

1. $\Psi(x,t) = A e^{-\lambda x} \cdot e^{-i\omega t}$ ($\lambda > 0$) 단, A, λ, ω 는 양의 상수

(a) Ψ 규격화

$$\begin{aligned}
 1 &= \int_0^{\infty} \Psi^*(x,t) \Psi(x,t) dx \\
 &= \int_0^{\infty} A^* e^{-\lambda x} e^{i\omega t} \cdot A e^{-\lambda x} e^{-i\omega t} dx \\
 &= \int_0^{\infty} |A|^2 e^{-2\lambda x} dx \\
 &= -\frac{|A|^2}{2\lambda} e^{-2\lambda x} \Big|_0^{\infty} \\
 &= 0 + \frac{|A|^2}{2\lambda} = 1
 \end{aligned}$$

$$\therefore A = \sqrt{2\lambda} \quad (A > 0)$$

(b) $\langle x \rangle = \int_0^{\infty} \Psi^* \cdot x \cdot \Psi dx$

$$\begin{aligned}
 &= \int_0^{\infty} A^* e^{-\lambda x} e^{i\omega t} \cdot x \cdot A e^{-\lambda x} e^{-i\omega t} dx \\
 &= A^* \cdot A \cdot \int_0^{\infty} e^{-2\lambda x} \cdot x dx \\
 &= |A|^2 \left[\frac{-1}{2\lambda} e^{-2\lambda x} x \Big|_0^{\infty} + \frac{1}{2\lambda} \int_0^{\infty} e^{-2\lambda x} dx \right] \\
 &= \int_0^{\infty} e^{-2\lambda x} dx \\
 &= \frac{-1}{2\lambda} e^{-2\lambda x} \Big|_0^{\infty} = \frac{1}{2\lambda}
 \end{aligned}$$

$$\begin{aligned}
 \langle x^2 \rangle &= \int_0^{\infty} \Psi^* \cdot x^2 \cdot \Psi dx \\
 &= \int_0^{\infty} A^* e^{-\lambda x} e^{i\omega t} \cdot x^2 \cdot A e^{-\lambda x} e^{-i\omega t} dx \\
 &= |A|^2 \int_0^{\infty} e^{-2\lambda x} x^2 dx \\
 &= 2\lambda \cdot \left[\frac{-1}{2\lambda} e^{-2\lambda x} x^2 \Big|_0^{\infty} + \int_0^{\infty} \frac{1}{2\lambda} e^{-2\lambda x} \cdot 2x dx \right] \\
 &= 2 \int_0^{\infty} e^{-2\lambda x} x dx \\
 &= 2 \left[\frac{-1}{2\lambda} e^{-2\lambda x} x \Big|_0^{\infty} + \frac{1}{2\lambda} \int_0^{\infty} e^{-2\lambda x} dx \right] \\
 &= \frac{1}{\lambda} \left(-\frac{1}{2\lambda} \right) e^{-2\lambda x} \Big|_0^{\infty} = +\frac{1}{2\lambda^2}
 \end{aligned}$$

$$\begin{aligned}\therefore \Delta x &= \sqrt{\langle x^2 \rangle - \langle x \rangle^2} \\ &= \sqrt{\frac{1}{2\lambda^2} - \left(\frac{1}{2\lambda}\right)^2} \\ &= \sqrt{\frac{1}{4\lambda^2}} = \frac{1}{2\lambda} \quad (\because \lambda > 0)\end{aligned}$$

$$2. \quad \langle p \rangle = m \cdot \frac{d\langle x \rangle}{dt} = -i\hbar \int_{-\infty}^{\infty} \Psi^* \frac{\partial \Psi}{\partial x} dx$$

$$\left(\begin{aligned} \therefore \langle x \rangle &= \int_{-\infty}^{\infty} \Psi^* x \Psi dx \\ \therefore \frac{d\langle x \rangle}{dt} &= \frac{d}{dt} \int_{-\infty}^{\infty} \Psi^* x \Psi dx \\ &= \int_{-\infty}^{\infty} x \frac{\partial}{\partial t} (\Psi^* \Psi) dx \\ &= \int_{-\infty}^{\infty} x \left(\Psi^* \frac{\partial \Psi}{\partial t} + \Psi \frac{\partial \Psi^*}{\partial t} \right) dx \quad - ① \end{aligned} \right.$$

$$\text{Since } i\hbar \frac{\partial \Psi}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \Psi}{\partial x^2} + V\Psi, \quad -i\hbar \frac{\partial \Psi^*}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \Psi^*}{\partial x^2} + V\Psi^*$$

$$\frac{\partial \Psi}{\partial t} = \frac{i\hbar}{2m} \frac{\partial^2 \Psi}{\partial x^2} - \frac{i}{\hbar} V\Psi, \quad \frac{\partial \Psi^*}{\partial t} = -\frac{i\hbar}{2m} \frac{\partial^2 \Psi^*}{\partial x^2} + \frac{i}{\hbar} V\Psi^*$$

$$\begin{aligned}\frac{\partial}{\partial t} (\Psi^* \Psi) &= \Psi^* \frac{\partial \Psi}{\partial t} + \Psi \frac{\partial \Psi^*}{\partial t} \\ &= \frac{i\hbar}{2m} \Psi^* \frac{\partial^2 \Psi}{\partial x^2} - \frac{i}{\hbar} \Psi^* V\Psi - \frac{i\hbar}{2m} \Psi \frac{\partial^2 \Psi^*}{\partial x^2} + \frac{i}{\hbar} \Psi V\Psi^* \\ &= \frac{i\hbar}{2m} \left(\Psi^* \frac{\partial^2 \Psi}{\partial x^2} - \Psi \frac{\partial^2 \Psi^*}{\partial x^2} \right) \\ &= \frac{i\hbar}{2m} \frac{\partial}{\partial x} \left(\Psi^* \frac{\partial \Psi}{\partial x} - \Psi \frac{\partial \Psi^*}{\partial x} \right)\end{aligned}$$

자분리 상태

$$\begin{aligned}\therefore ① &= \frac{i\hbar}{2m} \int_{-\infty}^{\infty} x \frac{\partial}{\partial x} \left(\Psi^* \frac{\partial \Psi}{\partial x} - \Psi \frac{\partial \Psi^*}{\partial x} \right) dx \\ \text{Integ. by parts} \quad \downarrow &= \frac{i\hbar}{2m} \left[x \left(\cancel{\Psi^* \frac{\partial \Psi}{\partial x}} - \cancel{\Psi \frac{\partial \Psi^*}{\partial x}} \right) \right]_{-\infty}^{\infty} - \int_{-\infty}^{\infty} \left(\Psi^* \frac{\partial \Psi}{\partial x} - \Psi \frac{\partial \Psi^*}{\partial x} \right) dx \\ &= -\frac{i\hbar}{2m} \int_{-\infty}^{\infty} \left(\Psi^* \frac{\partial \Psi}{\partial x} - \Psi \frac{\partial \Psi^*}{\partial x} \right) dx \quad ② \\ &= -\frac{i\hbar}{m} \int_{-\infty}^{\infty} \Psi^* \frac{\partial \Psi}{\partial x} dx \quad ③\end{aligned}$$

($\because \Psi^*$ 와 $\frac{\partial \Psi}{\partial x}$ 는 위치에서 함수이므로 commute)

$$\therefore \frac{d\langle p \rangle}{dt} = -i\hbar \int \frac{\partial}{\partial t} (\Psi^* \frac{\partial \Psi}{\partial x}) dx$$

Schrödinger
eqn. \rightarrow

$$\begin{aligned}
 &= -i\hbar \int \left(\frac{\partial \Psi^*}{\partial t} \cdot \frac{\partial \Psi}{\partial x} + \Psi^* \cdot \frac{\partial}{\partial t} \left(\frac{\partial \Psi}{\partial x} \right) \right) dx \\
 &= -i\hbar \int \left[\left(-\frac{i\hbar}{2m} \cdot \frac{\partial^2 \Psi^*}{\partial x^2} + \frac{i}{\hbar} V \Psi^* \right) \frac{\partial \Psi}{\partial x} + \Psi^* \frac{\partial}{\partial x} \left(\frac{i\hbar}{2m} \cdot \frac{\partial \Psi}{\partial x} - \frac{i}{\hbar} V \Psi \right) \right] dx \\
 &= -i\hbar \int \left[\frac{-i\hbar}{2m} \left(\frac{\partial^2 \Psi^*}{\partial x^2} \frac{\partial \Psi}{\partial x} - \Psi^* \frac{\partial^3 \Psi}{\partial x^3} \right) + \frac{i}{\hbar} \left(V \Psi^* \frac{\partial \Psi}{\partial x} - \Psi^* \frac{\partial}{\partial x} (V \Psi) \right) \right] dx \\
 &= -i\hbar \int \left[\underbrace{\frac{-i\hbar}{2m} \left(\frac{\partial^2 \Psi^*}{\partial x^2} \cdot \frac{\partial \Psi}{\partial x} - \Psi^* \frac{\partial^3 \Psi}{\partial x^3} \right)}_{\textcircled{1}} dx + \underbrace{\frac{i}{\hbar} \left\{ V \Psi^* \frac{\partial \Psi}{\partial x} - \Psi^* \frac{\partial}{\partial x} (V \Psi) \right\}}_{\textcircled{2}} dx \right]
 \end{aligned}$$

$$\begin{aligned} \textcircled{1} &= \int_{-\infty}^{\infty} -\frac{i\hbar}{2m} \left(\frac{\partial^2 \Psi^*}{\partial x^2} \cdot \frac{\partial \Psi}{\partial x} - \Psi^* \frac{\partial^3 \Psi}{\partial x^3} \right) dx \\ &= -\frac{i\hbar}{2m} \left[\frac{\partial \Psi^*}{\partial x} \cdot \frac{\partial \Psi}{\partial x} \right]_{-\infty}^{\infty} - \int_{-\infty}^{\infty} \frac{\partial \Psi^*}{\partial x} \cdot \frac{\partial^2 \Psi}{\partial x^2} dx - \left[\Psi^* \frac{\partial^2 \Psi}{\partial x^2} \right]_{-\infty}^{\infty} + \int_{-\infty}^{\infty} \frac{\partial \Psi^*}{\partial x} \cdot \frac{\partial^2 \Psi}{\partial x^2} dx \\ &= 0 \end{aligned}$$

$$\begin{aligned} (2) &= \int_{-\infty}^{\infty} \frac{i}{\hbar} \left\{ \Psi^* \frac{\partial \Psi}{\partial x} - \Psi \frac{\partial \Psi^*}{\partial x} \right\} dx \\ &= \frac{i}{\hbar} \int_{-\infty}^{\infty} \left(\Psi^* \frac{\partial \Psi}{\partial x} - \Psi \frac{\partial \Psi^*}{\partial x} \right) dx \\ &= \frac{i}{\hbar} \int_{-\infty}^{\infty} \Psi^* \left(-\frac{\partial \Psi}{\partial x} \right) dx \\ &= \frac{i}{\hbar} \left\langle -\frac{\partial \Psi}{\partial x} \right\rangle \end{aligned}$$

$$\therefore \frac{d\langle p \rangle}{dt} = -i\hbar \cdot \left(0 + \frac{i}{\hbar} \left\langle -\frac{\partial V}{\partial x} \right\rangle \right)$$

$$= \left\langle -\frac{\partial V}{\partial x} \right\rangle \quad / * \text{ 뉴턴 제2법칙 } \frac{dp}{dt} = -\frac{dV}{dx} \text{ 에 대한,}$$

양자역학적 analogue이다. */

$$3. \quad \Psi(x) = \begin{cases} A(a^2 - x^2), & |x| \leq a \\ 0, & |x| > a \end{cases}$$

$$\begin{aligned} (a) \quad 1 &= \int_{-\infty}^{\infty} \Psi^*(x) \cdot \Psi(x) dx \\ &= \int_{-a}^a A^*(a^2 - x^2)^* \cdot A(a^2 - x^2) dx \\ &= A \cdot A^* \cdot \int_{-a}^a (a^2 - x^2)^*(a^2 - x^2) dx \\ &= |A|^2 \cdot \int_{-a}^a |a^2 - x^2|^2 dx \\ &= 2|A|^2 \cdot \int_0^a (a^4 - 2a^2x^2 + x^4) dx \\ &= 2|A|^2 \cdot \left(a^4x - \frac{2a^2}{3}x^3 + \frac{1}{5}x^5 \right) \Big|_0^a \\ &= 2|A|^2 \cdot \left(a^5 - \frac{2a^5}{3} + \frac{1}{5}a^5 \right) \\ &= 2|A|^2 \cdot \frac{15-10+3}{15} a^5 = 2|A|^2 \cdot \frac{8}{15} a^5 \end{aligned}$$

$$\therefore |A| = \sqrt{\frac{15}{16a^5}}$$

$$\begin{aligned} (b) \quad \sigma_x^2 &= \langle x^2 \rangle - \langle x \rangle^2 \\ &= \int_{-a}^a \Psi^* x^2 \Psi dx - \left(\int_{-a}^a \Psi^* x \Psi dx \right)^2 \\ &= \int_{-a}^a x^2 |A|^2 (a^2 - x^2)^2 dx - \left(\int_{-a}^a x \cdot |A|^2 (a^2 - x^2) dx \right)^2 \\ &= 2|A|^2 \cdot \int_0^a x^2 (a^2 - x^2)^2 dx - 0 \quad \leftarrow \text{Considering even \& oddness} \\ &= 2|A|^2 \cdot \int_0^a x^2 (a^4 - 2a^2x^2 + x^4) dx \\ &= 2|A|^2 \cdot \int_0^a (a^4x^2 - 2a^2x^4 + x^6) dx \\ &= 2|A|^2 \cdot \left(\frac{a^4}{3}x^3 - \frac{2a^2}{5}x^5 + \frac{1}{7}x^7 \right) \Big|_0^a \quad (a) \text{ 적분이용} \\ &= 2|A|^2 \cdot \left(\frac{a^7}{3} - \frac{2a^7}{5} + \frac{1}{7}a^7 \right) \\ &= 2|A|^2 \cdot \frac{(35-42+15)}{105} a^7 = 2|A|^2 \cdot \frac{8}{105} a^7 = 2 \cdot \frac{15}{16a^5} \cdot \frac{8}{105} a^7 = \frac{1}{7} a^2 \end{aligned}$$

$$\sigma_p^2 = \langle p^2 \rangle - \langle p \rangle^2$$

$$= \int \Psi^* (-i\hbar \frac{\partial}{\partial x})^2 \Psi dx - \left(\int \Psi^* (-i\hbar \frac{\partial}{\partial x}) \Psi dx \right)^2$$

$$= -\hbar^2 \int \Psi^* \frac{\partial^2 \Psi}{\partial x^2} dx - \left(-i\hbar \int \Psi^* \frac{\partial \Psi}{\partial x} dx \right)^2$$

$$= -\hbar^2 \int A^*(a^2 - x^2)^* \cdot (-2A) - \left(-i\hbar \int A^*(a^2 - x^2)^* \cdot (-2Ax) dx \right)^2$$

$$= 2|A|^2 \hbar^2 \int (a^2 - x^2) dx - \left(2|A|^2 i\hbar \int (a^2 - x^2)x dx \right)^2$$

$$= 2|A|^2 \hbar^2 \left(a^2 x - \frac{1}{3} x^3 \right) \Big|_{-a}^a - 0$$

$$= 2|A|^2 \hbar^2 \left(a^3 - \frac{1}{3} a^3 + a^3 - \frac{1}{3} a^3 \right)$$

$$= 2 \cdot \frac{15}{16a^5} \cdot \hbar^2 \cdot \frac{4}{3} a^3$$

$$= \frac{5 \hbar^2}{2a^2}$$

$$\therefore \sigma_x = \frac{a}{\sqrt{11}}, \quad \sigma_p = \sqrt{\frac{5}{2}} \cdot \frac{\hbar}{a}$$

$$(C) \quad \sigma_x \cdot \sigma_p = \frac{a}{\sqrt{11}} \cdot \frac{\sqrt{5}}{\sqrt{2}} \cdot \frac{\hbar}{a}$$

$$= \frac{\sqrt{5}}{\sqrt{14}} \hbar \doteq 0.5976 \hbar > \frac{\hbar}{2}$$

\therefore 주어진 파동함수는 불확정성 원리를 만족

4. (a) $E = \frac{1}{2}mv(\dot{x}) + V(x)$, Conservation of Energy

$$\therefore v(x) = \sqrt{\frac{2}{m} \{E - V(x)\}}$$

(b) $\rho(x) = \frac{1}{v(x)T}$

$$= \frac{1}{T} \cdot \sqrt{\frac{m}{2\{E - V(x)\}}}$$

$$= \frac{1}{T} \cdot \sqrt{\frac{m}{2E - kx^2}} \quad \left\{ V(x) = \frac{1}{2}kx^2 \right.$$

since $T = \int_a^b \frac{1}{v(x)} dx$

$$= \int_a^b \sqrt{\frac{m}{2\{E - V(x)\}}} dx$$

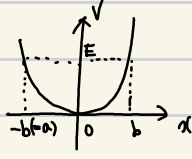
(a) 구간에서
의해

$$= \int_a^b \sqrt{\frac{m}{2\{E - \frac{1}{2}kx^2\}}} dx$$

$$= 2 \int_0^b \sqrt{\frac{m}{2E - kx^2}} dx$$

$$= 2 \int_0^b \sqrt{\frac{m}{2E(1 - \frac{k}{2E}x^2)}} dx$$

$V(a) = \frac{1}{2}ka^2 = \frac{1}{2}kb^2 = V(b) = E$
 $a = -b$ with $a < 0 < b$



Let, $x = \sqrt{\frac{2E}{k}} \cos \theta$

$\therefore \theta \rightarrow \frac{\pi}{2} \quad (x \rightarrow 0)$

$\theta \rightarrow 0 \quad (x \rightarrow b)$

($\because \frac{1}{2}kb^2 = E$)

$b = \sqrt{\frac{2E}{k}}$

$dx = -\sqrt{\frac{2E}{k}} \sin \theta d\theta$

$$= 2 \cdot \sqrt{\frac{m}{2E}} \int_0^b \frac{1}{\sqrt{1 - \frac{k}{2E}x^2}} dx$$

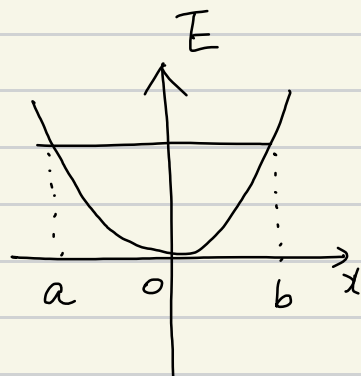
$$= \sqrt{\frac{2m}{E}} \int_{\frac{\pi}{2}}^0 \frac{1}{\sqrt{1 - \cos^2 \theta}} \left(-\sqrt{\frac{2E}{k}} \sin \theta \right) d\theta$$

$$= 2 \sqrt{\frac{m}{k}} \int_0^{\frac{\pi}{2}} d\theta = \pi \sqrt{\frac{m}{k}} \quad \left(\text{단조화진동자의} \right.$$

$\frac{1}{2}$ 주기 $= \pi \sqrt{\frac{m}{k}}$ 라임치)

$$\therefore P(x) = \frac{1}{\pi} \sqrt{\frac{k}{m}} \cdot \sqrt{\frac{m}{2E - kx^2}}$$

$$= \frac{1}{\pi} \cdot \sqrt{\frac{k}{2E - kx^2}}$$



$$(c) \langle x \rangle = \int_a^b x P(x) dx$$

$$= \int_a^b \frac{x}{\pi} \sqrt{\frac{k}{2E - kx^2}} dx$$

$$= 0 \quad (\because a = -b, \text{ 피적분함수는 odd func.})$$

$$\langle x^2 \rangle = \int_a^b x^2 P(x) dx$$

$$= \int_a^b x^2 \cdot \frac{1}{\pi} \sqrt{\frac{k}{2E - kx^2}} dx$$

$$= \frac{2}{\pi} \int_0^b x^2 \sqrt{\frac{k}{2E - kx^2}} dx$$

$$= \frac{2}{\pi} \int_0^b x^2 \sqrt{\frac{k}{2E(1 - \frac{k}{2E}x^2)}} dx$$

Let, $x = \sqrt{\frac{2E}{k}} \cos \theta$

$$dx = -\sqrt{\frac{2E}{k}} \sin \theta d\theta$$

$$\theta \rightarrow \frac{\pi}{2}$$

$$\theta \rightarrow \cos^{-1}\left(b \cdot \sqrt{\frac{k}{2E}}\right)$$

$$= \cos^{-1}\left(\sqrt{\frac{2E}{k}} \cdot \sqrt{\frac{k}{2E}}\right)$$

$$= 0$$

$$= \frac{2}{\pi} \cdot \sqrt{\frac{k}{2E}} \int_{\frac{\pi}{2}}^0 \frac{2E}{k} \cos^2 \theta \cdot \frac{1}{\sqrt{1 - \cos^2 \theta}} \cdot \left(-\sqrt{\frac{2E}{k}} \sin \theta\right) d\theta$$

$$= \frac{2}{\pi} \cdot \int_{\frac{\pi}{2}}^0 \left(-\frac{2E}{k} \cos^2 \theta\right) d\theta$$

$$= \frac{2}{\pi} \int_0^{\frac{\pi}{2}} \frac{2E}{k} \cdot \frac{(1 + \cos 2\theta)}{2} d\theta$$

$$= \frac{2}{\pi} \cdot \frac{E}{k} \cdot \left(\theta + \frac{1}{2} \sin 2\theta \Big|_0^{\frac{\pi}{2}}\right)$$

$$= \frac{2E}{\pi k} \cdot \left(\frac{\pi}{2}\right) = \frac{E}{k}$$

$$\sigma_x = \sqrt{\langle x^2 \rangle - \langle x \rangle^2}$$

$$= \sqrt{\frac{E}{k}}$$

$$= \sqrt{\frac{1}{2} b^2}$$

$$= \frac{b}{\sqrt{2}}$$

∴ 용수철 진동자에서 위치 x 의 표준편차 σ_x 는
용수철 상수 k 에 의존하지 않고, 초기에 당긴 예지 b 에만 의존