

Limit cycle attractors

Periodic signals

SVR

$$f_j(M\tau_{ij} x(t))$$

$$s_j(t - \tau_{ij})$$

time

timing control

$$s_o(t)$$

time

Non-periodic signal

Mixing model

$$\xi_i(t) = m_i + \sum_j w_{ij} s_j(t - \tau_{ij})$$

Joint angles

Kinematic model

3D positions

