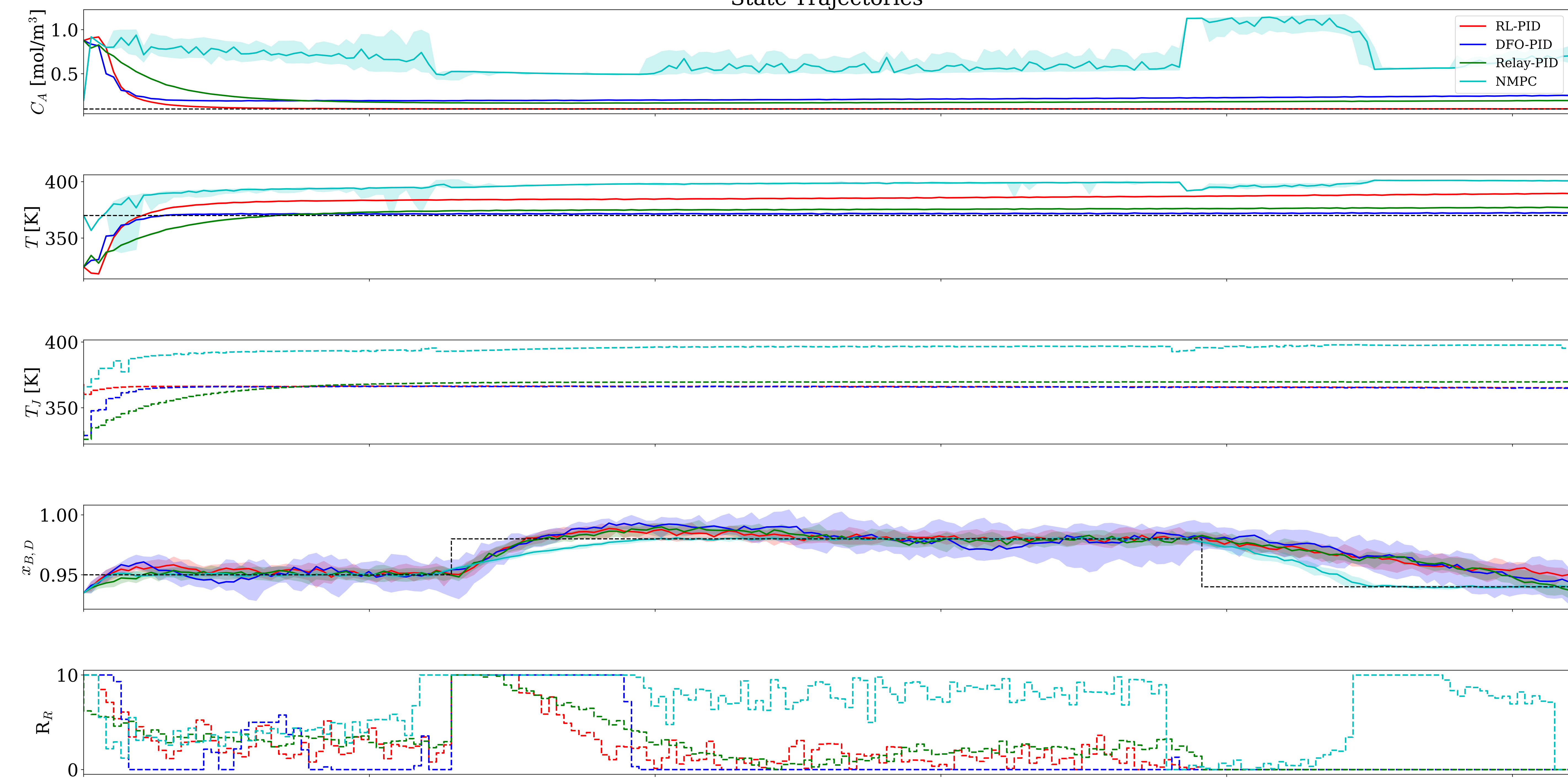


State Trajectories



PID Parameters

