

# Representation Theory and its Applications in Physics

June 5, 2024

CPTitlePage169

**Presented by**

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## **Outline:**

1. Introduction to Representation Theory
2. Examples in Physics
3. The Braid Group
4. Physical Applications of the Braid Group



# Definition of a Representation

## Definition

Let  $G$  be a group. A *representation* of  $G$  is a homomorphism from  $G$  to a group of operators on a linear vector space  $V$ . The dimension of  $V$  is the *dimension* or *degree* of the representation.

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If  $X$  is a representation of  $G$  on a vector space  $V$ , then  $X$  is a map

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## Remark

If  $V$  is finite-dimensional with basis  $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$ , then  $X$  can be realized as an  $n \times n$  matrix.

# Properties of Representations

## Group Multiplication

Representations are group morphisms, so they satisfy the group multiplication rule:

$$X(gh) = X(g)X(h), \quad \forall g, h \in G.$$

## Invertibility

If  $X$  is a representation of  $G$ , then  $X(g)^{-1} = X(g^{-1})$ ,  $\forall g \in G$ .

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2. In the matrix presentation of  $X$ ,  $X(g)$  is invertible for all  $g \in G$ .

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- ▶ For groups with more than one element, the trivial representation is not injective, so we call it a *degenerate representation*.
- ▶ If a representation is injective, then it is a *faithful representation*.



## Example: A Faithful Representation of $S_n$

### Defining representation of $S_n$

The defining representation  $D$  of  $S_n$  encodes the action of the symmetric group on the standard basis of  $\mathbb{R}^n$ . If a permutation sends  $i$  to  $j$ , then place a 1 the  $i$ -th column and  $j$ -th row of the representation matrix.

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E.g., in  $S_3$ :

$$D((23)) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \quad D((123)) = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

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- ▶ The defining representation of  $S_n$  is  $n$ -dimensional.
- ▶ This representation is faithful.

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**Representation:** Let  $X$  be a representation of  $R$  on  $V_2$  with<sup>1</sup>

$$X(\phi)\mathbf{e}_1 = \mathbf{e}_1 \cdot \cos \phi + \mathbf{e}_2 \cdot \sin \phi$$

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$$\left. \begin{aligned} X(\phi)\mathbf{e}_1 &= \mathbf{e}_1 \cdot \cos \phi + \mathbf{e}_2 \cdot \sin \phi \\ X(\phi)\mathbf{e}_2 &= -\mathbf{e}_1 \cdot \sin \phi + \mathbf{e}_2 \cdot \cos \phi \end{aligned} \right\} \Rightarrow \boxed{X(\phi) = \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix}}$$

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## Question

How do we classify representations of a group?

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- ▶ If two representations have the same character for all  $g \in G$ , then they are equivalent.
- ▶ We can use characters to classify representations.

# Decomposing Representations

## Definition

A representation  $X(G)$  on  $V$  is *irreducible* if there is no non-trivial invariant subspace<sup>2</sup> in  $V$  with respect to  $X(G)$ . Otherwise,  $X(G)$  is *reducible*.

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## Comments:

- ▶ Irreducible representations are the building blocks of all representations.
- ▶ A reducible representation can be decomposed into a direct sum of irreducible representations.
- ▶ The decomposition of a representation into irreducibles is unique up to equivalence.

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## Invariance of $\mathbf{e}_{\pm}$

Let  $\mathbf{e}_{\pm} = \frac{1}{\sqrt{2}} (\mp \mathbf{e}_1 + i \mathbf{e}_2)$ . Then,  $X(\phi) \mathbf{e}_{\pm} = e^{\pm i\phi} \mathbf{e}_{\pm}$ .

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## Decomposition of $X$

The span of each  $\mathbf{e}_{\pm}$  is an  $X$ -invariant subspace of  $V_2$ . In this basis, we rewrite  $X$  as a direct sum of the 1D irreducible representations<sup>3</sup>:

$$X(\phi) = \begin{bmatrix} e^{i\phi} & 0 \\ 0 & e^{-i\phi} \end{bmatrix}.$$

---

<sup>3</sup>1-dimensional representations are always irreducible!

# Schur's Lemmas (pt. 1)

## Lemma

*Let  $X : G \rightarrow V$  and  $Y : G \rightarrow W$  be irreducible representations of a group  $G$ . If there exists a fixed linear transformation  $T : V \rightarrow W$  such that  $TX(g) = Y(g)T$  for all  $g \in G$ , then  $T$  is either the zero map or invertible.*

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1. The kernel of  $T$  is invariant under  $X(G)$ .
2. The image of  $T$  is invariant under  $Y(G)$ .
3. Since  $X$  and  $Y$  are irreducible,  $\ker(T) = \{\mathbf{0}\}$  and  $\text{im}(T) = V$  or  $\ker(T) = V$  and  $\text{im}(T) = \{0\}$ .

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1. The kernel of  $T$  is invariant under  $X(G)$ .
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4. By the rank-nullity theorem, conclude that  $T$  is either the zero map or invertible.

# Schur's Lemma's (pt. 2)

## Lemma

*Let  $X$  be an irreducible representation of a group  $G$  and  $T$  a linear operator that commutes with all  $X(g)$  for  $g \in G$ . Then  $T$  is a scalar multiple of the identity operator.*

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2. Then  $T - \lambda I$  is not invertible.
3. By assumption,  $(T - \lambda I)X(g) = X(g)(T - \lambda I)$  for all  $g \in G$ .

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## Proof (sketch)

1. Consider  $\lambda$  to be an eigenvalue of  $T$ .
2. Then  $T - \lambda I$  is not invertible.
3. By assumption,  $(T - \lambda I)X(g) = X(g)(T - \lambda I)$  for all  $g \in G$ .
4. By previous lemma,  $T - \lambda I = 0 \implies T = \lambda I$ .



# Consequence of Schur's Lemmas

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6. One-dimensional representation are irreducible.



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## How does this help in physics?

Irreducible representations can describe symmetries of physical systems with remarkably fundamental implications.

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# Preliminaries

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- ▶ The action of an operator  $A$  on a vector  $|\psi\rangle$  is written as  $|A\psi\rangle = A|\psi\rangle$ .
- ▶ Equivalent ways to write the same thing:

$$\langle A^\dagger \phi | \psi \rangle = \langle \phi | A | \psi \rangle = \langle \phi | A \psi \rangle .$$

# Orthonormality, Completeness, and Wavefunctions

## Definition

Let  $\{|1\rangle, |2\rangle, |3\rangle, \dots\}$  be an orthonormal basis for some quantum Hilbert space. In the context of physics, the **orthonormality** and **completeness** relations of the basis vectors allow any state vector  $|\psi\rangle$  to be written as a linear combination of the basis vectors:

$$|\psi\rangle = \left( \sum_n |n\rangle \langle n| \right) |\psi\rangle = \sum_n |n\rangle \langle n|\psi\rangle,$$

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## Definition

For a continuous basis labelled by  $|x\rangle$  where  $x$  is a continuous parameter, the **wavefunction**  $\psi(x)$  is the projection:  $\langle x|\psi\rangle = \psi(x)$ .

# Preliminaries: Basic Quantum Mechanics

- Talk about probabilities and whatnot? Eigenvalues = observables? Or just mention when connecting later stuff to physics?

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This *special* property is summarized by noting  $\det R(\phi) = 1$  for all  $\phi \in [0, 2\pi)$ .

# The $SO(2)$ Group

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The *special orthogonal group* in two dimensions, denoted  $SO(2)$ , is the group of all  $2 \times 2$  orthogonal matrices with determinant equal to  $+1$ .<sup>5</sup>

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- ▶  $\text{SO}(2)$  is *reducible* (earlier example with  $\mathbf{e}_{\pm}$ ).

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- ▶ With  $R(0) = I$  boundary condition:  $R(\phi) = e^{-i\phi J}$ .
- ▶ We call  $J$  the *generator* of SO(2) rotations.

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To first order in  $d\phi$ :  $R(d\phi) = \begin{bmatrix} 1 & -d\phi \\ d\phi & 1 \end{bmatrix}$



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$$\begin{aligned} R(\phi) &= e^{-iJ\phi} = I - iJ\phi - I\frac{\phi^2}{2!} + iJ\frac{\phi^3}{3!} + \dots \\ &= I \left( \sum_{n=0}^{\infty} (-1)^n \frac{\phi^{2n}}{(2n)!} \right) - iJ \left( \sum_{n=0}^{\infty} (-1)^n \frac{\phi^{2n+1}}{(2n+1)!} \right) \end{aligned}$$

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$$\begin{aligned} R(\phi) &= e^{-iJ\phi} = I - iJ\phi - I\frac{\phi^2}{2!} + iJ\frac{\phi^3}{3!} + \dots \\ &= I \left( \sum_{n=0}^{\infty} (-1)^n \frac{\phi^{2n}}{(2n)!} \right) - iJ \left( \sum_{n=0}^{\infty} (-1)^n \frac{\phi^{2n+1}}{(2n+1)!} \right) \\ &= I \cos \phi - iJ \sin \phi \end{aligned}$$

# Recovering the Rotation Matrix from $J$

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**Process to obtaining irreducibles:**

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## Theorem

*The single-valued irreducible representations of  $SO(2)$  are defined as*

$$U^m(\phi) = e^{-im\phi}, \forall m \in \mathbb{Z}.$$

# Generalization to 3 Spatial Dimensions

- ▶ Show but don't derive  $R_n(\theta)$  decomposition into  $\mathbf{J}$  components.
- ▶ We have basis from the components of  $\mathbf{J}$ .
- ▶ Ladies and gentlemen, we got  $SO(3)$ ...
- ▶  $\mathbf{J}$  component differential forms?
- ▶ Commutation relations, in some form talk about  $J_{\pm}$ ,  $J^2$  and final eigenvalue results.

# Conservation of Angular Momentum

I think it makes most sense to do this after generalizing to 3D...

Let  $V$  be the vector space that  $U^m$  acts on.

- The Hermiticity of  $J$  allows us to obtain an eigenbasis of  $V$

# Connection to Quantum Mechanics

- ▶ Discuss connection between generators and quantum operators, eigenvalues and classical observables, discretization (!), etc.
- ▶ This is the kicker. I will get very excited here probably.

# Multi-valued Irreducible Representations and Spinors

Not sure where to put this. . .

- ▶ Let's come back to  $SO(2)$  for a second. . .
- ▶ Show  $m = 1/2$  irreps.
- ▶ Discuss implications, spinors, etc. . .





# Basic Definitions

- ▶ Formal definitions.
- ▶ Physical/intuitive visualization and interpretation.
- ▶ Standard generators.
- ▶ Automorphisms of  $\pi_1(\mathbb{D}_n)$ .
- ▶ Braid relations in this picture.
- ▶ 1D Reps.
- ▶ Burau representation.
- ▶ Note on faithfulness.
- ▶ Unitary representation from reduced Burau.



# Rotations of Quantum Hilbert Space

- ▶ 1D action on Hilbert space, permuting particles, compare/contrast to bosons/fermions.
- ▶ Talk about nontrivial braiding effects.
- ▶ Example of unitary braid rep acting on Hilbert space.

# Anyons: A Consequence of Braiding

- ▶ Introduce anyons.
- ▶ Discuss how anyons are described by the braid group.
- ▶ Fusion rules, abelian vs nonabelian anyons.
- ▶ Non-interacting anyons.
- ▶ Non-interacting anyons in harmonic potential.
- ▶ Nontrivial braiding effects anyone?
- ▶ Applications of anyons! (quantum computing, topological quantum field theory, FQHE, etc.)

# Summary/Conclusion

Acknowledgements, questions, references (?)