilde{ heta}^{J_1}(\Phi(0,C'))\widetilde{ heta}^{J_1}(\Phi(C,C'))$
M_0M_2	$\theta^{E_1 \times E_2}(0,0) \theta^{E_1 \times E_2}(C,0)$	\iff	$\widetilde{M_0M_2}$	$\widetilde{ heta}^{J_1}(\Phi(\mathcal{C}',0))\widetilde{ heta}^{J_1}(\Phi(\mathcal{C}',0))$
M_1M_3	$\theta^{E_1 \times E_2}(0,C)\theta^{E_1 \times E_2}(C,C)$	\iff	$\widetilde{M_1M_3}$	$\widetilde{ heta}^{J_1}(\Phi(\mathcal{C}',0))\widetilde{ heta}^{J_1}(\Phi(\mathcal{C}',\mathcal{C}))$
M_0M_3	$\theta^{E_1 \times E_2}(0,0)\theta^{E_1 \times E_2}(C,C)$	\iff	$\widetilde{M_0M_3}$	$\widetilde{ heta}^{J_1}(\Phi(\mathcal{C}',\mathcal{C}'))\widetilde{ heta}^{J_1}(\Phi(\mathcal{C}',\mathcal{C}'))$
M_1M_2	$\theta^{E_1 \times E_2}(0,C)\theta^{E_1 \times E_2}(C,0)$	\iff	$\widetilde{M_1M_2}$	$\widetilde{\theta}^{J_1}(\Phi(C',C'))\widetilde{\theta}^{J_1}(\Phi(C',-C'))$

Table: Correspondence between product of columns and theta points with C=(0:1) and $C'=(1:\pm 1)$.

Where are the *C* points

Position	Туре	ker(Φ)	(C, 0)	(0, C)	(<i>C</i> , <i>C</i>)
00	П	$\langle (C,C),(\alpha,\beta)\rangle$	S_2	$S_2 + T_1$	T_1
01	1	$\langle (C, \beta), (\alpha, C) \rangle$	S_2	S_1	$S_1 + S_2$
02	1	$\langle (C,\beta),(\alpha,\beta^{-1})\rangle$	S_2	$S_1+S_2+T_1$	S_1+T_1
10	1	$\langle (\alpha, C), (C, \beta) \rangle$	$\mathcal{S}_1 + \mathcal{T}_2$	$S_2 + T_1$	$S_1 + S_2 + T_1 + T_2$
11	П	$\langle (\alpha, \beta), (C, C) \rangle$	$\mathcal{S}_1+\mathcal{T}_2$	S_1	T_2
12	1	$\langle (\alpha, \beta), (C, \beta^{-1}) \rangle$	$\mathcal{S}_1 + \mathcal{T}_2$	$S_1+S_2+T_1$	$S_2+T_1+T_2$
20	1	$\langle (\alpha, C), (\alpha^{-1}, \beta) \rangle$	$S_1+S_2+T_2$	$S_2 + T_1$	$S_1+T_1+T_2$
21	1	$\langle (\alpha,\beta),(\alpha^{-1},C)\rangle$	$S_1+S_2+T_2$	S_1	$S_2 + T_2$
22	П	$\langle (\alpha, \beta), (\alpha^{-1}, \beta^{-1}) \rangle$	$S_1+S_2+T_2$	$S_1 + S_2 + T_1$	$T_1 + T_2$

Table: Different positions of C = (0:1) points in the symplectic basis depending on the kernel

Supergluing elliptic curves

 \bullet pos = 0:

$$\mathcal{H}\Big(\theta^{\mathsf{E}_1}(P+Q)\odot\theta^{\mathsf{E}_1}(P-Q)\Big) = \binom{b^2\big((u\pm w)^2 - v^2\big) + a^2\big((u\mp w)^2 - v^2\big)}{2ab(u^2 - v^2 - w^2)}$$

 \bullet pos = 1:

$$\mathcal{H}\Big(\theta^{E_1}(P+Q)\odot\theta^{E_1}(P-Q)\Big) = \begin{pmatrix} b^2((u\pm w)^2 - v^2) + a^2((u\mp w)^2 - v^2) \\ b^2((u\pm w)^2 - v^2) - a^2((u\mp w)^2 - v^2) \end{pmatrix}$$

• pos = 2:

$$\mathcal{H}\Big(\theta^{E_1}(P+Q)\odot\theta^{E_1}(P-Q)\Big) = \begin{pmatrix} 2ab(u^2 - v^2 - w^2) \\ b^2((u\pm w)^2 - v^2) + a^2((u\mp w)^2 - v^2) \end{pmatrix}$$

Superglue May 15, 2025