

# Real-time replanning with 3D obstacles for HRP2

Léo Baudouin, Nicolas Perrin  
Thomas Moulard

LAAS-CNRS, Université de Toulouse  
7, avenue du Colonel Roche  
31077 Toulouse cedex 4, France

Olivier Stasse, Eiichi Yoshida

AIST-CNRS, Joint Robotics Laboratory  
UMI3218/CRT AIST  
Umenozo 1-1-1, Tsukuba, Japan