



# Modern Machine Learning

## Lasso Regression

Kenneth E. Barner

Department of Electrical and Computer Engineering  
University of Delaware

**Lasso (Least Absolute Shrinkage and Selection Operator)**

- Penalizes the coefficients  $\beta$  using the  $\ell_1$  norm
- Formulation

$$\hat{\beta}_{lasso} = \underset{\beta \in \mathbb{R}^{(p+1)}}{\operatorname{argmin}} \|\mathbf{y} - \mathbf{X}\beta\|^2 + \lambda \|\beta\|_1 \quad (*)$$

**Lasso features:**

- Sets some coefficients to zero, yielding a sparse solution (model selection)
- No closed form solution, but can be solved efficiently using convex optimization methods

**Note:** Lasso Regression can be equivalently formulated as

$$\begin{aligned} \hat{\beta}_{lasso} = \underset{\beta \in \mathbb{R}^{(p+1)}}{\operatorname{argmin}} \|\mathbf{y} - \mathbf{X}\beta\|^2 \quad (**) \\ \text{subject to } \|\beta\|_1 < t \end{aligned}$$

There is a one-to-one correspondence between  $\lambda$  in (\*) and  $t$  in (\*\*)



## Lasso & Ridge Comparison

Lasso constraint/penalty:  $\|\boldsymbol{\beta}\|_1 \leq t$

- Lagrange multiplier:  $\lambda\|\boldsymbol{\beta}\|_1$

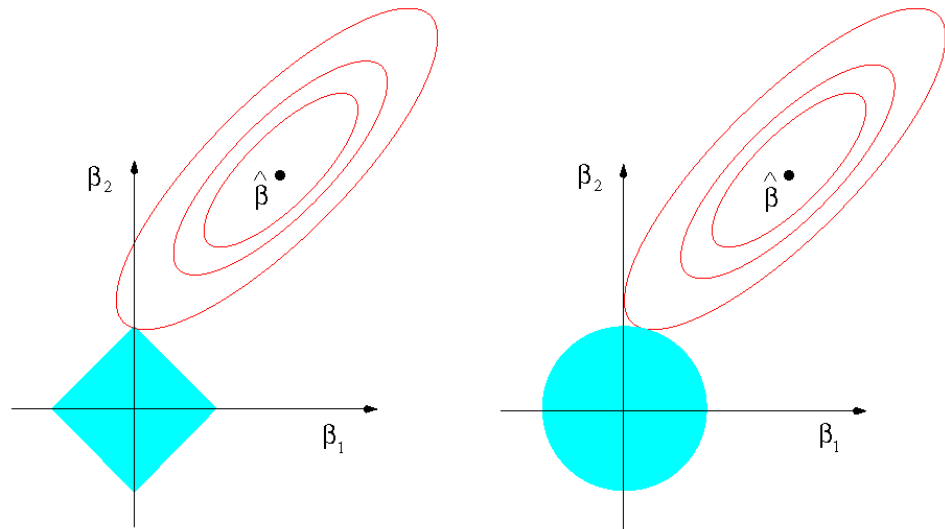
Ridge constraint/penalty:  $\|\boldsymbol{\beta}\|_2 \leq t$

- Lagrange multiplier:  $\lambda\|\boldsymbol{\beta}\|_2$

Thus

$$\hat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta} \in \mathbb{R}^{(p+1)}}{\operatorname{argmin}} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda\|\boldsymbol{\beta}\|_q \quad q \in \{1, 2\}$$

**Note:** The solutions are the intersection between the constraint functions and the error (cost function) contours



**Observation:** the lasso constraint is diamond-shaped

- If the solution occurs at a corner, one coefficient is zero valued
- For higher dimensions, there are many “corners” forcing solutions with multiple zero coefficients



## Shrinkage Constraint Comparison

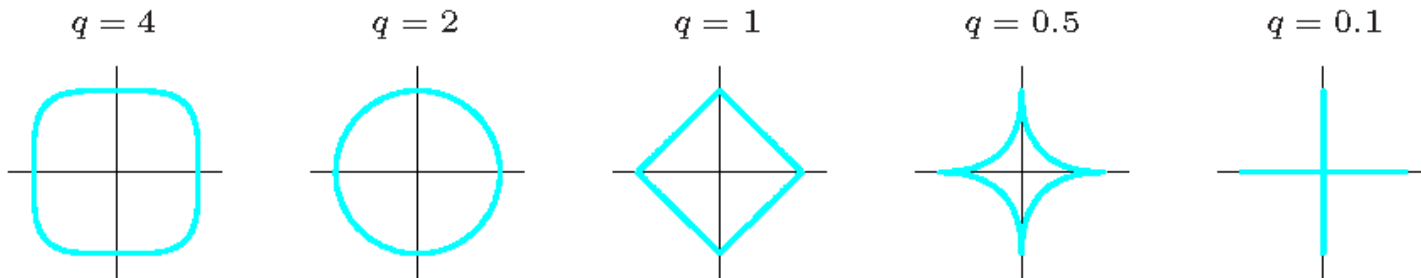
Consider the more generalized regression problem:

$$\hat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta} \in \mathbb{R}^{(p+1)}}{\operatorname{argmin}} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda \|\boldsymbol{\beta}\|_q \quad q \geq 0$$

The contours for  $\|\boldsymbol{\beta}\|_q$  are plotted below for the 2D case.

### Observations:

- The case  $q = 1$  (Lasso) is the smallest  $q$  such that the constraint region is convex
- Decreasing  $q$  forces solutions to the coordinate axis (reducing the number of nonzero coefficients)





### Shrinkage Comparison

Consider the case of  $\mathbf{X}$  with orthogonal columns. The resulting shrinkage of the LS solution is:

$$\hat{\beta}_j / (1 + \lambda) \quad [\text{Ridge}]$$

$$\text{sign}(\hat{\beta}_j)(|\hat{\beta}_j| - \lambda)_+ \quad [\text{Lasso}]$$

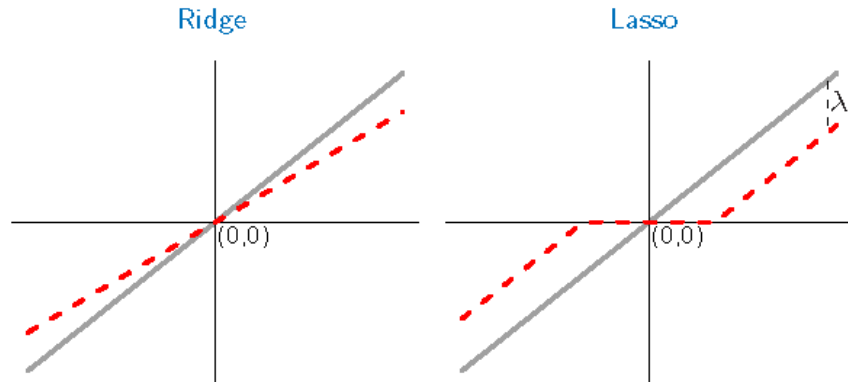
where  $\hat{\beta}_j$  is element  $j$  of  $\hat{\beta}_{LS}$ ,  $\text{sign}(\cdot)$  denotes the sign of its argument ( $\pm 1$ ) and

$$x_+ = \begin{cases} x & \text{if } x > 0 \\ 0 & \text{if } x \leq 0 \end{cases}$$

**Note:** results derived similarly to SVD analysis performed in Ridge Regression

#### Observations:

- Rigidly linearly scales (shrinks) coefficients
- Lasso translates (shrinks) each coefficient by a constant  $\lambda$ , truncating to 0. This is called **soft thresholding**



Example: solid 45° lines represent LS coefficient values and the dotted lines represent the resulting Ridge & Lasso coefficient values.



**Optimization:** No closed form Lasso solution exists, although the optimization problem is convex. One optimization approach is **cyclic coordinate descent**

**Coordinate descent:** based on the premise that minimizing a multivariate function  $f(\boldsymbol{\beta})$  can be achieved by repeatedly minimizing along one coordinate direction at a time

$$\beta_1^{(k+1)} = \arg \min_{\beta} f(\beta, \beta_2^k, \beta_3^k, \dots, \beta_p^k)$$

$$\beta_2^{(k+1)} = \arg \min_{\beta} f(\beta_1^k, \beta, \beta_3^k, \dots, \beta_p^k)$$

$$\beta_3^{(k+1)} = \arg \min_{\beta} f(\beta_1^k, \beta_2^k, \beta, \dots, \beta_p^k)$$

$$\vdots$$

$$\beta_p^{(k+1)} = \arg \min_{\beta} f(\beta_1^k, \beta_2^k, \beta_3^k, \dots, \beta)$$



Consider the optimization along a single coordinate (with the  $\frac{1}{2}$  included for convenience)

$$\begin{aligned} & \min_{\beta_i} \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda \|\boldsymbol{\beta}\|_1 \\ & \min_{\beta_i} \frac{1}{2} \sum_{l=1}^n \left( y_l - \sum_{m=1}^p x_{lm} \beta_m \right)^2 + \lambda \sum_{k=1}^p |\beta_k| \quad (*) \end{aligned}$$

Differentiating the first term in (\*) with respect to  $\beta_i$ :

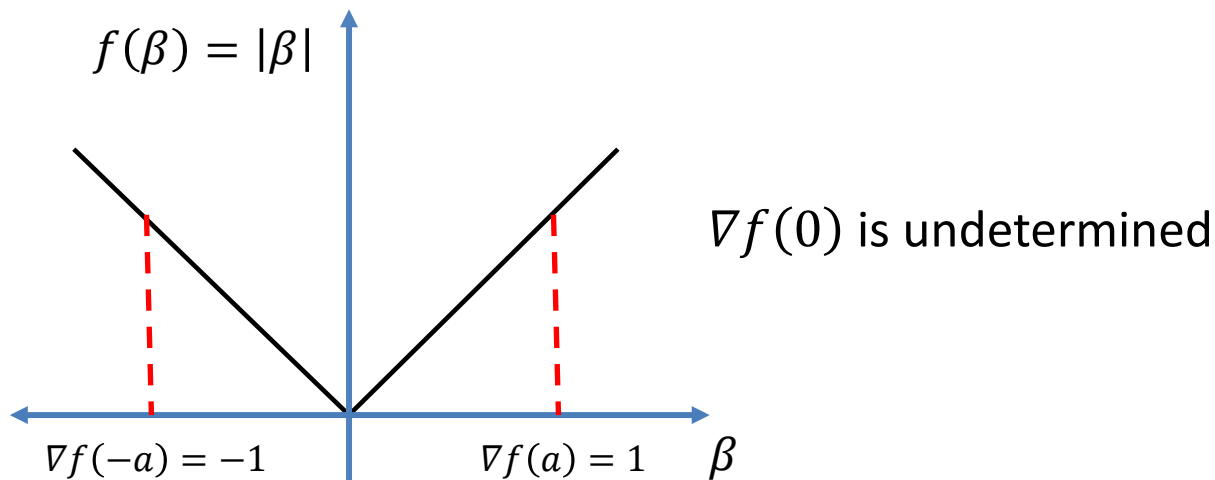
$$\begin{aligned} \frac{\partial}{\partial \beta_i} \frac{1}{2} \sum_{l=1}^n \left( y_l - \sum_{m=1}^p x_{lm} \beta_m \right)^2 &= \sum_{l=1}^n \left( y_l - \sum_{m=1}^p x_{lm} \beta_m \right) (-x_{li}) \\ &= \mathbf{X}_i^T (\mathbf{X}\boldsymbol{\beta} - \mathbf{y}) \\ &= \mathbf{X}_i^T (\mathbf{X}_{-i}\boldsymbol{\beta}_{-i} - \mathbf{y}) + \mathbf{X}_i^T \mathbf{X}_i \beta_i, \end{aligned}$$

where  $\mathbf{X}_{-i}$  denotes matrix  $\mathbf{X}$  excluding the  $i$ th column, and  $\mathbf{X}_i$  is the  $i$ th column of matrix  $\mathbf{X}$



Consider the second term in (\*). Note the non-differential term

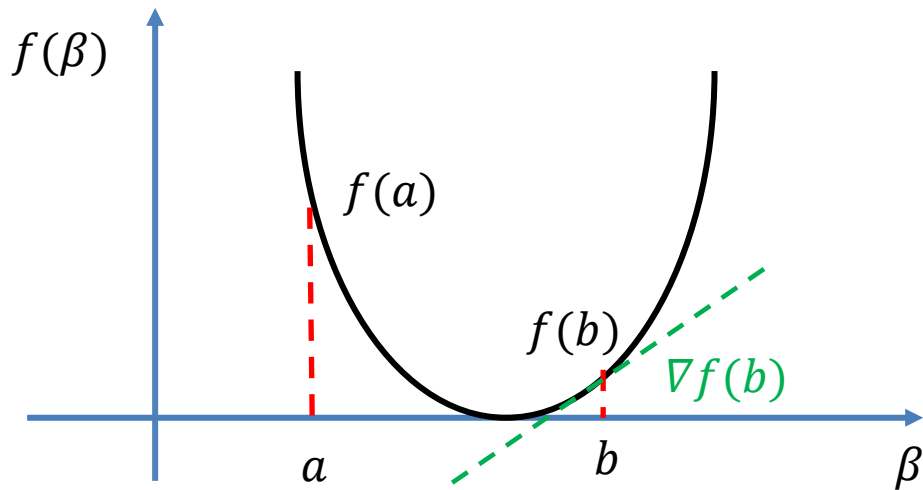
$$\frac{\partial}{\partial \beta} |\beta| = ??$$





**Convex function**

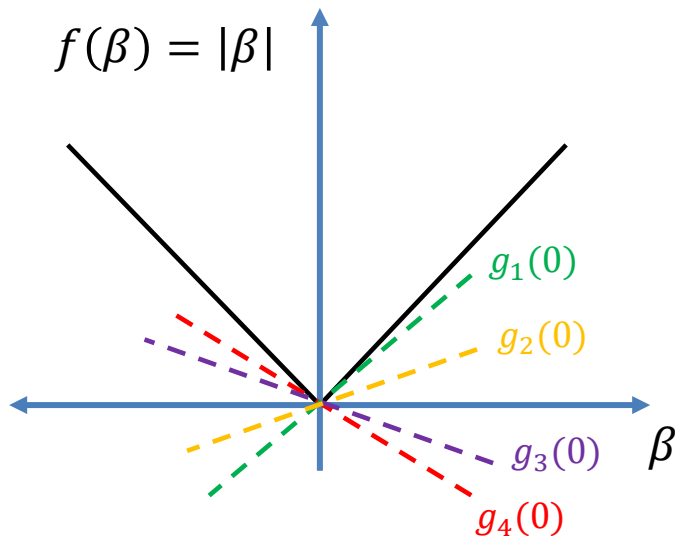
For any convex function we have that  $f(a) \geq f(b) + \nabla f(b)(a - b)$





**Subgradient:** Generalizes the concept to non-differentiable points

- $g$  is a subgradient if  $f(b) \geq f(a) + g(b - a)$
- $g(0)$ : = Any plane that lower bounds the function  $f(\beta)$  (it is a set)



$\partial f(\beta)$ : = all subgradients of  $f$  at  $\beta$

$$\partial f(\beta) = \begin{cases} -1 & \text{if } \beta < 0 \\ [-1, 1] & \text{if } \beta = 0 \\ 1 & \text{if } \beta > 0 \end{cases}$$



Define

$$f(\boldsymbol{\beta}) = \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda \|\boldsymbol{\beta}\|_1$$

and set

$$g_i = \frac{\partial}{\partial \beta_i} \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 = \mathbf{X}_i^T (\mathbf{X}_{-i} \boldsymbol{\beta}_{-i} - \mathbf{y}) + \mathbf{X}_i^T \mathbf{X}_i \beta_i$$

Complete solution has 3 cases:

$$\partial f(\beta_i) = \begin{cases} g_i - \lambda & \text{if } \beta_i < 0 \\ [g_i - \lambda, g_i + \lambda] & \text{if } \beta_i = 0 \\ g_i + \lambda & \text{if } \beta_i > 0 \end{cases}$$



To find the optimal solution, set the derivative to 0 for all 3 cases

**Case 1:**  $\beta_i < 0 \Rightarrow g_i - \lambda = 0$

$$g_i - \lambda = 0 \Leftrightarrow \beta_i = \frac{\mathbf{x}_i^T (\mathbf{y} - \mathbf{X}_{-i} \boldsymbol{\beta}_{-i}) + \lambda}{\mathbf{x}_i^T \mathbf{x}_i} = \tilde{g}_i + \frac{\lambda}{\|\mathbf{x}_i\|^2}$$

where  $\tilde{g}_i = \frac{\mathbf{x}_i^T (\mathbf{y} - \mathbf{X}_{-i} \boldsymbol{\beta}_{-i})}{\mathbf{x}_i^T \mathbf{x}_i}$

**Case 2:**  $\beta_i > 0 \Rightarrow g_i + \lambda = 0$

$$g_i + \lambda = 0 \Leftrightarrow \beta_i = \frac{\mathbf{x}_i^T (\mathbf{y} - \mathbf{X}_{-i} \boldsymbol{\beta}_{-i}) - \lambda}{\mathbf{x}_i^T \mathbf{x}_i} = \tilde{g}_i - \frac{\lambda}{\|\mathbf{x}_i\|^2}$$



**Case 3:**  $\beta_i = 0 \Rightarrow 0 \in [g_i - \lambda, g_i + \lambda]$  — need to prove conditions guaranteeing 0 is in this set

Consider the boundaries of Cases 1 & 2, and suppose:  $-\frac{\lambda}{\|\mathbf{X}_i\|^2} < \tilde{g}_i < \frac{\lambda}{\|\mathbf{X}_i\|^2}$

$$\begin{aligned} -\frac{\lambda}{\|\mathbf{X}_i\|^2} < \tilde{g}_i < \frac{\lambda}{\|\mathbf{X}_i\|^2} &\Leftrightarrow -\frac{\lambda}{\|\mathbf{X}_i\|^2} < \frac{\mathbf{X}_i^T(\mathbf{y} - \mathbf{X}_{-i}\boldsymbol{\beta}_{-i})}{\mathbf{X}_i^T\mathbf{X}_i} < \frac{\lambda}{\|\mathbf{X}_i\|^2} \\ &\Leftrightarrow -\lambda < \mathbf{X}_i^T(\mathbf{y} - \mathbf{X}_{-i}\boldsymbol{\beta}_{-i}) < \lambda \quad (*) \end{aligned}$$

Recall  $g_i = \mathbf{X}_i^T(\mathbf{X}_{-i}\boldsymbol{\beta}_{-i} - \mathbf{y}) + \mathbf{X}_i^T\mathbf{X}_i\beta_i$

Thus  $\beta_i = 0 \Rightarrow g_i = -\mathbf{X}_i^T(\mathbf{y} - \mathbf{X}_{-i}\boldsymbol{\beta}_{-i})$  and combining with (\*)

$$-\lambda < -g_i < \lambda \Rightarrow 0 \in [g_i - \lambda, g_i + \lambda]$$

Therefore we have shown that  $0 \in \partial f(\beta_i)$  for  $\beta_i = 0$  if  $-\frac{\lambda}{\|\mathbf{X}_i\|^2} < \tilde{g}_i < \frac{\lambda}{\|\mathbf{X}_i\|^2}$



Combining the 3 cases yields the Lasso shrinkage optimization

$$\hat{\beta}_i = \begin{cases} \tilde{g}_i + \frac{\lambda}{\|\mathbf{X}_i\|^2} & \text{if } \tilde{g}_i < -\frac{\lambda}{\|\mathbf{X}_i\|^2} \\ 0 & \text{if } -\frac{\lambda}{\|\mathbf{X}_i\|^2} < \tilde{g}_i < \frac{\lambda}{\|\mathbf{X}_i\|^2} \\ \tilde{g}_i - \frac{\lambda}{\|\mathbf{X}_i\|^2} & \text{if } \tilde{g}_i > \frac{\lambda}{\|\mathbf{X}_i\|^2} \end{cases}$$

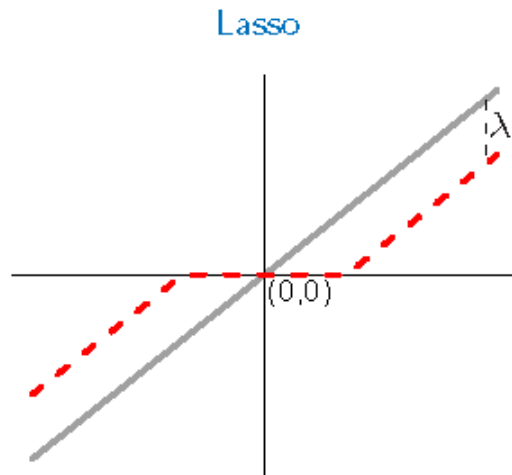
where  $\tilde{g}_i = \frac{\mathbf{x}_i^T (\mathbf{y} - \mathbf{X}_{-i} \boldsymbol{\beta}_{-i})}{\mathbf{x}_i^T \mathbf{x}_i}$

The solution can be expressed in terms of the soft thresholding operator

$$\hat{\beta}_i = \eta_{\lambda/\|\mathbf{x}_i\|^2}^S(\tilde{g}_i) = \eta_{\lambda/\|\mathbf{x}_i\|^2}^S \left( \frac{\mathbf{x}_i^T (\mathbf{y} - \mathbf{X}_{-i} \boldsymbol{\beta}_{-i})}{\mathbf{x}_i^T \mathbf{x}_i} \right)$$



Thus for  $\hat{\beta}_i = \eta_{\lambda/\|\mathbf{x}_i\|^2}^S(\tilde{g}_i)$  we use  
the **Soft-Thresholding** operator



$$\eta_{\lambda}^S(\beta) = \text{sign}(\beta)(|\beta| - \lambda)_+ = \begin{cases} \beta + \lambda & \text{if } \beta < -\lambda \\ 0 & \text{if } -\lambda < \beta < \lambda \\ \beta - \lambda & \text{if } \beta > \lambda \end{cases}$$



**Final Result:** Apply cyclic coordinate descent to obtain the lasso solution

$$\begin{aligned}\beta_1^{(k+1)} &= \eta_{\lambda/\|\mathbf{x}_1\|^2}^S(\tilde{g}_1) \\ \beta_2^{(k+1)} &= \eta_{\lambda/\|\mathbf{x}_2\|^2}^S(\tilde{g}_2) \\ &\vdots \\ \beta_p^{(k+1)} &= \eta_{\lambda/\|\mathbf{x}_p\|^2}^S(\tilde{g}_p),\end{aligned}$$

where  $\tilde{g}_i = \frac{\mathbf{x}_i^T(\mathbf{y} - \mathbf{X}_{-i}\boldsymbol{\beta}_{-i})}{\mathbf{x}_i^T \mathbf{x}_i}$

$\Rightarrow$  cycle through the coordinates until convergence