Modern Machine Learning — Support Vector Machines

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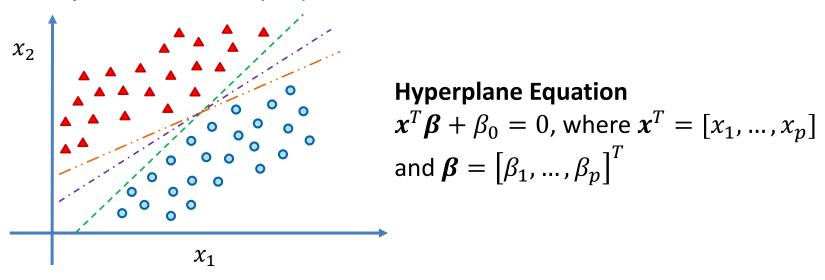
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Support Vector Machines produce nonlinear boundaries by constructing linear boundaries in a large, transformed version of the feature space

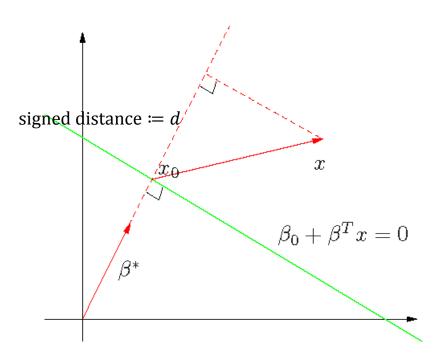
- First derive the case for linear support vector machines with separable data
 - Constructing an optimal separating hyperplane between two perfectly separated classes
- Generalize result to the linear support vector machines with nonseparable data
 - Construct an optimal separating hyperplane focusing on samples near the decision boundary
- Finally, employ the kernel trick to transform the data, yielding nonlinear boundaries in the observation space [covered in a subsequent section]

Assumption: two linearly separable classes



Observation: There are an infinite number of separating hyperplanes

To establish the optimal hyperplane, determine the hyperplane vector normal and the signed distances of samples to the hyperplane



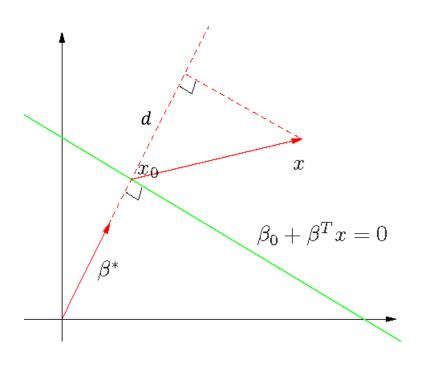
The hyperplane, or *afine set L*, is defined by: $f(\mathbf{x}) = \beta_0 + \mathbf{x}^T \boldsymbol{\beta} = 0$

Observations & Definitions:

- 1. For any two points $x_1, x_2 \in L$, we have: $f(x_1) f(x_2) = \beta^T (x_1 x_2) = 0$ $\Rightarrow \beta^* = \beta/\|\beta\|$ is the unit vector normal to L
- 2. For any point $x_0 \in L$, $\beta^T x_0 = -\beta_0$
- 3. This signed distance, d, of any point x to L is

$$\boldsymbol{\beta}^{*T}(\boldsymbol{x} - \boldsymbol{x}_0) = \frac{1}{\|\boldsymbol{\beta}\|} (\boldsymbol{\beta}^T \boldsymbol{x} + \beta_0)$$
$$= \frac{1}{\|f'(\boldsymbol{x})\|} f(\boldsymbol{x})$$

 \Rightarrow f(x) is proportional to the signed distance from x to the hyper plane defined by f(x); signed distance = f(x) when $\|\boldsymbol{\beta}\| = 1$



Observation: Signed distances can be used as metrics for classification, i.e.

$$G(x) = \operatorname{sgn}(d)$$

Problem Setup:

Binary class case: $(y_i, \mathbf{x}_i) \in \{+1, -1\} \times \mathbb{R}^p$

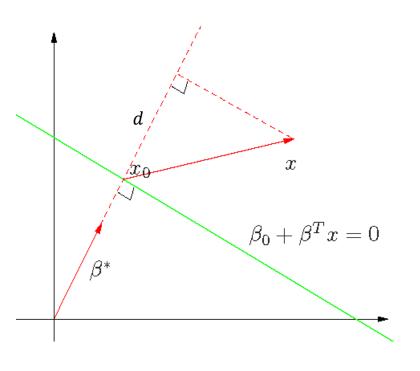
Separating hyperplane: $\beta_0 + \mathbf{x}^T \boldsymbol{\beta} = 0$, where we enforce the normalization $\|\boldsymbol{\beta}\| = 1$

Thus
$$G(\mathbf{x}_i) = \operatorname{sgn}(d) = \operatorname{sgn}(\mathbf{x}_i^T \boldsymbol{\beta} + \beta_0)$$

positives signed distance $\Longrightarrow G(\mathbf{x}_i) = 1$
negative signed distance $\Longrightarrow G(\mathbf{x}_i) = -1$

Moreover

$$G(\mathbf{x}_i)y_i = y_i(\mathbf{x}_i^T\boldsymbol{\beta} + \beta_0) > 0 \rightarrow \text{correct classification}$$
 $G(\mathbf{x}_i)y_i = y_i(\mathbf{x}_i^T\boldsymbol{\beta} + \beta_0) < 0 \rightarrow \text{incorrect classification}$ Finally, note that $|y_i(\mathbf{x}_i^T\boldsymbol{\beta} + \beta_0)|$ is the distance between \mathbf{x}_i and the separating hyperplane



Perfectly Separable Case: In this case,

$$G(\mathbf{x})y_i = y_i(\mathbf{x}_i^T\boldsymbol{\beta} + \beta_0) > 0 \forall i$$

Question: How large can we make the margin, M, separating points from the hyper plane?

Cast the problem as:

$$\max_{\beta_0, \boldsymbol{\beta}, \|\boldsymbol{\beta}\| = 1} M$$

subject to

$$y_i(\mathbf{x}_i^T\boldsymbol{\beta} + \beta_0) \ge M, i = 1, ..., n$$

Note: The condition $\|\boldsymbol{\beta}\| = 1$ can be included in the constraint as

$$\frac{1}{\|\boldsymbol{\beta}\|} y_i (\mathbf{x}_i^T \boldsymbol{\beta} + \beta_0) \ge M$$

$$\Rightarrow y_i (\mathbf{x}_i^T \boldsymbol{\beta} + \beta_0) \ge M \|\boldsymbol{\beta}\|$$

We can always rescale $(\beta_0, \boldsymbol{\beta})$ so that

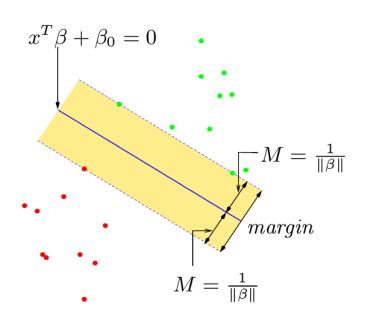
$$\|\boldsymbol{\beta}\| = \frac{1}{M}$$

Therefore, the optimization problem can be expressed as

$$\min_{oldsymbol{eta}_0, oldsymbol{eta} \in \mathbb{R}^p} \|oldsymbol{eta}\|$$

subject to

$$y_i(\mathbf{x}_i^T\boldsymbol{\beta} + \beta_0) \ge 1, i = 1, ..., n$$



Non-Separable Case: Maximize M, but allow for some points to be on the wrong side of the margin.

Define the slack variables $\xi = (\xi_1, \xi_2, ..., \xi_n)$

Options to modify $y_i(\mathbf{x}_i^T\boldsymbol{\beta} + \beta_0) \geq M$

$$y_i(\mathbf{x}_i^T \boldsymbol{\beta} + \beta_0) \ge M - \xi_i$$
 (*)

or

$$y_i(\mathbf{x}_i^T \boldsymbol{\beta} + \beta_0) \ge M(1 - \xi_i) \quad (**)$$

 $\forall i, \xi_i \geq 0, \sum_{i=1}^n \xi_i \leq C$, where C is a constant

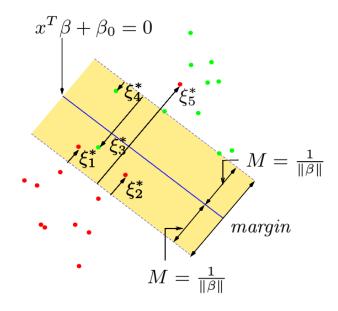
Observations:

- (*) measures overlap in distance from the margin, but results in a nonconvex optimization
- (**) measures overlap in relative distance that scales with the margin M, but yields a convex optimization

Thus (**) is referred to as the standard support vector classifier, which yields:

$$\min \|\boldsymbol{\beta}\| \text{ subject to } \begin{cases} y_i (\mathbf{x}_i^T \boldsymbol{\beta} + \beta_0) \ge 1 - \xi_i, \forall i \\ \xi_i \ge 0, \sum_{i=1}^n \xi_i \le C \end{cases}$$

where as previously, we set $M = 1/\|\boldsymbol{\beta}\|$



Summary:

- Linear Support Vector Machines determine the optimal separating hyperplane between two classes
- If the data is perfectly separable, the SVM problem statement is:

$$\min \|\boldsymbol{\beta}\|$$
 subject to $y_i(\mathbf{x}_i^T\boldsymbol{\beta} + \beta_0) \ge 1, \forall i$

• If the data is not separable, the SVM problem statement is:

$$\min \|\boldsymbol{\beta}\| \text{ subject to } \begin{cases} y_i (\mathbf{x}_i^T \boldsymbol{\beta} + \beta_0) \ge 1 - \xi_i, \forall i \\ \xi_i \ge 0, \sum_{i=1}^n \xi_i \le C \end{cases}$$

Where $\xi = (\xi_1, \xi_2, ..., \xi_n)$ are slack variables and C is a constant that controls the total amount of slack

• Classification is determined as $G(x) = \operatorname{sgn}(x^T \beta + \beta_0)$ for binary (± 1) classes