

INTRODUCTION TO STATISTICAL INFERENCE

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Third Semester

List of Symbols

Placeholder

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Chapter 1

SUFFICIENCY

1.1 Introduction to Sufficient Statistics

We start by defining terms for the sake of completion, whilst assuming the most basic definitions.

Definition 1.1. An *estimator* is any function of the random sample which is used to estimate the unknown value of the given parametric function $g(\theta)$.

If $\underline{X} = (X_1, \dots, X_n)$ is a random sample from a population with a probability distribution P_θ , a function $d(\underline{X})$ used for estimating $g(\theta)$ is known as an estimator. Let $\underline{x} = (x_1, \dots, x_n)$ be a realization of $\underline{X} = (X_1, \dots, X_n)$. Then $d(\underline{x})$ is called an *estimate*.

Definition 1.2. The *parameter space* is the set of all possible values of a parameter.

For example, the normal distribution $N(\mu, \sigma^2)$ has the parameter space $\mu \in \mathbb{R}$ and $\sigma^2 > 0$. Similarly, the binomial distribution $\text{Bin}(n, p)$ has the constraints $n \in \mathbb{N}$ and $p \in [0, 1]$.

Throughout this course, we will assume any data, otherwise stated, will be *independent and identically distributed*; the are separate datapoints that follow the same probability distribution and are independent.

Definition 1.3. Let X_1, \dots, X_n be a random sample from a population P_θ , where $\theta \in \Theta$. A statistic $T = T(X_1, \dots, X_n) = T(\underline{X})$ is said to be a *sufficient statistic* for the family $\mathcal{P} = \{P_\theta : \theta \in \Theta\}$ if the conditional distribution of X_1, \dots, X_n given $T = t$ is independent of θ .

We shall look at some examples.

Example 1.4. Let X_1, \dots, X_n be a random sample from the Bernoulli distribution with parameter $p \in (0, 1)$. We claim that $T = \sum_{i=1}^n X_i$ is sufficient for $\{\text{Ber}(p) \mid 0 < p < 1\}$. To show this, we simply have

$$P(X_i = x_i \text{ for all } i \mid T = t) = \frac{P(X_1 = x_1, \dots, X_{n-1} = x_{n-1}, X_n = t - \sum_{i=1}^{n-1} x_i)}{P(\sum_{i=1}^n X_i = t)} \quad (1.1)$$

$$\begin{aligned} &= \frac{P(X_1 = x_1) \cdots P(X_{n-1} = x_{n-1}) \cdot P(X_n = t - \sum_{i=1}^{n-1} x_i)}{\binom{n}{t} p^t (1-p)^{n-t}} \\ &= \frac{p^{x_1} (1-p)^{1-x_1} \cdots p^{x_{n-1}} (1-p)^{1-x_{n-1}} p^{t - \sum_{i=1}^{n-1} x_i} (1-p)^{1-t + \sum_{i=1}^{n-1} x_i}}{\binom{n}{t} p^t (1-p)^{n-t}} \\ &= \frac{1}{\binom{n}{t}}. \end{aligned} \quad (1.2)$$

Thus, the statistic T is sufficient. The above expression is valid when $\sum_{i=1}^n x_i = t$, and the probability

evaluates to 0 if $\sum_{i=1}^n x_i \neq t$.

Example 1.5. Let X_1, \dots, X_n be a random sample from $\text{Poisson}(\lambda)$ for $\lambda > 0$. We claim that the statistic $T = \sum_{i=1}^n X_i$ is sufficient. Recall that the probability mass function is $f(x, \lambda) = \frac{e^{-\lambda} \lambda^x}{x!}$ where x is a non-negative integer, and $\lambda > 0$. We have

$$P(X_i = x_i \mid T = t) = \frac{P(X_1 = x_1) \cdots P(X_{n-1} = x_{n-1}) \cdot P(X_n = t - \sum_{i=1}^{n-1} x_i)}{P(\sum_{i=1}^n X_i = t)} \quad (1.3)$$

$$\begin{aligned} &= \frac{\frac{e^{-\lambda} \lambda^{x_1}}{x_1!} \cdots \frac{e^{-\lambda} \lambda^{x_{n-1}}}{x_{n-1}!} \cdot \frac{e^{-\lambda} \lambda^{t - \sum_{i=1}^{n-1} x_i}}{(t - \sum_{i=1}^{n-1} x_i)!}}{\frac{e^{-n\lambda} (n\lambda)^t}{t!}} \\ &= \frac{e^{-n\lambda} \lambda^t}{x_1! \cdots x_{n-1}! (t - \sum_{i=1}^{n-1} x_i)!} \cdot \frac{t!}{e^{-n\lambda} (n\lambda)^t} \\ &= \frac{t!}{x_1! \cdots x_{n-1}! (t - \sum_{i=1}^{n-1} x_i)!} \cdot \frac{1}{n^t} \\ &= \binom{t}{x_1, x_2, \dots, x_n} \cdot \frac{1}{n^t}. \end{aligned} \quad (1.4)$$

This shows that the conditional distribution of (X_1, \dots, X_n) given $T = t$ does not depend on λ , so by the definition of sufficiency, T is a sufficient statistic for λ .

Definition 1.6. A *regular model* may be one of two things.

1. All P_θ are continuous with probability density function $f(x \mid \theta)$.
2. All P_θ are discrete with probability mass function $p(x \mid \theta)$, and there exists a countable set $S = \{x_1, x_2, \dots\}$ independent of θ such that $\sum_{i=1}^\infty p(x_i \mid \theta) = 1$.

1.2 Factorization Theorems

The following theorem proves to be useful for finding sufficiency.

Theorem 1.7 (The Neyman-Fisher factorization theorem). *Let $f(\underline{x} \mid \theta)$ be the density of \underline{X} under the probability model P_θ for $\theta \in \Theta$. Then if the model is regular, a statistic $T(\underline{X})$ is sufficient for θ if and only if there exist functions g and h such that*

$$f(\underline{x} \mid \theta) = g(T(\underline{x}), \theta) h(\underline{x}). \quad (1.5)$$

Note that the functions are defined with $T : \mathbb{R}^n \rightarrow I \subseteq \mathbb{R}^k$ (for $k \leq n$), $g : I \times \Theta \rightarrow \mathbb{R}_{\geq 0}$, and $h : \mathbb{R}^n \rightarrow \mathbb{R}_{\geq 0}$. The functions g and h need not be unique.

A little less formally, the theorem basically states this: let X be a random variable with probability mass/density function $f(x, \theta)$ for $\theta \in \Theta$. Then $T(X)$ is sufficient if and only if $f(x, \theta) = g(T(x), \theta)h(x)$ for all $\theta \in \Theta$.

Example 1.8. Let X_1, \dots, X_n be independent and identically distributed $N(\mu, \sigma^2)$ random variables, with $\mu \in \mathbb{R}$ and $\sigma^2 > 0$. Let us find a sufficient test statistic. We look at cases; the first case being when σ^2 is known ($\sigma^2 = 1$). Since these are independent, we have the joint probability density

function of these random variables as

$$f(x_1, \dots, x_n \mid \mu, \sigma^2) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}} = \frac{1}{(2\pi)^{n/2}} e^{-\sum_{i=1}^n (x_i - \mu)^2} \quad (1.6)$$

$$\begin{aligned} &= \frac{1}{(2\pi)^{n/2}} \exp\left(-\frac{1}{2} \left(\sum_{i=1}^n x_i^2 - 2\mu \sum_{i=1}^n x_i + n\mu^2\right)\right) \\ &= \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \sum_{i=1}^n x_i^2} \times e^{-\frac{1}{2}(-2\mu \sum_{i=1}^n x_i + n\mu^2)}. \end{aligned} \quad (1.7)$$

Make the former term $h(x)$ and the latter term $g(\sum_{i=1}^n x_i, \mu)$ with $T(x) = \sum_{i=1}^n x_i$. The second case now involves μ being known, and we set it to $\mu = 0$ to get $T(x) = \sum_{i=1}^n x_i^2$, $h(x) = 1/(2\pi)^{n/2}$, and $g(T(x), \sigma^2) = \sigma^{-n} e^{-T(x)/2\sigma^2}$.

We move on to another factorization theorem.

Definition 1.9. The family of distributions $\{P_\theta \mid \theta \in \Theta\}$ is said to be a *single parameter exponential family* if there exist real valued functions $c(\theta), d(\theta)$ on Θ and $T(x), S(x)$ on \mathbb{R}^n and a set $A \subset \mathbb{R}^n$ such that

$$f(x \mid \theta) = \exp(c(\theta)T(x) + d(\theta) + S(x))\mathbf{1}_A(x) \quad (1.8)$$

where A must not depend on θ .

Example 1.10. Suppose $X \sim \text{Poisson}(\lambda)$ for $\lambda > 0$. With $A = \{0, 1, 2, \dots\}$, we have

$$f(x \mid \lambda) = \exp(x \log(\lambda) - \lambda - \log(x!))\mathbf{1}_A(x) \quad (1.9)$$

with $T(x) = x$, $c(\lambda) = \log(\lambda)$, $d(\lambda) = -\lambda$, and $S(x) = -\log(x!)$.

Consider X_1, \dots, X_n independent and identically distributed random variables following the distribution P_θ , and suppose that $\{P_\theta \mid \theta \in \Theta\}$ is an exponential family, that is, $f(x \mid \theta) = \exp(c(\theta)T(x_i) + d(\theta) + S(x))\mathbf{1}_A(x)$. Then,

$$f_{x_1, \dots, x_n}(x_1, \dots, x_n \mid \theta) = \prod_{i=1}^n \exp(c(\theta)T(x_i) + d(\theta) + S(x_i))\mathbf{1}_A(x_i) \quad (1.10)$$

$$= \exp(c(\theta) \sum_{i=1}^n T(x_i) + nd(\theta) + \sum_{i=1}^n S(x_i))\mathbf{1}_{A^n}(x_1, \dots, x_n). \quad (1.11)$$

(x_1, \dots, x_n) has distribution belonging to a single parameter exponential family. Thus, if $\{P_\theta \mid \theta \in \Theta\}$ is a single parameter family with density $f(x, \theta) = \exp(c(\theta)T(x) + d(\theta) + S(x))\mathbf{1}_A(x)$, then $T(x)$ is sufficient for θ .

Corollary 1.11. If x_1, \dots, x_n are independent and identically distributed random variables following the distribution P_θ with density $f(x \mid \theta) = \exp(c(\theta)T(x) + d(\theta) + S(x))\mathbf{1}_A(x)$, then $\sum_{i=1}^n T(X_i)$ is sufficient for θ .

The exponential family is expanded.

Definition 1.12. A family of distributions $\{P_\theta : \theta \in \Theta\}$ with density $f(x \mid \theta)$ is called a *k-parameter exponential family* if there exists real valued functions $c_1(\theta), \dots, c_k(\theta), d(\theta)$ on Θ and

$T_1(\underline{x}), \dots, T_k(\underline{x}), S(\underline{x})$ on \mathbb{R}^n , and a set $A \subset \mathbb{R}^n$ such that

$$f(\underline{x} | \theta) = \left(\exp \left(\sum_{j=1}^n c_j(\theta) T_j(\underline{x}) + d(\theta) + S(\underline{x}) \right) \right) \mathbf{1}_A(\underline{x}). \quad (1.12)$$

Here, (T_1, \dots, T_k) is a k -dimensional sufficient statistic for θ . Note that the parameter here is θ and not $(c_1(\theta), \dots, c_k(\theta))$.

We look at more examples.

Example 1.13. For a normal distribution with $\sigma^2 = 1$, we have

$$f(x | \theta) = \frac{1}{\sqrt{2\pi}} e^{-\frac{(x-\theta)^2}{2}} \mathbf{1}_A(x) = \exp \left(-\frac{1}{2} \log(2\pi) - \frac{x^2}{2} + x\theta - \frac{\theta^2}{2} \right) \mathbf{1}_A(x). \quad (1.13)$$

Here, $c(\theta) = \theta$, $T(x) = x$, $S(x) = -\frac{x^2}{2} - \frac{1}{2} \log(2\pi)$, and $d(\theta) = -\frac{\theta^2}{2}$.

Remark 1.14. 1. The Neyman-Fisher factorization theorem holds if $\underline{\theta}$ and \underline{T} are vectors. Their dimensions need not be equal.

2. If T is sufficient and T is a function of U , then U is also sufficient.

3. If V is a function of T , then V need not be sufficient. But if V is one-to-one with T , then V is also sufficient. $V = B(T)$ and $T = B^{-1}(V)$ shows that $g(T, \theta) = g(B^{-1}(V), \theta) = g^*(V, \theta)$.

1.3 Minimal Sufficiency

Again, we begin with a few definitions.

Definition 1.15. A *partition* of a space \mathcal{H} is a collection $\{E_i\}$ of subsets of \mathcal{H} such that

$$\bigcup_{i \geq 1} E_i = \mathcal{H} \text{ and } E_i \cap E_j = \emptyset \text{ for } i \neq j. \quad (1.14)$$

The E_i 's are called *partition sets*. Let $T : \mathcal{H} \rightarrow \mathcal{J}$. The partition of \mathcal{H} induced by the function T is the collection of the sets $T_y = \{x \mid T(x) = y\}$ for $y \in \mathcal{J}$.

We say that \mathcal{P}_2 is a *reduction* of \mathcal{P}_1 if each partition set of \mathcal{P}_2 is the union of the same members of \mathcal{P}_1 .

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