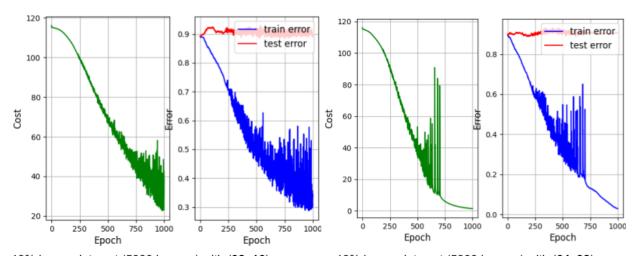
Assignment requirement:

- A. Increase the number of neurons in the two hidden layers from (32, 16) to (64, 32), compare the training/testing error in the two cases, and explain it.
 - a. For 10% of the total image data set and hidden layers 32, 16 we get pretty terrible results with both the training data set and testing data set.
 - b. For 10% of the total image data set and hidden layers 64, 32 we get a much better accuracy for the training data set but our testing error is still garbage
 - c. The testing error/accuracy is terrible and makes sense considering weve decreased our sample size which hurts the generalization of our model



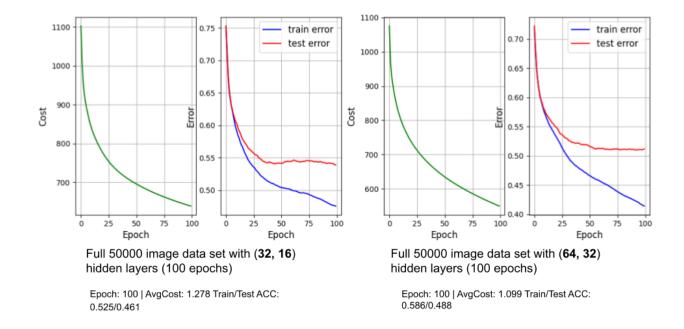
10% image data set (5000 images) with (**32, 16**) hidden layers (1000 epochs)

Epoch: 1000 | AvgCost: 0.778 Train/Test ACC: 0.663/0.103

10% image data set (5000 images) with (**64, 32**) hidden layers (1000 epochs)

Epoch: 1000 | AvgCost: 0.027 Train/Test ACC: 0.971/0.094

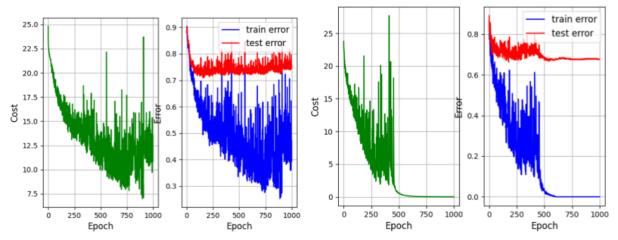
- d. For the full image data set and hidden layers 32, 16 we get much smoother accuracy curves over time. However, because it was the full data set I only did 100 epochs. It was observed for 1000 epochs that the cost and error also fluctuated quite a bit around the 500-700 epoch.
- e. For the full image data set and hidden layers 64, 32 we decrease our accuracy/ increase our error and decrease our cost by about 2 units.
- f. However, compared to the 10% data set cases, our testing error and accuracy (aka our generalization, is much better. This makes sense considering we increased our sample size which can benefit the generalization of our model



In general, increasing the neurons in each hidden layer has a positive effect on the training accuracy of our neural network but not necessary the testing accuracy.

B. Replace the sigmoid function with the ReLU function, compare the training/testing error in the two cases, and explain it.

a. Below are the results for 16 and 32 hidden layers(left) and 64 32 hidden layers(right). Compared to the sigmoid function (for the 64/32 case), with the all other variables held the same, it seems that the using the Relu activation function converges faster than the sigmoid function. That is, it brings the cost quicker to zero. It also seems that it has has generalized better than the sigmoid function by observing the increase in testing accuracy.



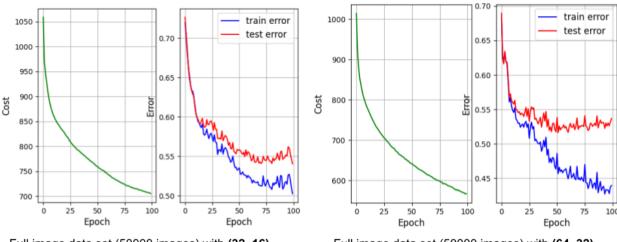
10% image data set (5000 images) with (32, 16) hidden layers (1000 epochs) Relu Func

10% image data set (5000 images) with (64, 32) hidden layers (1000 epochs) Relu Func

Epoch: 1000 | AvgCost: 1.084 Train/Test

Epoch: 1000 | AvgCost: 0.001 Train/Test ACC: 0.528/0.240 ACC: 1.000/0.324

b. Below, we can see that results after using the full data set. There seems to be very little difference between the above graphs which use the Relu function and the sigmoid graphs in part A. The only noticeable difference is the increase in chatter in the accuracy for both the trained and testing results.



Full image data set (50000 images) with (32, 16) hidden layers (100 epochs) Relu Func

Full image data set (50000 images) with (64, 32) hidden layers (100 epochs) Relu Func

Epoch: 100 | AvgCost: 1.411 Train/Test ACC: 0.497/0.459

Epoch: 100 | AvgCost: 1.134 Train/Test ACC:

Below are screenshots of my code. Notable changes occur on lines. For example on line 73 it is required to change the size to (32, 32, 3). As a result it is necessary to add line

79: flattened = tf.layers.flatten(tf_x, name='flatten'). Also it is necessary to change how we increment batch size on lines 125 and 126.

```
mport numpy as np
mport matplotlib.pyplot as plt
   mport random
rom tensorflow.keras import datasets
rom tensorflow.keras.utils import to
                                              rt to categorical
 (train_images, train_labels), (test_images, test_labels) = datasets.cifar10.load_data()
 test_images = np.array(random.sample(list(test_images),1000))
test_labels = np.array(random.sample(list(test_labels),1000))
train_labels = to_categorical(train_labels, 10)
test_labels = to_categorical(test_labels, 10)
print(train_labels[0])
print(train_images.shape)
print(train_labels.shape)
print(test_images.shape)
print(test_labels.shape)
 # Hyperparameters
training_epochs = 50
learning_rate = 0.1
batch_size = 100
 img_h = img_w = 32
n_input = 32, 32, 3
n_hidden_1 = 64
n_hidden_2 = 32
n_classes = 10
      tf_x = tf.placeholder(tf.float32, [None.32.32.3], name='features')
      tf_y = tf.placeholder(tf.float32, [None,n_classes], name='targets')
     fc1 = tf.layers.dense(inputs=flattened, units=n_hidden_1, activation=tf.nn.sigmoid, name='fc1')
      fc2 = tf.layers.dense(inputs=fc1, units=n_hidden_2, activation=tf.nn.sigmoid, name='fc2')
       out_layer = tf.layers.dense(inputs=fc2, units=n_classes, activation=None, name='out_layer')
      # Cost and optimizer
loss = tf.nn.softmax_cross_entropy_with_logits(logits=out_layer, labels=tf_y)
cost = tf.reduce_mean(loss, name='cost')
      # Training method is gradient descent
optimizer = tf.train.GradientDescentOptimizer(learning_rate=learning_rate)
train = optimizer.minimize(cost, name='train')
      correct prediction = tf.equal(tf.argmax(tf.y, 1), tf.argmax(out layer, 1))
      saver = tf.train.Saver()
 cost_vector = np.zeros(training_epochs)
train_acc_vector = np.zeros(training_epochs)
test_acc_vector = np.zeros(training_epochs)
```

```
loss = tf.nn.softmax_cross_entropy_with_logits(logits=out_layer, labels=tf_y)
    cost = tf.reduce_mean(loss, name='cost'
    optimizer = tf.train.GradientDescentOptimizer(learning rate=learning rate)
    train = optimizer.minimize(cost, name='train')
    correct_prediction = tf.equal(tf.argmax(tf_y, 1), tf.argmax(out_layer, 1))
    accuracy = tf.reduce_mean(tf.cast(correct_prediction, tf.float32), name='accuracy')
    saver = tf.train.Saver()
cost_vector = np.zeros(training_epochs)
train_acc_vector = np.zeros(training_epochs)
 test_acc_vector = np.zeros(training_epochs)
with tf.Session(graph=g) as sess:
    sess.run(tf.global_variables_initializer())
    for epoch in range(training_epochs):
        avg_cost = 0.
        total_batch = train_images.shape[0] // batch_size
        print(total_batch)
        for i in range(total_batch):
           bx = train_images[i*batch_size:(i+1)*batch_size]
by = train_labels[i*batch_size:(i+1)*batch_size]
            _, c = sess.run(['train', 'cost:0'], feed_dict={'features:0': bx, 'targets:0': by})
            avg cost += c
        cost_vector[epoch] = avg_cost
        print("Epoch: %03d | AvgCost: %.3f Train/Test ACC: %.3f/%.3f" % (epoch + 1, avg_cost / (i + 1),train_acc_vec
Fontsize = 12
fig, _axs = plt.subplots(nrows=1, ncols=2)
axs = _axs.flatten()
l01, = axs[0].plot(range(training_epochs), cost_vector,'g')
axs[0].set_xlabel('Epoch',fontsize=Fontsize)
axs[0].set_ylabel('Cost',fontsize=Fontsize)
axs[0].grid(True)
l11, = axs[1].plot(range(training_epochs), 1-train_acc_vector,'b')
l12, = axs[1].plot(range(training_epochs), 1-test_acc_vector,'r')
axs[1].set_xlabel('Epoch',fontsize=Fontsize)
axs[1].set_ylabel('Error',fontsize=Fontsize)
axs[1].grid(True)
axs[1].legend(handles = [ll1, ll2], labels = ['train error', 'test error'],loc = 'upper right', fontsize=Fontsize)
plt.show()
```

I would also like to note that implementing the neural network using keras sequential model, was 10 times easier to implement and used less code than the code you supplied and resulted in even better training performance. I.e. model = models. Sequential(). I achieved upwards of 70% accuracy for both training and testing.