

Machine Learning Project: Image Augmentation and Transfer Learning

Cifar-10 dataset

We will be using the CIFAR-10 dataset for the entirety of the assignment. The CIFAR-10 dataset consists of 60000 32x32 color images in 10 classes, with 6000 images per class. There are 50000 training images and 10000 test images. The images were collected by Alex Krizhevsky, Vinod Nair, and Geoffrey Hinton.

The 10 different classes in the dataset are as follows:

Number	Class Label
1	Airplane
2	Automobile
3	Bird
4	Cat
5	Deer
6	Dog
7	Frog
8	Horse
9	Ship
10	Truck

In [1]:

```
#install required libraries
import pandas as pd
import numpy as np

#data visualization packages
import matplotlib.pyplot as plt

#keras packages
import keras
from keras.models import Sequential
from keras.layers import Convolution2D
from keras.layers import MaxPooling2D
from keras.layers import Flatten
from keras.layers import Dense
from keras.wrappers.scikit_learn import KerasClassifier
from keras.layers import Dropout

#model evaluation packages
from sklearn.metrics import f1_score, roc_auc_score, log_loss
from sklearn.model_selection import cross_val_score, cross_validate

#other packages
import time as time
from IPython.display import display, Markdown
from IPython.display import display
from time import sleep
from IPython.display import Markdown as md

from keras.datasets import cifar10
```

Using TensorFlow backend.

CNN model without Image Augmentation and Transfer Learning for the benchmark results

Data Preparation

In [2]:

```
#read mnist dataset
mnist = keras.datasets.fashion_mnist
(X_train, y_train), (X_test, y_test) = cifar10.load_data()

#split the dataset into training and validation set
from sklearn.model_selection import train_test_split
X_train, X_val, y_train, y_val = train_test_split(X_train, y_train, test_size=0.2, random_s
print(X_train.shape, y_train.shape, X_val.shape, y_val.shape, X_test.shape, y_test.shape)

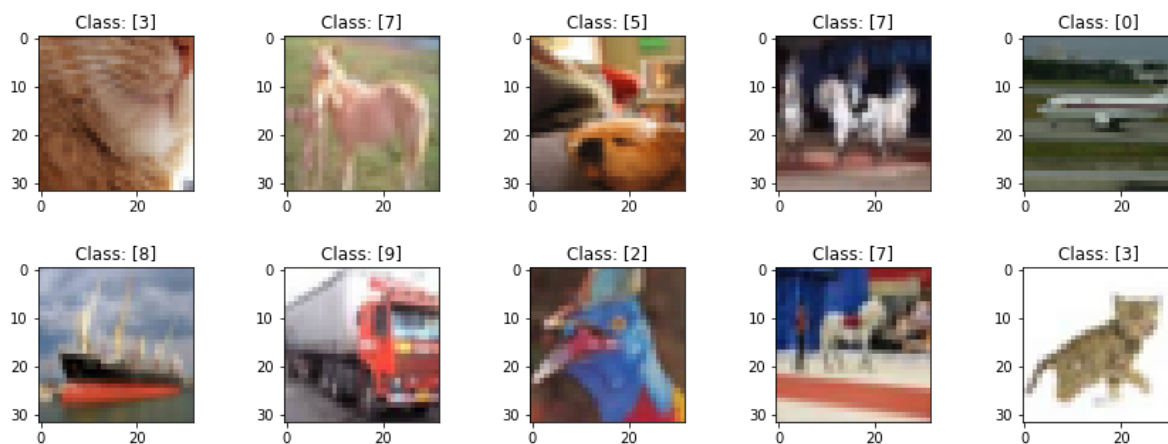
#feature scaling
X_train_scaled = X_train / 255.0
X_val_scaled = X_val / 255.0
X_test_scaled = X_test / 255.0
```

```
(40000, 32, 32, 3) (40000, 1) (10000, 32, 32, 3) (10000, 1) (10000, 32, 32,
3) (10000, 1)
```

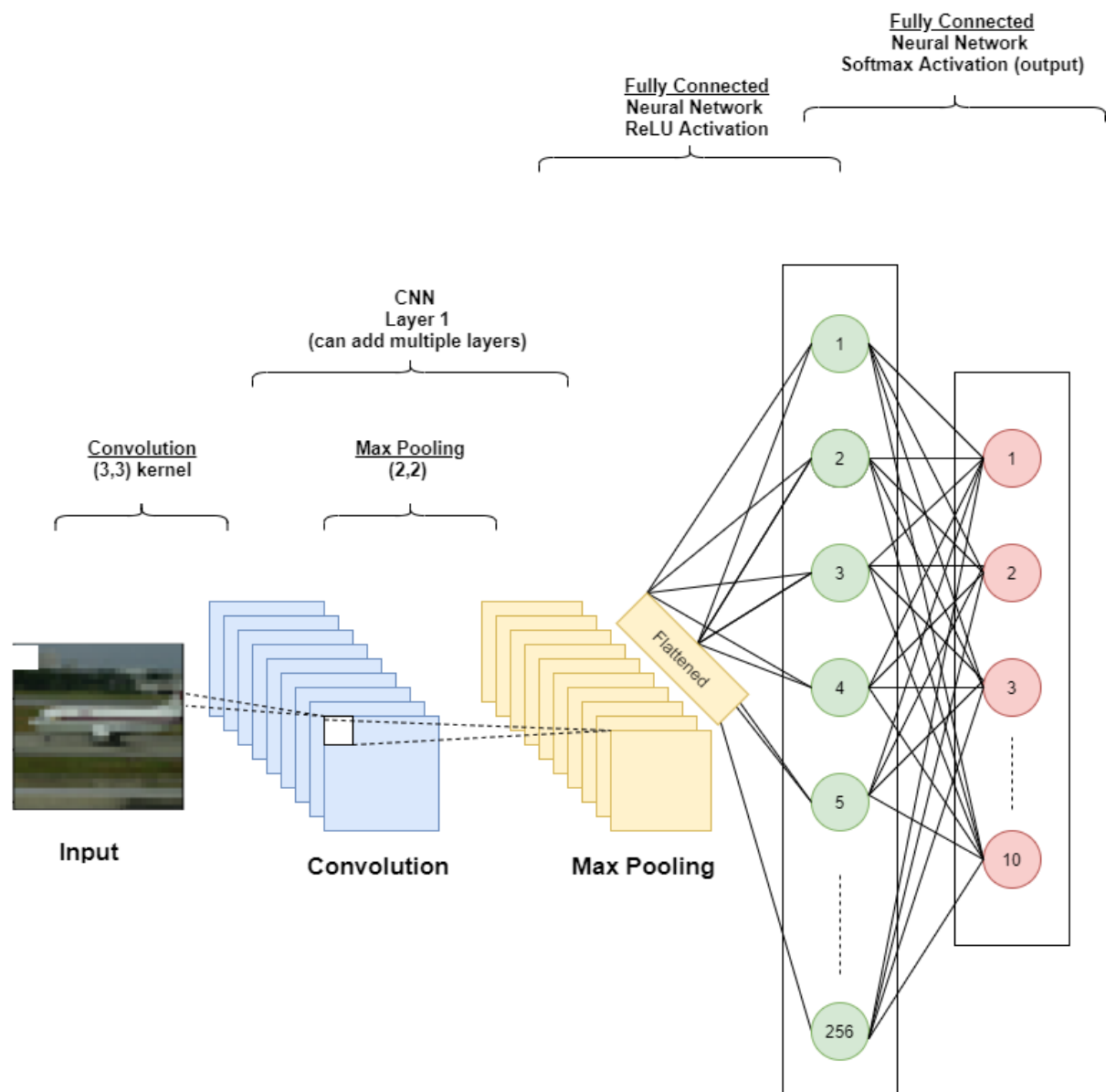
In [3]:

```
#display first 10 images of the dataset
fig, axes = plt.subplots(nrows=2, ncols=5, figsize=(15,5))          #create subplot
ax = axes.ravel()

#Loop through 10 images
for i in range(10):
    ax[i].imshow(X_train[i])                                         #print image
    ax[i].title.set_text('Class: ' + str(y_train[i]))               #print class
plt.subplots_adjust(hspace=0.5)                                     #increase horizontal spa
plt.show()                                                          #display image
```



Convolution Neural Network Model



We have implemented the sequential model as our neural network model. The sequential model is a linear stack of layers, we have added layers to the network by using the `.add()` method.

`kernel_initializer` defines which statistical distribution or function to use for initialising the weights. In case of statistical distribution, the library will generate numbers from that statistical distribution and use as starting weights. In our code above we have used uniform distribution to initialize the weights.

In a neural network, the activation function is responsible for transforming the summed weighted input from the node into the activation of the node or output for that input. The rectified linear activation (Relu) function is a piecewise linear function that will output the input directly if is positive, otherwise, it will output zero. The rectified linear activation function overcomes the vanishing gradient problem, allowing models to learn faster and perform better.

The output of the softmax function is equivalent to a categorical probability distribution, it tells you the probability that any of the classes are true. The class with the highest probability is chosen as the output.

Optimization is the task of searching for parameters that minimize our loss function. We open

use categorical crossentropy when it is a multiclass classification task. **Cross entropy** is a loss function, used to measure the dissimilarity between the distribution of observed class labels and the predicted probabilities of class membership. In our model we have implemented **sparse categorical crossentropy** since we have integers numbered from 0-9 as our class labels.

We have implemented **Adam** which is an optimization algorithm that can be used instead of the classical stochastic gradient descent procedure to update network weights iterative based on training data.

In [4]:

[illegible]

```
ax[0].plot(range(0,classifer_fit.params['epochs']), [acc * 100 for acc in classifier_f
ax[0].plot(range(0,classifer_fit.params['epochs']), [acc * 100 for acc in classifier_f
ax[0].set_title('Accuracy vs. epoch', fontsize=15)
ax[0].set_ylabel('Accuracy', fontsize=15)
ax[0].set_xlabel('epoch', fontsize=15)
ax[0].legend()

#Loss graph
ax[1].plot(range(0,classifer_fit.params['epochs']), classifier_fit.history['loss'], la
ax[1].plot(range(0,classifer_fit.params['epochs']), classifier_fit.history['val_loss']
ax[1].set_title('Loss vs. epoch', fontsize=15)
ax[1].set_ylabel('Loss', fontsize=15)
ax[1].set_xlabel('epoch', fontsize=15)
ax[1].legend()

#display the graph
plt.show()

#Evaluate the model
dh = display('',display_id=True)
dh.update(md("<br>Model evaluation is in progress..."))
t2 = time.time()

#model evaluation
test_loss = classifier.evaluate(X_test_scaled, y_test, verbose=0)
et = time.time()-t2
dh.update(md("<br>Model evaluation is completed! Total evaluation time: **{} seconds**")
display(Markdown('<br>**\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*' Model Evaluation Su

#calculate the model evaluation parameters
f1 = f1_score(y_test, classifier.predict_classes(X_test_scaled), average='micro')
roc = roc_auc_score(y_test, classifier.predict_proba(X_test_scaled) , multi_class='ovr'

#create model evaluation dtaafame
stats = pd.DataFrame({'Test accuracy': round(test_loss[1]*100,3),
                      'F1 score': round(f1,3),
                      'ROC AUC score': round(roc,3),
                      'Total Loss': round(test_loss[0],3)}, index=[0])

#print the dataframe
display(stats)

#return the classifier and model evaluation details
return classifier fit, stats
```

Number of CNN layer = 2

In [5]:

```
#run the CNN model with 1 layer
classifier_1cnn, stats_1cnn = model_cnn(2)
```

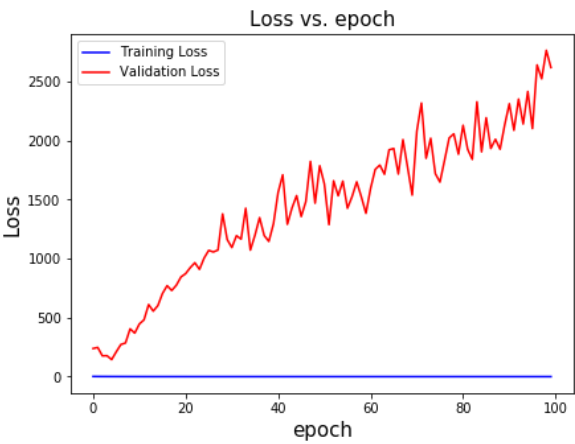
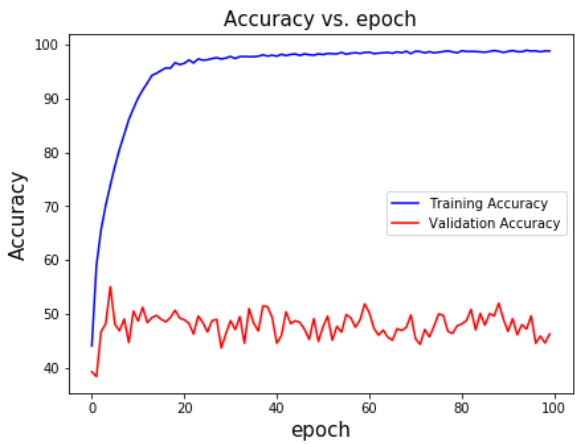
<IPython.core.display.Markdown object>

Model: "sequential_1"

Layer (type)	Output Shape	Param #
=====		
conv2d_1 (Conv2D)	(None, 30, 30, 32)	896
=====		
max_pooling2d_1 (MaxPooling2	(None, 15, 15, 32)	0
=====		
conv2d_2 (Conv2D)	(None, 13, 13, 32)	9248
=====		
max_pooling2d_2 (MaxPooling2	(None, 6, 6, 32)	0
=====		
flatten_1 (Flatten)	(None, 1152)	0
=====		
dense_1 (Dense)	(None, 256)	295168
=====		
dense_2 (Dense)	(None, 512)	131584
=====		
dense_3 (Dense)	(None, 10)	5130
=====		
Total params: 442,026		
Trainable params: 442,026		
Non-trainable params: 0		
=====		

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	Test accuracy	F1 score	ROC AUC score	Total Loss
0	65.08	0.651	0.927	5.479

Key Inferences

- 1) The training accuracy is more than 96% and the validation accuracy is nearby 50%.
- 2) There is a clear indication of the overfitting happening in the model as we can see the big gap between the two curves.
- 3) Since the training and validation loss accuracy diverged consistently and the difference increases as we increase the number of epochs, it would be advisable to limit the number of epochs for this model.
- 4) We can further increase the performance of the model by incorporating below points:
 - 1) We can increase the training size as the model is not generalizing well with the given data size.
 - 2) We can add regularization (dropout) within the model.
 - 3) Use Image Augmentation
 - 4) Add Transfer Learning model architecture

We will demonstrate a few of the methods discussed above in the following analysis.

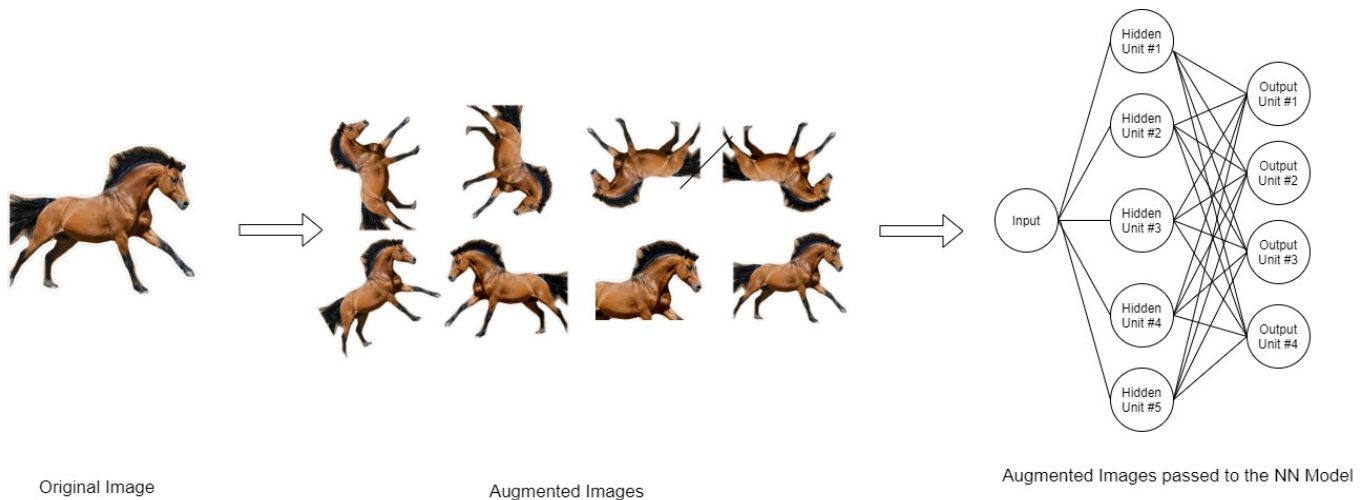
CNN Model with Image Augmentation

1. When humans see an image they see a 2-D representation of a 3-D object. When our computer inputs an image, all it comprehends is an array of numbers. These numeric values are the values of the pixel and cumulatively make up the image.
2. If we manipulate the image by altering the values of the pixels slightly, for us humans that change will be miniscule and we can still visualize the original image from the altered image, for the computer however, the array containing the pixel values of the altered image will be different than the array of the original image and the new altered image will be considered as a different image by the computer.
3. We make sure to assign the new altered image the same class label as the original label to ensure that tasks such as classification are performed correctly. 4. This concept of artificially increasing the size of the training dataset by slightly altering the already existing training dataset is known as **Image Augmentation**.
5. Training deep learning neural network models on more data can result in more skillful models, and the augmentation techniques can create variations of the images that can improve the ability

of the fit models to generalize what they have learned to new images.

6.The Keras deep learning neural network library provides the capability to fit models using image data augmentation via the **ImageDataGenerator class**.

7.So, to get more data, we just need to make minor alterations to our existing dataset. Minor changes such as flips or translations or rotations. Our neural network would think these are distinct images.



We have performed augmentation on our dataset by using the ImageDataGenerator Class. ImageDataGenerator generates batches of image data with real-time data augmentation. The paramaters we have used are explained below in detail.

1. **Zoom_range:** Zoom_range enables us to randomly zoom in the images. The value of zoom_range ranges from 0 to 1 and the intensity of the zoom increases as we increase from 0 to 1.
2. **height_shift_range:** In this method, we provide a value between 0 and 1 which specifies the maximum amount of vertical shift the image will undergo.
3. **rotation_range:** The values provided to this parameyer in degree provides the range for the random roatations for our dataset.
4. **shear_range:** The value passed to the shear_range parameter dictates the intensity of the shear transformation that is applied to the image.
5. **width_shift_range:** Here we pass the fraction of the total width which acts as the range for the random horizontal shift of the images.
6. **horizontal_flip:** The boolean parameter decides whether or not randomly chosen images in the dataset will be flipped horizontally. The value True passed means that some images that are randomly selected will be horizontally flipped.
7. **fill_mode:** Fill Mode has 4 values that we can choose from, namely, 'Constant','nearest','reflect' and 'wrap'. Fill mode is used to fill the newly created pixels that get created when we shift our images horizontally or vertically.

In [6]:

```
#Image Augmentation Library
from keras.preprocessing.image import ImageDataGenerator

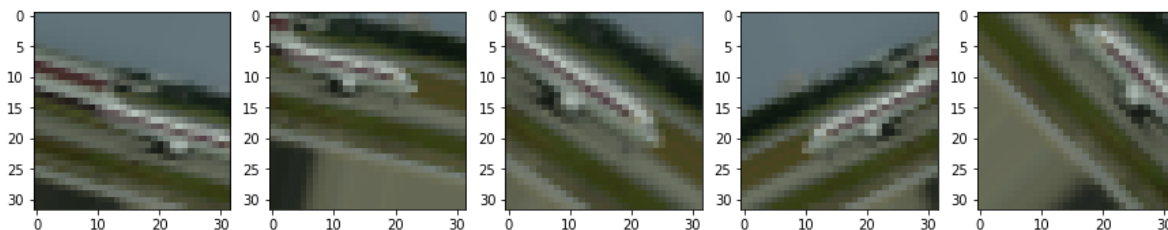
#training dataset
train_datagen = ImageDataGenerator(zoom_range=0.25,           #Range for random zoom
                                   height_shift_range=0.25,    #fraction of total height
                                   rotation_range=45,          #Degree range for random rota
                                   shear_range=0.25,           #(Shear angle in counter-cloc
                                   width_shift_range=0.3,       #fraction of total width
                                   horizontal_flip=True,        #Randomly flip inputs horizon
                                   fill_mode='nearest')          #Points outside the boundarie

#validation dataset
val_datagen = ImageDataGenerator()
```

In [7]:

```
#image augmentation samples
#pick any random image
img_id = 4
number_of_images = 5
image = train_datagen.flow(X_train_scaled[img_id:img_id+1], y_train[img_id:img_id+1], batch

#pick 5 augmentation image
cat = [next(image) for i in range(0,number_of_images)]
fig, ax = plt.subplots(1,number_of_images, figsize=(15, 7.5))
l = [ax[i].imshow(cat[i][0][0]) for i in range(0,5)]
```



In [8]:

[illegible]

```
<IPython.core.display.Markdown object>
```

```
Model: "sequential_2"
```

Layer (type)	Output Shape	Param #
conv2d_3 (Conv2D)	(None, 30, 30, 32)	896
max_pooling2d_3 (MaxPooling2D)	(None, 15, 15, 32)	0
flatten_2 (Flatten)	(None, 7200)	0
dense_4 (Dense)	(None, 256)	1843456
dense_5 (Dense)	(None, 512)	131584
dense_6 (Dense)	(None, 10)	5130
Total params: 1,981,066		
Trainable params: 1,981,066		
Non-trainable params: 0		

In [9]:

```
#training dataset image augmentation
train_generator = train_datagen.flow(X_train_scaled,
                                     y_train,
                                     batch_size=40)

#validation dataset image augmentation
val_generator = val_datagen.flow(X_val_scaled,
                                 y_val,
                                 batch_size=20)

#image size
input_shape = (32, 32, 3)

#include timing information
dh = display('',display_id=True)
dh.update(md("<br>Training is in progress....."))
t1 = time.time()

#model fitting
history_ia = classifier_ia.fit_generator(train_generator,
                                       validation_data=val_generator,
                                       epochs=100,
                                       steps_per_epoch=1000,
                                       validation_steps=500,
                                       verbose=0)

tt = time.time()-t1
avg_per_epoch_ia = round(tt/(history_ia.epoch[-1]+1),3)
dh.update(md("<br>Training is completed! <br><br>Total training time: **{} seconds** <br>Av
```

<IPython.core.display.Markdown object>

In [10]:

```
#plot the graph
```

[illegible]

#accuracy graph

```
fig, axes = plt.subplots(nrows=1, ncols=2, figsize=(15,5))
ax = axes.ravel()
ax[0].plot(range(0, history_ia.params['epochs']), [acc * 100 for acc in history_ia.history['acc']])
ax[0].plot(range(0, history_ia.params['epochs']), [acc * 100 for acc in history_ia.history['val_acc']])
ax[0].set_title('Accuracy vs. epoch', fontsize=15) #title
ax[0].set_ylabel('Accuracy', fontsize=15) #y-label
ax[0].set_xlabel('epoch', fontsize=15) #x-label
ax[0].legend() #legend
```

#Loss graph

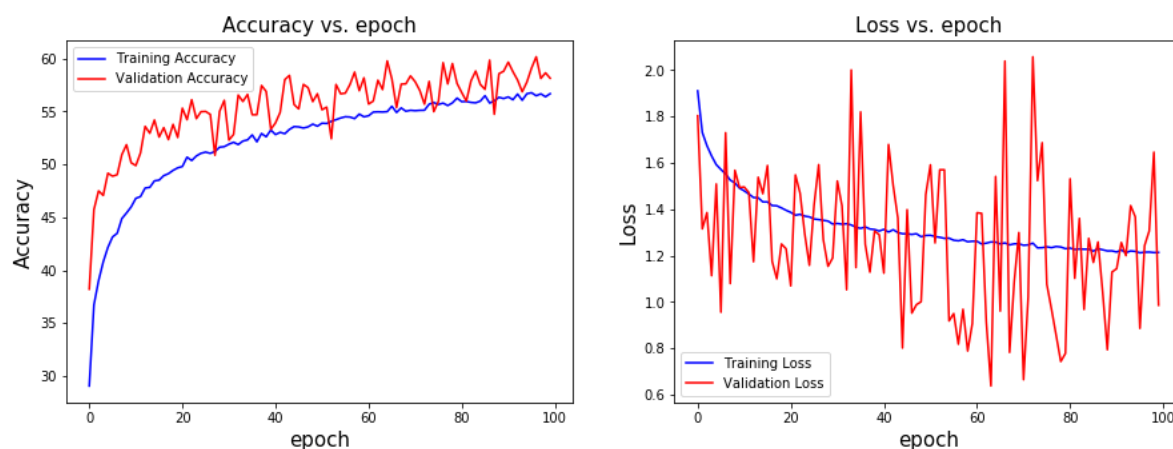
```
ax[1].plot(range(0, history_ia.params['epochs']), history_ia.history['loss'], label='Trainin  
ax[1].plot(range(0, history_ia.params['epochs']), history_ia.history['val_loss'], label='Val  
ax[1].set_title('Loss vs. epoch', fontsize=15)  
ax[1].set_ylabel('Loss', fontsize=15)  
ax[1].set_xlabel('epoch', fontsize=15)  
ax[1].legend()
```

```
#display the graph
```

```
plt.show()
```

◀ [REDACTED] ▶

```
<IPython.core.display.Markdown object>
```



Key Inferences

- 1) We have successfully mitigated the problem of overfitting by introducing the Image Augmentation method which helps the model in generalizing the features well.
- 2) The validation accuracy increased by approx. 6% than our previous model.
- 3) The trend in the graph shows that, increasing then number of epochs results in an increase in the accuracy of the model.

In [11]:

[illegible]

```
<IPython.core.display.Markdown object>
```

```
<IPython.core.display.Markdown object>
```

	Test accuracy	F1 score	ROC AUC score	Total Loss
0	58.36	0.584	0.925	1.234

Transfer Learning

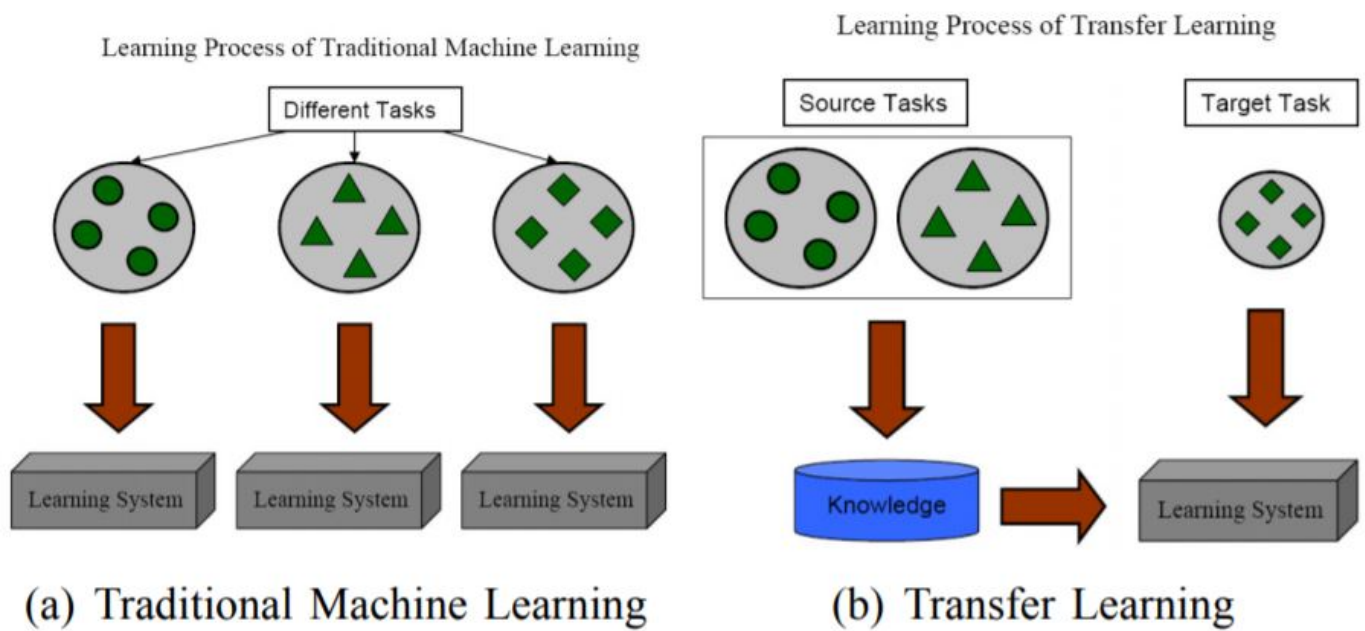
When working on a problem specific to our domain, often the amount of data needed to build models of this size is impossible to find. However models trained on one task capture relations in the data type and can easily be reused for different problems in the same domain. This technique is referred to as **Transfer Learning**.

With transfer learning, we can take a pretrained model, which was trained on a large readily available dataset (trained on a completely different task, with the same input but different output). Then try to find layers which output reusable features. We use the output of that layer as input features to train a much smaller network that requires a smaller number of parameters. This smaller network only needs to learn the relations for your specific problem having already learnt about patterns in the data from the pretrained model.

While deciding whether or not to perform transfer learning, we try to figure out and map the commonalities in the knowledge of the source and target task. The knowledge that can be transferred from the source task to the target task will play an important role in deciding the efficiency and effectiveness of the model and in turn will boost the performance on the target task. It is very important that the source and target task be of the same domain otherwise the performance will degrade. Such a scenario is often called as Negative Transfer because of the

negative impact of the transfer learning model on the performance of the target task.

The figure below provides a representation of the concept behind Transfer Learning.



Qiang Yang, Sinno Jialin Pan, "A Survey on Transfer Learning", IEEE Transactions on Knowledge and Data Engineering, vol. 22, no. , pp. 1345–1359, October 2010, doi:10.1109/TKDE.2009.191

We have implemented Transfer Learning in our project by implementing two pre-trained models - VGG16 and MobileNet. A detailed model achitecture and under-the-hood working of the pre-trained models is given below.

VGG-16

VGG16 is a convolutional neural network model proposed by K. Simonyan and A. Zisserman from the University of Oxford in the paper "Very Deep Convolutional Networks for Large-Scale Image Recognition". It's trained on the ImageNet dataset which consists of more than 14 million images and comprises of more than 1000 classes.

The model architecture of VGG-16 is shown below.

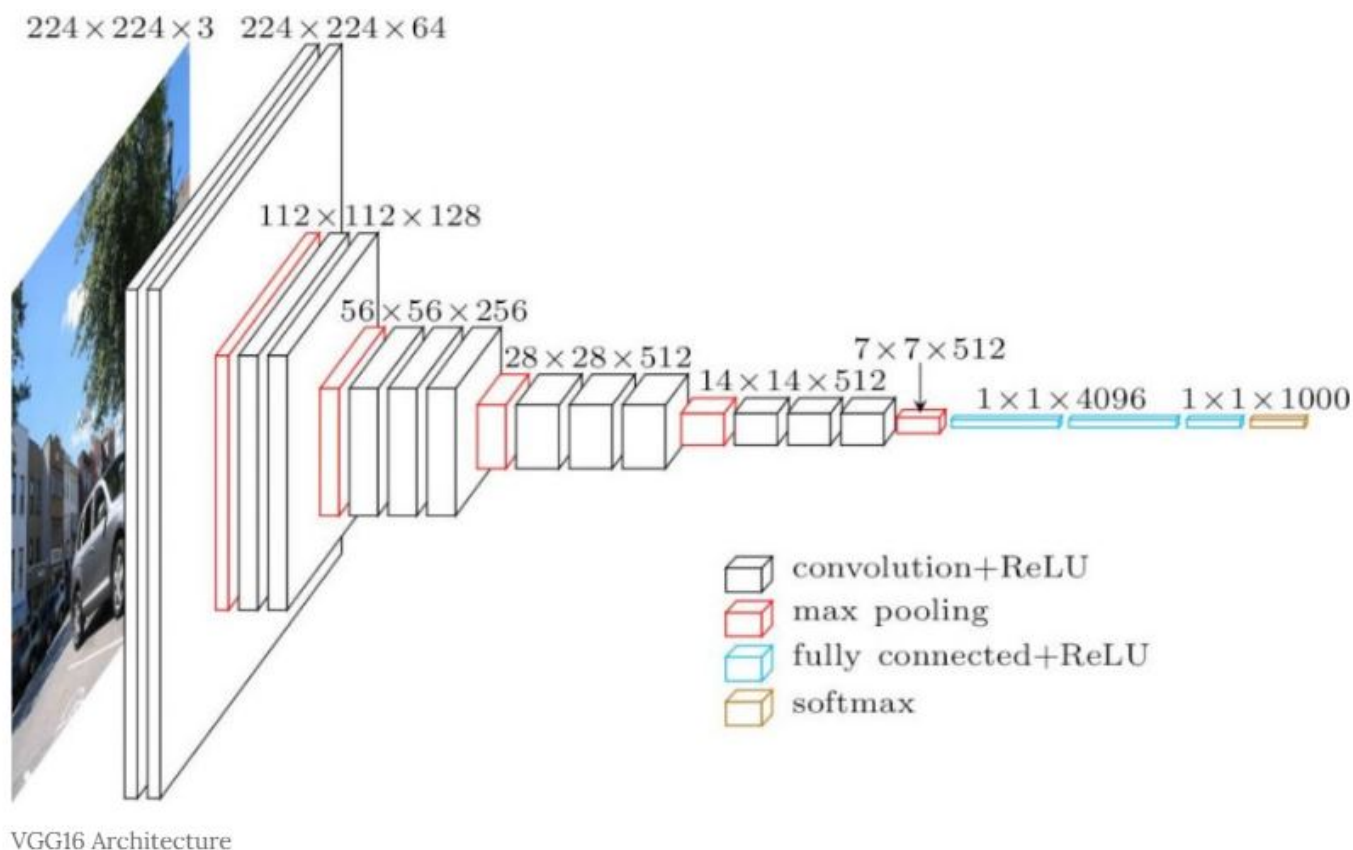


Image Courtesy : [VGG16 – Convolutional Network for Classification and Detection](https://neurohive.io/en/popular-networks/vgg16/)
[\(https://neurohive.io/en/popular-networks/vgg16/\)](https://neurohive.io/en/popular-networks/vgg16/)

Although there are 21 layers in the model, the model derives its name from the fact that there are 16 weight layers. The various layers encompassed in the model are Convolutional layers, Max Pooling layers, Activation layers and Fully Connected layers.

Model 1: Feature Extraction

In [12]:

```
#import required libraries
from keras.applications import vgg16
from keras.models import Model
import keras
```

In [13]:

```
#image size of CIFAR-10 dataset
input_shape = (32, 32, 3)

#import model from Keras
TL1 = vgg16.VGG16(include_top=False,          #include_top: whether to include the 3 fully
                  weights='imagenet',         #weights: one of None (random initialization)
                  input_shape=input_shape)    #input_shape: optional shape tuple, only if
```

We begin transfer learning process by removing the output classifier layer which has softmax implemented over 1000 units for the 1000 classes in the imagenet dataset used by VGG16 model to make the model consistent with our problem statement.

In [14]:

```
#remove the classifier layer from the model
output = TL1.layers[-1].output
output = keras.layers.Flatten()(output)
TL1_model = Model(TL1.input, output)
```

We then proceed by freezing the layers of the VGG16 model, since we would like to take advantage of the generic image features that the VGG16 model has already learned and utilize the knowledge that the model has already learned to our benefit. By freezing the layers we prevent the weights of the layers of the pretrained model from being updated.
<\b>

In [15]:

```
#freeze all the layers of the model
TL1_model.trainable = False
for layer in TL1_model.layers:
    layer.trainable = False
```

In [16]:

```
#details of model with trainable flag set to True/False
TL1_details = pd.DataFrame([(layer, layer.name, layer.trainable) for layer in TL1_model.layers])

#display model details
TL1_details
```

Out[16]:

	Layer Type	Layer Name	Trainable
0	<keras.engine.input_layer.InputLayer object at 0...	input_1	False
1	<keras.layers.convolutional.Conv2D object at 0...	block1_conv1	False
2	<keras.layers.convolutional.Conv2D object at 0...	block1_conv2	False
3	<keras.layers.pooling.MaxPooling2D object at 0...	block1_pool	False
4	<keras.layers.convolutional.Conv2D object at 0...	block2_conv1	False
5	<keras.layers.convolutional.Conv2D object at 0...	block2_conv2	False
6	<keras.layers.pooling.MaxPooling2D object at 0...	block2_pool	False
7	<keras.layers.convolutional.Conv2D object at 0...	block3_conv1	False
8	<keras.layers.convolutional.Conv2D object at 0...	block3_conv2	False
9	<keras.layers.convolutional.Conv2D object at 0...	block3_conv3	False
10	<keras.layers.pooling.MaxPooling2D object at 0...	block3_pool	False
11	<keras.layers.convolutional.Conv2D object at 0...	block4_conv1	False
12	<keras.layers.convolutional.Conv2D object at 0...	block4_conv2	False
13	<keras.layers.convolutional.Conv2D object at 0...	block4_conv3	False
14	<keras.layers.pooling.MaxPooling2D object at 0...	block4_pool	False
15	<keras.layers.convolutional.Conv2D object at 0...	block5_conv1	False
16	<keras.layers.convolutional.Conv2D object at 0...	block5_conv2	False
17	<keras.layers.convolutional.Conv2D object at 0...	block5_conv3	False
18	<keras.layers.pooling.MaxPooling2D object at 0...	block5_pool	False
19	<keras.layers.core.Flatten object at 0x0000027...	flatten_3	False

We now add fully connected classifier layers on top of the pretrained model to learn the features that are specific to our dataset. Since our dataset consists of 10 classes, our output layer consists of 10 units with the softmax activation function to give us the probability of each class with respect to every input.

In [18]:

```
from keras.layers import InputLayer

#Model Initializing, Compiling and Fitting
classifier_tl1 = Sequential()

#fully connected layer
#input Layer
classifier_tl1.add(InputLayer(input_shape=(TL1_model.output_shape[1],)))

#dense (hidden) Layer
classifier_tl1.add(Dense(units = 256, kernel_initializer='uniform', activation='relu', input_dim=TL1_model.output_shape[1]))

#dense (hidden) Layer
classifier_tl1.add(Dense(units = 512, kernel_initializer='uniform', activation='relu'))

#output Layer
classifier_tl1.add(Dense(units = 10, kernel_initializer='uniform', activation='softmax'))

#compile the model
classifier_tl1.compile(optimizer='adam', loss='sparse_categorical_crossentropy', metrics=['accuracy'])

#model summary
display(Markdown('<br>***\n\n Model Summary \n\n'))
classifier_tl1.summary()
```

```
<IPython.core.display.Markdown object>
```

```
Model: "sequential_3"
```

Layer (type)	Output Shape	Param #
dense_7 (Dense)	(None, 256)	131328
dense_8 (Dense)	(None, 512)	131584
dense_9 (Dense)	(None, 10)	5130
Total params: 268,042		
Trainable params: 268,042		
Non-trainable params: 0		

We then extract the features, from the pre-trained layers that are frozen and use these extracted features to train the classifier layers that we've added on our model. We can visualize it by considering that the output from the layer before the flatten operation of the pretrained model now becomes the input to the new layers added by us on top of the pretrained model.

In [19]:

```
#function to extract features from the images
def model_image(model, image):
    image_feature = model.predict(image, verbose=0)
    return image_feature

#training dataset feature extraction from the pre-trained layers
X_train_features = model_image(TL1_model, X_train_scaled)

#validation dataset feature extraction from the pre-trained layers
X_val_features = model_image(TL1_model, X_val_scaled)

#print dataset shapes
print('Training Image shape:', X_train_features.shape,
      '\tValidation Image shape:', X_val_features.shape)
```

Training Image shape: (40000, 512) Validation Image shape: (10000, 512)

In [20]:

```
#include timing information
dh = display('',display_id=True)
dh.update(md("<br>Training is in progress....."))
t1 = time.time()

#model fitting
history_tl1 = classifier_tl1.fit(x=X_train_features,
                                y=y_train,
                                validation_data=(X_val_features, y_val),
                                batch_size=30,
                                epochs=100,
                                verbose=0)

tt = time.time()-t1
avg_per_epoch_tl1 = round(tt/(history_tl1.epoch[-1]+1),3)
dh.update(md("<br>Training is completed! <br><br>Total training time: **{} seconds** <br>Av
```

<IPython.core.display.Markdown object>

In [21]:

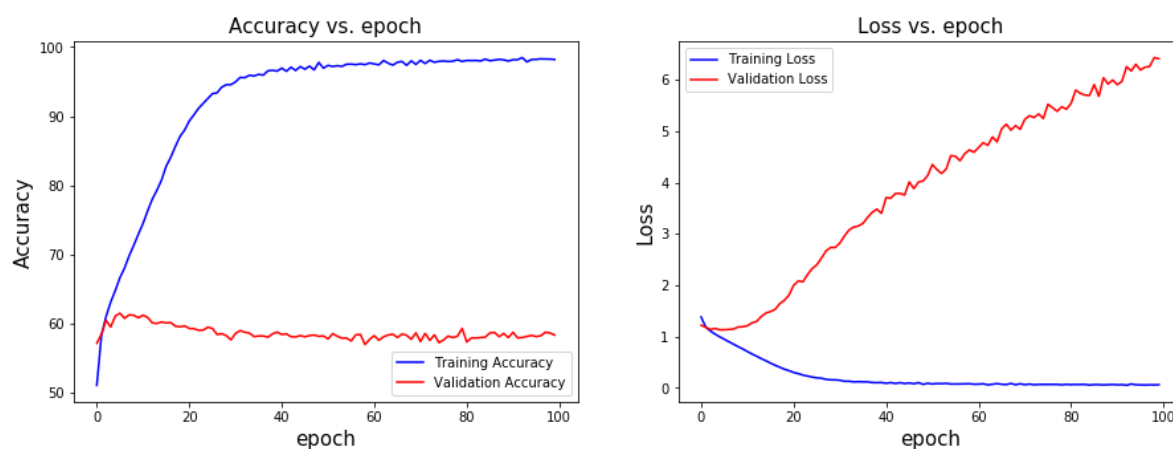
```
#plot the graph
display(Markdown('<br>***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***\n\n***'))
```

```
#accuracy graph
fig, axes = plt.subplots(nrows=1, ncols=2, figsize=(15,5))
ax = axes.ravel()
ax[0].plot(range(0,history_tll.params['epochs']), [acc * 100 for acc in history_tll.history])
ax[0].plot(range(0,history_tll.params['epochs']), [acc * 100 for acc in history_tll.history])
ax[0].set_title('Accuracy vs. epoch', fontsize=15)
ax[0].set_ylabel('Accuracy', fontsize=15)
ax[0].set_xlabel('epoch', fontsize=15)
ax[0].legend()
```

```
#Loss graph
ax[1].plot(range(0,history_tll.params['epochs']), history_tll.history['loss'], label='Train')
ax[1].plot(range(0,history_tll.params['epochs']), history_tll.history['val_loss'], label='V')
ax[1].set_title('Loss vs. epoch', fontsize=15)
ax[1].set_ylabel('Loss', fontsize=15)
ax[1].set_xlabel('epoch', fontsize=15)
ax[1].legend()
```

```
#display the graph
plt.show()
```

```
<IPython.core.display.Markdown object>
```



Key Inferences

- 1) The training accuracy is more than 96% and the validation accuracy is nearby 60%.
- 2) Because of the large gap between training and validation accuracy, we can infer that the model is overfitting.
- 3) We can prevent the model from overfitting and thereby increasing the validation accuracy by incorporating Image augmentation as shown below.

In [22]:

[illegible]

```
<IPython.core.display.Markdown object>
```

```
<IPython.core.display.Markdown object>
```

	Test accuracy	F1 score	ROC AUC score	Total Loss
0	58.13	0.581	0.903	6.506

Model 2: Feature Extractor + Image Augmentation

We then proceed to fine-tune the layers added by us by freezing the layers of the pre-trained model and by using data augmentation. By freezing the layers of the pretrained models, the weights of those layers will not change and only the layers added by us will alter their weight and learn the features specific to our dataset. The augmentation of the images in our dataset enables us to train our layers with additional data to enhance the learning with respect to our dataset

In [23]:

[illegible]

```
<IPython.core.display.Markdown object>
```

Model: "sequential 4"

Layer (type)	Output Shape	Param #
model_1 (Model)	(None, 512)	14714688
dense_10 (Dense)	(None, 256)	131328
dense_11 (Dense)	(None, 512)	131584
dense_12 (Dense)	(None, 10)	5130
Total params: 14,982,730		
Trainable params: 268,042		
Non-trainable params: 14,714,688		

In [24]:

```
#include timing information
dh = display('',display_id=True)
dh.update(md("<br>Training is in progress....."))
t1 = time.time()

#model fitting
history_feia = classifier_feia.fit_generator(train_generator,
                                             validation_data=val_generator,
                                             epochs=100,
                                             steps_per_epoch=1000,
                                             validation_steps=500,
                                             verbose=0)

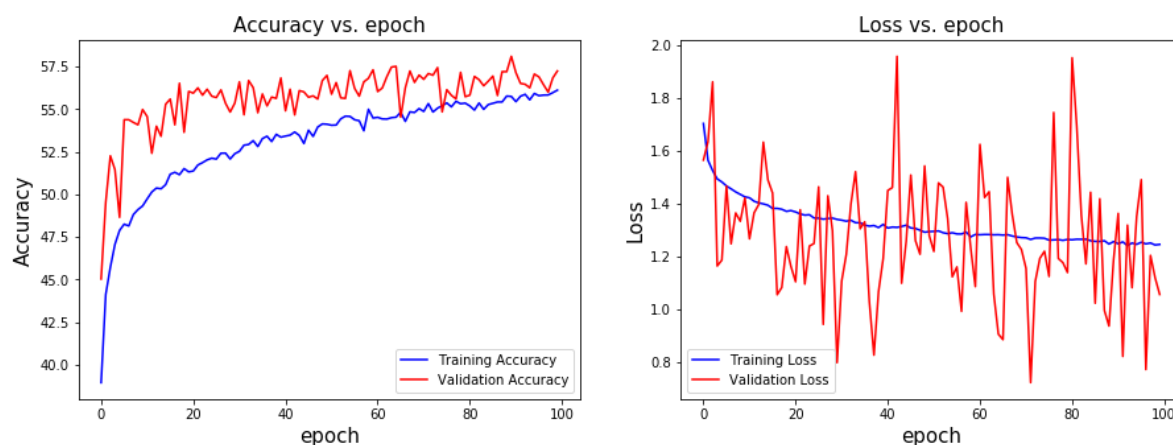
tt = time.time()-t1
avg_per_epoch_feia = round(tt/(history_feia.epoch[-1]+1),3)
dh.update(md("<br>Training is completed! <br><br>Total training time: **{} seconds** <br>Av
```

<IPython.core.display.Markdown object>

In [25]:

[illegible]

```
<IPython.core.display.Markdown object>
```



Key Inferences

- 1) The training accuracy is more than 55% and the validation accuracy is also nearby the training accuracy.
- 2) We have successfully mitigated overfitting in our model by introducing the Image Augmentation in the dataset.
- 3) The accuracy, however, is not as good as the previous model, to further boost the accuracy we need to fine-tune our model according to our dataset which is demonstrated below.

In [26]:

[illegible]

```
<IPython.core.display.Markdown object>
```

```
<IPython.core.display.Markdown object>
```

	Test accuracy	F1 score	ROC AUC score	Total Loss
0	56.84	0.568	0.914	1.256

Model 3: Fine-tuning (whole network) + Image Augmentation

Finally, we proceed to fine-tune the entire model by unfreezing the layers of the pre-trained model training the entire model with the augmented dataset. By unfreezing the pretrained layers we make it possible for the pretrained layers to learn the features specific to our dataset by altering the weights of its layers. Implementing data augmentation just increases the size of the training dataset and enables the model to learn with a larger dataset. The motive of implementing fine-tuning is to permit a way for the model to learn the intricate details of the current data and not just rely on the dataset it was previously trained on.

In [27]:

```
#unfreeze all the layers of the model
TL1_model.trainable = True

#Loop through all the layers of the model
for layer in TL1_model.layers:
    layer.trainable = True

#print layers details with trainable parameter set to True/False
layers = pd.DataFrame([(layer, layer.name, layer.trainable) for layer in TL1_model.layers],
layers
```

Out[27]:

	Layer Type	Layer Name	Trainable
0	<keras.engine.input_layer.InputLayer object at 0...	input_1	True
1	<keras.layers.convolutional.Conv2D object at 0...	block1_conv1	True
2	<keras.layers.convolutional.Conv2D object at 0...	block1_conv2	True
3	<keras.layers.pooling.MaxPooling2D object at 0...	block1_pool	True
4	<keras.layers.convolutional.Conv2D object at 0...	block2_conv1	True
5	<keras.layers.convolutional.Conv2D object at 0...	block2_conv2	True
6	<keras.layers.pooling.MaxPooling2D object at 0...	block2_pool	True
7	<keras.layers.convolutional.Conv2D object at 0...	block3_conv1	True
8	<keras.layers.convolutional.Conv2D object at 0...	block3_conv2	True
9	<keras.layers.convolutional.Conv2D object at 0...	block3_conv3	True
10	<keras.layers.pooling.MaxPooling2D object at 0...	block3_pool	True
11	<keras.layers.convolutional.Conv2D object at 0...	block4_conv1	True
12	<keras.layers.convolutional.Conv2D object at 0...	block4_conv2	True
13	<keras.layers.convolutional.Conv2D object at 0...	block4_conv3	True
14	<keras.layers.pooling.MaxPooling2D object at 0...	block4_pool	True
15	<keras.layers.convolutional.Conv2D object at 0...	block5_conv1	True
16	<keras.layers.convolutional.Conv2D object at 0...	block5_conv2	True
17	<keras.layers.convolutional.Conv2D object at 0...	block5_conv3	True
18	<keras.layers.pooling.MaxPooling2D object at 0...	block5_pool	True
19	<keras.layers.core.Flatten object at 0x0000027...	flatten_3	True

In [28]:

```
#import required library  
from keras.layers import InputLayer  
  
#Model Initializing, Compiling and Fitting  
classifier_ftia = Sequential()  
  
#fully connected layer  
#input Layer  
classifier_ftia.add(TL1_model)  
  
#dense (hidden) Layer  
classifier_ftia.add(Dense(units = 256, kernel_initializer='uniform', activation='relu', inp  
  
#dense (hidden) Layer  
classifier_ftia.add(Dense(units = 512, kernel_initializer='uniform', activation='relu'))  
  
#output Layer  
classifier_ftia.add(Dense(units = 10, kernel_initializer='uniform', activation='softmax'))  
  
#compile the model  
classifier_ftia.compile(optimizer='adam', loss='sparse_categorical_crossentropy', metrics=[  
  
#model summary  
display(Markdown('<br>***\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\*\\* Model Summary \\*\\*\\*\\*\\*\\n  
classifier_ftia.summary()
```

```
<IPython.core.display.Markdown object>
```

```
Model: "sequential_5"
```

Layer (type)	Output Shape	Param #
model_1 (Model)	(None, 512)	14714688
dense_13 (Dense)	(None, 256)	131328
dense_14 (Dense)	(None, 512)	131584
dense_15 (Dense)	(None, 10)	5130
Total params: 14,982,730		
Trainable params: 14,982,730		
Non-trainable params: 0		

In [29]:

```
#include timing information
dh = display('',display_id=True)
dh.update(md("<br>Training is in progress....."))
t1 = time.time()

#model fitting
history_ftia = classifier_ftia.fit_generator(train_generator,
                                             steps_per_epoch=1000,
                                             epochs=100,
                                             validation_data=val_generator,
                                             validation_steps=500,
                                             verbose=0)

tt = time.time()-t1
avg_per_epoch_ftia = round(tt/(history_ftia.epoch[-1]+1),3)
dh.update(md("<br>Training is completed! <br><br>Total training time: **{} seconds** <br>Av
```



<IPython.core.display.Markdown object>

In [30]:

```
#plot the graph
```

[illegible]

#accuracy graph

```
fig, axes = plt.subplots(nrows=1, ncols=2, figsize=(15,5))
ax = axes.ravel()
ax[0].plot(range(0, history_ftia.params['epochs']), [acc * 100 for acc in history_ftia.history['acc']])
ax[0].plot(range(0, history_ftia.params['epochs']), [acc * 100 for acc in history_ftia.history['val_acc']])
ax[0].set_title('Accuracy vs. epoch', fontsize=15)
ax[0].set_ylabel('Accuracy', fontsize=15)
ax[0].set_xlabel('epoch', fontsize=15)
ax[0].legend()
```

#Loss graph

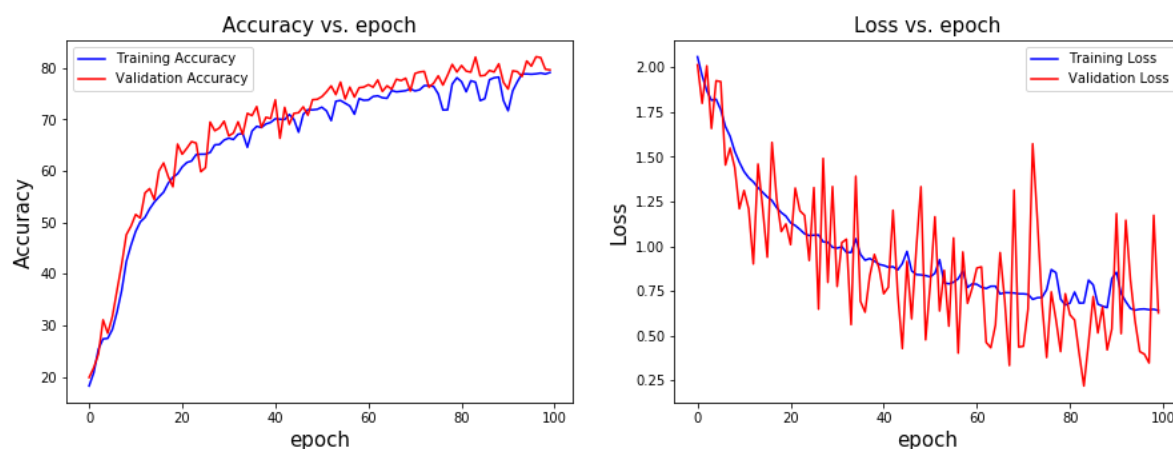
```
ax[1].plot(range(0, history_ftia.params['epochs']), history_ftia.history['loss'], label='Tra')
ax[1].plot(range(0, history_ftia.params['epochs']), history_ftia.history['val_loss'], label='Val')
ax[1].set_title('Loss vs. epoch', fontsize=15)
ax[1].set_ylabel('Loss', fontsize=15)
ax[1].set_xlabel('epoch', fontsize=15)
ax[1].legend()
```

```
#display the graph
```

```
plt.show()
```

◀ [REDACTED] ▶

```
<IPython.core.display.Markdown object>
```



Key Inferences

Out of all the model which we have discussed so far, the above model seems to be the best one because of the following:

- 1) The accuracy is approx 80% for both training and the validation dataset.
- 2) The model is generalizing well for the validation dataset, thereby preventing overfitting.
- 3) We can further increase the performance of the model by increasing the number of epochs as we can see the upward trend for both training as well as the validation dataset.

In [31]:

[illegible]

```
<IPython.core.display.Markdown object>
```

```
<IPython.core.display.Markdown object>
```

	Test accuracy	F1 score	ROC AUC score	Total Loss
0	78.43	0.784	0.974	0.717

MobileNet

The concept of MobileNet neural network architecture was proposed by a group of researchers at Google. The motive behind building MobileNet was to build lightweight deep neural networks by using depthwise separable convolutions. MobileNet is a significantly lightweight model when compared to VGG-16 we have implemented above.

The MobileNet model is also trained on the ImageNet image classification dataset. The MobileNet model consists of 88 layers and works great with smaller datasets. One of the main advantages of using MobileNet is its ability to reduce overfitting.

The model architecture of MobileNet is shown below.

Table 1. MobileNet Body Architecture

Type / Stride	Filter Shape	Input Size
Conv / s2	$3 \times 3 \times 3 \times 32$	$224 \times 224 \times 3$
Conv dw / s1	$3 \times 3 \times 32$ dw	$112 \times 112 \times 32$
Conv / s1	$1 \times 1 \times 32 \times 64$	$112 \times 112 \times 32$
Conv dw / s2	$3 \times 3 \times 64$ dw	$112 \times 112 \times 64$
Conv / s1	$1 \times 1 \times 64 \times 128$	$56 \times 56 \times 64$
Conv dw / s1	$3 \times 3 \times 128$ dw	$56 \times 56 \times 128$
Conv / s1	$1 \times 1 \times 128 \times 128$	$56 \times 56 \times 128$
Conv dw / s2	$3 \times 3 \times 128$ dw	$56 \times 56 \times 128$
Conv / s1	$1 \times 1 \times 128 \times 256$	$28 \times 28 \times 128$
Conv dw / s1	$3 \times 3 \times 256$ dw	$28 \times 28 \times 256$
Conv / s1	$1 \times 1 \times 256 \times 256$	$28 \times 28 \times 256$
Conv dw / s2	$3 \times 3 \times 256$ dw	$28 \times 28 \times 256$
Conv / s1	$1 \times 1 \times 256 \times 512$	$14 \times 14 \times 256$
$5 \times$	Conv dw / s1	$3 \times 3 \times 512$ dw
	Conv / s1	$1 \times 1 \times 512 \times 512$
	Conv dw / s2	$3 \times 3 \times 512$ dw
	Conv / s1	$1 \times 1 \times 512 \times 1024$
	Conv dw / s2	$3 \times 3 \times 1024$ dw
	Conv / s1	$1 \times 1 \times 1024 \times 1024$
	Avg Pool / s1	Pool 7×7
	FC / s1	1024×1000
	Softmax / s1	Classifier

Mobilenet full architecture

Image Courtesy : [Transfer Learning using Mobilenet and Keras \(https://towardsdatascience.com/transfer-learning-using-mobilenet-and-keras-c75daf7ff299\)](https://towardsdatascience.com/transfer-learning-using-mobilenet-and-keras-c75daf7ff299)

We have used the MobileNet model as the pretrained model in our neural network. The dimensions of the images in our dataset is 32X32 pixels with RGB color model.

We then proceed to follow the same steps that we implemented with the VGG-16 pretrained model.

Model 1: Feature Extraction

In [32]:

```
#import required libraries  
from keras.applications.mobilenet import MobileNet
```

In [33]:

```
#create object of MobileNet class  
TL2 = MobileNet(weights='imagenet', include_top = False, input_shape=(32, 32, 3))
```

C:\Users\prtk1\Anaconda3\envs\tf-gpu\lib\site-packages\keras_applications\mobilenet.py:207: UserWarning: `input_shape` is undefined or non-square, or `rows` is not in [128, 160, 192, 224]. Weights for input shape (224, 224) will be loaded as the default.

```
warnings.warn("`input_shape` is undefined or non-square, '
```

In [34]:

```
#print layer details
TL2.layers
```

Out[34]:

```
[<keras.engine.input_layer.InputLayer at 0x27f26c00888>,
 <keras.layers.convolutional.ZeroPadding2D at 0x27f26c00548>,
 <keras.layers.convolutional.Conv2D at 0x27f26b44188>,
 <keras.layers.normalization.BatchNormalization at 0x27f26bfdd48>,
 <keras.layers.advanced_activations.ReLU at 0x27f26bfd548>,
 <keras.layers.convolutional.DepthwiseConv2D at 0x27f26d06f08>,
 <keras.layers.normalization.BatchNormalization at 0x27f26d74d48>,
 <keras.layers.advanced_activations.ReLU at 0x27f26d74a08>,
 <keras.layers.convolutional.Conv2D at 0x27f26d897c8>,
 <keras.layers.normalization.BatchNormalization at 0x27f26da9bc8>,
 <keras.layers.advanced_activations.ReLU at 0x27f26f53b88>,
 <keras.layers.convolutional.ZeroPadding2D at 0x27f26f53288>,
 <keras.layers.convolutional.DepthwiseConv2D at 0x27f26f69908>,
 <keras.layers.normalization.BatchNormalization at 0x27f26fa5a88>,
 <keras.layers.advanced_activations.ReLU at 0x27f26fa5b88>,
 <keras.layers.convolutional.Conv2D at 0x27f26faed48>,
 <keras.layers.normalization.BatchNormalization at 0x27f26fcfc48>,
 <keras.layers.advanced_activations.ReLU at 0x27f26ff8b08>,
 <keras.layers.convolutional.DepthwiseConv2D at 0x27f26ff8d08>,
 <keras.layers.normalization.BatchNormalization at 0x27f2704a808>,
 <keras.layers.advanced_activations.ReLU at 0x27f2704a908>,
 <keras.layers.convolutional.Conv2D at 0x27f2704aec8>,
 <keras.layers.normalization.BatchNormalization at 0x27f27073188>,
 <keras.layers.advanced_activations.ReLU at 0x27f270a2088>,
 <keras.layers.convolutional.ZeroPadding2D at 0x27f270a2048>,
 <keras.layers.convolutional.DepthwiseConv2D at 0x27f270afcc8>,
 <keras.layers.normalization.BatchNormalization at 0x27f270eae88>,
 <keras.layers.advanced_activations.ReLU at 0x27f270f2108>,
 <keras.layers.convolutional.Conv2D at 0x27f270f2cc8>,
 <keras.layers.normalization.BatchNormalization at 0x27f24c03fc8>,
 <keras.layers.advanced_activations.ReLU at 0x27d4ca7c548>,
 <keras.layers.convolutional.DepthwiseConv2D at 0x27d4ca7cc48>,
 <keras.layers.normalization.BatchNormalization at 0x27d4ca727c8>,
 <keras.layers.advanced_activations.ReLU at 0x27d4ca78908>,
 <keras.layers.convolutional.Conv2D at 0x27d4ca78d08>,
 <keras.layers.normalization.BatchNormalization at 0x27ef428c888>,
 <keras.layers.advanced_activations.ReLU at 0x27ef421cdc8>,
 <keras.layers.convolutional.ZeroPadding2D at 0x27ef421ce08>,
 <keras.layers.convolutional.DepthwiseConv2D at 0x27ed1949488>,
 <keras.layers.normalization.BatchNormalization at 0x27f25c5c988>,
 <keras.layers.advanced_activations.ReLU at 0x27f25e3c908>,
 <keras.layers.convolutional.Conv2D at 0x27f25c80cc8>,
 <keras.layers.normalization.BatchNormalization at 0x27f25be7208>,
 <keras.layers.advanced_activations.ReLU at 0x27f27106a48>,
 <keras.layers.convolutional.DepthwiseConv2D at 0x27f27106788>,
 <keras.layers.normalization.BatchNormalization at 0x27f25c1cf88>,
 <keras.layers.advanced_activations.ReLU at 0x27f25c10608>,
 <keras.layers.convolutional.Conv2D at 0x27f25c10688>,
 <keras.layers.normalization.BatchNormalization at 0x27f1e402c88>,
 <keras.layers.advanced_activations.ReLU at 0x27f1e431048>,
 <keras.layers.convolutional.DepthwiseConv2D at 0x27f1e431308>,
 <keras.layers.normalization.BatchNormalization at 0x27f1e479e48>,
 <keras.layers.advanced_activations.ReLU at 0x27f1e481188>,
 <keras.layers.convolutional.Conv2D at 0x27f1e481608>]
```

```

<keras.layers.normalization.BatchNormalization at 0x27f1e4a4c08>,
<keras.layers.advanced_activations.ReLU at 0x27f1e4cde08>,
<keras.layers.convolutional.DepthwiseConv2D at 0x27f1e4cd6c8>,
<keras.layers.normalization.BatchNormalization at 0x27f1e51ce48>,
<keras.layers.advanced_activations.ReLU at 0x27f1e51cf88>,
<keras.layers.convolutional.Conv2D at 0x27f1e524508>,
<keras.layers.normalization.BatchNormalization at 0x27f25e77b08>,
<keras.layers.advanced_activations.ReLU at 0x27f25ea0d88>,
<keras.layers.convolutional.DepthwiseConv2D at 0x27f25ea0e48>,
<keras.layers.normalization.BatchNormalization at 0x27f25ef0f48>,
<keras.layers.advanced_activations.ReLU at 0x27f25ef0d88>,
<keras.layers.convolutional.Conv2D at 0x27f25ef7448>,
<keras.layers.normalization.BatchNormalization at 0x27f25f19dc8>,
<keras.layers.advanced_activations.ReLU at 0x27f25f44c88>,
<keras.layers.convolutional.DepthwiseConv2D at 0x27f25f44fc8>,
<keras.layers.normalization.BatchNormalization at 0x27f25f93f08>,
<keras.layers.advanced_activations.ReLU at 0x27f25f93e48>,
<keras.layers.convolutional.Conv2D at 0x27f25f98108>,
<keras.layers.normalization.BatchNormalization at 0x27f27137688>,
<keras.layers.advanced_activations.ReLU at 0x27f27168b48>,
<keras.layers.convolutional.ZeroPadding2D at 0x27f27168988>,
<keras.layers.convolutional.DepthwiseConv2D at 0x27f271788c8>,
<keras.layers.normalization.BatchNormalization at 0x27f271b4f88>,
<keras.layers.advanced_activations.ReLU at 0x27f271bca48>,
<keras.layers.convolutional.Conv2D at 0x27f271bcfc8>,
<keras.layers.normalization.BatchNormalization at 0x27f271e4188>,
<keras.layers.advanced_activations.ReLU at 0x27f27210588>,
<keras.layers.convolutional.DepthwiseConv2D at 0x27f27210788>,
<keras.layers.normalization.BatchNormalization at 0x27f27256f08>,
<keras.layers.advanced_activations.ReLU at 0x27f2725e608>,
<keras.layers.convolutional.Conv2D at 0x27f2725e848>,
<keras.layers.normalization.BatchNormalization at 0x27f27283f48>,
<keras.layers.advanced_activations.ReLU at 0x27f272b2d08>]

```

We begin transfer learning process by removing the output classifier layer which has softmax implemented over 1000 units for the 1000 classes in the imagenet dataset used by MobileNet model to make the model consistent with our problem statement.

In [35]:

```

#remove the last layer (Classifier) from the model
output = TL2.layers[-1].output
output = keras.layers.Flatten()(output)
TL2_model = Model(TL2.input, output)

```

We then proceed by freezing the layers of the MobileNet model, since we would like to take advantage of the generic image features that the MobileNet model has already learned and utilize the knowledge that the model has already learned to our benefit. By freezing the layers we prevent the weights of the layers of the pretrained model from being updated.

<\b>

In [36]:

```
#set the trainable parameter to false for all the layer (freeze the model)
TL2_model.trainable = False
for layer in TL2_model.layers:
    layer.trainable = False
```

In [37]:

```
#layer and its trainable parameter details
TL2_details = pd.DataFrame([(layer, layer.name, layer.trainable) for layer in TL2_model.layers])
TL2_details
```

Out[37]:

	Layer Type	Layer Name	Layer Trainable
0	<keras.engine.input_layer.InputLayer object at...	input_3	False
1	<keras.layers.convolutional.ZeroPadding2D object at...	conv1_pad	False
2	<keras.layers.convolutional.Conv2D object at 0...	conv1	False
3	<keras.layers.normalization.BatchNormalization object at...	conv1_bn	False
4	<keras.layers.advanced_activations.ReLU object at...	conv1_relu	False
...
83	<keras.layers.advanced_activations.ReLU object at...	conv_dw_13_relu	False
84	<keras.layers.convolutional.Conv2D object at 0...	conv_pw_13	False
85	<keras.layers.normalization.BatchNormalization object at...	conv_pw_13_bn	False
86	<keras.layers.advanced_activations.ReLU object at...	conv_pw_13_relu	False
87	<keras.layers.core.Flatten object at 0x0000027...	flatten_4	False

88 rows × 3 columns

We now add fully connected classifier layers on top of the pretrained model to learn the features that are specific to our dataset. Since our dataset consists of 10 classes, our output layer consists of 10 units with the softmax activation function to give us the probability of each class with respect to every input.

In [39]:

[illegible]

```
<IPython.core.display.Markdown object>
```

Model: "sequential 6"

Layer (type)	Output Shape	Param #
dense_16 (Dense)	(None, 256)	262400
dense_17 (Dense)	(None, 512)	131584
dense_18 (Dense)	(None, 10)	5130
Total params: 399,114		
Trainable params: 399,114		
Non-trainable params: 0		

We then extract the features, from the pre-trained layers that are frozen and use these extracted features to train the classifier layers that we've added on our model. We can visualize it by considering that the output from the layer before the flatten operation of the pretrained model now becomes the input to the new layers added by us on top of the pretrained model.

In [40]:

```
#function to extract features from the images
def model_image(model, input_imgs):
    image_feature = model.predict(input_imgs, verbose=0)
    return image_feature

#training dataset feature extraction from the pre-trained layers
X_train_features = model_image(TL2_model, X_train_scaled)

#validation dataset feature extraction from the pre-trained layers
X_val_features = model_image(TL2_model, X_val_scaled)
```

In [41]:

```
#dataset shape
print('Train Image shape:', X_train_features.shape,
      '\tValidation Image shape:', X_val_features.shape)
```

```
Train Image shape: (40000, 1024)      Validation Image shape: (10000, 1024)
```

In [42]:

```
#include timing information
dh = display('', display_id=True)
dh.update(md("<br>Training is in progress....."))
t1 = time.time()

#model fitting
history_TL2 = classifier_TL2.fit(x=X_train_features,
                                y=y_train,
                                validation_data=(X_val_features, y_val),
                                batch_size=30,
                                epochs=100,
                                verbose=0)

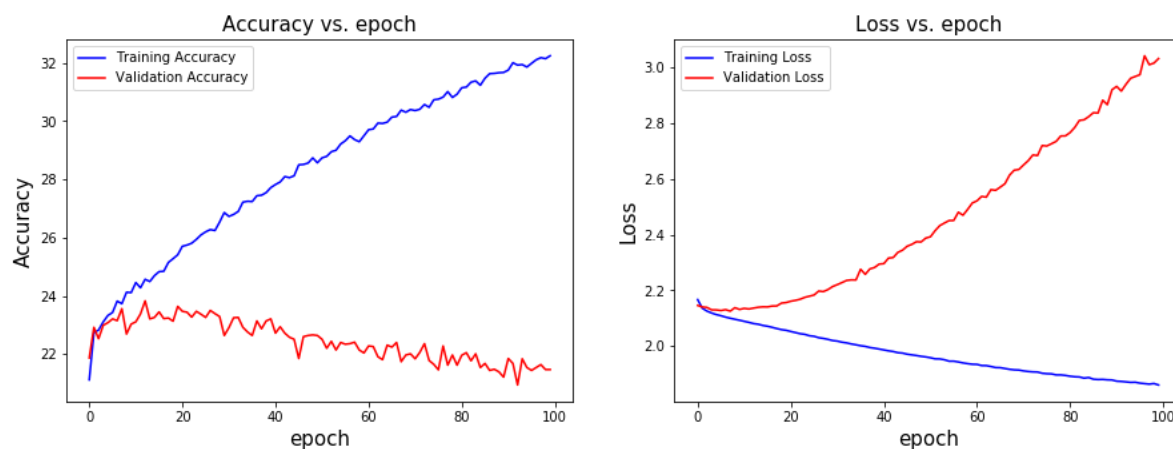
tt = time.time()-t1
avg_per_epoch_TL2 = round(tt/(history_TL2.epoch[-1]+1),3)
dh.update(md("<br>Training is completed! <br><br>Total training time: **{} seconds** <br>Av
```

<IPython.core.display.Markdown object>

In [43]:

[illegible]

```
<IPython.core.display.Markdown object>
```



Key Inferences

- 1) The training accuracy is 32% and the validation accuracy is 22%.
- 2) As we can see the Model is not generalizing well after the first few epochs (5 to 7) for the validation dataset, hence overfitting occurred.
- 3) We can try increasing the dataset size using Image Augmentation to prevent overfitting which is demonstrated below.

In [44]:

[illegible]

```
<IPython.core.display.Markdown object>
```

```
<IPython.core.display.Markdown object>
```

	Test accuracy	F1 score	ROC AUC score	Total Loss
0	21.53	0.215	0.646	3.034

Model 2: Feature Extraction + Image Augmentation

We then proceed to fine-tune the layers added by us by freezing the layers of the pre-trained model and by using data augmentation. By freezing the layers of the pretrained models, the weights of those layers will not change and only the layers added by us will alter their weight and learn the features specific to our dataset. The augmentation of the images in our dataset enables us to train our layers with additional data to enhance the learning with respect to our dataset

In [45]:

[illegible]

```
<IPython.core.display.Markdown object>
```

```
Model: "sequential_7"
```

Layer (type)	Output Shape	Param #
model_2 (Model)	(None, 1024)	3228864
dense_19 (Dense)	(None, 256)	262400
dense_20 (Dense)	(None, 512)	131584
dense_21 (Dense)	(None, 10)	5130
Total params: 3,627,978		
Trainable params: 399,114		
Non-trainable params: 3,228,864		

In [46]:

```
#include timing information
dh = display('',display_id=True)
dh.update(md("<br>Training is in progress....."))
t1 = time.time()

#model fitting
history_tl2_feia = classifier_tl2_feia.fit_generator(train_generator,
                                                    steps_per_epoch=1000,
                                                    epochs=100,
                                                    validation_data=val_generator,
                                                    validation_steps=500,
                                                    verbose=0)

tt = time.time()-t1
avg_per_epoch_tl2_feia = round(tt/(history_tl2_feia.epoch[-1]+1),3)
dh.update(md("<br>Training is completed! <br><br>Total training time: **{} seconds** <br>Av
```

<IPython.core.display.Markdown object>

In [47]:

```
#plot the graph
```

[illegible]

#accuracy graph

```
fig, axes = plt.subplots(nrows=1, ncols=2, figsize=(15,5))
ax = axes.ravel()
ax[0].plot(range(0, history_t12_feia.params['epochs']), [acc * 100 for acc in history_t12_feia.params['acc']])
ax[0].plot(range(0, history_t12_feia.params['epochs']), [acc * 100 for acc in history_t12_feia.params['acc']])
ax[0].set_title('Accuracy vs. epoch', fontsize=15)
ax[0].set_ylabel('Accuracy', fontsize=15)
ax[0].set_xlabel('epoch', fontsize=15)
ax[0].legend()
```

#Loss graph

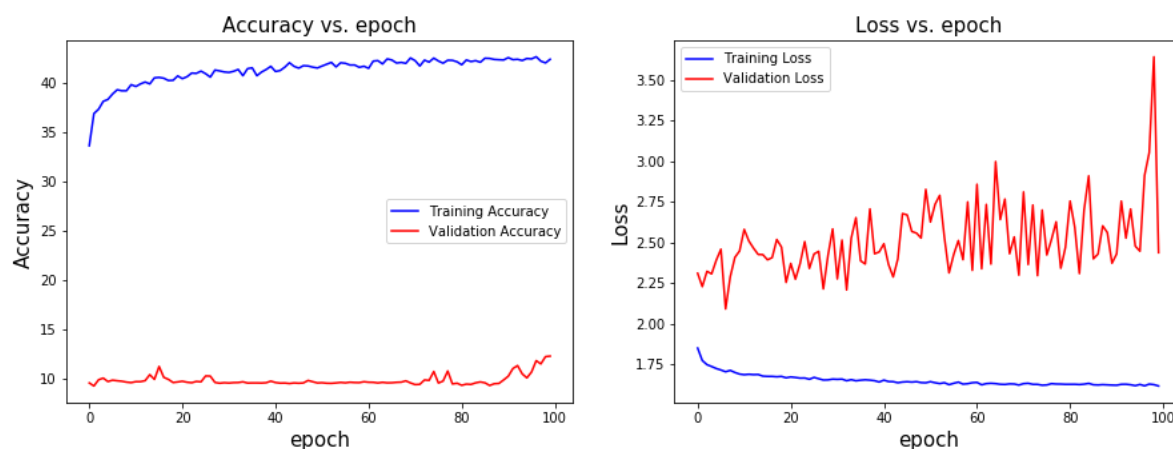
```
ax[1].plot(range(0, history_tl2_feia.params['epochs']), history_tl2_feia.history['loss'], label='loss')
ax[1].plot(range(0, history_tl2_feia.params['epochs']), history_tl2_feia.history['val_loss'], label='val_loss')
ax[1].set_title('Loss vs. epoch', fontsize=15)
ax[1].set_ylabel('Loss', fontsize=15)
ax[1].set_xlabel('epoch', fontsize=15)
ax[1].legend()
```

```
#display the graph
```

```
plt.show()
```

◀ ▶

```
<IPython.core.display.Markdown object>
```



Key Inferences

- 1) The training accuracy is more than 42% and the validation accuracy is nearby 10%.
- 2) In this case, Image Augmentation did not help much to prevent overfitting. Hence, we can try to fine-tune the model for the CIFAR-10 dataset which is demonstrated below.

In [48]:

[illegible]

```
<IPython.core.display.Markdown object>
```

```
<IPython.core.display.Markdown object>
```

	Test accuracy	F1 score	ROC AUC score	Total Loss
0	12.48	0.125	0.543	3.121

Model 3: Fine-tuning (whole network) + Image Augmentation

Finally, we proceed to fine-tune the entire model by unfreezing the layers of the pre-trained model training the entire model with the augmented dataset. By unfreezing the pretrained layers we make it possible for the pretrained layers to learn the features specific to our dataset by altering the weights of its layers. Implementing data augmentation just increases the size of the training dataset and enables the model to learn with a larger dataset. The motive of implementing fine-tuning is to permit a way for the model to learn the intricate details of the current data and not just rely on the dataset it was previously trained on.

In [49]:

```
#unfreeze the model (set trainable parameter to True for all the layers)
TL2_model.trainable = True

#Loop through all the layers of the model
for layer in TL2_model.layers:
    layer.trainable = True

#model layer and trainable parameter details
layers = pd.DataFrame([(layer, layer.name, layer.trainable) for layer in TL2_model.layers],
layers
```

Out[49]:

	Layer Type	Layer Name	Layer Trainable
0	<keras.engine.input_layer.InputLayer object at...	input_3	True
1	<keras.layers.convolutional.ZeroPadding2D obje...	conv1_pad	True
2	<keras.layers.convolutional.Conv2D object at 0...	conv1	True
3	<keras.layers.normalization.BatchNormalization...	conv1_bn	True
4	<keras.layers.advanced_activations.ReLU object...	conv1_relu	True
...
83	<keras.layers.advanced_activations.ReLU object...	conv_dw_13_relu	True
84	<keras.layers.convolutional.Conv2D object at 0...	conv_pw_13	True
85	<keras.layers.normalization.BatchNormalization...	conv_pw_13_bn	True
86	<keras.layers.advanced_activations.ReLU object...	conv_pw_13_relu	True
87	<keras.layers.core.Flatten object at 0x0000027...	flatten_4	True

88 rows × 3 columns

In [50]:

```
#Model Initializing, Compiling and Fitting  
classifier_tl2_ftia = Sequential()  
  
#fully connected layer  
#input Layer  
classifier_tl2_ftia.add(TL2_model)  
  
#dense (hidden) layer  
classifier_tl2_ftia.add(Dense(units = 256, kernel_initializer='uniform', activation='relu',  
  
#dense (hidden) layer  
classifier_tl2_ftia.add(Dense(units = 512, kernel_initializer='uniform', activation='relu'))  
  
#output layer  
classifier_tl2_ftia.add(Dense(units = 10, kernel_initializer='uniform', activation='softmax'))  
  
#compile the model  
classifier_tl2_ftia.compile(optimizer='adam', loss='sparse_categorical_crossentropy', metrics=['accuracy'])  
  
#model summary  
display(Markdown(' <br> **\n\n Model Summary \n\n classifier tl2 ftia.summary()'
```

```
<IPython.core.display.Markdown object>
```

```
Model: "sequential_8"
```

Layer (type)	Output Shape	Param #
model_2 (Model)	(None, 1024)	3228864
dense_22 (Dense)	(None, 256)	262400
dense_23 (Dense)	(None, 512)	131584
dense_24 (Dense)	(None, 10)	5130
Total params: 3,627,978		
Trainable params: 3,606,090		
Non-trainable params: 21,888		

In [51]:

```
#include timing information
dh = display('',display_id=True)
dh.update(md("<br>Training is in progress....."))
t1 = time.time()

#model fitting
history_tl2_ftia = classifier_tl2_ftia.fit_generator(train_generator,
                                                    steps_per_epoch=1000,
                                                    epochs=100,
                                                    validation_data=val_generator,
                                                    validation_steps=500,
                                                    verbose=0)

tt = time.time()-t1
avg_per_epoch_tl2_ftia = round(tt/(history_tl2_ftia.epoch[-1]+1),3)
dh.update(md("<br>Training is completed! <br><br>Total training time: **{} seconds** <br>Av
```

<IPython.core.display.Markdown object>

In [52]:

```
#plot the graph
```

[illegible]

#accuracy graph

```
fig, axes = plt.subplots(nrows=1, ncols=2, figsize=(15,5))
ax = axes.ravel()
ax[0].plot(range(0, history_t12_ftia.params['epochs']), [acc * 100 for acc in history_t12_ft
ax[0].plot(range(0, history_t12_ftia.params['epochs']), [acc * 100 for acc in history_t12_ft
ax[0].set_title('Accuracy vs. epoch', fontsize=15)
ax[0].set_ylabel('Accuracy', fontsize=15)
ax[0].set_xlabel('epoch', fontsize=15)
ax[0].legend()
```

#Loss graph

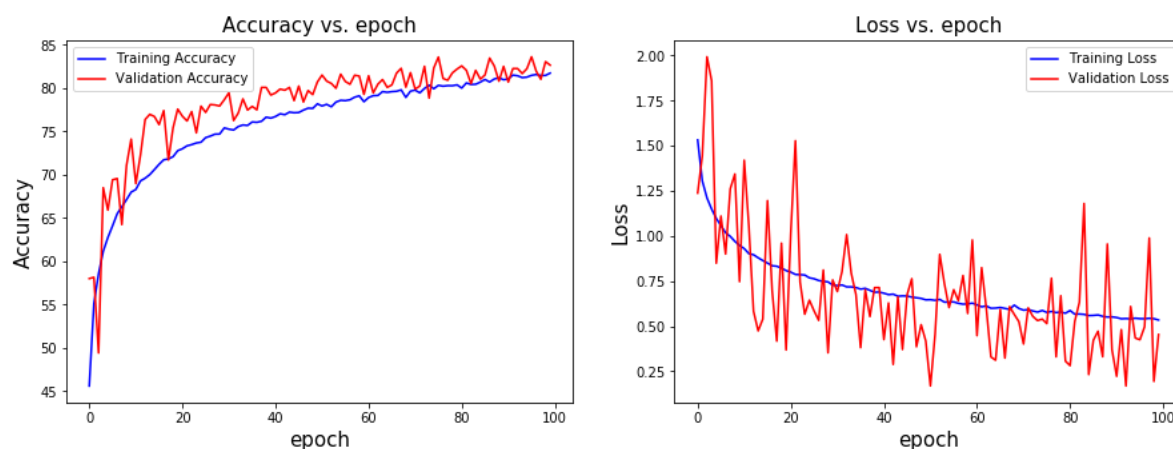
```
ax[1].plot(range(0, history_tl2_ftia.params['epochs']), history_tl2_ftia.history['loss'], la
ax[1].plot(range(0, history_tl2_ftia.params['epochs']), history_tl2_ftia.history['val_loss']
ax[1].set_title('Loss vs. epoch', fontsize=15)
ax[1].set_ylabel('Loss', fontsize=15)
ax[1].set_xlabel('epoch', fontsize=15)
ax[1].legend()
```

```
#display the graph
```

```
plt.show()
```

◀ ▶

```
<IPython.core.display.Markdown object>
```



Key Inferences

Out of all the model which we have discussed so far, the above model seems to perform the best because of the following:

- 1) The accuracy is approx 80% for both training and the validation dataset as the model layers learned the features of the CIFAR10 dataset, hence classified the images with considerable accuracy.
- 2) No overfitting occurred, hence the model generalized well for the validation dataset.
- 3) We can further increase the performance of the model by increasing the number of epochs as we can see the upward trend for both training as well as the validation dataset.

```
#Evaluate the model
dh = display('',display_id=True)
dh.update(md("<br>Model evaluation is in progress..."))
t2 = time.time()

#model evaluation
test_loss = classifier_tl2_ftia.evaluate(X_test_scaled, y_test, verbose=0)
et = time.time()-t2
dh.update(md("<br>Model evaluation is completed! Total evaluation time: **{} seconds**".format(et)))
display(Markdown('<br>' + "Model Evaluation Summary"))

#calculate the model evaluation parameters
f1 = f1_score(y_test, classifier_tl2_ftia.predict_classes(X_test_scaled), average='micro')
roc = roc_auc_score(y_test, classifier_tl2_ftia.predict_proba(X_test_scaled), multi_class='ovo')

#create model evaluation dataframe
stats_tl2_ftia = pd.DataFrame({'Test accuracy' : round(test_loss[1]*100,3),
                              'F1 score'      : round(f1,3),
                              'ROC AUC score'  : round(roc,3),
                              'Total Loss'     : round(test_loss[0],3)}, index=[0])

#print the dataframe
display(stats_tl2_ftia)
```

```
<IPython.core.display.Markdown object>
```

	Test accuracy	F1 score	ROC AUC score	Total Loss
0	82.2	0.822	0.984	0.52

Accuracy Score

In [54]:

```
#plot details and values
labels = ['Model 1', 'Model 2', 'Model 3']
vgg16_values = [stats_t11['Test accuracy'][0], stats_feia['Test accuracy'][0], stats_ftia['
mNet_values = [stats_TL2['Test accuracy'][0], stats_t12_feia['Test accuracy'][0], stats_t12

#label location
x = np.arange(len(labels))

#width
width = 0.35
fig, ax = plt.subplots(figsize=(10,5))
rects1 = ax.bar(x - width/2, vgg16_values, width, label='VGG16')           #VGG16 model
rects2 = ax.bar(x + width/2, mNet_values, width, label='MobileNet')       #MobileNet model

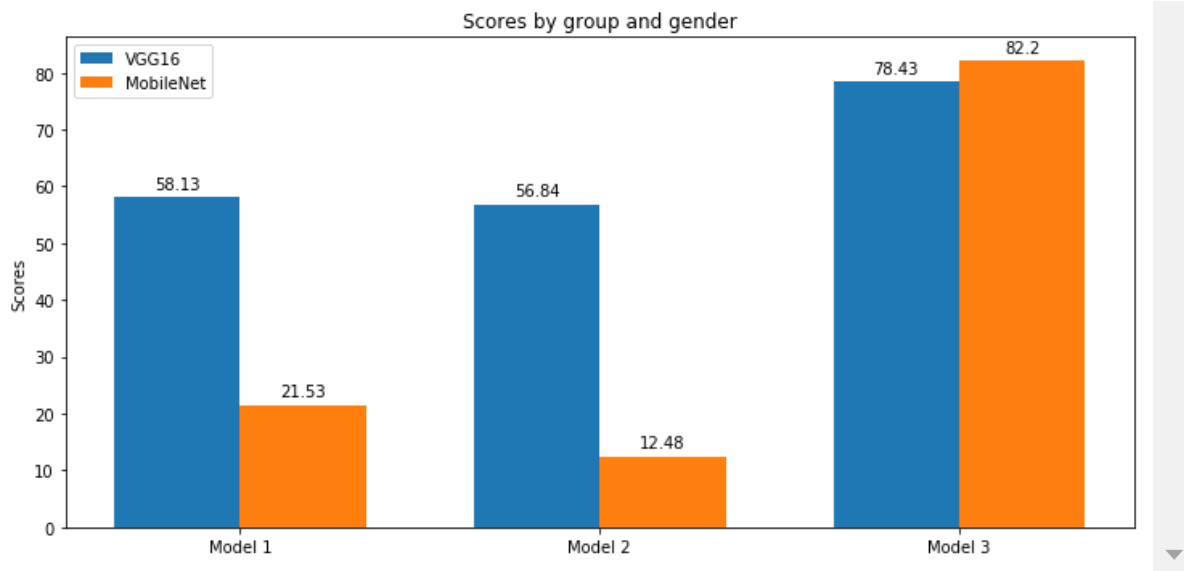
ax.set_ylabel('Scores')           #y-Label
ax.set_title('Scores by group and gender') #title
ax.set_xticks(x)                 #x-ticks
ax.set_xticklabels(labels)       #x-Label
ax.legend()                      #Legend

#function to add label on each graph
def autolabel(rects):
    """Attach a text label above each bar in *rects*, displaying its height."""
    for rect in rects:
        height = rect.get_height()
        ax.annotate('{}' .format(height),
                    xy=(rect.get_x() + rect.get_width() / 2, height),
                    xytext=(0, 3), # 3 points vertical offset
                    textcoords="offset points",
                    ha='center', va='bottom')

#call function
autolabel(rects1)
autolabel(rects2)

#set layout
fig.tight_layout()

#plot the graph
plt.show()
```



where:

- Model 1: Feature Extraction
- Model 2: Feature Extraction + Image Augmentation
- Model 3: Fine-tuning (whole network) + Image Augmentation

From the above graph we can conclude the following:

- Both VGG and MobileNet model were trained on the ImageNet dataset, however, the results show a huge discrepancy in the accuracy of the models when tested on the CIFAR-10 dataset. We believe that this discrepancy is caused because of the different model architectures which allows VGG16 model to learn the general features in the images from the ImageNet dataset and apply them to classify the the CIFAR-10 dataset better than MobileNet.
- The absence of fine tuning in the first two models means that the classification task of CIFAR-10 dataset is completed by the models based on the knowledge learned from the ImageNet dataset.
- In model 3, when we fine tune the models on the CIFAR-10 dataset, we observe that MobileNet achieves a higher accuracy score than VGG16 model. The reason can be attributed to fine-tuning the entire model which helped the model learn feaures and characteristics of the images specific to the CIFAR-10 dataset.

Parameters

Total Parameters

Model	VGG16	MobileNet
1	268,042	399,114
2	14,982,730	3,627,978
3	14,982,730	3,627,978

Trainable Parameters

Model	VGG16	MobileNet
1	268,042	399,114
2	268,042	399,114
3	14,982,730	3,606,090

Non-Trainable Parameters

Model	VGG16	MobileNet
1	0	0
2	14,714,688	3,228,864
3	0	21,888

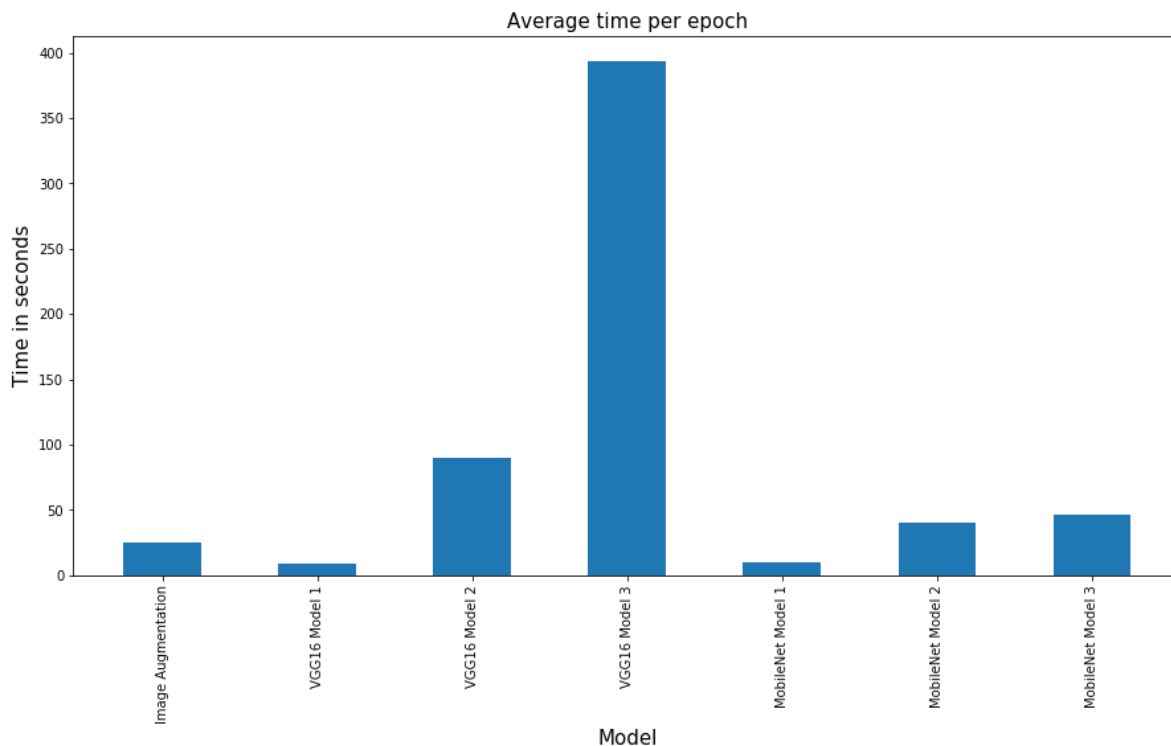
where:

- Model 1: Feature Extraction
- Model 2: Feature Extraction + Image Augmentation
- Model 3: Fine-tuning (whole network) + Image Augmentation

Training Time per epoch

In [74]:

```
plt.figure(figsize=(15,7.5))
plt.bar(['Image Augmentation',
        'VGG16 Model 1',
        'VGG16 Model 2',
        'VGG16 Model 3',
        'MobileNet Model 1',
        'MobileNet Model 2',
        'MobileNet Model 3'],
        [avg_per_epoch_ia,
        avg_per_epoch_tl1,
        avg_per_epoch_feia,
        avg_per_epoch_ftia,
        avg_per_epoch_TL2,
        avg_per_epoch_tl2_feia,
        avg_per_epoch_tl2_ftia], width=0.5)
plt.xlabel('Model', fontsize=15)
plt.ylabel('Time in seconds', fontsize=15)
plt.title('Average time per epoch', fontsize=15)
plt.xticks(rotation=90)
plt.show()
```



The average training time per epoch is the highest for VGG16 Model where we fine tune the whole network with the augmented dataset. The reason for this considerable increase in the training time per epoch is number of **trainable parameters** in VGG model 3 as compared to the other models. The number of trainable parameters in VGG16 model 3 are 300% more than the number of trainable parameters in MobileNet Model 3.

Conclusion

In this project we have successfully demonstrated the use of a Convolutional Neural Network with the implementation of Transfer Learning and Image Augmentation for the purpose of classification. We have shown and explained the results of these techniques by experimenting them with the CIFAR-10 dataset. After implementing two pretrained models and image augmentation to this

project we feel that our understanding of Convolutional Neural Networks has increased multifold along with understanding new and efficient ways to overcome the challenges in machine learning like lack of data, lack of computation resources and enhancing the model efficiency.

Areas of improvement

- **Dataset image size** - Having images of higher resolution might result in the the model learning the features better and in turn having better classification accuracy. However, the complexity of the model will increase because of the added pixels.
- **Optimizing Hyperparameters** - Hyperparameters like the number of epochs, optimizers, activation functions can be varied and compared to find the ideal model with the ideal hyperparameters.
- **Add more Dense layers** - The layers of the CNN are responsible for learning the features in the neural network, adding the dense layers in the network will make sure that our model will learn the features of the multiple image classes in the dataset. Learning the features efficiently will also help the model to make better classification.
- **Add Regularization parameter (Drop layers)** - We can also try and implement dropout technique which randomly drops a predefined number of units per epoch. Adding dropout may prevent the model from overfitting to the training dataset.
- **Check other Transfer Network for better accuracy** - Some pre-trained models may work better than other models for the CIFAR-10 dataset. Exploring other pre-trained networks and their architecture might provide insightful outcomes.

Acknowledgment

We would like to express our gratitude to Dr. Timothy Havens, who helped us along the project with his insightful notes and lectures. We would also like to thank the TAs for their guidance in moments of difficulty.

References

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(https://mtu.instructure.com/courses/1304186/files/84790571?module_item_id=15186271)