

EM algorithm and Simulated EM algorithms

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- The EM algorithm helps to find the Maximum Likelihood Estimator in incomplete data problems.

Let $Y_1^*, Y_2^*, \dots, Y_n^*$ be iid random variables with density $f_\theta(y^*)$. We do not observe y_i^* . We observe $y_i = Y_i(Y_i^*)$ (incomplete sampling scheme).

- The EM algorithm has two steps : an E-step and an M-step.
- The E-step is the calculation of the conditional expectation of the log-likelihood in complete information given the observed data.
- The M-step is the maximization of the previous quantity.
- These two steps are iterated .

Let $f_\theta(y)$ denote the marginal density of y . Let us assume we observe an iid sample (y_1, \dots, y_n) .

The likelihood function is

$$L(\theta) = \prod_{i=1}^n f_\theta(y_i)$$

where θ is a vector of parameters.

For instance, $y^* = (y, z)$ and $Y(y^*) = y$ (z can be considered as an unobserved heterogeneity component). For example, $y = y^* \mathbb{1}[y^* \geq 0]$ (selection).

Let us assume that it is difficult to maximize such a likelihood function. Indeed, the density in the context on an incomplete sample scheme is an expectation. It can be easier to maximize an objective function that involve the expectation of the log of a density.

EM algorithm (Dempster, Laird, Rubin, 1977):

Let us consider the following function of the parameters

$$Q(\theta \mid \theta') = \frac{1}{n} \sum_{i=1}^n E_{\theta'}[\log(f_{\theta}(y_i^*)) \mid y_i].$$

We start with an initial value for the vector of parameters $(\theta' \leftarrow \theta^{(0)})$.

One iteration of the algorithm :

The **E-step**: Calculation of $Q(\theta \mid \theta')$ for θ' fixed.

The **M-step**: Consists to maximize $Q(\theta \mid \theta')$ with respect to θ .

Then we replace θ' by the new value of θ obtained from the M-step and we iterate from step k to step $k+1$ ($\theta' \leftarrow \theta^{(k)}$).

Let $M(\theta') = \operatorname{argmax}_{\theta} Q(\theta \mid \theta')$. The MLE of the θ (namely $\hat{\theta}$) is a **fixed point** of $M(\theta)$: it is such that $\hat{\theta} = M(\hat{\theta})$.

Let $\theta^{(k)}$ denote the value of θ obtained at the iteration k of the EM algorithm. The algorithm is such that $L(\theta^{(k)}) \geq L(\theta^{(k-1)})$.

Let $\Omega(\theta, \theta^{(k)}) = L(\theta) - L(\theta^{(k)})$. We are going to show that $\Omega(\theta^{(k+1)}, \theta^{(k)}) \geq 0$.

Let us assume to simplify the presentation of the proof that $y^* = (y, z)$ and the variable z is discrete.

Sketch of proof: Let

$$\Omega(\theta, \theta^{(k)}) = \frac{1}{n} \sum_{i=1}^n \log(f_{\theta}(y_i)) - \frac{1}{n} \sum_{i=1}^n \log(f_{\theta^{(k)}}(y_i))$$

where $\log(f_{\theta}(y)) = \sum_z f_{\theta}(y \mid z) \pi_{\theta}(z)$.

$$\begin{aligned}
\Omega(\theta, \theta^{(k)}) &= \frac{1}{n} \sum_{i=1}^n \log \left(\sum_z f_{\theta}(y_i | z) \pi_{\theta}(z) \right) - \frac{1}{n} \sum_{i=1}^n \log(f_{\theta^{(k)}}(y_i)) \\
&= \frac{1}{n} \sum_{i=1}^n \log \left(\sum_z \frac{f_{\theta}(y_i | z) \pi_{\theta}(z)}{\text{Prob}[z | y_i; \theta^{(k)}]} \text{Prob}[z | y_i; \theta^{(k)}] \right) \\
&\quad - \frac{1}{n} \sum_{i=1}^n \sum_z \text{Prob}[z | y_i; \theta^{(k)}] \log(f_{\theta^{(k)}}(y_i))
\end{aligned}$$

As $-\log(x)$ is a convex function, the **Jensen's inequality** allows to write

$$\begin{aligned}
\Omega(\theta, \theta^{(k)}) &\geq \frac{1}{n} \sum_{i=1}^n \sum_z \text{Prob}[z | y_i; \theta^{(k)}] \log \left(\frac{f_{\theta}(y_i | z) \pi_{\theta}(z)}{\text{Prob}[z | y_i; \theta^{(k)}]} \right) \\
&\quad - \frac{1}{n} \sum_{i=1}^n \sum_z \text{Prob}[z | y_i; \theta^{(k)}] \log(f_{\theta^{(k)}}(y_i))
\end{aligned}$$

$$\begin{aligned}
 \Omega(\theta, \theta^{(k)}) &\geq \frac{1}{n} \sum_{i=1}^n \sum_z \text{Prob}[z|y_i; \theta^{(k)}] \log\left(\frac{f_\theta(y_i | z) \pi_\theta(z)}{\text{Prob}[z|y_i; \theta^{(k)}] f_{\theta^{(k)}}(y_i)}\right) \\
 &= \frac{1}{n} \sum_{i=1}^n \sum_z \text{Prob}[z|y_i; \theta^{(k)}] \log\left(\frac{f_\theta(y_i; z)}{f_{\theta^{(k)}}(y_i; z)}\right) \equiv \omega(\theta, \theta^{(k)})
 \end{aligned}$$

Let us remark that

$$\begin{aligned}
 \theta^{(k+1)} &= \underset{\theta}{\operatorname{argmax}} \omega(\theta, \theta^{(k)}) \\
 &= \underset{\theta}{\operatorname{argmax}} \frac{1}{n} \sum_{i=1}^n \sum_z \text{Prob}[z|y_i; \theta^{(k)}] \log\left(\frac{f_\theta(y_i; z)}{f_{\theta^{(k)}}(y_i; z)}\right) \\
 &= \underset{\theta}{\operatorname{argmax}} \frac{1}{n} \sum_{i=1}^n \sum_z \text{Prob}[z|y_i; \theta^{(k)}] \log(f_\theta(y_i; z))
 \end{aligned}$$

$$\begin{aligned}
 \theta^{(k+1)} &= \underset{\theta}{\operatorname{argmax}} \frac{1}{n} \sum_{i=1}^n \sum_z \frac{\pi_{\theta^{(k)}}(z) f_{\theta^{(k)}}(y_i; z)}{\sum_z \pi_{\theta^{(k)}}(z) f_{\theta^{(k)}}(y_i; z)} \log(f_{\theta}(y_i; z)) \\
 &= \underset{\theta}{\operatorname{argmax}} \frac{1}{n} \sum_{i=1}^n E_{\theta^{(k)}} [\log(f_{\theta}(y_i; z) \mid y_i)]
 \end{aligned}$$

We have shown that $\log(L(\theta^{(k+1)})) - \log(L(\theta^{(k)})) = \Omega(\theta^{(k+1)}, \theta^{(k)}) \geq \omega(\theta^{(k+1)}, \theta^{(k)}) \geq \omega(\theta^{(k)}, \theta^{(k)}) = 0$. QED

Example

An example : EM algorithm for the exponential distribution and right censoring.

Remark : this distribution belongs to the exponential family (see Gouriéroux, Monfort, Trognon, 1984).

The density (complete observation scheme) :

$$f_{\theta}(y^*) = \lambda \exp(-\lambda y^*)$$

for all $y^* > 0$. The cumulative distribution function is

$$Prob[Y^* \leq a] = 1 - \exp(-\lambda a)$$

Incomplete sampling scheme : We observe $y = Y(y^*)$ such that

$$y = y^* \text{ if } y^* < a$$

$$y = a \text{ if } y^* \geq a > 0$$

Example

Interpretation : Y^* is a duration and this duration can be right censored.

The likelihood function is

$$L(\theta) = \prod_{i=1}^n (\lambda \exp(-\lambda y_i^*)) \mathbf{1}_{\{y_i < a\}} (\exp(-\lambda a)) \mathbf{1}_{\{y_i = a\}}$$

In this example, the likelihood function can be maximized with respect to the parameter λ ($\lambda > 0$).

The distribution of Y^* given $Y = y$ is given by the density

$$\kappa_{\theta}(y^* | y) = 1 \text{ if } y < a \text{ and } y^* = y,$$

$$\kappa_{\theta}(y^* | y) = 0 \text{ if } y < a \text{ and } y^* \neq y,$$

$$\kappa_{\theta}(y^* | y) = \lambda \exp(-\lambda y^*) / \exp(-\lambda a), \text{ if } y = a,$$

Example

The E-step of the EM algorithm consists in calculating

$$Q(\theta \mid \theta') = \frac{1}{n} \sum_{i=1}^n E_{\theta'} [\log(f_{\theta}(Y_i^*)) \mid y_i]$$

for θ' fixed. A fixed point of the function $M(\theta)$ is such that

$$\frac{\partial}{\partial \theta} Q(\theta \mid \theta') \mid_{\theta=\theta'} = 0$$

this is equivalent to find θ' such that

$$\frac{1}{n} \sum_{i=1}^n \frac{\partial}{\partial \theta} E_{\theta'} [\log(f_{\theta}(Y_i^*)) \mid y_i] \mid_{\theta=\theta'} = 0$$

In order to find the root of this previous equation, we operate iteratively. We start with a value θ' and the next value is such that

$$\frac{\partial}{\partial \theta} Q(\theta \mid \theta') = 0$$

Example (continued):

$$\begin{aligned}
 Q(\theta \mid \theta') &= \frac{1}{n} \sum_{i: y_i < a} E_{\lambda'}[\log(\lambda \exp(-\lambda Y_i^*)) \mid y_i] \\
 &\quad + \frac{1}{n} \sum_{i: y_i = a} E_{\lambda'}[\log(\lambda e^{-\lambda Y_i^*}) \mid y_i] \\
 Q(\theta \mid \theta') &= \frac{1}{n} \sum_{i: y_i < a} \log(\lambda \exp(-\lambda y_i)) \\
 &\quad + \frac{1}{n} \sum_{i: y_i = a} \int_a^\infty \log(\lambda e^{-\lambda y}) \lambda' e^{-\lambda' y} / e^{-\lambda' a} dy
 \end{aligned}$$

Example

$$\begin{aligned}
 Q(\theta \mid \theta') &= \frac{1}{n} \sum_{i: y_i < a} (\log(\lambda) - \lambda y_i) \\
 &+ \frac{1}{n} \sum_{i: y_i = a} [\log(\lambda) - \lambda \int_a^\infty y \lambda' e^{-\lambda' y} / e^{-\lambda' a} dy] \\
 Q(\theta \mid \theta') &= \frac{1}{n} \sum_{i: y_i < a} (\log(\lambda) - \lambda y_i) \\
 &+ \frac{1}{n} \sum_{i: y_i = a} [\log(\lambda) - \lambda(a + \frac{1}{\lambda'})]
 \end{aligned}$$

Example

Let us assume that $\lambda = \lambda' = \hat{\lambda}_n$ then we obtain

$$\frac{1}{n} \sum_{i: y_i < a} \left[\frac{1}{\hat{\lambda}_n} - y_i \right] + \frac{1}{n} \sum_{i: y_i = a} \left[\frac{1}{\hat{\lambda}_n} - (a + \frac{1}{\hat{\lambda}_n}) \right] = 0$$

$$\frac{1}{\hat{\lambda}_n} \sum_{i: y_i < a} 1 = \sum_{i: y_i < a} y_i + \sum_{i: y_i = a} a$$

$\hat{\lambda}_n$ is the fixed point of $M(\theta)$. It is the **Maximum Likelihood Estimator** of $\theta = \lambda$.

The likelihood function is

$$L(\theta) = \prod_{i: y_i < a} \lambda \exp(-\lambda y_i) \prod_{i: y_i = a} \exp(-\lambda a)$$

Example

The log-likelihood function is

$$\log(L(\theta)) = \sum_{i: y_i < a} \log(\lambda) - \sum_{i: y_i < a} \lambda y_i - \sum_{i: y_i = a} \lambda a$$

The first order condition is

$$\frac{1}{\hat{\lambda}_n} \sum_{i: y_i < a} 1 = \sum_{i: y_i < a} y_i + \sum_{i: y_i = a} a$$

Consequently one can verify that the EM algorithm allows to obtain at the **stationarity of the Markov chain** the value of the MLE.

The EM algorithm can be extended to the cases such that the expectation to be evaluated in the Maximization step **do not have any analytical expression**.

Example (continued): Description of the Markov Chain

Let us consider the first order condition associated to $Q(\lambda \mid \lambda')$,

$$\begin{aligned} \frac{1}{n} \sum_{i: y_i < a} \frac{1}{\lambda} - \frac{1}{n} \sum_{i: y_i < a} y_i + \\ + \frac{1}{n} \sum_{i: y_i = a} \frac{1}{\lambda} - \frac{1}{n} \sum_{i: y_i = a} \left(a + \frac{1}{\lambda'} \right) = 0 \end{aligned}$$

Consequently,

$$\frac{1}{\lambda} = \frac{1}{n} \sum_{i: y_i < a} y_i + \frac{1}{n} \sum_{i: y_i = a} \left(a + \frac{1}{\lambda'} \right).$$

Then let us fix $\lambda' \leftarrow \lambda$ and we iterate.

Let , y_{ik}^* , $k = 1, \dots, H$, be a random draw from the conditional distribution $\kappa_{\theta'}(y^* | y)$. An **unbiased** estimate of $Q(\theta | \theta')$ is given by

$$\hat{Q}(\theta | \theta') = \frac{1}{n} \sum_{i=1}^n \frac{1}{H} \sum_{k=1}^H \log(f_{\theta}(y_{ik}^*))$$

The draws y_{ik}^* are often obtained using independent uniform random numbers $y_{ik}^* = \psi(u_{ik} | y_i, \theta')$ (or vectors of independent uniform random numbers). The expression of ψ is related to the one of $\kappa_{\theta'}(y^* | y)$.

We can have two different Simulated EM algorithms :

- If we draw new independent variables u_{ik} in each iteration, the sequence of θ obtained from the algorithm is an ergodic Markov chain. It is the **StEM algorithm** (Nielsen 2000).
- If we use the same independent variables u_{ik} for all iterations, it is the **SimEM algorithm** (Nielsen 2000).

Example (continued):

$$\kappa_{\theta'}(y^* | y) = \frac{\lambda' \exp(-\lambda' y^*)}{\exp(-\lambda' a)}$$

where $y^* \geq a$ ($y = a$).

The conditional cumulative distribution function is

$$\eta_{\theta'}(y^*) = 1 - \frac{\exp(-\lambda' y^*)}{\exp(-\lambda' a)}$$

Let u_{ik} denote an independent random draw in the uniform distribution. Then $y_{ik}^* = \eta_{\lambda'}^{-1}(u_{ik}) = \psi(u_{ik} | a; \lambda')$ is an independent random draw in the conditional distribution $\kappa_{\theta'}(y^* | y)$.

One can verify that

$$y_{ik}^* = \eta_{\lambda'}^{-1}(u_{ik}) = \frac{1}{\lambda'} [a \lambda' - \log(1 - u_{ik})] = a - \frac{1}{\lambda'} \log(1 - u_{ik})$$

SimEM algorithm: The drawings u_{ik} , $k = 1, \dots, H$ are **constant** through the iterations of the algorithm. As the expression of the objective function $\hat{Q}(\theta \mid \theta')$ do not vary for θ and θ' fixed, the **E-step** is very simple and consists to replace the former value of θ' by a new one (the argmax of the previous **maximization step**).

We start with a value of θ' and we solve the equation (f.o.c. of the maximization step)

$$\frac{\partial}{\partial \theta} \hat{Q}(\theta \mid \theta') = \frac{1}{n} \sum_{i=1}^n \frac{1}{H} \sum_{k=1}^H \frac{\partial}{\partial \theta} \log(f_{\theta}(\psi(u_{ik} \mid y_i, \theta'))) = 0$$

with respect to θ . We assume that we can permute the order of differentiation and of expectation (i.e. the derivative of the expectation is the expectation of the derivative).

This root θ is then used to replace the value of θ' for the next iteration of the algorithm.

SimEM algorithm: Example (continued)

$$\begin{aligned}\hat{Q}(\theta \mid \theta') &= \frac{1}{n} \sum_{i: y_i < a} (\log(\lambda) - \lambda y_i) \\ &\quad + \frac{1}{n} \sum_{i: y_i = a} \left[\log(\lambda) - \lambda \frac{1}{H} \sum_{k=1}^H y_{ik}^* \right]\end{aligned}$$

where $y_{ik}^* = \psi(u_{ik} \mid y, \theta') = \eta_{\lambda'}^{-1}(u_{ik}) = \frac{1}{\lambda'} [a \lambda' - \log(1 - u_{ik})]$.

We have to find the root of

$$\begin{aligned}\frac{\partial}{\partial \theta} \hat{Q}(\theta \mid \theta') &= \frac{1}{n} \sum_{i: y_i < a} \left(\frac{1}{\lambda} - y_i \right) \\ &\quad + \frac{1}{n} \sum_{i: y_i = a} \left[\frac{1}{\lambda} - \frac{1}{H} \sum_{k=1}^H y_{ik}^* \right] = 0\end{aligned}$$

The root λ is such that

$$\frac{1}{\lambda} = \frac{1}{n} \sum_{i: y_i < a} y_i + \frac{1}{n} \sum_{i: y_i = a} \frac{1}{H} \sum_{k=1}^H y_{ik}^*$$

The $\lambda' \leftarrow \lambda$ and we iterate until we find a **fixed point**.

For the StEM algorithm, at the iteration ℓ we solve the equation (f.o.c. of the maximization step)

$$\frac{\partial}{\partial \theta} \hat{Q}(\theta \mid \theta') = \frac{1}{n} \sum_{i=1}^n \frac{1}{H} \sum_{k=1}^H \frac{\partial}{\partial \theta} \log(f_{\theta}(\psi(u_{ik}^{\ell} \mid y_i, \theta'))) = 0$$

with respect to θ .

So we consider two Simulated EM algorithms : **SimEM** and **StEM**. When H is relatively small, the two simulated EM algorithms may produce different value of $\hat{\theta}_n$.

Table: Monte Carlo experiment. Exponential duration model with censoring time a and parameter λ_0 .

	H=1	H=20	H=100	H=1000
Mean MLE	0.010004	0.0100088	0.009998	0.010001
Stand. Dev.	0.0004721	0.000477	0.000465	0.000463
Mean SimEM	0.009871	0.009946	0.009987	0.009998
Stand. Dev.	0.000587	0.000483	0.000465	0.000463

Note : N=1000. Monte Carlo replications=1000. $a = 60$. $\lambda_0 = 0.01$. \simeq

52% obs censored.

The table on the previous slide regroups the results of a Monte Carlo simulation. The number of MC replications is fixed to 1000. 1000 data sets of size $n = 1000$ are generated independently. For each individual, we draw a duration y_i^* distributed as an exponential random variable with density

$$f_{\theta_0}(y^*) = \lambda_0 \exp(-\lambda_0 y^*)$$

where $\theta_0 = 0.01$.

The observation scheme is such that duration are right censored when $y_i^* \geq a$ (for $a = 60$).

For each data sets, we calculate the MLE and the SimEM estimator. The table, for each value of the number of random uniforms for the SimEM algorithm ($H=1, 20, 100, 1000$), contains the average and the standard deviation of the ML and SimEM estimates.

Both estimators are in average close to the true value of the parameter. The empirical standard deviations are similar for H large.

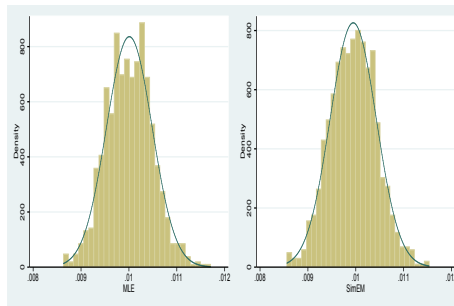


Figure: 1. Distributions of ML and SimEM estimates ($H = 20$)

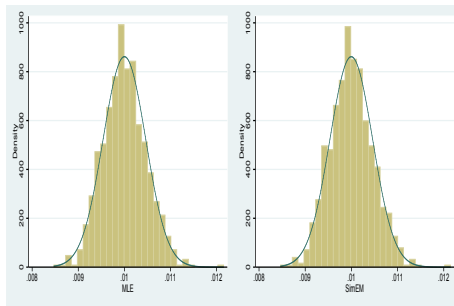


Figure: 2. Distributions of ML and SimEM estimates ($H = 1000$)

Ruud (1991) gives some applications of the use of EM algorithm for econometric models. Let us consider the latent variable

$$Y_{ij}^* = x_i' \beta_j + u_{ij},$$

where i is the index of individual, j the index of equation and $u_i \sim N(0, \Omega)$. β_j is a vector of parameters, x_i is a vector of K explanatory variables.

- Multinomial probit : $y_{ij} = 1$ if $y_{ij}^* = \max(y_{i1}^*, \dots, y_{iJ}^*)$, and $y_{ij} = 0$ otherwise.
- Ordered probit : $y_i = g$ when $\alpha_g \leq y_i^* < \alpha_{g+1}$, where $-\infty = \alpha_0 < \alpha_1 < \dots < \alpha_G < \alpha_{G+1} = \infty$.
- Non random selection (2): $y_{i1} = \mathbb{1}\{y_{i1}^* > 0\}$ and $y_{i2} = y_{i1} y_{i2}^* > 0$ (i.e. $J = 2$).
- Non random selection (1) : $y_i = \mathbb{1}\{y_i^* > 0\} y_i^*$ (i.e. $J = 1$).

We can add, for instance, models with unobserved heterogeneity (panel data models, duration models, consumer choice, see Kenneth Train, etc).

Simulated EM algorithm in the literature

StEm : Celeux and Diebolt (1985), Diebolt and Celeux (1993), for $H = 1$. Baillif et al. (2021).

SimEM : Ruud (1991), Train (2008)

MCEM : Wei and Tanner (1990), in the E-step, the conditional expectation is calculated via Monte Carlo integration ($H = \infty$). In practice, as $H < \infty$, the results applies : StEM if we draw new uniforms at each iteration or SimEm if we re-use the uniform random draws.

Let $f_{\theta}(y^*)$, $\theta \in \Theta \subseteq \mathbf{R}^p$, denote the density of Y^* and $s_{Y^*}(\theta) = \frac{\partial}{\partial \theta} f_{\theta}(Y^*)$ the score function. We assume the score function as a zero expectation for θ_0 (model correctly specified). θ_0 is the true value of the vector θ .

The variance covariance matrix $V(\theta) = E_{\theta}[s_{Y^*}(\theta) s_{Y^*}(\theta)']$ (**complete data**). The density of the conditional distribution of Y^* given $Y = y$ is $\kappa_{\theta}(Y^* | y)$. The corresponding score function is denoted $s_{Y^*|Y}(\theta)$. Let $I_Y(\theta) = E_{\theta}[s_{Y^*|Y}(\theta) s_{Y^*|Y}(\theta)']$ denote variance of Y^* given $Y = y$.

Let $s_Y(\theta)$ denote the score function of the marginal distribution of Y . Let us consider the variance $I(\theta) = E_{\theta}[s_Y(\theta) s_Y(\theta)']$ of Y (**incomplete data**).

Assumption : $I(\theta_0)$ and $V(\theta_0)$ are positive definite.

Let us remark that $s_Y(\theta) = s_{Y^*}(\theta) - s_{Y^*|Y}(\theta)$ and $I(\theta) = V(\theta) - E_{\theta}[I_Y(\theta)]$.

Theorem (1)

Asymptotics, StEM algorithm (Nielsen, 2000)

Under regularity assumptions (singularly if the markov chain is erogodic), then

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{\mathcal{D}} N(0, \Sigma_H(\theta_0))$$

where

$\Sigma_H(\theta_0) = I(\theta_0)^{-1} + \frac{1}{H} V(\theta_0)^{-1} E_{\theta_0}[I_Y(\theta_0)] V(\theta_0)^{-1} (I - F(\theta_0)^2)^{-1}$,
 $F(\theta_0) = E_{\theta_0}[I_Y(\theta_0)] V(\theta_0)^{-1}$ and I is the identity matrix.

$\hat{\theta}_n$ is a random variable drawn from the stationary initial distribution of the Markov chain corresponding to the StEM algorithm. The stationary distribution of the Markov Chain converges to a normal distribution as n becomes large.

Let us consider the derivative of the objective function (M step)

$$G_n(\theta') = \frac{1}{n} \sum_{i=1}^n \frac{1}{H} \sum_{k=1}^H \frac{\partial}{\partial \theta} \log(f_{\theta}(\psi(u_{ik} | y_i, \theta')))|_{\theta=\theta'}$$

$G_n(\theta) \xrightarrow{\mathcal{P}} G(\theta)$ (Law of large number). Some technical conditions are needed to obtain uniform convergence.

Assumptions:

- (A1) $\sup_{\theta \in C} \|G_n(\theta) - G(\theta)\| / (1 + \|G_n(\theta)\| + \|G(\theta)\|) \xrightarrow{\mathcal{P}} 0$,
for a compact neighbourhood, C , of θ_0 .
- (A2) $\sup_{\|\theta - \theta_0\| < \delta_n} (\sqrt{n} \|G_n(\theta) - G(\theta) - G_n(\theta_0)\|) / (1 + \sqrt{n} \|G_n(\theta)\| + \sqrt{n} \|G(\theta)\|) \xrightarrow{\mathcal{P}} 0$, for any $\delta_n \rightarrow 0$.

Theorem (2)

Asymptotics, SimEM algorithm (Nielsen, 2000)

Under (A1) there is exists $\hat{\theta}_n$, an asymptotic local minimum of $\|G_n(\theta)\|$, such that $\hat{\theta}_n \xrightarrow{\mathcal{P}} \theta_0$.

Under (A2), if $\hat{\theta}_n$ is consistent, then

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{\mathcal{D}} N(0, I(\theta_0)^{-1} + \frac{1}{H} I(\theta_0)^{-1} E_{\theta_0}[I_Y(\theta_0)] I(\theta_0)^{-1})$$

Theorem (3)

Comparison of SimEM and StEM algorithms (Nielsen, 2000)

Let H denote the number of random numbers we draw per iteration. For the same value of H , the estimator we obtain from the StEM algorithm has a smaller asymptotic variance than the asymptotic variance of the estimator resulting from the SimEM algorithm.

Table: Monte Carlo experiment. Exponential duration model with censoring time a and parameter λ_0 .

	H=1	H=100	H=200
Mean MLE	0.00999111	0.00999719	0.01000250
Standard Dev	0.00047180	0.00045565	0.00047809
Mean SimEM	0.00951538	0.01005405	0.00998016
Standard Dev	0.00058965	0.00045668	0.00047958
Mean StEM	0.00999263	0.00999533	0.01000003
Standard Dev	0.00053429	0.00045658	0.00047919

Note : N=1000. Monte Carlo replications=1000. $a = 60$. $\lambda_0 = 0.01$.

Let us consider n individuals and for each individual we observe T realizations of a vector y_{it} of q elements. The realizations are independent across individuals but not (necessarily) across time. Let $y_i = (y_{i1}, \dots, y_{iT})'$.

We can have K different (unobserved) types for individuals. Let p_k denote the probability to belong to type k and $p = (p_1, \dots, p_K)'$.

Let $f_\theta(y | k)$ denote the density of Y given the type k and $\theta = (\theta_1, \dots, \theta_E)'$ is a vector of parameters.

The density of Y_i is

$$f_{\theta,p}(y_i) = \sum_{k=1}^K p_k f_\theta(y_i | k)$$

The conditional probability that individual belongs to type k is

$$Prob(k \mid y_i; \theta, p) = \frac{p_k f_{\theta}(y_i \mid k)}{f_{\theta, p}(y_i)} \quad (1)$$

The log-likelihood function is

$$L(\theta, p) = \sum_{i=1}^n \log(f_{\theta, p}(y_i))$$

Maximizing the likelihood function under the restriction that $\sum_{k=1}^K p_k = 1$ and using equation (1), the maximum likelihood estimator of p_k is

$$\hat{p}_k = \frac{1}{n} \sum_{i=1}^n Prob(k \mid y_i; \hat{\theta}, \hat{p}) \quad (2)$$

Theorem

The MLE of θ is a solution of the optimization problem

$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^n \sum_{k=1}^K \operatorname{Prob}(k \mid y_i; \hat{\theta}, \hat{p}) \log(f_{\theta}(y_i \mid k))$$

Proof:

$\hat{\theta}$ is solution of the optimization problem

$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^n \log\left(\sum_{k=1}^K \hat{p}_k f_{\theta}(y_i \mid k)\right)$$

Then the MLE of θ is a solution of the first order condition (f.o.c.):

$$\hat{\theta} = \sum_{i=1}^n \sum_{k=1}^K \hat{p}_k \frac{\frac{\partial f_{\theta}(y_i | k)}{\partial \theta} \big|_{\theta=\hat{\theta}}}{f_{\hat{\theta}, \hat{p}}(y_i)} = 0$$

$$\hat{\theta} = \sum_{i=1}^n \sum_{k=1}^K \hat{p}_k \frac{f_{\theta}(y_i | k)}{f_{\theta}(y_i | k)} \frac{\frac{\partial f_{\theta}(y_i | k)}{\partial \theta}}{f_{\hat{\theta}, \hat{p}}(y_i)} \Big|_{\theta=\hat{\theta}} = 0$$

$$\hat{\theta} = \sum_{i=1}^n \sum_{k=1}^K \hat{p}_k \frac{f_{\theta}(y_i | k)}{f_{\hat{\theta}, \hat{p}}(y_i)} \frac{\frac{\partial f_{\theta}(y_i | k)}{\partial \theta}}{f_{\theta}(y_i | k)} \Big|_{\theta=\hat{\theta}} = 0$$

There is a condition that can be obtained if we consider the following optimization program

$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^n \sum_{k=1}^K \frac{\hat{p}_k f_{\hat{\theta}}(y_i | k)}{\sum_{k=1}^K \hat{p}_k f_{\hat{\theta}}(y_i | k)} \log(f_{\theta}(y_i | k))$$

$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^n \sum_{k=1}^K \operatorname{Prob}(k | y_i; \hat{\theta}, \hat{p}) \log(f_{\theta}(y_i | k))$$

QED

Then the MLE $\hat{\theta}$ of θ is a solution of

$$\sum_{i=1}^n \sum_{k=1}^K \text{Prob}(k \mid y_i; \hat{\theta}, \hat{p}) \frac{\partial \log(f_{\theta}(y_i \mid k))}{\partial \theta} \Big|_{\theta=\hat{\theta}} = 0 \quad (3)$$

Consequently,

$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^n \sum_{k=1}^K \text{Prob}(k \mid y_i; \hat{\theta}, \hat{p}) \log(f_{\theta}(y_i \mid k)) \quad (4)$$

The MLE $\hat{\theta}$ maximizes

- the log of the likelihood function

$$\sum_{i=1}^n \log(\sum_{k=1}^K \hat{p}_k f_{\theta}(y_i \mid k))$$

- the conditional expectation (indeed an component of a likelihood function)

$$\sum_{i=1}^n \sum_{k=1}^K \text{Prob}(k \mid y_i; \hat{\theta}, \hat{p}) \log(f_{\theta}(y_i \mid k))$$

where $\hat{\theta}$ and \hat{p} are the MLE if θ and p respectively. The E-step consists to maximize the last object with respect to θ .

EM algorithm:

- At the iteration ℓ , θ^0 is replaced by $\theta^{\ell-1}$ and p^0 is replaced by $p^{\ell-1}$.
- The E-step consists to calculate $Prob(k | y_i; \theta^{\ell-1}, p^{\ell-1})$.
- The M-step consists to use equation (2) to obtain p^ℓ and the equation (4) to deduce θ^ℓ .

The algorithm is such that we iterate until we achieve convergence.

Theorem

MLE of p_k

$$\hat{p}_k = \frac{1}{n} \sum_{i=1}^n \text{Prob}(k \mid y_i; \hat{\theta}, \hat{p})$$

where $\text{Prob}(k \mid y_i; \theta, p) = \frac{p_k f_{\theta}(y_i | k)}{f_{\theta, p}(y_i)}$.

Proof: $L(\theta, p) = \sum_{i=1}^n \ln(f_{\theta, p}(y_i)) = \sum_{i=1}^n \ln(\sum_{k=1}^K p_k f_{\theta}(y_i | k))$
is the likelihood function we maximize under the constraint that $\sum_{k=1}^K p_k = 1$.

$$\frac{\partial}{\partial p_k} L(\theta, p) = \sum_{i=1}^n \frac{f_{\theta}(y_i | k) - f_{\theta}(y_i | K)}{f_{\theta, p}(y_i)} = 0$$

$$\sum_{i=1}^n \sum_{k=1}^K \frac{p_k f_{\theta}(y_i | k)}{f_{\theta, p}(y_i)} = \sum_{i=1}^n \sum_{k=1}^K \frac{p_k f_{\theta}(y_i | K)}{f_{\theta, p}(y_i)} = \sum_{i=1}^n \frac{f_{\theta}(y_i | K)}{f_{\theta, p}(y_i)}$$

Then

$$n = \sum_{i=1}^n \frac{f_{\theta}(y_i | K)}{f_{\theta,p}(y_i)}$$

as $\sum_{k=1}^K p_k f_{\theta}(y_i | k) = f_{\theta,p}(y_i)$ and

$$\sum_{i=1}^n \frac{f_{\theta}(y_i | k)}{f_{\theta,p}(y_i)} = n$$

$$\sum_{i=1}^n \frac{p_k f_{\theta}(y_i | k)}{f_{\theta,p}(y_i)} = p_k n$$

$$\hat{p}_k = \frac{1}{n} \sum_{i=1}^n \frac{\hat{p}_k f_{\hat{\theta}}(y_i | k)}{f_{\hat{\theta}, \hat{p}}(y_i)} = \frac{1}{n} \sum_{i=1}^n \text{Prob}[k | y_i; \hat{\theta}, \hat{p}]$$

Q.E.D.

Let us consider that $\theta = (\theta_1, \theta_2)'$. We can maximize the equation (4) (M-step) jointly with respect to θ or by maximizing the expression with respect to θ_2 taking the last value of $\hat{\theta}_1$ as fixed and then, maximizing the expression with respect to θ_1 given the last value $\hat{\theta}_2$ of θ_2 .

The sequential way of resolution of the EM algorithm is called **Expectation-Conditional Maximization (ECM)**, see Meng and Rubin (1993) and Arcidiacono and Bailey Jones (2003). The **ECM algorithm** keeps the convergence properties of the EM algorithm.

Singularly, let us assume that

$$f_{\theta_1, \theta_2}(y_i | k) = f_{1, \theta_1}(y_i | k) f_{2, \theta_1, \theta_2}(y_i | k)$$

The log-likelihood function is

$$L(\theta, p) = \sum_{i=1}^n \log \left(\sum_{k=1}^K p_k f_{1,\theta_1}(y_i | k) f_{2,\theta_1,\theta_2}(y_i | k) \right)$$

The expression **cannot** directly **be factorized** as a product $L_1(\Theta_1)L(\Theta_1, \Theta_2)$ in order to implement a sequential estimation. Within the EM algorithm, equation (4) can be (re)written

$$\begin{aligned} (\hat{\theta}_1, \hat{\theta}_2) = \underset{\theta_1, \theta_2}{\operatorname{argmax}} & \sum_{i=1}^n \sum_{k=1}^K \operatorname{Prob}(k | y_i; \hat{\theta}, \hat{p}) \log(f_{1,\theta_1}(y_i | k)) \\ & + \sum_{i=1}^n \sum_{k=1}^K \operatorname{Prob}(k | y_i; \hat{\theta}, \hat{p}) \log(f_{2,\theta_1,\theta_2}(y_i | k)) \end{aligned}$$

We can resolve sequentially

$$\hat{\theta}_1 = \underset{\theta_1}{\operatorname{argmax}} \sum_{i=1}^n \sum_{k=1}^K \operatorname{Prob}(k \mid y_i; \hat{\theta}, \hat{p}) \log(f_{1,\theta_1}(y_i \mid k)) \quad (5)$$

$$\hat{\theta}_2 = \underset{\theta_2}{\operatorname{argmax}} \sum_{i=1}^n \sum_{k=1}^K \operatorname{Prob}(k \mid y_i; \hat{\theta}, \hat{p}) \log(f_{2,\hat{\theta}_1,\theta_2}(y_i \mid k)) \quad (6)$$

The EM algorithm allows to estimate θ sequentially in such a way that, for each stage, we use the estimates of other parameters obtained from the previous stage (each step comprises two stages).

We can remark that we do not need to derivate equation $f_{2,\hat{\theta}_1,\theta_2}(y_i \mid k)$ with respect to θ_1 so that the estimator is **less efficient than the FIML** one (Acidiacono and Jones, 2003). Moreover, the EM algorithm allows to obtain the FIML estimates (**estimates** obtained using **ECM algorithm** \neq **FIML estimates**).

When we use a star, the corresponding parameters are the population parameters. **At the level of population**

$$(\theta^*, p^*) = \underset{\theta, p}{\operatorname{argmax}} E_{y, k} \log(p_k f_{1, \theta_1}(y | k) f_{2, \theta_1, \theta_2}(y | k)) \quad (7)$$

where $E_{y, k}$ states the expectation with respect to the distribution of the (y, k) .

The expectation with respect to the joint distribution of (y, k) is also the expectation with respect to the distribution of y of the conditional expectation with respect to k given y .

Consequently,

$$(\theta^*, p^*) = \underset{\theta, p}{\operatorname{argmax}} E_y \left[\sum_{k=1}^K \operatorname{Prob}[k | y; \theta^*, p^*] \right. \\ \left. \times \log(p_k f_{1, \theta_1}(y | k) f_{2, \theta_1, \theta_2}(y | k)) \right] \quad (8)$$

where $\operatorname{Prob}[k | y; \theta^*, p^*] = \frac{p_k^* f_{\theta^*}(y|k)}{f_{\theta^*, p^*}(y)}$ and E_y is the marginal expectation with respect to the distribution of y .
From the previous equation we can remark that

$$\theta_2^* = \underset{\theta_2^*}{\operatorname{argmax}} E_y \left[\sum_{k=1}^K \operatorname{Prob}[k | y; \theta^*, p^*] \log(f_{2, \theta_1^*, \theta_2}(y | k)) \right]$$

It is the population analog of the equation (6).

Asymptotic behavior of the Sequential estimator

Let us remark that $f_{1,\theta_1}(y | k)$ is a conditional density and let us consider the population of individuals with the same value of y . Each individual in this population has a probability $Prob[k | y; \theta^*, p^*]$ to belong to type k .

The population objective function is

$$E_y \left[\sum_{k=1}^K Prob[k | y; \theta^*, p^*] \log(f_{1,\theta_1}(y | k)) \right] +$$

$$E_y \left[\sum_{k=1}^K Prob[k | y; \theta^*, p^*] \log(Prob[k | y; \theta^*, p^*]) \right]$$

that have to be maximized with respect to θ_1 .

The first order conditions are

$$E_y \left[\sum_{k=1}^K Prob[k | y; \theta^*, p^*] \frac{\partial \log(f_{1,\theta_1^*}(y | k))}{\partial \theta_1} \right] = 0$$

The population moment conditions are

$$E_y \begin{bmatrix} \sum_{k=1}^K \text{Prob}[k | y; \theta^*, p^*] \frac{\partial \log(f_{1, \theta_1^*}(y|k))}{\partial \theta_1} \\ \sum_{k=1}^K \text{Prob}[k | y; \theta^*, p^*] \frac{\partial \log(f_{2, \theta_1^*, \theta_2^*}(y|k))}{\partial \theta_2} \\ \text{Prob}[1 | y; \theta^*, p^*] - p_1^* \\ \vdots \\ \text{Prob}[K | y; \theta^*, p^*] - p_K^* \end{bmatrix} = 0 \quad (9)$$

where $\text{Prob}[k | y; \theta^*, p^*] = \frac{p_k^* f_{\theta^*}(y|k)}{f_{\theta^*, p^*}(y)}$ and E_y is the expectation with respect to the marginal distribution of y .

Under the usual regularity conditions (Hansen, 1982 or Newey and McFadden, 1994), $(\hat{\theta}_1, \hat{\theta}_2, \hat{p})'$ solution of (2), (5) and (6) are **consistent and asymptotically normal**.

The variance-covariance matrix of this method of moments estimator is given by the standard formula. The calculation of this variance-covariance matrix involve all these **moment conditions** despite that p , θ_1 and θ_2 **are estimated sequentially**.

If we consider equation (9) we can remark that the two first components of the vector of moment conditions are not part of the score vector of the MLE since

$$\frac{\partial \log(f_{\theta^*, p^*}(y))}{\partial \theta_1} = \sum_{k=1}^K \frac{p_k^* f_{\theta^*}(y|k)}{f_{\theta^*, p^*}(y)} \left[\frac{\partial \log(f_{1, \theta_1^*}(y|k))}{\partial \theta_1} + \frac{\partial \log(f_{2, \theta_1^*, \theta_2^*}(y|k))}{\partial \theta_1} \right]$$

$$\frac{\partial \log(f_{\theta^*, p^*}(y))}{\partial \theta_2} = \sum_{k=1}^K \frac{p_k^* f_{\theta^*}(y|k)}{f_{\theta^*, p^*}(y)} \frac{\partial \log(f_{2, \theta_1^*, \theta_2^*}(y|k))}{\partial \theta_2}$$

So the **sequential estimator is not as efficient as the MLE**.

Asymptotic behavior of the Sequential estimator

In order to satisfy the regularity conditions usually assumed in order to obtain **consistency and asymptotic normality** (see Newey and McFadden, 1994), Acidiacono and Jones (2003) assume that the expectation of the log-likelihood function has a unique maximum for (θ^*, p^*) and the moment conditions (9) are the features of this optimum.

Let $Q(\theta, p)$ denote the negative of the GMM criterium function behind the sequential estimator. The mixture of conditional likelihood is **not in general globally concave**. The objective function on the data set can have multiple local maximizers. The approach consists to select among these local maximizers, the one that maximizes the log-likelihood (Wu, 1983).

Consequently, we should use this likelihood criterion when the system (9) has more than one solution. This rule of selection ensure **consistency of the sequential estimator** (ECM estimator). The ECM estimator is distinct from the FIML estimator.

Indeed, Bonhomme (2006) gives an alternative estimate of the variance-covariance matrix of the parameters.

Assumption : There exists a partition $\theta = (\theta_1, \theta_2)$ such that for all $\theta_1, \theta_2, \theta'_1$ and $k = 1, \dots, K$ we have

$$f_{\theta}(y_i | k) = f_{1,\theta_1}(y_i | k) f_{2,\theta_1,\theta_2}(y_i | k), \quad (10)$$

$$\int f_{1,\theta_1}(y | k) f_{2,\theta'_1,\theta_2}(y | k) dy = 1. \quad (11)$$

In order to apply the GMM theory, let us consider

$$\Psi(y_i; \xi) = \begin{pmatrix} \text{Prob}[k = 1 | y_i; \xi] - p_1 \\ \vdots \\ \text{Prob}[k = K | y_i; \xi] - p_K \\ \sum_{k=1}^K \text{Prob}[k | y_i; \xi] \frac{\partial \ln(f_{1,\theta_1}(y_i | k))}{\partial \theta_1} \\ \sum_{k=1}^K \text{Prob}[k | y_i; \xi] \frac{\partial \ln(f_{2,\theta_1,\theta_2}(y_i | k))}{\partial \theta_2} \end{pmatrix}$$

where $\xi = (\theta_1, \theta_2, p)$.

Then the moment conditions are

$$E[\Psi(y_i; \xi^0)] = 0$$

The variance-covariance matrix of the estimator is given by the sandwich formula (see Newey and McFadden, 1994)

$$\Sigma = E\left[\frac{\partial \Psi(y_i; \xi^0)}{\partial \xi'}\right]^{-1} E[\Psi(y_i; \xi^0) \Psi(y_i; \xi^0)'] E\left[\frac{\partial \Psi(y_i; \xi^0)}{\partial \xi'}\right]^{-1}$$

Theorem

For all $\xi = (\theta_1, \theta_2, p)'$ we have

$$\int \Psi(y_i; \xi) f(y; \xi) dy = 0 \quad (12)$$

where $f(y; \xi) = \sum_{k=1}^K p_k f_{\theta}(y | k)$.

Theorem

The variance covariance matrix Σ depends on the first derivatives of the likelihood and on the posterior probabilities only.

$$E \left[\frac{\partial \Psi(y; \xi^0)}{\partial \xi'} \right] = -E \left[\psi(y; \xi^0) \frac{\partial \ln(f(y; \xi^0))}{\partial \xi'} \right] \quad (13)$$

For the expression of $\frac{\partial \ln(f(y; \xi^0))}{\partial \xi'}$ see the Appendix.

Generalizations of the Sequential estimator (ECM)

This part is dedicated to the **extension of the sequential approach** to general moment conditions in models incorporating unobserved heterogeneity (we consider a finite mixture but it can be extended to general mixtures).

Any function $h_{\theta}(y, k)$ that verifies

$$E_{y,k}[h_{\theta^*}(y, k)] = 0$$

also verifies

$$E_y\left[\sum_{k=1}^K \text{Prob}[k | y; \theta^*, p^*] h_{\theta^*}(y, k)\right] = 0$$

This **population condition** is similar to the **sample condition** (3)

$$\frac{1}{n} \sum_{i=1}^n \sum_{k=1}^K \text{Prob}[k | y_i; \hat{\theta}, \hat{p}] \frac{\partial \log(f_{\hat{\theta}}(y_i | k))}{\partial \theta} = 0$$

where $\hat{\theta}$ is the ML estimator of θ .

In this case we have

$$h_{\theta}(y, k) = \frac{\partial \log(f_{\hat{\theta}}(y_i | k))}{\partial \theta}$$

Example: Switching regressions (Kiefer, 1980).

Let us consider the following linear regression model

$$y_i = x_i' \beta_k^* + u_i$$

where x_i is a vector of explanatory variables for individual i , β_k is a vector of parameters and u_i is a normal error term (0 expectation and variance σ^2). u_i is assumed to be independent of the unobserved type k and x_i . Let $\theta = (\beta_1', \dots, \beta_K')'$. Let us remark that

$$E_{y,x} (Prob[k | y, x; \theta^*, p^*] x(y - x' \beta_k^*)) = 0$$

for all $k \in \{1, \dots, K\}$

Generalizations of the Sequential estimator (ECM)

Let us consider a diagonal weighting matrix \hat{W}_k such that the element i of the main diagonal is $\sqrt{\text{Prob}[k \mid y_i, x_i; \hat{\theta}, \hat{p}]}$.

The algorithm consists to estimate β_k using matrices $\hat{W}_k X$ and vectors $\hat{W}_k y$. Then, we use these estimates in order to update obtain a new value of \hat{W}_k .

In order to update \hat{W}_k , we need

$$\text{Prob}[k \mid y_i, x_i; \theta, p; \sigma^2] = \frac{p_k f_{\beta_k, \sigma^2}(y_i \mid x_i; k)}{f(y_i \mid x_i; \theta, p, \sigma^2)}$$

where

$$f(y_i \mid x_i; \theta, p, \sigma^2) = \sum_{k=1}^K p_k f_{\beta_k, \sigma^2}(y_i \mid x_i; k)$$

and

$$p_k = \frac{1}{n} \sum_{i=1}^n \text{Prob}[k \mid y_i, x_i; \theta, p; \sigma^2]$$

Generalizations of the Sequential estimator (ECM)

Let us consider the case such that we have two regimes ($K = 2$).

In this case the distribution of $k \mid x; y; \theta, p, \sigma^2$ is logistic. Let us assume that $\delta_i = 1$ if the individual i is in regime 1 and $\delta_i = 0$ otherwise.

The conditional probability that δ_i is equal to 1 is

$$\text{Prob}[k \mid y_i, x_i; \theta, p; \sigma^2] = \frac{1}{1 + \exp(a_i + b_i y_i)} \equiv \omega_i \quad (14)$$

where $a_i = \ln\left(\frac{1-p_1}{p_1}\right) + \frac{1}{2\sigma^2}((x'_i\beta_1)^2 - (x'_i\beta_2)^2)$ and $b_i = \frac{1}{\sigma^2}(x'_i\beta_2 - x_i\beta_1)$.

Let us consider the matrix $W = \text{diag}(\omega_1, \dots, \omega_n)$, where n is the number of individuals in the sample.

Let us consider the following estimators

$$\hat{\beta}_1 = (X'WX)^{-1}X'Wy \quad (15)$$

$$\hat{\beta}_2 = (X'(I_n - W)X)^{-1} X'(I_n - W)y \quad (16)$$

$$\hat{\sigma}^2 = \frac{1}{n} [(y - X\beta_1)' W (y - X\beta_1) + (y - X\beta_2)' (I_n - W) (y - X\beta_2)] \quad (17)$$

$$\hat{p}_1 = \frac{1}{n} \text{tr} W \quad (18)$$

Algorithm: Start with an initial value for $\xi = (\beta_1, \beta_2, \sigma^2, p_1)'$, namely $\xi^{(1)}$. The index k is set to the value 1.

- 1) Calculate the corresponding ω_i using (14) (namely $\omega_i^{(k)}$).
- 2) $k \leftarrow k + 1$. Update the value of ξ using (15)-(18) to obtain $\xi^{(k)}$.
- 3) Then go to 1) or stop if the convergence is achieved.

The algorithm allows to obtain the **MLE** of ξ (see Kiefer 1980).

Remark : In the paper of Baillif et al. (2021), the algorithm exploit similar relationship to system (15)-(18). The main difference is that the "regimes" are not observed as there are discrete unobserved heterogeneity components.

Consequently, they draw the "regimes" - unobserved heterogeneity components - conditionally to current values of parameters - at step k - in a multinomial distribution.

Remark : The problem of estimation of models with discrete unobserved heterogeneity components is important in econometrics (see Heckman and Singer, 1984, Bonhomme, Lamadon and Manresa, 2017).

Some models with finite mixtures:

Baillif, de Lapparent and Kazagli (2021): Study of real estate Price.

Bonhomme and Robin (2006): Wage and Employment dynamics.

Cameron and Heckman (1998, 2001): Impact of family background on educational attainment.

Eckstein and Wolpin (1999) : Models of dynamic discrete choice.

Heckman and Singer (1984): Models for duration data.

Some models with finite mixtures (continued):

Keane and Wolpin (1997) : Labor economics.

Kiefer (1980): Switching regressions.

Mroz (1999) : Impact of a Dummy Endogenous Variable on a Continuous Outcome.

Train (2008) : Mixed logit model of households' choices among alternative-fueled vehicle.

Provencher, B., K. Baerenklau and R. Bishop (2002) : Model of recreational angling.

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The expression of $\frac{\partial \ln(f(y; \xi^0))}{\partial \xi'}$, where $\xi = (\theta_1, \theta_2, p)'$ (see sequential likelihood section).

$$\frac{\partial \ln(f(y; \xi^0))}{\partial p_k} = \frac{Prob[k | y; \xi^0]}{\partial p_k}, k = 1, \dots, K, \quad (19)$$

$$\frac{\partial \ln(f(y; \xi^0))}{\partial \theta_1} = \sum_{k=1}^K Prob[k | y; \xi^0] \frac{\partial (\ln(f_{1, \theta_1^0}(y | k)) + \ln(f_{2, \theta_1^0, \theta_2^0}(y | k)))}{\partial \theta_1} \quad (20)$$

$$\frac{\partial \ln(f(y; \xi^0))}{\partial \theta_2} = \sum_{k=1}^K Prob[k | y; \xi^0] \frac{\partial (\ln(f_{2, \theta_1^0, \theta_2^0}(y | k)))}{\partial \theta_2} \quad (21)$$