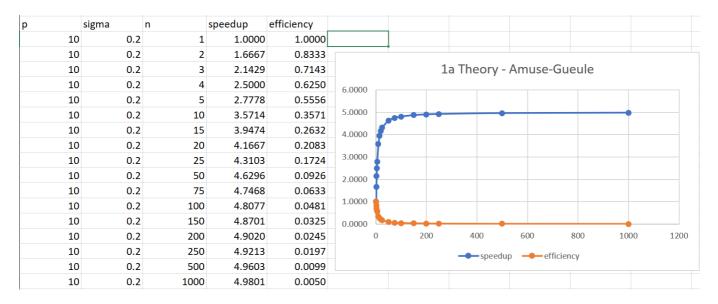
# Exercise 1

# **System Configuration**

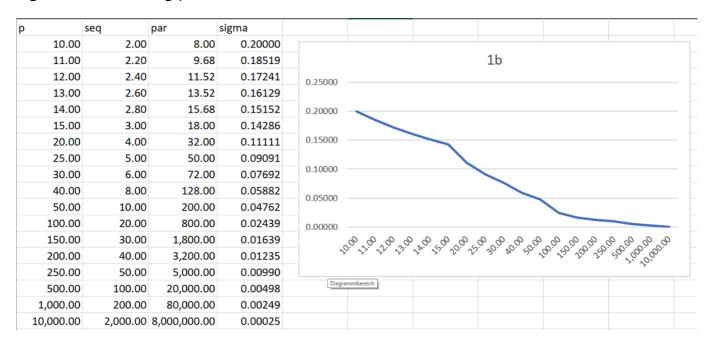
СРИ	Intel Core i7-7700K		
CPU Base Speed	4.20 GHz		
CPU Boost Speed	4.50 GHz		
Memory Size	16 GB		
Memory Speed	3000 MHz		
Hard Drive	1 TB M.2 SSD		
Operating System	Windows 10 Pro		
IDE	Jetbrains Rider V2021.2.2		

# Theory - Amuse-Gueule

## Speedup and Efficiency



## Sigma with increasing problem size



### Efficiency with more processors

р	seq	par	sigma	n	speedup	efficiency
10.00	2.00	8.00	0.20000	1	1	1
11.00	2.20	9.68	0.18519	2	1.6875	0.84375
12.00	2.40	11.52	0.17241	2	1.70588235	0.85294118
13.00	2.60	13.52	0.16129	2	1.7222222	0.86111111
14.00	2.80	15.68	0.15152	2	1.73684211	0.86842105
15.00	3.00	18.00	0.14286	2	1.75	0.875
20.00	4.00	32.00	0.11111	3	2.45454545	0.81818182
25.00	5.00	50.00	0.09091	3	2.53846154	0.84615385
30.00	6.00	72.00	0.07692	4	3.25	0.8125
40.00	8.00	128.00	0.05882	5	4.04761905	0.80952381
50.00	10.00	200.00	0.04762	6	4.84615385	0.80769231
100.00	20.00	800.00	0.02439	11	8.84313725	0.80392157
150.00	30.00	1,800.00	0.01639	16	12.8421053	0.80263158
200.00	40.00	3,200.00	0.01235	21	16.8415842	0.8019802
250.00	50.00	5,000.00	0.00990	26	20.8412698	0.8015873
500.00	100.00	20,000.00	0.00498	51	40.8406375	0.80079681
1,000.00	200.00	80,000.00	0.00249	101	80.8403194	0.8003992
10,000.00	2,000.00	8,000,000.00	0.00025	1001	800.840032	0.80003999

### Wator World

#### Review

While WinForms is still supported by Microsoft, it is quite old technology and should not be used anymore. It also makes it harder to port the Application to other operating systems.

The Code suffers from issues with readability and efficiency in quite a few spots. The GetNeighbour-Method is one of the worst offenders for that. The method should extract some functionality (like looking at neighbouring cells) into another function.

General Settings should not be hardcoded, they could be imported from a settings file.

### Improvements

**Baseline Performance:** 

```
X
Performance Analysis
 Runs:
                         100
 Iterations:
 Runtime in Milliseconds: 18233.0054
Avg. Milliseconds / Run: 3646.60108
 Std. Deviation: 16.6409777197036
 Runtimes in Milliseconds:
 Run 01:
                         3675.1448
                         3626.0803
 Run 02:
 Run 03:
                         3641.4022
 Run 04:
                         3652.862
 Run 05:
                          3637.5161
```

### **Optimization 1**

Points required for the GetNeighbour-Method are allocated with every call. This has been reworked to only allocate the array once and reuse it for every call. **Speedup: 1.1**.

```
×
Performance Analysis
 Runs:
 Iterations:
                          100
 Runtime in Milliseconds: 16500.218
 Avg. Milliseconds / Run: 3300.0436
 Std. Deviation:
                          17.3198099336057
 Runtimes in Milliseconds:
 Run 01:
                          3331.5905
 Run 02:
                          3302.5733
 Run 03:
                          3296.7283
 Run 04:
                          3282.0028
                          3287.3231
 Run 05:
```

```
private Point[] neighbors = new Point[4];
// find all neighboring cells of the given position and type
public Point[] GetNeighbors(Type type, Point position) {
   //Point[] neighbors = new Point[4];
   int neighborIndex = 0;
   int i, j;
   // look north
   i = position.X;
   j = (position.Y + Height - 1) % Height;
   if ((type == null) && (Grid[j * Width + i] == null)) {
        neighbors[neighborIndex] = new Point(i, j);
        neighborIndex++;
   } else if ((type != null) && (type.IsInstanceOfType(Grid[j * Width + i]))) {
        if ((Grid[j * Width + i] != null) && (!Grid[j * Width + i].Moved)) {
            // ignore animals moved in the current iteration
            neighbors[neighborIndex] = new Point(i, j);
            neighborIndex++;
        }
   }
    // look east
   i = (position.X + 1) \% Width;
   j = position.Y;
   if ((type == null) && (Grid[j * Width + i] == null)) {
        neighbors[neighborIndex] = new Point(i, j);
        neighborIndex++;
    } else if ((type != null) && (type.IsInstanceOfType(Grid[j * Width + i]))) {
        if ((Grid[j * Width + i] != null) && (!Grid[j * Width + i].Moved)) {
            neighbors[neighborIndex] = new Point(i, j);
            neighborIndex++;
        }
   // look south
   i = position.X;
   j = (position.Y + 1) % Height;
   if ((type == null) && (Grid[j * Width + i] == null)) {
        neighbors[neighborIndex] = new Point(i, j);
        neighborIndex++;
    } else if ((type != null) && (type.IsInstanceOfType(Grid[j * Width + i]))) {
        if ((Grid[j * Width + i] != null) && (!Grid[j * Width + i].Moved)) {
            neighbors[neighborIndex] = new Point(i, j);
            neighborIndex++;
        }
   }
    // look west
   i = (position.X + Width - 1) % Width;
   j = position.Y;
   if ((type == null) && (Grid[j * Width + i] == null)) {
        neighbors[neighborIndex] = new Point(i, j);
        neighborIndex++;
```

```
} else if ((type != null) && (type.IsInstanceOfType(Grid[j * Width + i]))) {
    if ((Grid[j * Width + i] != null) && (!Grid[j * Width + i].Moved)) {
        neighbors[neighborIndex] = new Point(i, j);
        neighborIndex++;
    }
}

// create result array that only contains found cells
Point[] result = new Point[neighborIndex];
for (int x = 0; x < neighborIndex; x++)
        result[x] = neighbors[x];
return result;
}</pre>
```

#### **Optimization 2**

Operations on a 2-Dimensional Array can be quite performance hungry, so both matrixes are replaced with an array. The index can be calculated using the width of the world. **Speedup: 1.06**.

```
\times
Performance Analysis
 Runs:
 Iterations:
                         100
 Runtime in Milliseconds: 15527.309
 Avg. Milliseconds / Run: 3105.4618
 Std. Deviation: 42.409367845947
 Runtimes in Milliseconds:
 Run 01:
                          3174.7234
 Run 02:
                          3070 7694
 Run 03:
                          3080.6307
 Run 04:
                          3066.475
 Run 05:
                          3134.7105
```

```
private int[] randomMatrix;
public Animal[] Grid { get; private set; }

Grid = new Animal[Width * Height];

private void RandomizeMatrix(int[] matrix) {
    // perform Knuth shuffle
(http://en.wikipedia.org/wiki/Fisher%E2%80%93Yates_shuffle)
    int temp, selectedRow, selectedCol;

int row = 0;
    int col = 0;
    for (int i = 0; i < Height * Width; i++) {
        temp = matrix[row * Width + col];

    // select random element from remaining elements
    // already processed elements must not be chosen a second time
        selectedRow = random.Next(row, Height);
        if (selectedRow == row) selectedCol = random.Next(col, Width);</pre>
```

```
// current row selected -> select from remaining columns
else selectedCol = random.Next(Width);
// new row selected -> select any column

// swap
matrix[row * Width + col] = matrix[selectedRow * Width + selectedCol];
matrix[selectedRow * Width + selectedCol] = temp;

// incremet col and row
col++;
if (col >= Width) { col = 0; row++; }
}
```

#### **Optimization 3**

The RandomizeMatrix method uses an inefficient version of the Knuth shuffle. This has been replaced with the more efficient version which brings the asymptotic runtime complexity from  $O(n^2)$  to O(n). **Speedup: 1.1**.

```
X
Performance Analysis
 Runs:
 Iterations:
                         100
 Runtime in Milliseconds: 14097.3747
 Avg. Milliseconds / Run: 2819.47494
 Std. Deviation:
                     22.4575668697784
 Runtimes in Milliseconds:
                          2856.6924
 Run 01:
 Run 02:
                         2806.3503
 Run 03:
                          2799.5477
 Run 04:
                          2834.1036
 Run 05:
                          2800.6807
```

```
private void RandomizeMatrix(int[] matrix) {
    // perform Knuth shuffle
(http://en.wikipedia.org/wiki/Fisher%E2%80%93Yates_shuffle)
    int temp;

for (int i = 0; i < Height * Width; i++) {
        int j = random.Next(i, Height * Width);
        temp = matrix[i];
        matrix[i] = matrix[j];
        matrix[j] = temp;
    }
}</pre>
```