

SDS 4130/5130: Linear Statistical Models

Topic 4: Multiple Linear Regression Model III

Fitted and Residual Values, Hat Matrix, and MSE

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Today's Class

- ① Fitted Values, the Hat Matrix, and Residuals
- ② Estimation of σ^2 , $SSE = SS_{Res}$, and MSE

Fitted Values

- The fitted value corresponding to the levels of the regressor variables $X_1 = x_1, \dots, X_k = x_k$ is defined as

$$\hat{\mathbf{y}} = \hat{\beta}_0 + \sum_{j=1}^k \hat{\beta}_j x_j = \mathbf{x}' \hat{\boldsymbol{\beta}},$$

where $\mathbf{x}' = [1, x_1, \dots, x_k]$ and $\hat{\boldsymbol{\beta}} = [\hat{\beta}_0, \dots, \hat{\beta}_k]'$ is the OLS.

- $\hat{\mathbf{y}}$ is a point estimate of the mean value of the response,
 $E[Y|X_1 = x_1, \dots, X_k = x_k] = \beta_0 + \sum_{j=1}^k \beta_j x_j$, for a case with predictor values $X_1 = x_1, \dots, X_k = x_k$.
- The fitted value \hat{y}_i corresponding to the i^{th} -case is

$$\hat{y}_i = \mathbf{x}'_i \hat{\boldsymbol{\beta}} = \hat{\beta}_0 + \sum_{j=1}^k \hat{\beta}_j x_{ij}, \quad i = 1, \dots, n,$$

where $\mathbf{x}'_i = [1, x_{i1}, \dots, x_{ik}]$.

Vector of Fitted Values

- The column vector

$$\hat{\mathbf{y}} = [\hat{y}_1, \dots, \hat{y}_n]'$$

is called the **vector of fitted values**.

- If we recall that the design matrix \mathbf{X} takes the form:

$$\mathbf{X} = \begin{bmatrix} 1 & x_{11} & \dots & x_{1k} \\ 1 & x_{21} & \dots & x_{2k} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_{n1} & \dots & x_{nk} \end{bmatrix},$$

we have the following short-hand formula for $\hat{\mathbf{y}}$:

$$\hat{\mathbf{y}} = \mathbf{X}\hat{\beta}$$

- The fitted values can be found using the function `fitted(model)` in R.

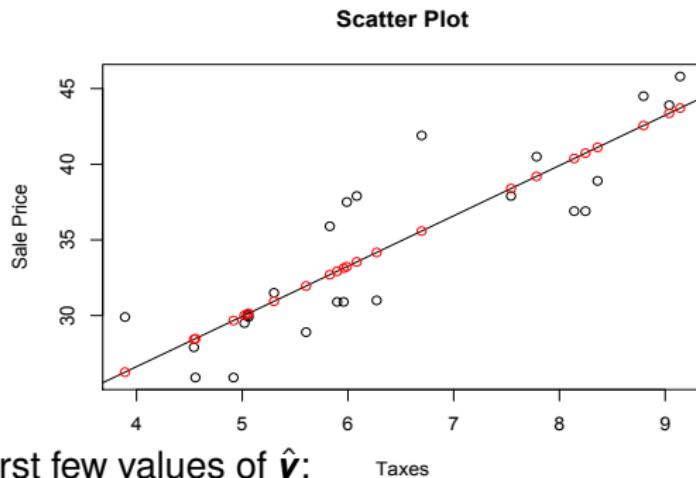
Example 1

Recall the Example 1 from Lect. 2 regarding sale prices of houses. Let us regress the sale price y against the first predictor x_1 (taxes). The following code shows how to generate the scatter plot of y vs. x_1 , the least-squares regression line, and the fitted values (red points):

```
> data(table.b4)
> mymodel<-lm(y~x1,data=table.b4)
> plot(table.b4$x1,table.b4$y,xlab='Taxes',ylab='Sale Price',main=
> abline(coef(mymodel))
> points(table.b4$x1,fitted(mymodel),col='red')
```

Example 1. Continued...

We generate the following graph:



These are the first few values of \hat{y} :

```
>fitted(mymodel)
```

1	2	3	4	5	6	7	...
30.01118	28.42247	28.47034	30.14050	26.25531	32.92732	31.94962	...

The Hat Matrix

- It has some advantages to write things as linear combinations of the observations vector $\mathbf{y} = [y_1, \dots, y_n]'$. This is easy to do for $\hat{\mathbf{y}}$ since we know that $\hat{\beta} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$ and, thus,

$$\hat{\mathbf{y}} = \mathbf{X}\hat{\beta} = \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y} =: \mathbf{H}\mathbf{y},$$

where \mathbf{H} is called the **hat matrix** and is defined as

$$\mathbf{H} := \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'.$$

- This matrix maps the vector of observed values into a vector of fitted values.

Comments

The hat matrix $\mathbf{H} = [h_{ij}]$ allows us to write the fitted values as linear combinations of the observed response variables y_j 's:

$$\hat{y}_i = \sum_{j=1}^n h_{ij} y_j.$$

The entry h_{ij} is sometimes called the **leverage** of the j^{th} response in the i^{th} fitted value and can be interpreted as the effect that j^{th} response in the i^{th} fitted value.

Vector Of Residuals

- The difference between the observed and the fitted values,

$$e_i := y_i - \hat{y}_i,$$

is called the **residual** of the i^{th} -case.

- The column vector $\mathbf{e} = [e_1, \dots, e_n]'$ is called the **vector of residuals**.
- It is easy to see that

$$\mathbf{e} = \mathbf{y} - \hat{\mathbf{y}} = \mathbf{y} - \mathbf{H}\mathbf{y} = (\mathbf{I} - \mathbf{H})\mathbf{y},$$

where $\mathbf{I} = \mathbf{I}_{n \times n}$ is the $n \times n$ identity matrix.

- The residuals can be found using the function `resid(model)` in R.

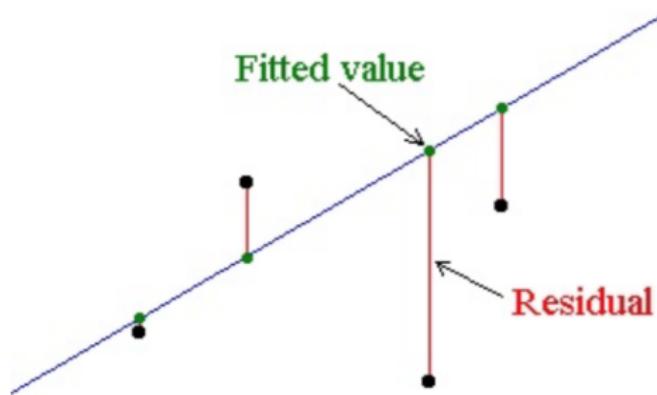
Interpretation Of Residuals

- **Important:** The residual e_i is **not** the error term $\varepsilon_i = Y_i - \mathbb{E}(Y_i)$;
But, if the model has a good fit so that $\hat{\beta} \approx \beta$, then the residual can be thought as a proxy for the error:

$$e_i \approx \varepsilon_i.$$

- In particular, residuals are useful in assessing the statistical properties of the errors ε_i and analyzing the appropriateness of the model (model diagnostics).

Illustration of Fitted Values and Residuals for $k = 1$



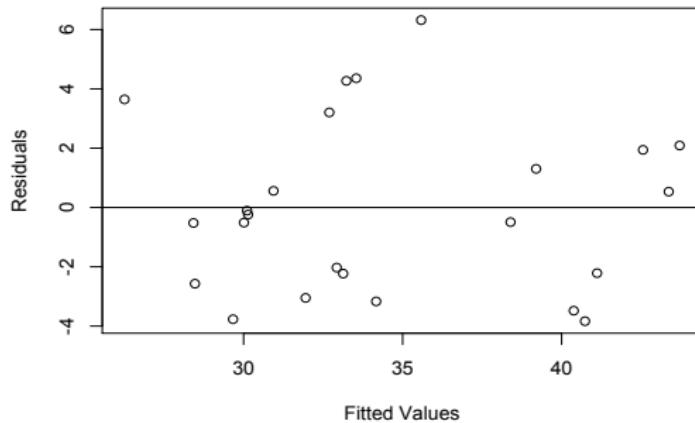
- The blue line represents the least-squares line $\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x$
- The black dots are the data points (x_i, y_i)
- The green dots are the fitted values (x_i, \hat{y}_i)
- The vertical distance between the green and black dots are the residuals

e_i

Example 2

This is a continuation of the code of the Example 1. The following code generates a plot of the residuals against the fitted values:

```
>plot(fitted(mymodel), resid(mymodel), xlab='Fitted Values',  
      ylab='Residuals')  
  
>abline(h=0)
```



Properties of the Hat Matrix

The Hat Matrix $\mathbf{H} = [h_{ij}] := \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}' \in \mathbb{R}^{n \times n}$ has some interesting properties:

- ① **Symmetric:** $\mathbf{H}' = \mathbf{H}$
- ② **Idempotent:** $\mathbf{H}\mathbf{H} = \mathbf{H}$
- ③ $\mathbf{I} - \mathbf{H}$ is also symmetric and idempotent
- ④ $\mathbf{H}\mathbf{X} = \mathbf{X}$ and $\mathbf{X}'\mathbf{H} = \mathbf{X}'$.
- ⑤ The trace¹ $tr(\mathbf{H}) := \sum_{i=1}^n h_{ii}$ equals the number of coefficients $p = k + 1$:

$$tr(\mathbf{H}) = \text{tr}(\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}') = \text{tr}(\mathbf{X}'\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}) = \text{tr}(\mathbf{I}_{p \times p}) = p, \quad (1)$$

(where we used the property $tr(\mathbf{AB}) = tr(\mathbf{BA})$)

-
- ⑥ $tr(\mathbf{I} - \mathbf{H}) = n - p$

¹The trace of a matrix is the sum of the matrix's diagonal elements.

Estimation of σ^2 |

- As an application of the previous formulas and concepts, we now devise a "good" estimator for $\sigma^2 = \text{Var}(\varepsilon_i)$, the variance of the regression errors ε_i .
- For simplicity, suppose for now that the errors $\varepsilon_1, \dots, \varepsilon_n$ are iid (independent identically distributed). Recall from elementary statistics that the natural estimator of σ^2 is the sample variance of the ε_i 's:

$$\frac{\sum_{i=1}^n (\varepsilon_i - \bar{\varepsilon})^2}{n-1}.$$

- However, we don't observe directly the errors ε_i !. Nevertheless, it is natural to use its observable proxies, the residuals e_i :

$$\tilde{\sigma}^2 = \frac{\sum_{i=1}^n (e_i - \bar{e})^2}{n-1} = \frac{\sum_{i=1}^n e_i^2}{n-1},$$

where the last equality is because, as it turns out, $\bar{e} = \frac{\sum_{i=1}^n e_i}{n}$ is always equal to 0 (see p. 19 below).

Estimation of σ^2 II

- The numerator of $\tilde{\sigma}^2$ is called the **sum of square errors** or **sum of the residuals squares**:

$$SSE = SS_{Res} = \sum_{i=1}^n (y_i - \hat{y}_i)^2 = \sum_{i=1}^n e_i^2.$$

- As it turns out $\mathbb{E}[SS_{Res}] = \sigma^2(n - p)$ (see pages 17-18 below). Then,
 $E(\tilde{\sigma}^2) = \frac{1}{n-p} E(SS_{Res}) = \sigma^2 \left(\frac{n-p}{n-1} \right) < \sigma^2$ because $p = k + 1 \geq 2$.
- However, the following estimator is UNBIASED for σ^2 :

$$s^2 = \hat{\sigma}^2 = \frac{SS_{Res}}{n-p} = \frac{\sum_{i=1}^n e_i^2}{n-p}.$$

This is called **Mean-Square Error** and is sometimes denoted as MSE or MS_{Res} . From now on, we shall use s^2 as our estimator for σ^2 .

Connection between residuals and errors

To show the unbiasedness statement of the last point above, we first need to connect the residuals \mathbf{e} with the errors ε . Remember that $\mathbf{e} = (\mathbf{I} - \mathbf{H})\mathbf{y}$ and $\mathbf{y} = \mathbf{X}\beta + \varepsilon$. Then,

$$\mathbf{e} = (\mathbf{I} - \mathbf{H})(\mathbf{X}\beta + \varepsilon) = (\mathbf{I} - \mathbf{H})\mathbf{X}\beta + (\mathbf{I} - \mathbf{H})\varepsilon.$$

But, the first term cancels out because

$(\mathbf{I} - \mathbf{H})\mathbf{X}\beta = (\mathbf{I}\mathbf{X} - \mathbf{H}\mathbf{X})\beta = (\mathbf{X} - \mathbf{X})\beta = \mathbf{0}$ (here, we used that $\mathbf{H}\mathbf{X} = \mathbf{X}$). Then,

$$\mathbf{e} = (\mathbf{I} - \mathbf{H})\varepsilon.$$

Verification that $E(SS_{Res}) = \sigma^2(n - p) \mathbf{I}$

- Note that

$$SS_{Res} = \sum_{i=1}^n e_i^2 = \mathbf{e}' \mathbf{e}.$$

- Then, using the connection between \mathbf{e} and $\boldsymbol{\varepsilon}$ of the previous page,

$$SS_{Res} = ((\mathbf{I} - \mathbf{H})\boldsymbol{\varepsilon})'(\mathbf{I} - \mathbf{H})\boldsymbol{\varepsilon} = \boldsymbol{\varepsilon}'(\mathbf{I} - \mathbf{H})'(\mathbf{I} - \mathbf{H})\boldsymbol{\varepsilon} = \boldsymbol{\varepsilon}'(\mathbf{I} - \mathbf{H})\boldsymbol{\varepsilon},$$

because $\mathbf{I} - \mathbf{H}$ is symmetric and idempotent. We conclude that

$$\mathbb{E}[SS_{Res}] = \mathbb{E}[\boldsymbol{\varepsilon}'(\mathbf{I} - \mathbf{H})\boldsymbol{\varepsilon}].$$

- Let us denote $\mathbf{A} = \mathbf{I} - \mathbf{H}$. We can show that

$$\boldsymbol{\varepsilon}' \mathbf{A} \boldsymbol{\varepsilon} = \sum_{i,j=1}^n a_{i,j} \varepsilon_i \varepsilon_j,$$

where $a_{i,j}$ is the (i, j) entry of \mathbf{A} .

Verification that $E(SS_{Res}) = \sigma^2(n - p)$ //

- Then,

$$\mathbb{E}[SS_{Res}] = \mathbb{E}(\boldsymbol{\varepsilon}' \mathbf{A} \boldsymbol{\varepsilon}) = \sum_{i,j=1}^n a_{i,j} \mathbb{E}(\varepsilon_i \varepsilon_j).$$

- Remember the assumptions we have for the errors (see Topic 2, page 5):
 - $\mathbb{E}(\varepsilon_i) = 0$,
 - $\text{Var}(\varepsilon_i) = \sigma^2$ (**Homoskedasticity Assumption**),
 - $\text{Cov}(\varepsilon_i, \varepsilon_j) = 0$, for $i \neq j$.

Then, when $i = j$, $\mathbb{E}(\varepsilon_i \varepsilon_j) = \mathbb{E}(\varepsilon_i^2) = \text{Var}(\varepsilon_i) = \sigma^2$, and, when $i \neq j$,

$\mathbb{E}(\varepsilon_i \varepsilon_j) = \text{Cov}(\varepsilon_i, \varepsilon_j) = 0$. Thus, we have

$$\sum_{i,j=1}^n a_{i,j} \mathbb{E}(\varepsilon_i \varepsilon_j) = \sigma^2 \sum_{i=1}^n a_{i,i} = \sigma^2 \text{tr}(\mathbf{A}) = \text{tr}(\mathbf{I} - \mathbf{H}).$$

- Finally, using the last property of page 13,

$$\mathbb{E}[SS_{Res}] = \sigma^2 \text{tr}(\mathbf{I} - \mathbf{H}) = \sigma^2(n - p).$$

Verification of $\bar{e} = 0$

- To show that $\bar{e} = 0$ or, equivalently, $\sum_{i=1}^n e_i = 0$, we can use the first equation of the normal equations given in page 5 of Topic 3:

$$-2 \sum_{i=1}^n \left(y_i - \hat{\beta}_0 - \sum_{j=1}^k \hat{\beta}_j x_{ij} \right) = -2 \sum_{i=1}^n e_i = 0.$$

Finding $\hat{\sigma}^2$ in R I

- ① The value of $\hat{\sigma}$ is directly reported in the summary of the `lm` function as the “Residual standard error”.
- ② The following shows three different methods to compute the MSE $\hat{\sigma}^2$ in the case of Table.B4 in Montgomery et al. (sale prices of 24 houses), regressing the sale price y against x_1 (taxes) and x_3 (lot size). Exercise: Run the code and check you get the same value.

Finding $\hat{\sigma}^2$ in R II

```
# Extracting the residual standard error or MSE  
mymodel<-lm(y~x1+x3,data=table.b4)  
  
# Method 1  
sigma(mymodel)  
  
# Method 2  
(summ<-summary(mymodel))  
(MSE<-summ$sig^2)  
  
# method 3  
e<-resid(mymodel)  
(SS_Res<-t(e) %*% e)  
(MSE2<-SS_Res/ (24-3))
```

Note the use of `resid` to find the residuals, `t (A)` to find the transpose, and `% * %` for matrix multiplication.

Estimated Variance-Covariance Matrix of $\hat{\beta}$ in R I

- The natural estimate of the covariance matrix $\text{Cov}(\hat{\beta}) = \sigma^2(\mathbf{X}'\mathbf{X})^{-1}$ is

$$s^2(\hat{\beta}) := \widehat{\text{Cov}}(\hat{\beta}) := \hat{\sigma}^2(\mathbf{X}'\mathbf{X})^{-1}$$

- The function `vcov(mymodel)` returns the above matrix.
- The following code show the use of this function.

Estimated Variance-Covariance Matrix of $\hat{\beta}$ in R II

```
# Regress House Sale Price against x1=taxes (in thousand dollars)
# and x3 lot size (in thousand of square feet)
data(table.b4)

mymodel<-lm(y~x1+x3,data=table.b4)

summ<-summary(mymodel)

> # Extracting the Covariance Matrix of the OLS
> # Method 1: Use of vcov function:
> (V=vcov(mymodel))
```

	(Intercept)	x1	x3
(Intercept)	6.8693708	-0.9133021	-0.1066774
x1	-0.9133021	0.2987683	-0.1658113
x3	-0.1066774	-0.1658113	0.1937260

Estimated Variance-Covariance Matrix of $\hat{\beta}$ in R III

Let us verify the answer using matrix operations:

```
# Method 2: by hand  
> X<-model.matrix(mymodel)  
> C<-solve(t(X) %*% X)  
> sigma(mymodel)^2*C
```

	(Intercept)	x1	x3
(Intercept)	6.8693708	-0.9133021	-0.1066774
x1	-0.9133021	0.2987683	-0.1658113
x3	-0.1066774	-0.1658113	0.1937260

Note the use of the function `model.matrix(mymodel)` to extract the design matrix \mathbf{X} and `solve(A)` to find A^{-1} .