

Tips	First, Follow, and LL(1)	LR(1) parsing algorithm
<ul style="list-style-type: none"> ϵ is not a terminal symbol 		
Context-free Grammars	Calculating First sets	Put \$0 on the <i>Parsing stack</i> , and the input string, followed by \$, in the <i>Input</i> queue
Left-associative - $(1 \oplus 2) \oplus 3$	<ul style="list-style-type: none"> If production of form $N \rightarrow \epsilon$, add ϵ to first set for N to indicate nullability If production of form $N \rightarrow S_1 S_2 \dots S_n$, then if $\forall i \in 1..n, \forall j \in 1..i-1 \cdot S_j$ is nullable, we add current first set for S_i to first set for N If every construct S_1, \dots, S_n is nullable, add ϵ to first set for N 	1. Choose transition action based on look-ahead. If it is
$E \rightarrow E \oplus T \mid T$ $T \rightarrow N$		(a) <i>shift</i> , dequeue start symbol of <i>Input</i> queue, and put dequeued symbol on the <i>Parsing stack</i>
Right-associative - $1 \oplus (2 \oplus 3)$	Perform for all productions, repeating the process until no sets are modified	(b) <i>reduce</i> , pop start symbol of the RHS of the reduction, and all stack elements above the start symbol, off the stack. Transition to state indicated by number currently on top of stack. Put reduced symbol on the stack. If $LR(1)$, choose production s.t. $queue_0 \in T$, where T is look-ahead set. Follow transition path of current state, based on the reduced symbol.
$E \rightarrow T \oplus E \mid T$ $T \rightarrow N$	LL(1) Grammars	
$E \rightarrow TE'$ $E' \rightarrow \epsilon \mid \oplus TE'$ $T \rightarrow N$	Definition	
Left-factoring and left-recursion removal	A BNF grammar is LL(1) if for each nonterminal, N , where $N \rightarrow a_1 \mid a_2 \mid \dots \mid a_n$,	
Removing left recursion	the first sets of each pair of alternatives for N are disjoint:	(c) <i>accept</i> , do nothing
$E \rightarrow E \oplus T \mid T$	$\forall i, j \in 1..n \cdot i \neq j \implies First(a_i) \cap First(a_j) = \{\}$	2. Put number indicating current state on the stack
is transformed into	if N is nullable, $First(N)$ and $Follow(N)$ are disjoint, i.e.,	Repeat numbered process
$E \rightarrow TE'$ $E' \rightarrow \epsilon \mid \oplus TE'$	$N \xRightarrow{*} \epsilon \implies First(N) \cup Follow(N) = \{\}$	
This transformers a left-associative grammar into a right-associative grammar	Because the first set for an alternative includes ϵ if the alternative is nullable, the constraint that the first sets of all the alternatives are pairwise disjoint implies at most one alternative is nullable. [This is the reason for including ϵ in the First sets.]	Parameters
Recogniser Code	Bottom up parsing	Kinds of parameter passing mechanisms
T	LR(x) parsing automaton	<i>Call by const</i> : the formal parameter acts as a read-only local variable that is initially assigned the value of the actual parameter expression.
tokens.match(Token.T);	Don't forget to first add production: $S' \rightarrow E$.	<i>Call by value</i> : the formal parameter acts as a local variable that is initially assigned the value of the actual parameter expression.
N	LR(x) parsing action conflicts	<i>Call by result</i> : the formal parameter acts as a local variable whose final value is assigned to the actual parameter variable.
parseN();	There is no such thing as a <i>shift/shift</i> conflict	<i>Call by value-result</i> : a single parameter acts as both a value and a result parameter
$S_1 \dots S_n$	Derived LR(1) items	
recog(S_1); ...; recog(S_n);	If a state has an LR(1) item of the form	Kinds of parameter passing
$S_1 S_2 \dots S_n$	$[N \rightarrow a \cdot M\beta, T]$	<i>Call by reference</i> : the formal parameter is really the address of the actual parameter variable; all references to the formal parameter are applied (via that address) to the actual parameter variable immediately. (In Pascal known as a var parameter).
if (token.isIn(First(S_1))) {	where the nonterminal M has productions	<i>Call by name</i> : the actual parameter expression is evaluated every time the formal parameter is accessed.
recog(S_1);	$M \rightarrow a_1 \mid a_2 \mid \dots \mid a_m$	<i>Passing procedures (or functions) as parameters</i> : need to pass the address of the procedure as well as the static link for the procedures environment.
...}	and $T = \{a_1, a_2, \dots, a_m\}$, then the state also includes the derived items	<i>Returning procedures (or functions)</i> : need to return the address of the procedure as well as the static link for the procedures environment - note that this requires the environment of the returned procedure to be maintained which means that the simple stack-based allocation of frames is not sufficient.
else if ($[M \rightarrow \cdot a_1, T']$	
tokens.isIn(First(S_n)))	...	
recog(S_n);	$[M \rightarrow \cdot a_m, T']$	
else {		
errors.error("Syntax_error");		
}		
[S]		
if (token.isIn(First(S))) {		
recog(S);		
}		
{S}		
while (token.isIn(First(S)))		
recog(S);		
}		
(S)		
recog(S);		
Methods like token.getValue() do not consume the token. match(NUMBER) will need to be called immediately afterwards.	where $T' = First(\beta a_1) \cup \dots \cup First(\beta a_n)$. If β is not nullable $T' = First(\beta)$ and if β is nullable, $T' = First(\beta) - \{\epsilon\} \cup T$.	

Dynamic Memory Allocation/Deallocation

Garbage collection schemes

Mark and sweep garbage collection consists of

- a phase that *marks* all the accessible objects
- a phase that *sweeps* up the objects left unmarked and adds them to the free list

Stop-and-copy (or two-space) garbage collection

- divides the available memory into two (large) spaces
- memory is allocated sequentially from one space until it runs out
- garbage collection consists of relocating all accessible objects from the first space to the second space
- because the objects are allocated sequentially in the second space, they are compacted
- when the copy is completed the roles of the spaces are swapped for the next garbage collection

Find all objects accessible from the runtime stack or global variables (either directly or indirectly) and copy them into the second space, allocating them sequentially (so that they are allocated more compactly), and placing a forwarding pointer with the old object to the new copy, so that other references to the (old) object can be updated to point to the new object. Generational schemes use a scheme similar to the two-space scheme but make use of multiple spaces

- the spaces are organised based on the length of time its objects have survived
- the age of an object is the number of times it has been collected
- older objects are migrated to an old object space
- newer objects go in the new object space
- the objects in the old object space don't need to be copied when the new object space is garbage collected
- the old object space may have to be garbage collected at some stage

Regular expressions and finite state machines

Definitions

The empty closure of a state x in an NFA N , $\epsilon\text{-closure}(x, N)$, is the set of states in N that are reachable from x via any number of empty transitions.

The empty closure of a set of states X in an NFA N , $\epsilon\text{-closure}(X, N)$, is the set of states in N that are reachable from any of the states in X via any number of empty transitions.

Constructing the DFA from the NFA

- The label of the start state of the DFA consists of the set of states containing the start state s_0 of the NFA plus all the states in the NFA that are reachable from its start state by one or more empty transitions.

$$S_0 = \epsilon\text{-closure}(s_0, N)$$

- The process for forming a DFA works with a set of unmarked DFA states by selecting an unmarked DFA state and considering all transitions from it on symbols.
- The initial set of unmarked states contains just S_0 .
The following process is repeated until there are no unmarked DFA states left.
- An unmarked DFA state S is selected (the first one is S_0).
- For each symbol a ,
 - we consider the set of states that can be reached from any state in S by a transition on a ; call this set of states X
 - if X is nonempty, we add a new state to the DFA labelled with $X' = \epsilon\text{-closure}(X, N)$, unless a state with that label already exists
 - a transition from S to X' on a is added to the DFA.
- The state S is marked as having been processed.

Stack Machine

Definitions

Each activation contains:

a static link (at offset 0 from fp) also called an access link, it is used for accessing non-local variables;

a dynamic link (at offset 1) also called a control link, it contains the address of the activation record of the calling procedure (so the frame pointer can be restored on return from the procedure);

a return address (at offset 2) which is the address of the instruction to execute on return from the procedure (used for restoring the program counter on return);

local variables which are allocated sequentially on the stack with addresses relative to the frame pointer starting from offset 3; and **parameters** which are allocated sequentially on the stack with negative addresses relative to the frame pointer.

Calling a procedure

1. any parameters to the procedure are pushed onto the stack;
2. the static link is pushed onto the stack;
3. the current frame pointer is pushed onto the stack to create the dynamic link;
4. the frame pointer is set so that it contains the address of the start of the new stack frame (i.e., the address of the location containing the static link);
5. the current value of the program counter (which is the address of the instruction after the call) is pushed onto the stack to form the return address;
6. the program counter is set to the address of the procedure and execution of the body of the procedure begins;
7. space is allocated on the stack for any local variables (using instruction **ALLOC_STACK**).

Returning from a procedure

1. the program counter is set to the return address in the current activation record;
2. the frame pointer is set to the dynamic link;
3. the stack pointer is set so that all the space used by the stack frame (but not parameters) is popped from the stack;
4. execution continues at the instruction addressed by the (restored) program counter; and
5. after return the calling procedure handles deallocating any parameters (using instruction **DEALLOC_STACK**)

Static semantics

$$e ::= n \mid id \mid e.id \mid \text{record}(id, fe)$$

$$fe ::= id \mapsto e$$

$$syms \vdash n : int$$

$$\frac{id \in \text{dom}(syms) \quad syms(id) = \text{VarEntry}(T)}{syms \vdash id : T}$$

$$\frac{syms \vdash e : \text{RecordType}(fields) \quad id \in \text{dom}(fields)}{syms \vdash e.id : fields(id)}$$

$$\frac{id \in \text{dom}(syms) \quad syms(id) = \text{TypeEntry}(\text{RecordType}(fields)) \quad \text{dom}(fields) = \text{dom}(fe) \quad \forall id \in \text{dom}(fields) \cdot syms \vdash fe(id) : fields(id)}{syms \vdash \text{record}(id, fe) : \text{RecordType}(fields)}$$

$$e ::= n \mid id \mid \dots \mid \lambda id_1 : id_2 \ e \mid e_1(e_2)$$

$$\frac{id \in \text{dom}(syms) \quad syms(id_2) = \text{TypeEntry}(T_1) \quad syms \oplus \{id_1 \mapsto \text{VarEntry}(T_1)\} \vdash e : T_2}{syms \vdash (\lambda id_1 : id_2 \ e) : (T_1 \rightarrow T_2)}$$

$$\frac{syms \vdash e_1 : T_1 \rightarrow T_2 \quad syms \vdash e_2 : T_1}{syms \vdash e_1(e_2) : T_2}$$

$$e ::= n \mid id \mid \dots \mid \text{let } id = e \text{ in } end$$

$$\frac{syms \vdash e_1 : T_1 \quad syms \vdash e_1 \xrightarrow{e} v_1 \quad syms \oplus \{id \mapsto \text{ConstEntry}(T_1, v_1)\} \vdash e_2 : T_2 \quad syms \oplus \{id \mapsto \text{ConstEntry}(T_1, v_1)\} \vdash e_2 \xrightarrow{e} v_2}{syms \vdash \text{let } id = e_1 \text{ in } e_2 \text{ end} : T_2 \quad syms \vdash \text{let } id = e_1 \text{ in } e_2 \text{ end} \xrightarrow{e} v_2}$$