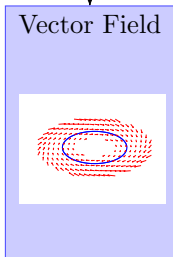
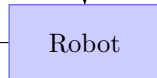
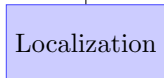
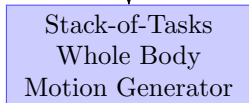




Reference trajectory



$\mathbf{c}_{ref}, \mathbf{z}_{ref}, \mathbf{LF}_{ref}, \mathbf{RF}_{ref}$



Motion capture

\mathbf{w}

v

κ

Power Law
 γ, β

\mathbf{c}^*

\mathbf{q}