

# PHIL3110 - Assignment 2

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## Problem 1

**Definition 1**  $f : \mathcal{X} \rightarrow \mathcal{Y}$  is injective  $\Leftrightarrow \forall x_1, x_2 \in \mathcal{X}$  if  $F(x_1) = F(x_2)$  then  $x_1 = x_2$ .

**Theorem 1** If  $f : \mathcal{X} \rightarrow \mathcal{Y}$  is injective and  $g : \mathcal{Y} \rightarrow \mathcal{Z}$  is injective, then  $g \circ f$  is injective.

**Proof 1** Suppose  $f : \mathcal{X} \rightarrow \mathcal{Y}$  is injective and  $g : \mathcal{Y} \rightarrow \mathcal{Z}$  is injective. We must show that  $g \circ f$  is injective. Suppose  $x_1$  and  $x_2$  are elements of  $\mathcal{X}$  such that

$$(g \circ f)(x_1) = (g \circ f)(x_2)$$

By definition of composition of functions,

$$g(f(x_1)) = g(f(x_2))$$

Since  $g$  is injective

$$f(x_1) = f(x_2)$$

And since  $f$  is injective

$$x_1 = x_2$$

**Theorem 2** There is some injection  $f : A \rightarrow B \Leftrightarrow A \preceq B$ .

If  $A$ ,  $B$  and  $C$  are sets such that  $A \preceq B$  and  $B \preceq C$ , there exists an injective  $f : A \rightarrow B$  and injective  $g : B \rightarrow C$ . Per theorem 1,  $g \circ f : A \rightarrow C$  is injective. Per theorem 2,  $g \circ f$  entails  $A \preceq C$ .

## Problem 2

1.

$$\varphi_1 := (\exists x)(x)$$

says that there is at least 1 object, and

$$\varphi_2 := (\exists x)(\exists y)(x \neq y)$$

says that there at least 2 objects.

Thus

$$\varphi_n := (\exists x_1)(\exists x_2) \dots (\exists x_n)(x_1 \neq x_2 \neq \dots \neq x_n)$$

says that for any natural number  $n$ , there are at least  $n$  objects.

2. We need to prove that every finite subset  $\Delta$  of  $S$  has a model, e.g. there exists a model  $\mathcal{M}$  such that  $\mathcal{M} \models \Delta$ .

First, we'll define a stage based definition of  $S$ , where:

$$s(0) = T$$

$$s(n+1) = s(n) \cup \{\varphi_{n+1}\}$$

such that  $\{s(n) \mid n \in \omega\} = S$ .

At each step, we need to show that

- The model that satisfies  $s(n)$  defines  $s(n)$  objects
- The model is finitely satisfiable

### Base

$0 \in A$ . We can fix some  $\mathcal{M}$  where  $\mathcal{T} \subseteq \mathcal{M}$ , where  $\mathcal{T} \models T$  for every finite subset  $\Delta$  of  $s(0)$ .

The only finite subset of  $s(0)$  is  $T$ .

By our fix of  $\mathcal{M}$ ,  $\mathcal{M} \models T$ . Therefore,  $s(0)$  is finitely satisfiable -  $\mathcal{M} \models s(0)$ .

$\mathcal{M}$  defines at least 0 objects.

### Induction Step

Suppose  $n \in A$ .

Let  $\mathcal{N}$  be the model that satisfied  $s(n)$ . It defined at least  $n$  objects.

$\mathcal{N} \not\models \Delta$  for each finite subset  $\Delta$  of  $s(n+1)$ .

Why?

The only finite subset  $\Delta$  of  $s(n+1) \setminus s(n)$  is  $\{\varphi_{n+1}\}$ .

Consider the only sentence in  $\Delta$ ,  $\varphi_{n+1}$ .

In order for  $\mathcal{N} \models \varphi_{n+1}$ ,  $\mathcal{N}$  would need to define  $n+1$  objects.

Consider some  $\mathcal{M}$  that defines a new object, so that  $\mathcal{N} \subseteq \mathcal{M}$ . Now  $\mathcal{M}$  defines at least  $n+1$  objects.

By theorem 139, as  $\gamma$  is of the form  $\Sigma_1$ , and  $\mathcal{N} \models \varphi_n^1$ ,  $\mathcal{M} \models \varphi_{n+1}$ .

As  $\mathcal{M} \models s(n)$ , and  $\mathcal{M} \models s(n+1) \setminus s(n)$ , every finite subset  $\Delta$  of  $s(n) \cup (s(n+1) \setminus s(n))$  is satisfiable.

Thus, every finite subset  $\Delta$  of  $s(n+1)$  is satisfiable.

Thus,  $n+1 \in A$ . Then by induction, we see that every  $n \in A$ .

$S$  is finitely satisfiable.

3. As every finite subset  $\Delta$  of  $S$  has a model, by the compactness theorem, there is a model  $\mathcal{M}$  such that  $\mathcal{M} \models S$ . By the previous step, we know that  $\mathcal{M}$  defines  $\omega$  objects to satisfy  $S$ .  $\omega$  is infinite. Therefore,  $\mathcal{M}$  is infinite, and we are thus able to say that  $S$  has, or requires, an infinite model.

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<sup>1</sup> $\varphi_n \in s(n) \setminus s(n-1)$

### Problem 3

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; This program accepts a block of n-many 1s and outputs a block of 2n-many 1s,
; after the original block with a single blank space separating them;

; Henceforth:
; - the n-many 1's will be referred to as the "parameter array"
; - the 2n-many 1's will be referred to as the "accumulator array"
; - the single blank space separating them will be referred to as "the divider"

; ALGORITHM SUMMARY: Move a loop pointer through the parameter array,
; terminating the loop when the pointer reaches the end of the parameter array.
; On each loop, append two 1s to the end of the accumulator array.

; ### State 0: as per the assignment sheet, the head should start under the 1th cell
0 - -R 1

; ### State 1 deals with placing our loop pointer, and halting the loop
; Our loop pointer is a blank, that shifts through our parameter array.
; where [_ 1 1 1] starts the loop, and [1 1 1 1] halts the loop

; This instruction puts down the new loop pointer.
; This either initializes it (if we came from State 0),
; or increments it (if we came from State 6)
1 1 -R 2

; ### State 2 deals with getting to the start of the accumulator array
; Glide over the parameter array
2 1 1 R 2

; Jump over the divider
2 --R 3

; ### State 4 and 5 deal with getting to the end of the accumulator,
; and appending two 1s.
; Glide over the accumulator...
3 1 1 R 3

; ... until we pop out the end of the accumulator. Put down a 1...
3 -1 R 4

; ... and another one. Now we've gotta turn back around and increment the loop variable.
4 -1 L 5

; ### State 5 deals with trying to get back to the end of the parameter array
; Glide back over the accumulator array
5 1 1 L 5
; Jump over the divider
5 --L 6

; ### State 6 deals with incrementing our loop variable
; Glide over our parameter array...
6 1 1 L 6

; ...until we hit our loop pointer. We clear the current loop pointer, shift the
; head right, and loop back to state 1, so that it may deal with the next loop iteration.
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6 -1 R 1

; This is our loop halting condition. State 6 has cleared the loop pointer,  
; and pushed the head onto the divider. We still have to move the head to the 1th cell.  
1 --L 7

; ##### State 7 deals with getting to the 1th cell, and halting  
; Glide back over our parameter array...  
7 1 1 L 7

; ... and when we pop out past the head of the parameter array, shift right to  
; the 1th cell, and halt  
7 --R halt

## Problem 4

We will attempt to demonstrate that  $A$  is recursive. The same process may be repeated to show that  $B$  and  $C$  are also recursive.

By definition,  $A$  is recursively enumerable, and that  $A \subseteq \omega$ . To prove that  $A$  is recursive, we must show that  $\omega \setminus A$  is recursively enumerable.

Suppose  $\omega \setminus A$  was not recursively enumerable.

There exists an  $n \in \omega \setminus A$ , such that no  $\varphi_e$  exists, that has a domain  $\omega \setminus A$ , and halts when applied to  $n$ .

As  $B$  and  $C$  are recursively enumerable there are partial recursive functions  $\varphi_B$  and  $\varphi_C$  which have the domains of  $B$  and  $C$  respectively. We can define a function

$$\varphi_{B \cup C}(n) = \begin{cases} \varphi_b(n), & \text{if } \varphi_b(n) \text{ halts.} \\ \varphi_c(n), & \text{if } \varphi_c(n) \text{ halts.} \\ \text{undefined,} & \text{otherwise.} \end{cases}$$

which has the domain  $B \cup C$ . By definition  $A \cap B \cap C = \omega$ ,  $B \cap C = \omega \setminus A$ .

This means we have found a partially recursive function,  $\varphi_{B \cup C}$ , that has the domain  $n \in \omega \setminus A$  and halts on every  $n \in \omega \setminus A$ . This is a contradiction.

Thus,  $\omega \setminus A$  is recursively enumerable.

Thus,  $A$  is recursive.