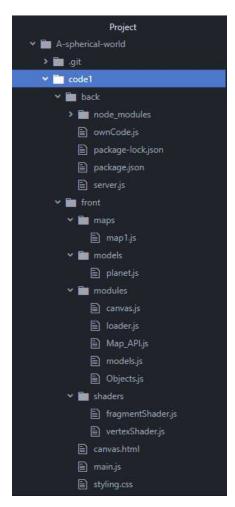
Bit by bit, and line by line

The sphere emerges...

Max Silin

Starting Structure

Folder Structure



Backbone of the application

Modularising javascript code into different files means you need a backend server to serve these files.

I am using node npm (Node Package Manager) to install the express package and leverage its power.

Express allows you to create a back end server quickly. Here, I am only serving scripts and static assets.

```
server.js

1   const express = require('express')
2   const app = express()
3   app.use(express.json())
4

5   app.use(express.static('../front'))
6

7   const PORT = 5000;
8
9   app.listen(PORT, ()=>{
10    console.log(`Listening on port ${PORT}.`)
11  })
12
```

CSS to layout and style canvas element and error box.

```
styling.css

canvas#canvas{
   height: 80%;
   width: 80%;
   margin: 5% 10%;

   info_yellow{
   width: 80%;
   margin: auto 8%;
   padding: 2%;
   background: #eeee77;
   border: solid 1px #dddd66;
   border-radius: 5px;
}
```

And of course, the main Javascript file to call, which calls every other.

```
import { Canvas } from './modules/canvas.js';
import loader from './modules/loader.js';

let myCanvas;

window.addEventListener("load", function onLoad (evt) {
    "use strict"

// Cleaning after ourselves. The event handler removes
// itself, because it only needs to run once.
window.removeEventListener(evt.type, onLoad, false);
myCanvas = new Canvas('canvas');
if (!myCanvas.WebGLAvailable){
    // Show fallback message
    let fallbackElement = document.getElementById('WebGL_Fallback');
    fallbackElement.hidden = false;
}
const runningGame = loader(myCanvas);
};
```

It sees if WebGL is available and reports an info box if the user's browser does not use WebGL.

Some code that almost works

Loader.js

The file with the game logic.

```
loaderjs

import Map_API from '../modules/Map_API.js';
import {Object4D} from './Objects.js';

import map from '../maps/map1.js';

function loader(Canvas){

// Save meshes to renderer Canvas object.
let meshIndexes = Object.keys(map.meshes);
for (let i=0; i < meshIndexes.length; i++){
    let index = meshIndexes[i];
    let mesh = map.meshes[index];
    Canvas.add_Indexed_Mesh(index, mesh.vertices, mesh.trianglesIndexed);
}

// For first object on map only (0)
let meshIndex = Map_API.get_Object_mesh_index(0, map)
let size = Map_API.get_Object_size(0, map)
let pvuw = Map_API.get_Object_pvuw(0, map)

// Try to find mesh in Canvas object
let meshBufferLocations = Canvas.findMesh(meshIndex);</pre>
```

```
if (meshBufferLocations){
    // Do this before drawing
    function UnifromsAttribsAtDraw(gl, {attributeReferences}){
        gl.bindBuffer(gl.ARRAY_BUFFER, meshBufferLocations.vertexBufferRef);
        gl.enableVertexAttribArnay(attributeReferences['coordinates']);
        gl.vertexAttribPointer(attributeReferences['coordinates'], 4, gl.FLOAT, false, 0, 0);

        // bind the buffer containing the indices
        // this.gl.bindBuffer(gl.ARRAY_BUFFER, the_Mesh.vertexBufferRef);
        gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, meshBufferLocations.indexBufferRef);
    }

    // Draw the object
    Canvas.drawObject(UnifromsAttribsAtDraw, meshBufferLocations.trianglesIndexed.length);
}

// Let success = Canvas.drawObject(meshIndex, size, pvun)

function UnifromsAttribsAtDraw(gl, {meshBuffers}, {attributeReferences}){
        gl.bindBuffer(gl.ARRAY_BUFFER, meshBuffers[meshIndex]);
        gl.enableVertexAttribArray(attributeReferences['coordinates']);
        gl.vertexAttribPointer(attributeReferences['coordinates'], 4, gl.FLOAT, false, 0, 0);
    }

export default loader;
```

Canvas.js

Responsible for communicating with WebGL and setting up the HTML canvas.

```
compileShader(shaderSource, shaderType) {

// Get rendering context
let gl = this.gl;

// Create the shader object
var shader = gl.createShader(shaderType);

// Set the shader source code.
gl.shaderSource(shader, shaderSource);

// Compile the shader
gl.compileShader(shader);

// Check if it compiled
var success = gl.getShaderParameter(shader, gl.COMPILE_STATUS);
if (!success) {
    // Something went wrong during compilation; get the error
    throw "could not compile shader:" + gl.getShaderInfoLog(shader);
}

return shader;
}
```

```
createProgram() {
    let gl = this.gl;

// create a program.

var program = gl.createProgram();

// compile and attach the shaders.

// (SOURCES IMPORTED FROM EXTERNAL FILES)

var vertexShader = this.compileShader(vertexShaderSource);

gl.attachShader(program, vertexShader);

var fragmentShader = this.compileShader(fragmentShaderSource);

gl.attachShader(program, fragmentShader);

// tink the program.

gl.linkProgram(program);

// Check if it linked.

var success = gl.getProgramParameter(program, gl.LINK_STATUS);

if (!success) {

// something went wrong with the link

throw ("program failed to link:" + gl.getProgramInfoLog (program));

this.program = program;

};

this.program = program;

};
```

```
// TEST with invalid dictionary
add_AttributeReference(KeyToVarDict){
// in { key : Shader Variable Name String } dictionary
// out { key : Attribute Location Reference } dictionary
// saves in this attributeReferences

// For every attribute
let keys = Object.keys(KeyToVarDict);
for (let i=0; i < keys.length; i++){
    let key = keys[i];
    let ShaderAttributeName = KeyToVarDict[key];
// Add the Location of the attribute
this.attributeReferences[key] = this.gl.getAttribLocation(this.program, ShaderAttributeName);
}

// Indexed_Mesh(ID, vertices, trianglesIndexed){
    let gl = this.gl;
// Create and bind buffer, then add vertex coordinates.
const vertexBuffer = gl.createBuffer();
gl.bindBuffer(gl.ARRAY_BUFFER, vertexBuffer);
gl.bufferData(
gl.ARRAY_BUFFER,
new Float32Array(vertices),
gl.STATIC_DRAW</pre>
Activate

Act
```

```
const indexBuffer = gl.createBuffer();
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, indexBuffer);
gl.bufferData(
   new Uint16Array(trianglesIndexed),
   gl.STATIC DRAW
this.meshBuffers.push({meshID: ID, vertexBufferRef: vertexBuffer , indexBufferRef: indexBuffer });
findMesh(meshID){
 let found = false;
 let meshIndex = 0;
 let the Mesh;
 while ((found !== true) && (meshIndex < this.meshBuffers.length)){
    the_Mesh = this.meshBuffers[meshIndex];
   if (the_Mesh.mesh_ID === meshID){
      found = true
      return the Mesh;
 if (found !== true){
    console.log("Mesh was not found. Hey, programmer! Seems like there's a little mistake!")
```

```
drawObject(beforeDraw, numElementsToDraw){

// Call the requested function to Link correct buffers
beforeDraw(this.gl, {attributeReferences: this.attributeReferences});

let primitiveType = gl.TRIANGLES;
let offset = 0;

// Number of vertices
let indexType = gl.UNSIGNED_SHORT;
this.gl.drawElements(primitiveType, count, indexType, offset);

// gl.drawArrays(primitiveType, offset, count);

// Success
return true;
}

export { Canvas }

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```

Planet.js.

Stores planet mesh. Contains some random data as a prototype right now.

Map1.js

Stores the objects on the map, and the meshes associated with them.

```
map1.js
import Model_planet from '../models/planet.js';
const map = {
    0: Model_planet,
 },
  objects: [
      meshIndex: 0,
      pvuw: [
        [0.0, 1.0, 0.0, 0.0],
        [1.0, 0.0, 0.0, 0.0],
        [0.0, 0.0, 0.0, 1.0],
        [0.0, 0.0, 1.0, 0.0]
      1,
      size: 0.5,
export default map;
```

Map_API.js

A set of useful functions for handling map objects.

```
map_APljs

function get_Object_mesh_index(objectIndex, map){
    return map.objects[objectIndex].meshIndex;

}
function get_Object_size(objectIndex, map){
    return map.objects[objectIndex].size;

}
function get_Object_pvuw(objectIndex, map){
    return map.objects[objectIndex].pvuw;

}

function get_Object(objectIndex, map){
    return map.objects[objectIndex];

}

const Map_API = {get_Object_mesh_index, get_Object_pvuw, get_Object_size};

export default Map_API;
```

Otherfiles

Some files, like models.js, are currently empty.

Testing.

When testing, the window remains blank, and the loader keeps going. There is a slow down in the sensitivity of the mouse. This seems to imply that an infinite loop is taking over the processing power.

I have found the error to be here:

```
findMesh(meshID){
    // Find buffers to use
    // using linear search
let found = false;
let meshIndex = 0;
let the_Mesh;
    while ((found !== true) && (meshIndex < this.meshBuffers.length)){
    the_Mesh = this.meshBuffers[meshIndex];
    if (the_Mesh.mesh_ID === meshID){
        found = true
        return the_Mesh;
    }
}
if (found !== true){
    console.log("Mesh was not found. Hey, programmer! Seems like there's a little mistake!")
    return undefined;
}
</pre>
```

Correction: add meshIndex = meshIndex + 1 at the end of the loop.

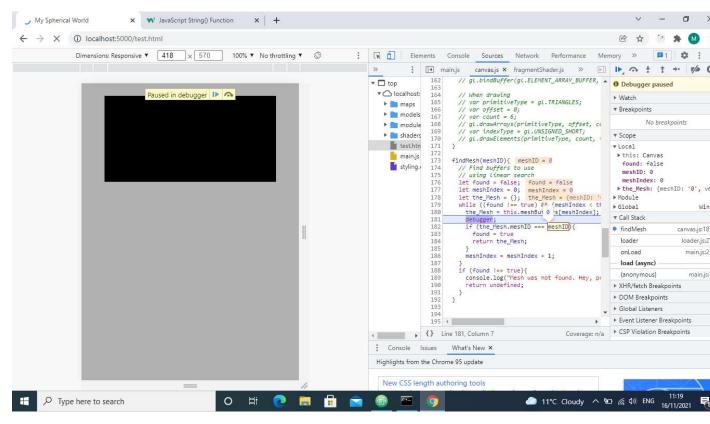
Another error:

```
Created <a href="main.js:28">canvas.js:28</a>
Mesh was not found. Hey, programmer! Seems like there's a little mistake!
Canvas.js:189
Done
main.js:22
```

Correction: meshID instead of mesh_ID.

```
findMesh(meshID){
    // Find buffers to use
    // using Linear search
    let found = false;
    let meshIndex = 0;
    let the_Mesh = {};
    while ((found !== true) && (meshIndex < this.meshBuffers.length)){
        the_Mesh = this.meshBuffers[meshIndex];
        if (the_Mesh.meshID === meshID){
            found = true
                return the_Mesh;
        }
        meshIndex = meshIndex + 1;
    }
    if (found !== true){
        console.log("Mesh was not found. Hey, programmer! Seems like there's a little mistake!")
        return undefined;
    }
}</pre>
```

Error: Same. Checking debugger:



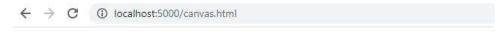
One is a string but one is an integer. They are not equal.

Correction: toString()

```
findMesh(meshID){
    // Find buffers to use
    // using linear search
    let found = false;
    let meshIndex = 0;
    let the_Mesh = {};
    while ((found !== true) && (meshIndex < this.meshBuffers.length)){
        the_Mesh = this.meshBuffers[meshIndex];
        debugger;
    if (the_Mesh.meshID === meshID.toString()){
        found = true
        return the_Mesh;
    }
    meshIndex = meshIndex + 1;
}
if (found !== true){
    console.log("Mesh was not found. Hey, programmer! Seems like there's a little mistake!")
    return undefined;
}
</pre>
```

Added a fragment shader to colour further objects darker, just to test.

Outcome:





More coherent vertex and fragment shader testing

I have made a tetrahedron of width 1.0 as a test polyhedron for the algorithm. I am going to check whether it renders correctly.

I made a new method Canvas.add_UniformReference to allow the program to fetch the GPU locations (addresses) of uniforms to write data to the uniform when needed.

```
// TEST with invalid dictionary
add_UniformReference(KeyToVarDict){
// in { key : Shader Variable Name String } dictionary
// out { key : Uniform Location Reference } dictionary
// saves in this.uniformReferences

// For every uniform
let keys = Object.keys(KeyToVarDict);
for (let i=0; i < keys.length; i++){
let key = keys[i];
let ShaderUniformName = KeyToVarDict[key];
// Add the Location of the uniform
this.uniformReferences[key] = this.gl.getUniformLocation(this.program, ShaderUniformName);
}

}

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}</pre>
```

Loader.js was modified to include the new uniforms - time and a rotation matrix based on time.

It also now has a function loop(), that runs every few milliseconds to update the scene. It only updates after 16ms have passed.

```
Canvas.add_AttributeReference({
    'coordinates': 'coordinates'
})

Canvas.add_UniformReference({
    'time': 'time',
    'rotationZX': 'rotationZX',
})

// Try to find mesh in Canvas object
let meshBufferLocations = Canvas.findMesh(meshIndex);
let numPoints = Map_API.get_Mesh_NumPoints(meshIndex, map);
const frameRate = 16; // milliseconds per frame

if (meshBufferLocations){
    let startTime = Date.now();
    let previousTime = Date.now();
```

```
// Attributes do not vary so this function can be defined once.
function At_Draw_2_setAttribs(canvasThis){
let gl = canvasThis.gl;
//canvasThis.gl.bindBuffer(gl.ARRAY_BUFFER, meshBufferLocations.vertexBufferRef);
// bind the buffer containing the indices
gl.bindBuffer(gl.ARRAY_BUFFER, meshBufferLocations.vertexBufferRef);
gl.enableVertexAttribArray(canvasThis.attributeReferences['coordinates']);
gl.vertexAttribPointer(canvasThis.attributeReferences['coordinates'], 3, gl.FLOAT, false, 0, 0);

gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, meshBufferLocations.indexBufferRef);

gl.enable(gl.OEPTH_TEST);

gl.useProgram(canvasThis.program);
}

function loop(){

let timeNow = Date.now();
let dt = timeNow - previousTime;
let elapsedTime = timeNow - startTime;

if (dt >= frameRate){

// iniferent warm so must be recalculated event loop.
```

The vertex shader rotates the starting coordinates by the matrix rotationZX, and sinusoidally displaces the shape from the origin with time.

```
main.js loader.js vertexShader.js

const vertexShader = `

attribute vec3 coordinates;
uniform float time;
uniform mat3 rotationZX;
varying vec3 coords;

void main() {
    vec3 c_2 = rotationZX * coordinates;
    gl_Position = vec4(c_2.x + rotationZX[2][0]/3.0, c_2.y, c_2.z, 1.0);
    coords = coordinates;
}

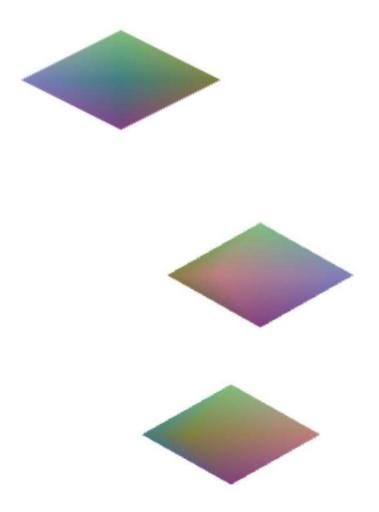
coords = coordinates;

export {vertexShader};
```

The fragment shader uses the coordinates of a point to colour in the shape. Gl_FragColor is in RGBA mode, with floats from 0.0 to 1.0 acting as colours.

The result is almost as expected. It is a rotating diamond. The thing I didn't expect is that WebGL stretches the shape to the size of the canvas, so gl_Position is actually the % position from the centre, resulting in a stretched shape.

To solve this, I can specify the screen width and height into the vertex shader. I will do this when I actually have a meaningful vertex shader.



Code Refactoring

I have refactored my code to be able to draw multiple objects easily.

```
loader.js
import Map_API from '../modules/Map_API.js';
import {Object4D} from './Objects.js';
import map from '../maps/map1.js';
function loader(Canvas){
  let meshIndexes = Object.keys(map.meshes);
 for (let i=0; i < meshIndexes.length; i++){
   let index = meshIndexes[i];
   let mesh = map.meshes[index];
   Canvas.add_Indexed_Mesh(index, mesh.vertices, mesh.trianglesIndexed);
  Canvas.add_AttributeReference({
   'coordinates': 'coordinates'
  Canvas.add UniformReference({
    'time': 'time',
    'rotationZX': 'rotationZX',
    'object_pvuw': 'object_pvuw',
    'camera_pvuw': 'camera_pvuw'
  let amount_of_objects = Map_API.get_num_Objects(map);
  let processed objects = []
```

```
// Turn map objects into list of those ready for processing

let amount_of_objects = Map_API.get_num_Objects(map);

let processed_objects = []

for (let i=0; ixamount_of_objects; i++){

    // Find mesh reference in preloaded meshes

let meshIndex = Map_API.get_Object_mesh_index(i, map)

let meshBufferLocations = Canvas.findMesh(meshIndex);

if (meshBufferLocations){

    // Only add if mesh was found

    // map_object_index to access map properties like position

    // meshBufferLocations to access gl vertex rendering function

processed_objects.push({

    map_object_index: i,

    meshBufferLocations: meshBufferLocations
}

}

// Player with no mesh but acting as a camera

let Player_pvuw =

[

    0.0, 0.0, 0.0, 0.0,

    0.0, -1.0, 0.0, 0.0,

    0.0, -1.0, 0.0,

    0.0, 0.0, -1.0, 0.0,

    0.0, 0.0, -1.0, 0.0,

    0.0, 0.0, -1.0, 0.0,

    10, 0.0, 0.0, 0.0,

    10, 0.0, 0.0, 0.0,

    10, 0.0, 0.0, 0.0,

    10, 0.0, 0.0, 0.0,

    10, 0.0, 0.0, 0.0,

    10, 0.0, 0.0, 0.0,

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    10, 0.0, 0.0,

    10, 0.0, 0.0,

    10, 0.0, 0.0,

    10, 0.
```

```
let startTime = Date.now();
let previousTime = Date.now();
const frameRate = 16; // milliseconds per frame

// Set up the program here
function At_Draw_1_generalSetup(canvasThis){
let gl = canvasThis.gl;
gl.useProgram(canvasThis.program);
gl.enable(gl.DEPTH_TEST);
}

// Attributes are Lists of vertices to render
function At_Draw_2_setAttribs(canvasThis, {vertexBufferRef, indexBufferRef}){
let gl = canvasThis.gl;

// vertex buffer
gl.bindBuffer(gl.ARRAY_BUFFER, vertexBufferRef);
gl.enableVertexAttribArray(canvasThis.attributeReferences['coordinates']);
gl.vertexAttribPointer(canvasThis.attributeReferences['coordinates'], 3, gl.FLOAT, false, 0, 0);

// Index buffer
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, indexBufferRef);
}
```

```
function At_Draw_3a__setUniforms(canvasThis, {timeFromStart}){
    let gl = canvasThis.gl;
    gl.uniform1f(canvasThis.uniformReferences['time'], timeFromStart);
     Math.cos(timeFromStart/1000), 0, Math.sin(timeFromStart/1000),
     Math.sin(-timeFromStart/1000), 0, Math.cos(timeFromStart/1000)
function At_Draw_3b__setUniforms_Player(canvasThis, {Player_pvuw}){
  let gl = canvasThis.gl;
 gl.uniformMatrix4fv(canvasThis.uniformReferences['camera_pvuw'], false, Player_pvuw);
function At_Draw_3c__setUniforms_Object(canvasThis, {Object_pvuw}){
  let gl = canvasThis.gl;
  gl.uniformMatrix4fv(canvasThis.uniformReferences['object_pvuw'], false, Object_pvuw');
function At_Draw_3a__setUniforms(canvasThis, {timeFromStart}){
    let gl = canvasThis.gl;
    gl.uniformMatrix3fv(canvasThis.uniformReferences['rotationZX'], false, [
     Math.cos(timeFromStart/1000), 0, Math.sin(timeFromStart/1000),
     Math.sin(-timeFromStart/1000), 0, Math.cos(timeFromStart/1000)
function At_Draw_3b__setUniforms_Player(canvasThis, {Player_pvuw}){
 let gl = canvasThis.gl;
 gl.uniformMatrix4fv(canvasThis.uniformReferences['camera_pvuw'], false, Player_pvuw);
function At_Draw_3c__setUniforms_Object(canvasThis, {Object_pvuw}){
 let gl = canvasThis.gl;
  gl.uniformMatrix4fv(canvasThis.uniformReferences['object_pvuw'], false, Object_pvuw);
```

```
const Generate_At_Draw = ({vertexBufferRef, indexBufferRef, Player_pvuw, Object_pvuw, timeFromStart}) => (canvasThis) =
    At_Draw_1__generalSetup(canvasThis)
    At_Draw_3b__setUniforms_Player(canvasThis, {Player_pvuw: Player_pvuw})
    At_Draw_3c__setUniforms_Object(canvasThis, {Object_pvuw: Object_pvuw})
    let timeNow = Date.now();
    let dt = timeNow - previousTime;
    let elapsedTime = 0.2*(timeNow - startTime);
    if (dt >= frameRate){
     let At Draw;
      for (let i=0; i< processed_objects.length; i++){
        let object_for_drawing = processed_objects[i];
        At_Draw = Generate_At_Draw({
          vertexBufferRef: object_for_drawing.meshBufferLocations.vertexBufferRef,
          indexBufferRef: object_for_drawing.meshBufferLocations.indexBufferRef,
         Player_pvuw: Player_pvuw,
         Player_pvuw: Player_pvuw,
         Object_pvuw: Map_API.get_Object_pvuw(object_for_drawing.map_object_index, map),
         timeFromStart: elapsedTime
      Canvas.drawObject(At_Draw, object_for_drawing.meshBufferLocations.metadata.numPoints);
    previousTime = timeNow;
  requestAnimationFrame(loop)
requestAnimationFrame(loop);
```

Explanation of commands called just before drawing to screen every frame.

At_Draw_1__generalSetup (canvasThis)

+ Sets up general WebGL settings.

At Draw 2 setAttribs(canvasThis, {vertexBufferRef, indexBufferRef})

+ Tells WebGL which array of points and which array of triangles to use to draw each object.

At_Draw_3a__setUniforms(canvasThis, {timeFromStart})

+ Sets the things invariant for all points of all objects. For example, time, or orientation of object.

At_Draw_3b__setUniforms_Player (canvasThis, {Player_pvuw})

+ Sets the things invariant to do with the camera.

At_Draw_3c__setUniforms_Object (canvasThis, {Object_pvuw})

+ Sets the things invariant to do with each object.

These are combined using Generate_At_Draw for every object every draw call. All the parameters for the At_Draw_x functions are passed into this. It returns a function At_Draw to which the canvas object can be passed.

This function is passed (as before Draw) to Canvas. drawObject(before Draw, numPoints)

```
drawObject(beforeDraw, numElementsToDraw){

// Call the requested function to link correct buffers
beforeDraw(this);

let primitiveType = this.gl.TRIANGLES;
let offset = 0;

// Number of vertices
let indexType = this.gl.UNSIGNED_SHORT;
this.gl.drawElements(primitiveType, numElementsToDraw, indexType, offset);

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```

Adding a 4D Sphere Vertex Shader

```
vertexShader.js
const vertexShader = *
  attribute vec3 coordinates;
  uniform float time;
  uniform mat3 rotationZX;
 uniform mat4 camera pvuw;
  uniform mat4 object_pvuw;
 varying vec3 coords;
  float magnitude(vec4 vector){
   return sqrt(vector.x*vector.x + vector.y*vector.y + vector.z*vector.z + vector.w*vector.w);
  float det(mat2 matrix){
   return ( matrix[0].x*matrix[1].y - matrix[0].y*matrix[1].x );
  mat3 inverse(mat3 matrix) {
     vec3 row0 = matrix[0];
      vec3 row1 = matrix[1];
     vec3 row2 = matrix[2];
      vec3 minors0 = vec3(
         det(mat2(row1.y, row1.z, row2.y, row2.z)),
          det(mat2(row1.z, row1.x, row2.z, row2.x)),
          det(mat2(row1.x, row1.y, row2.x, row2.y))
      vec3 minors1 = vec3(
          det(mat2(row2.y, row2.z, row0.y, row0.z)),
          det(mat2(row2.z, row2.x, row0.z, row0.x)),
```

```
det(mat2(row2.x, row2.y, row0.x, row0.y))
           vec3 minors2 = vec3(
              det(mat2(row0.y, row0.z, row1.y, row1.z)),
              det(mat2(row0.z, row0.x, row1.z, row1.x)),
              det(mat2(row0.x, row0.y, row1.x, row1.y))
           mat3 adj;
           adj[0] =vec3(minors0.x, minors1.x, minors2.x);
           adj[1] =vec3(minors0.y, minors1.y, minors2.y);
          adj[2] =vec3(minors0.z, minors1.z, minors2.z);
          return (1.0 / dot(row0, minors0)) * adj;
<
      void main() {
        vec3 c = rotationZX * coordinates;
        vec4 direction = object pvuw * vec4(0.0, c.xyz);
        direction = direction / magnitude(direction);
        float Distance = magnitude(vec4(0.0,c));
        vec4 center = object_pvuw[0].xyzw;
        float cosD = cos(6.28+Distance*3.14);
        float sinD = sin(6.28+Distance*3.14);
        vec4 Vertex_4D_coordinates = (cosD * center) + (sinD * direction);
```

```
vertexShader.js
    // Calculating distance and direction player to object
    vec4 P1 = camera_pvuw[0].xyzw;
    vec4 P2 = Vertex_4D_coordinates;
    cosD = dot(P1, P2);
    sinD = sqrt(1.0-cosD*cosD);
    vec4 player_to_object = (P2 - (P1 * cosD))/( sinD );
    if (dot(player_to_object, camera_pvuw[1].xyzw) < 0.0) {
      // Facing wrong way
      player_to_object = -player_to_object;
    // Calculate the 3D direction from player to object
    mat3 concatenated axes;
    concatenated_axes[0] = camera_pvuw[1].xyz;
    concatenated_axes[1] = camera_pvuw[2].xyz;
    concatenated_axes[2] = camera_pvuw[3].xyz;
    mat3 invConcatAxes = inverse(concatenated_axes);
    vec3 abc = invConcatAxes * player_to_object.xyz;
    // Calculate screen coordinates
    // ...based on distance to screen
    float xy_ratio = 2.0;
    float screen_x_coord = ( abc.y / (abc.x * dist) ) / xy_ratio;
    float screen_y_coord = ( abc.z / (abc.x * dist) );
    float screen_z_coord = 0.5;
    // gl_Position = vec4(c, 1.0);
    gl_Position = vec4(screen_x_coord, screen_y_coord, screen_z_coord, 1.0);
    coords = coordinates;
export {vertexShader};
```

xy_ratio is a constant and is used to handle the **stretching bug** described earlier.

I will later make it change based on the canvas width and height.

This vertex shader displays the objects passed into the vertex shader, rotating and viewed from the Player_pvuw 4D coordinates, as if on a 4D sphere.

I can uncomment line 85 to view the shape in normal 3D coordinates.

Program to generate spherical objects

I made a program to generate a more spherical looking object of specified radius and smoothness.

It uses this algorithm...



Start with a double square based pyramid.



2. For every triangle in the structure...



Select the midpoints of the lines making the triangle.



4. Extrude midpoints to sphere.



5. Make four triangles using these new vertices, and the old vertices.



 Repeat the process for these new triangles to make the shape smoother and smoother.

I have programmed it in python.

```
NUM ITERATIONS = 1
RADIUS = 0.1
# Use iterative vertex generation method with triangles
# Every triangle becomes four triangles
# Vertex Position (3D) array. Every 3 floats are one coordinate.
    0.0, 0.0, RADIUS,
    0.0, RADIUS, 0.0,
    RADIUS, 0.0, 0.0,
    0.0, 0.0, -RADIUS,
    0.0, -RADIUS, 0.0,
    -RADIUS, 0.0, 0.0,
 # Triangles made using 3 indexed points. Indexes to _v array.
     0, 1, 2,
     3, 2, 1,
     2, 4, 0,
     1, 0, 5,
     1, 5, 3,
     4, 5, 0,
     2, 3, 4,
 # Above is a starting solid
 # Below is excitement!
 for hmm in range(NUM ITERATIONS):
     # Make a new point for every pair of connected vertices
     # lines_visited stores [[v1, v2, newVertexIndex]...]
     lines_visited = []
     _i_new = []
     for tri_index in range(len(_i)//3):
         # For every side of triangle, check and make new vertex.
         # Store their indexes temporarily here as [[v1, v2, vN]...]
         midpoints = []
         for connection in [0, 1, 2]:
             line = [_i[3*tri_index + (connection)%3], _i[3*tri_index + (connection+1)%3]]
             result = find Line found vN reversed(lines visited, line)
```

```
if result[0] == True: # found
          vN = result[1] # mid vertex index
      else: # not found
          vN coords = generate new vertex coords from other two(
              [v[3*line[0]], v[3*line[0] + 1], v[3*line[0] + 2]],
              [_v[3*line[1]], _v[3*line[1] + 1], _v[3*line[1] + 2]],
              RADIUS)
          vN = len(_v)//3
          _v.append(vN_coords[0])
          _v.append(vN_coords[1])
          v.append(vN coords[2])
          lines_visited.append([line[0],line[1], vN])
      # Add to list of midpoints of this triangle for next part
      midpoints.append([line[0], line[1], vN])
# Now make new triangles
# Middle Triangle
_i_new.append(midpoints[0][2])
_i_new.append(midpoints[1][2])
_i_new.append(midpoints[2][2])
# Triangle 1
_i_new.append(midpoints[0][0])
_i_new.append(midpoints[0][2])
_i_new.append(midpoints[2][2])
```

Triangle 2

Triangle 3

_i = _i_new

print(_v)
print(_i)

_i_new.append(midpoints[1][0])
_i_new.append(midpoints[1][2])
_i_new.append(midpoints[0][2])

_i_new.append(midpoints[2][0])
_i_new.append(midpoints[2][2])
_i_new.append(midpoints[1][2])

```
def find Line_found_vN_reversed(v1v2vN_list, line):
    # Tries to find the line or the line reversed in a list of lines.
    # Returns found, the vertex associated with the line, whether the line is stored reversed.
    found = False
    reversed = False
    vertex = -1
    for v1v2vN in v1v2vN_list:
        if (v1v2vN[0] == line[0]) and (v1v2vN[1] == line[1]):
            found = True
            reversed = False
            vertex = v1v2vN[2]
        elif (v1v2vN[0] == line[1]) and (v1v2vN[1] == line[0]):
            found = True
            reversed = False
            vertex = v1v2vN[2]
    return [found, vertex, reversed]
def generate new vertex coords from other two(v1, v2, radius):
    mid = [(v1[0]+v2[0]), (v1[1]+v2[1]), (v1[2]+v2[2])]
    magnitude = (mid[0]**2 + mid[1]**2 + mid[2]**2)**(0.5)
    sf = radius/magnitude
    return [sf*mid[0], sf*mid[1], sf*mid[2]]
```

NUM_ITERATIONS is the number of times to run the loop for, and corresponds to the smoothness of the shape.

RADIUS is the maximum radius of the resulting object.

The program turns one array of triangles into a completely new one every iteration.

Here is the output for radius=0.1, and 1 iteration. First is the vertex array, and second is the triangle index array.

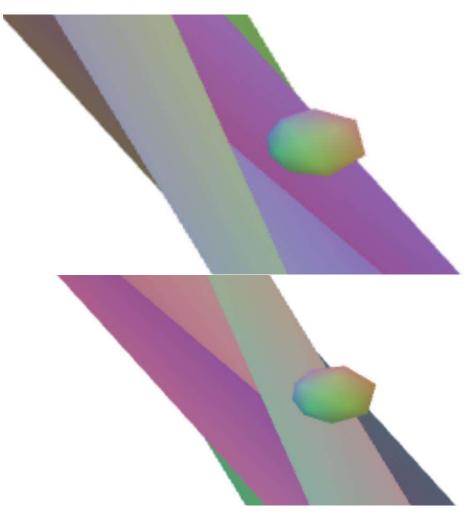
The start of the output for 2 iterations.

I have put the vertex and index arrays into models/planet.js. I will use the 1-iteration sphere.

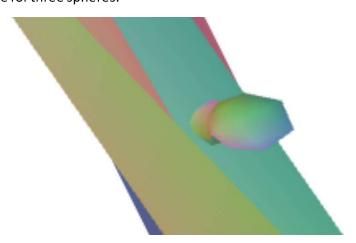
(pv = planet vertices pti = planet triangles indexed)

Testing the vertex shader and sphere generator

Here are the results for 2 spheres at different PVUW positions.



Some for three spheres.



The massive folded structure at the back seems to be a logic error. It may be due to 4D effects.

The other two spheres seem as expected.

Here is the output without the 4D calculation, for one sphere. (The sphere is rotating)



It seems to be squashed, but that is because the xy_ratio is not applied to this debugging mode.

It seems to be a little pixelated - a problem I will need to solve.

Max Silin