

Firewall

ufw

robot

.bashrc

ros2

eeen484

run

ros2 launch slam\_toolbox  
online\_async

run

authentic

x86\_ubuntu

run ~/.bashrc

ros2 launch eeen484\_robot EEEN325\_Robot\_Platform.launch.py

ros2 launch slam\_toolbox

ros2 run rviz2 rviz2

IP:

127.0.0.1/8

192.168.0.101/24

192.168.0.255

low\_level\_interface\_node  
re cmd\_vel → cmd\_vel\_robotclaw

Twist\_max  
re cmd\_vel\_out → cmd\_vel\_robotclaw

Teleop\_twist\_joy  
re cmd\_vel → cmd\_vel\_joy

~~Twist~~

Twist\_stamper  
cmd\_vel\_in → cmd\_vel\_out

run joy + twist mux

modif, low level to use stamped

check config perms - some files may be being treated as read-only

Daemon?

SD

changelogs for jazzy vs humble

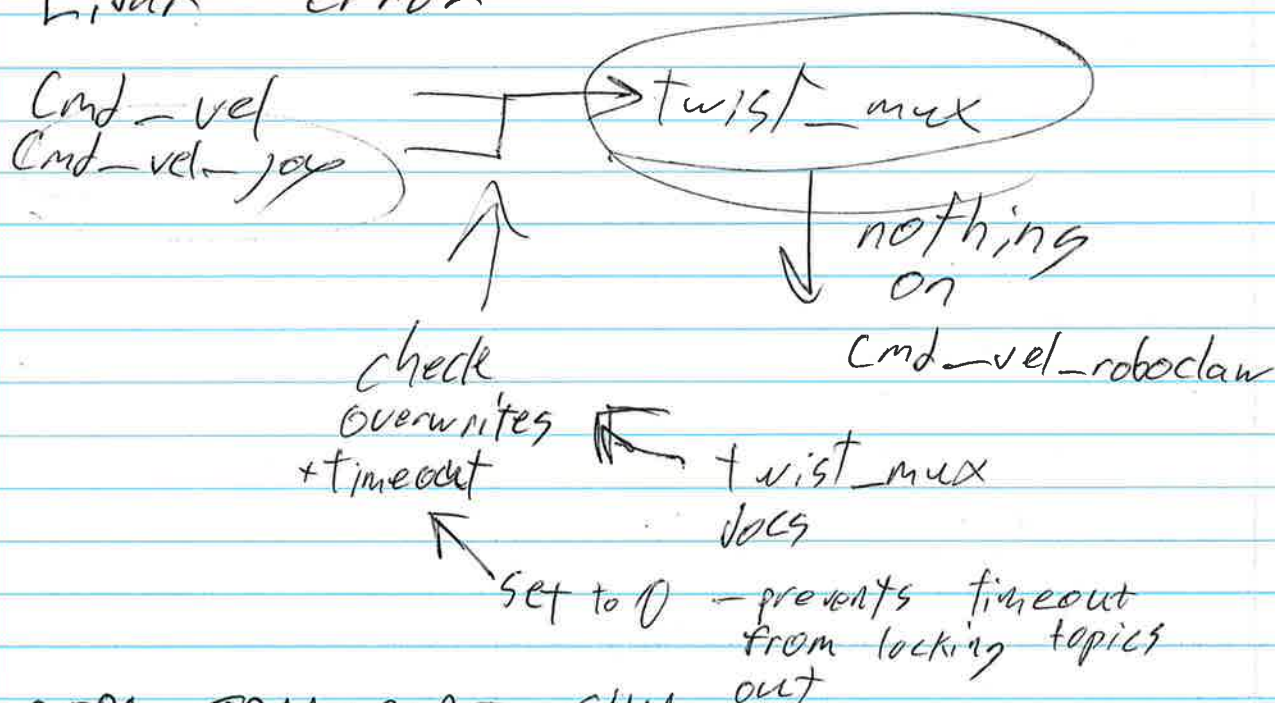
cmd-vel works with just teleop-tast-joy

use stamper  
- remap topics

fact32

git

Lidar error — linked to xone somehow??



RTPS-TRANSPORT-SHM

fastdds-port 7021

open-and-lock-file

open-port-internal

install kernel headers

ros2 twist-stamper

+ cmd\_vel\_joy-stamped

active configs in install/.../share/.../config