Multi-agent deep reinforcement learning in mobile robotics

Mapping of ideas

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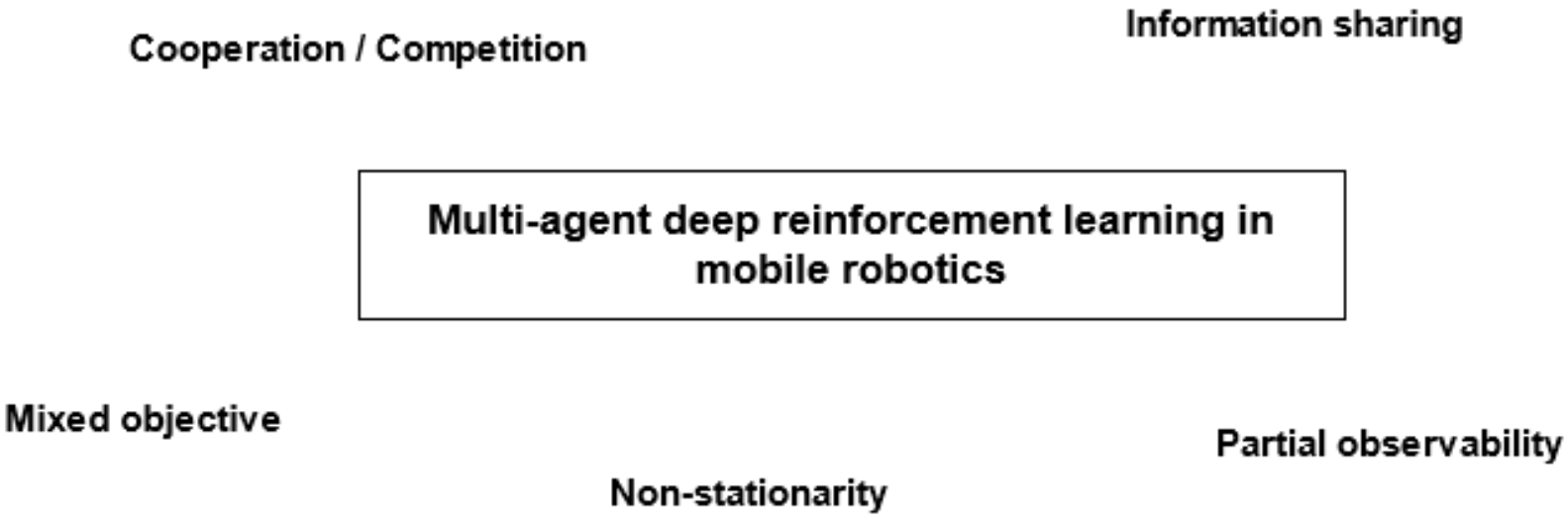
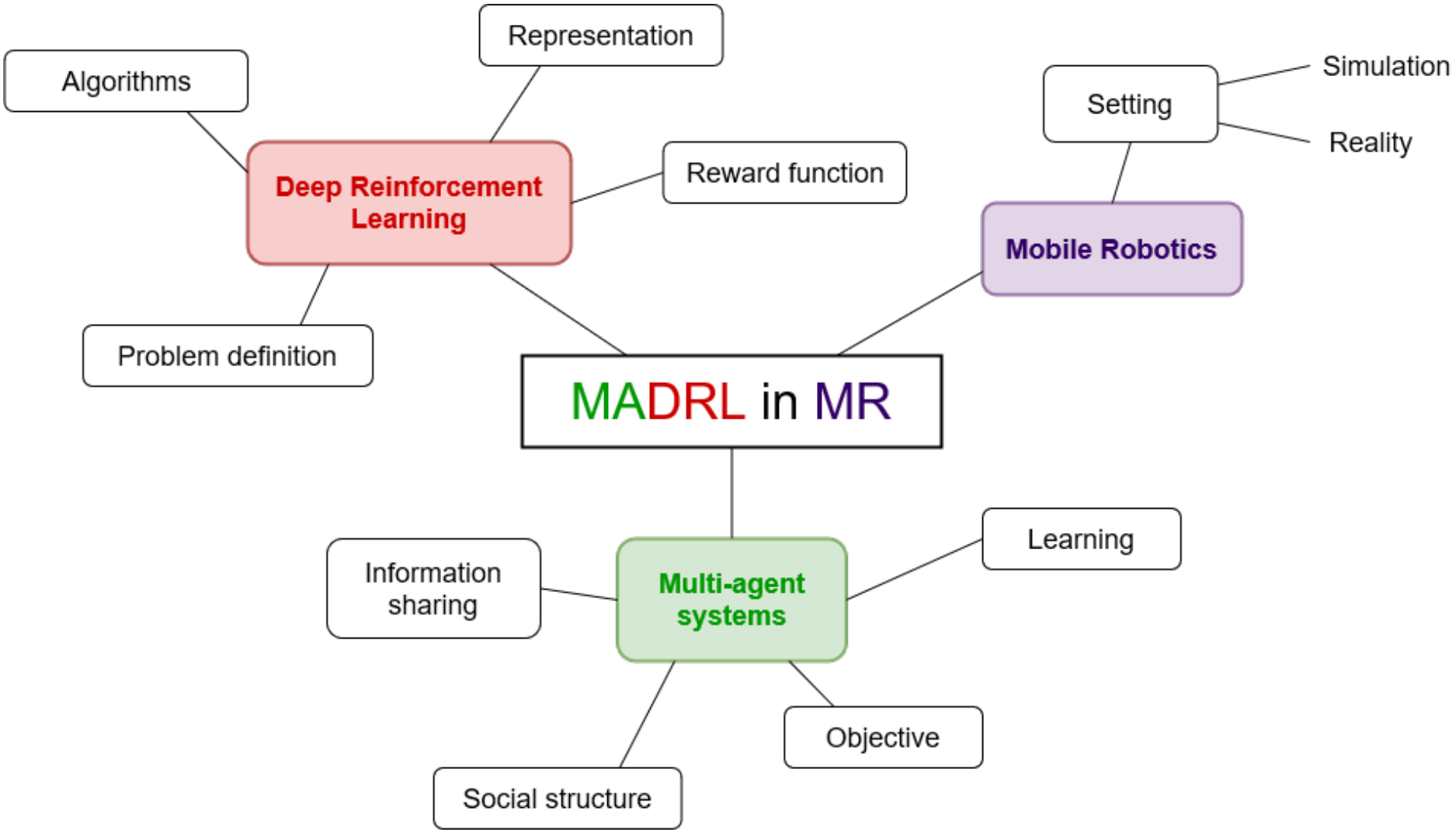
1st of March 2021

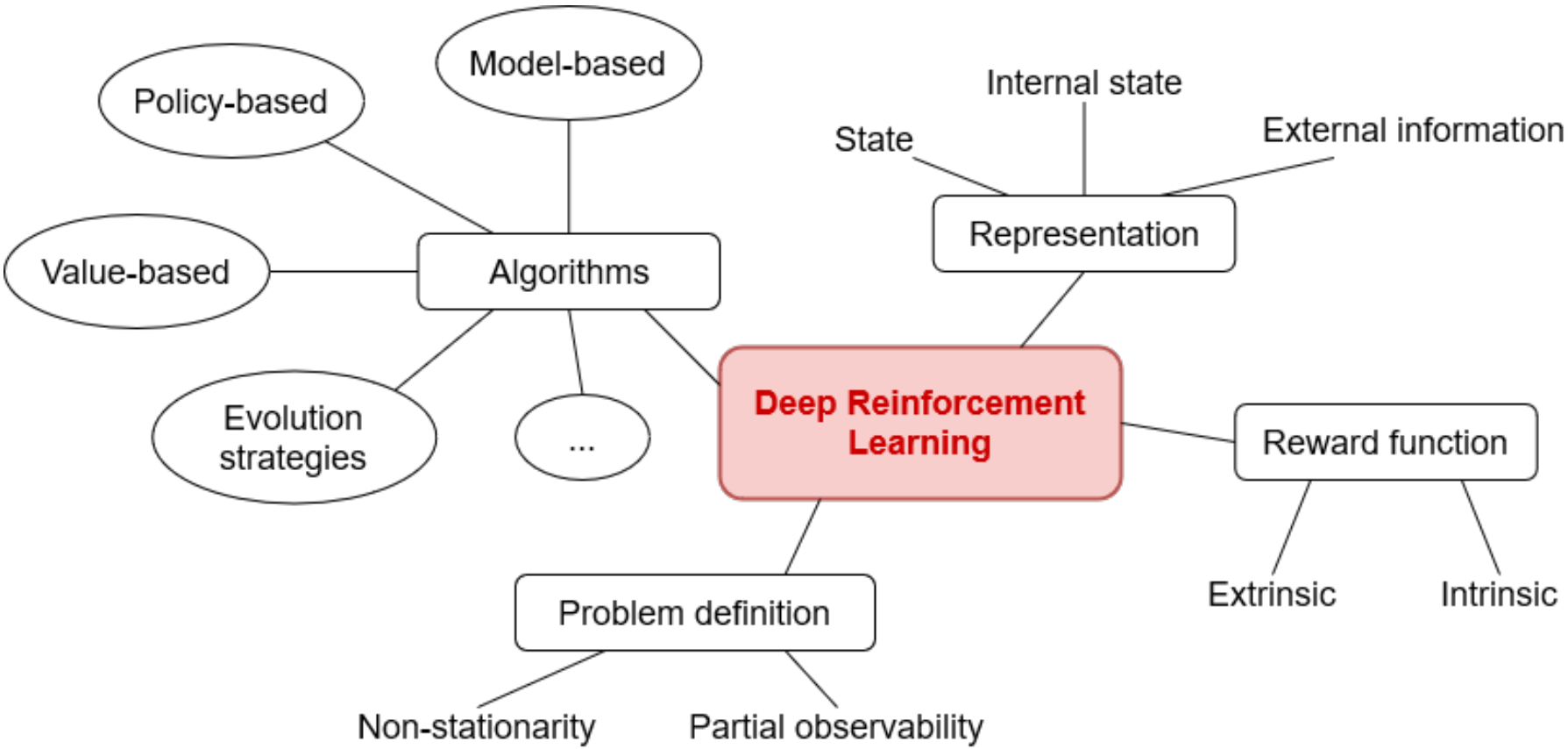
Main Ideas


Cooperation / Competition
Information sharing
Multi-agent deep reinforcement learning in mobile robotics
Mixed objective
Partial observability
Non-stationarity

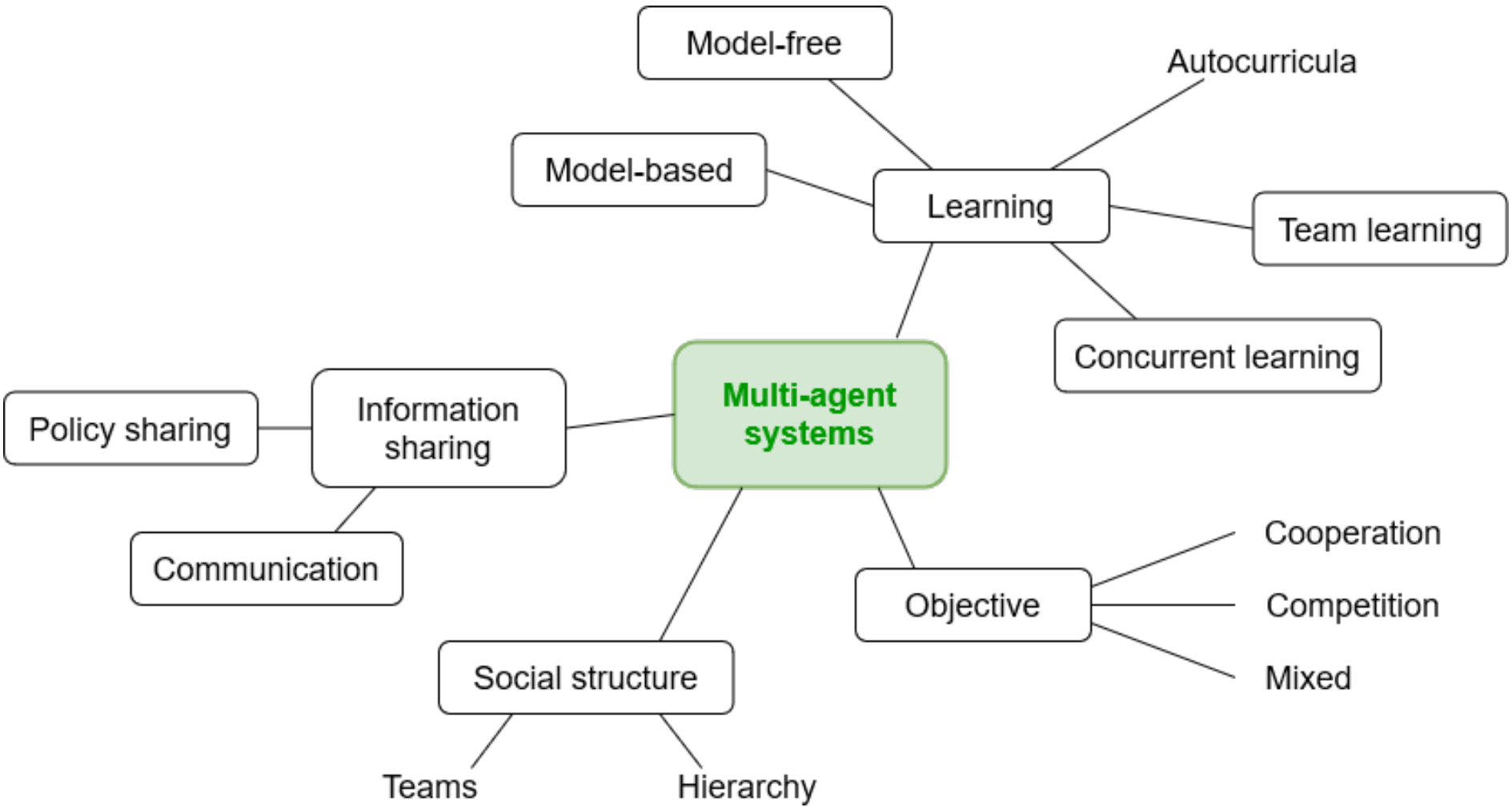
Extracting main concepts



Deep reinforcement learning



Multi-agent systems



Thank you!