

# Convex Optimization and Optimal Control

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# Contents

<b>1</b>	<b>Reminders on Real Analysis</b>	<b>5</b>
1.1	Normed vector spaces and inner product spaces . . . . .	5
1.1.1	Norms and balls . . . . .	5
1.1.2	Open sets, closed sets . . . . .	5
1.1.3	Closure, interior . . . . .	5
<b>2</b>	<b>Convex Sets</b>	<b>7</b>
2.1	Definition and first properties . . . . .	7
2.1.1	Definition and first algebraic properties . . . . .	7
2.1.2	First topological properties . . . . .	7
2.2	Convex combinations and convex hull . . . . .	7
2.2.1	Convex combinations . . . . .	7
2.2.2	Convex hull . . . . .	8
2.3	Projection and separation . . . . .	8
2.3.1	Projection of a point onto a closed convex set . . . . .	8
2.3.2	Representation of linear functionals and applications: gra- dient, adjoint . . . . .	9
2.3.3	Separation of convex sets . . . . .	10
2.4	Cones . . . . .	11
2.4.1	Definitions . . . . .	11
2.4.2	Polar cones . . . . .	11
2.4.3	Normal cone and tangent cone of a convex set . . . . .	12
<b>3</b>	<b>Convex functions</b>	<b>13</b>
3.1	Definitions and first properties . . . . .	13
3.1.1	Extended real valued functions . . . . .	13
3.1.2	Convex functions . . . . .	13
3.1.3	Level sets . . . . .	14
3.2	Particular cases . . . . .	14
3.2.1	Marginal functions . . . . .	14
3.2.2	Indication function . . . . .	15
3.2.3	Support function . . . . .	15
3.3	Continuity and lower semicontinuity . . . . .	15
3.3.1	Continuity . . . . .	15
3.3.2	Lower semicontinuity . . . . .	15
3.4	Closed convex hull of an extended real valued function . . . . .	16
3.4.1	Affine minorant . . . . .	16

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3.4.2	Closed convex hull . . . . .	16
3.5	Legendre-Fenchel transform . . . . .	17
3.5.1	Definition . . . . .	17
3.5.2	Fenchel-Moreau-Rockafellar theorem . . . . .	17

# Chapter 1

## Reminders on Real Analysis

Lecture 0: Reminders on Real Analysis

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### 1.1 Normed vector spaces and inner product spaces

#### 1.1.1 Norms and balls

#### 1.1.2 Open sets, closed sets

#### 1.1.3 Closure, interior



# Chapter 2

## Convex Sets

Lecture 1: Convex sets

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### 2.1 Definition and first properties

#### 2.1.1 Definition and first algebraic properties

**Definition 1.** Let  $X$  be a (real) vector space. A set  $A \subset X$  is said to be convex if

$$\forall (x, y) \in A^2, \forall \theta \in [0, 1], \theta x + (1 - \theta)y \in A.$$

**Proposition 1.** An (arbitrary) intersection of convex subsets of  $X$  is convex.

**Proposition 2.** The sum of two convex sets is convex.

#### 2.1.2 First topological properties

**Proposition 3.** If  $X$  is a normed vector space then all balls (open or closed) of  $X$  are convex.

*Proof.*

□

**Proposition 4.** If  $A$  is convex subset of a normed vector space then  $\overline{A}$  and  $\text{int } A$  are also convex.

*Proof.*

□

### 2.2 Convex combinations and convex hull

#### 2.2.1 Convex combinations

**Definition 2.** Let  $X$  be a vector space. A convex combination of  $m$  elements  $x_1, \dots, x_m \in X$  is an element  $y \in X$  that can be decomposed as

$$y = \sum_{i=1}^m \theta_i x_i \quad \text{with} \quad (\theta_1, \dots, \theta_m) \in (\mathbb{R}_+)^m, \quad \sum_{i=1}^m \theta_i = 1.$$

**Proposition 5.** If  $A$  is convex then any convex combination of elements of  $A$  belong to  $A$ .

*Proof.*

□

**Theorem 1** (Carathéodory). In a vector space of dimension  $n$ , all convex combination of  $m$  elements,  $m > n + 1$ , can be written as a convex combination of at most  $n + 1$  of these elements.

*Proof.*

□

## 2.2.2 Convex hull

**Definition 3.** Let  $X$  be a vector space and  $A$  be a subset of  $X$ . The convex hull of  $A$ , denoted by  $\text{conv } A$  is the smallest (inclusion) convex subset of  $X$  containing  $A$ . It is the intersection of all convex sets containing  $A$ .

**Proposition 6.** The convex hull of  $A$  is the set of all convex combinations of elements of  $A$ .

**Proposition 7.** Let  $X, Y$  be two vector spaces,  $A \subset X, B \subset Y$ . We have

$$\text{conv}(A \times B) = \text{conv } A \times \text{conv } B.$$

*Proof.*

□

## 2.3 Projection and separation

### 2.3.1 Projection of a point onto a closed convex set

**Theorem 2.** Let  $X$  be a Hilbert space and  $A$  be a nonempty closed convex subset of  $X$ . For all  $x \in X$  there exists a unique  $y \in A$  such that

$$\|x - y\| = \min_{z \in A} \|x - z\|.$$

This element is characterized by the variational inequality (see in ??)

$$\langle x - y, z - y \rangle \leq 0 \quad \forall z \in A.$$

It is called the projection of  $x$  onto  $A$ , denoted by  $y = P_A(x)$ .



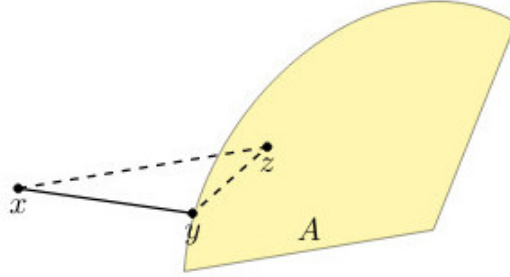


Figure 2.9: Projection onto a convex set

*Proof.*

□

**Proposition 8.** *Under the assumptions of the above theorem, we have*

$$\|P_A(x) - P_A(y)\| \leq \|x - y\| \quad \forall x, y \in X,$$

*i.e. the projection operator is 1-Lipschitz continuous.*

*Proof.*

□

**Proposition 9.** *Let  $X$  be a Hilbert space and  $M$  be a closed linear subspace of  $X$ . The projection  $y = P_M(x) \in M$  is characterized by*

$$\langle x - y, v \rangle = 0 \quad \forall v \in M.$$

*Moreover  $P_M$  is a linear map. It is called orthogonal projection.*

*Proof.*

□

### 2.3.2 Representation of linear functionals and applications: gradient, adjoint

**Theorem 3 (Riesz).** *Let  $X$  be a Hilbert space and  $\varphi$  be a continuous linear functional on  $X$ . There exists a unique  $w \in X$  such that*

$$\langle w, x \rangle = \varphi(x) \quad \forall x \in X.$$

*The vector  $w$  is called the Riesz representation of  $\varphi$ .*

*Proof.*

□

**Definition 4.** *Let  $X$  be a Hilbert space and  $f : X \rightarrow \mathbb{R}$  be a function. Let  $x \in X$  be such that  $f$  is Fréchet differentiable at  $x$ . The gradient of  $f$  at  $x$ , denoted by  $\nabla f(x)$  is the Riesz representation of the linear functional  $df(x)$ .*

**Theorem 4.** Let  $X, Y$  be two Hilbert spaces and  $L \in \mathcal{L}(X, Y)$ . There exists a unique map  $L^* \in \mathcal{L}(Y, X)$ , called the adjoint of  $L$  such that

$$\langle Lx, y \rangle = \langle x, L^*y \rangle \quad \forall (x, y) \in X \times Y..$$

### 2.3.3 Separation of convex sets

**Theorem 5.** Let  $A$  be a closed convex subset of a Hilbert space  $X$  and let  $x \in X \setminus A$ . There exists  $r \in X \setminus \{0\}$  such that

$$\sup_{z \in A} \langle r, z \rangle < \langle r, x \rangle.$$

*Proof.*

□

**Corollary 1.** For all subset  $A$  of a Hilbert space,  $\overline{\text{conv } A}$  is equal to the intersection of all affine half-spaces containing  $A$ . It is called the closed convex hull of  $A$ .

*Proof.*

□

**Theorem 6.** Let  $A$  and  $B$  be two disjoint convex subsets of a Hilbert space  $X$  with  $A$  closed and  $B$  compact. There exists  $r \in X \setminus \{0\}$  such that

$$\sup_{x \in A} \langle r, x \rangle < \inf_{y \in B} \langle r, y \rangle.$$

*Proof.*

□

**Theorem 7.** Let  $A$  be a nonempty open convex subset of a finite dimensional Hilbert space  $X$  and let  $x \in X \setminus A$ . There exists  $r \in X \setminus \{0\}$  such that

$$\langle r, z \rangle \leq \langle r, x \rangle \quad \forall z \in A..$$

*Proof.*

□

## 2.4 Cones

### 2.4.1 Definitions

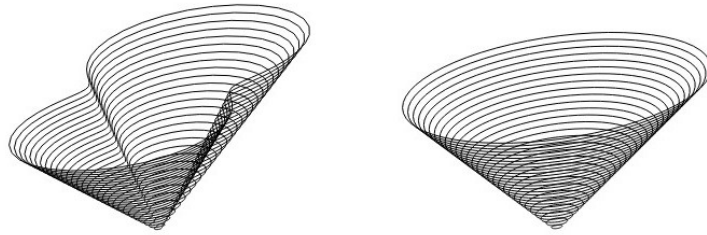


Figure 2.15: Non-convex cone (left) and convex cone (right)

**Definition 5.** A subset  $C$  of a vector space  $X$  is said to be a cone if

$$\forall (\alpha, x) \in \mathbb{R}_+ \times C, \alpha x \in C.$$

*Cones can be convex or not as we can see in ??.*

**Proposition 10.** If  $C$  is a cone of a normed vector space  $X$  then  $\overline{C}$  is also a cone.

*Proof.*

□

### 2.4.2 Polar cones

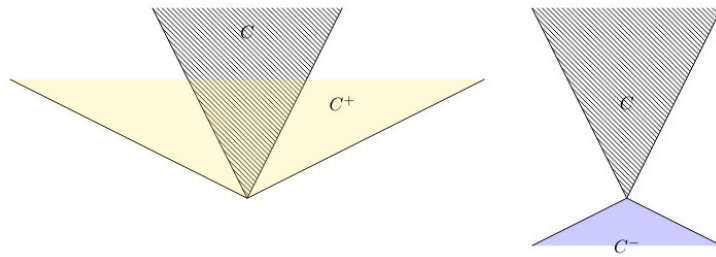


Figure 2.16: Positive and negative polar cones

**Definition 6.** Let  $C$  be a cone of a Hilbert space  $X$ . The positive and negative polar (or dual) cones of  $C$  are respectively defined by (see ??)

$$C^+ = \{x \in X \text{ s.t } \langle x, y \rangle \geq 0, \forall y \in C\}$$

$$C^- = \{x \in X \text{ s.t } \langle x, y \rangle \leq 0, \forall y \in C\}.$$

**Example 1.** For the positive orthant it is easily checked that

$$(\mathbb{R}_+^n)^+ = \mathbb{R}_+^n, \quad (\mathbb{R}_+^n)^- = \mathbb{R}_-^n.$$

Indeed, the negative polar cone is

$$(\mathbb{R}_+^n)^- = \left\{ (x_1, \dots, x_n) \in \mathbb{R}^n \text{ s.t. } \sum_{i=1}^n x_i y_i \leq 0 \quad \forall (y_1, \dots, y_n) \in \mathbb{R}_+^n \right\}.$$

**Theorem 8.** If  $C$  is a convex cone of a Hilbert space  $X$  then

$$C^{--} = \overline{C}.$$

*Proof.*

□

### 2.4.3 Normal cone and tangent cone of a convex set

**Definition 7.** Let  $A$  be a convex set of a Hilbert space  $X$  and let  $a \in A$ . The normal cone of  $A$  at point  $a$  is the set

$$N_A(a) = \{x \in X \text{ s.t. } \langle x, y - a \rangle \leq 0 \quad \forall y \in A\}.$$

**Definition 8.** Let  $A$  be a convex set of a Hilbert space  $X$  and let  $a \in A$ . The tangent cone of  $A$  at point  $a$  is the smallest (inclusion) closed convex cone containing  $A - a$ . It is the intersection of all closed convex cones containing  $A - a$ . It is denoted by  $T_A(a)$ .

**Lemma 1.** The tangent cone  $T_A(a)$  is the closure of the convex cone (called radial cone)

$$T_A^\circ(a) = \{\alpha(x - a), \quad \alpha \geq 0, \quad x \in A\}.$$

*Proof.*

□

**Theorem 9.** Let  $A$  be a convex set of a Hilbert space  $X$  and let  $a \in A$ . We have

$$N_A(a) = (T_A(a))^-.$$

*Proof.*

□

# Chapter 3

## Convex functions

Lecture 3: Convex functions

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### 3.1 Definitions and first properties

#### 3.1.1 Extended real valued functions

#### 3.1.2 Convex functions

**Definition 9.** Let  $X$  be a vector space and  $f : X \rightarrow \overline{\mathbb{R}}$ . The epigraph of  $f$  is the set

$$\text{epi } f = \{(x, \zeta) \in X \times \mathbb{R} \text{ s.t. } \zeta \geq f(x)\}..$$

**Proposition 11.** Let  $X$  be a vector space and  $f, g : X \rightarrow \overline{\mathbb{R}}$  be two functions. Then

$$f = g \Leftrightarrow \text{epi } f = \text{epi } g..$$

**Definition 10.** Let  $X$  be a vector space and  $f : X \rightarrow \overline{\mathbb{R}}$ . The function  $f$  is said to be convex if its epigraph is convex.

**Proposition 12.** A function  $f : X \rightarrow \overline{\mathbb{R}}$  is convex iff

$$\forall x, y \in \text{dom } f, \forall \theta \in (0, 1), \quad f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y).$$

*Proof.*

□

**Proposition 13.** If  $f : X \rightarrow \overline{\mathbb{R}}$  is convex then we have that for all  $(x_1, \dots, x_m) \in$

$\text{dom } f$  and all  $(\theta_1, \dots, \theta_m) \in (0, 1)^m$  with  $\sum_{i=1}^m \theta_i = 1$ ,

$$f\left(\sum_{i=1}^m \theta_i x_i\right) \leq \sum_{i=1}^m \theta_i f(x_i).$$

*Proof.*

□

**Definition 11.** A function  $f : X \rightarrow \overline{\mathbb{R}}$  is strictly convex iff

$$\forall x, y \in \text{dom } f, x \neq y, \forall \theta \in (0, 1), \quad f(\theta x + (1 - \theta)y) < \theta f(x) + (1 - \theta)f(y).$$

A function  $f : X \rightarrow \overline{\mathbb{R}}$  is said to be (strictly) concave if  $-f$  is (strictly) convex.

### 3.1.3 Level sets

**Definition 12.** Let  $X$  be a vector space,  $f : X \rightarrow \overline{\mathbb{R}}$  and  $\gamma \in \overline{\mathbb{R}}$ . The  $\gamma$ -level set of  $f$  is the set

$$\text{lev}_\gamma f = \{x \in X \text{ s.t. } f(x) \leq \gamma\}.$$

**Proposition 14.** Let  $X$  be a vector space,  $f : X \rightarrow \overline{\mathbb{R}}$  and  $\gamma \in \overline{\mathbb{R}}$ . If  $f$  is convex then  $\text{lev}_\gamma f$  is convex.

## 3.2 Particular cases

### 3.2.1 Marginal functions

**Definition 13.** Let  $X$  be a vector space,  $I$  be an arbitrary set and  $(f_i)_{i \in I}$  be a family of functions  $f_i : X \rightarrow \overline{\mathbb{R}}$ . We define the upper marginal function

$$\begin{aligned} \sup_{i \in I} f_i : X &\rightarrow \overline{\mathbb{R}} \\ x &\mapsto \sup_{i \in I} f_i(x). \end{aligned}$$

**Lemma 2.** Let  $X$  be a vector space,  $I$  be a set and  $(f_i)_{i \in I}$  be a family of functions  $f_i : X \rightarrow \overline{\mathbb{R}}$ . We have

$$\text{epi} \sup_{i \in I} f_i = \bigcap_{i \in I} \text{epi } f_i.$$

**Corollary 2.** Let  $X$  be a vector space,  $I$  be an arbitrary set and  $(f_i)_{i \in I}$  be a family of convex functions  $f_i : X \rightarrow \overline{\mathbb{R}}$ . Then,  $\sup_{i \in I} f_i$  is convex.

**Proposition 15.** Let  $X, Y$  be vector spaces and  $f : X \times Y \rightarrow \overline{\mathbb{R}}$  be a convex function. The function  $g : X \rightarrow \overline{\mathbb{R}}$  defined by

$$g(x) = \inf_{y \in Y} f(x, y).$$

is convex.

### 3.2.2 Indication function

**Definition 14.** Let  $A$  be a subset of a vector space  $X$ . The indicator function of  $A$  is the function  $I_A : X \rightarrow \mathbb{R} \cup \{+\infty\}$  defined by

$$I_A(x) = \begin{cases} 0 & \text{if } x \in A \\ +\infty & \text{if } x \notin A \end{cases}.$$

**Proposition 16.** A subset  $A$  of a vector space  $X$  is convex iff its indicator function  $I_A$  is convex.

### 3.2.3 Support function

**Definition 15.** Let  $A$  be a nonempty subset of a Hilbert space  $X$ . The support function of  $A$  is the function  $\sigma_A : X \rightarrow \mathbb{R} \cup \{+\infty\}$  defined by

$$\sigma_A(p) = \sup_{x \in A} \langle p, x \rangle.$$

**Theorem 10.** Let  $A$  be a nonempty subset of a Hilbert space  $X$ . Then

$$\overline{\text{conv } A} = \{x \in X \text{ s.t. } \langle p, x \rangle \leq \sigma_A(p), \quad \forall p \in X\}.$$

## 3.3 Continuity and lower semicontinuity

### 3.3.1 Continuity

**Proposition 17.** Let  $X$  be a normed vector space and  $f : X \rightarrow \overline{\mathbb{R}}$  be a convex function. If  $f(x_0) \in \mathbb{R}$  and  $f$  is bounded from above in a neighborhood of  $x_0$ , then  $f$  is Lipschitz continuous in a (possibly smaller) neighborhood of  $x_0$ .

**Proposition 18.** Let  $f : X \rightarrow \overline{\mathbb{R}}$  be a convex function, where  $X$  is a normed vector space of finite dimension. Then  $f$  is continuous at each  $x_0 \in \text{int dom } f$  such that  $f(x_0) \in \mathbb{R}$ .

### 3.3.2 Lower semicontinuity

**Definition 16.** Let  $X$  be a normed vector space and  $f : X \rightarrow \overline{\mathbb{R}}$ . We say that  $f$  is lower semicontinuous (or closed) if its epigraph is a closed subset of  $X \times \mathbb{R}$ .

**Proposition 19.** Let  $X$  be a normed vector space and  $f : X \rightarrow \overline{\mathbb{R}}$ . The following assertions are equivalent.

- $f$  is lower semicontinuous;
- all level sets  $\text{lev}_\gamma f$ ,  $\gamma \in \mathbb{R}$  are closed;
- for all sequence  $(x_n)$  of elements of  $X$  such that

$$\lim_{n \rightarrow +\infty} x_n = x \in X \quad \text{and} \quad \lim_{n \rightarrow +\infty} f(x_n) = y \in \overline{\mathbb{R}}.$$

it holds  $f(x) \leq y$ .

**Proposition 20.** Let  $X$  be a normed vector space,  $I$  be a set and  $(f_i)_{i \in I}$  be a family of lower semicontinuous functions  $f_i : X \rightarrow \overline{\mathbb{R}}$ . Then  $\sup_{i \in I} f_i$  is lower semicontinuous.

## 3.4 Closed convex hull of an extended real valued function

### 3.4.1 Affine minorant

**Definition 17.** Let  $X$  be a Hilbert space and  $f : X \rightarrow \overline{\mathbb{R}}$ . We say that  $f$  admits an affine minorant if there exists  $(a, \alpha) \in X \times \mathbb{R}$  such that

$$f(x) \geq \langle a, x \rangle + \alpha \quad \forall x \in X.$$

**Proposition 21.** Let  $X$  be a Hilbert space and  $f : X \rightarrow \mathbb{R} \cup \{+\infty\}$  be a lower semicontinuous convex function. Then  $f$  admits an affine minorant.

### 3.4.2 Closed convex hull

**Proposition 22.** Let  $X$  be a Hilbert space and  $f : X \rightarrow \overline{\mathbb{R}}$  be a function with affine minorant. Let  $G$  be the set of convex lower semicontinuous functions  $g : X \rightarrow \mathbb{R} \cup \{+\infty\}$  such that  $g(x) \leq f(x)$  for all  $x \in X$ . Then

- $G \neq \emptyset$ ;
- $\cap_{g \in G} \text{epi } g$  is the epigraph of a convex lower semicontinuous function called the closed convex hull of  $f$ , denoted by  $\overline{\text{conv}} f$ ;  
 $\overline{\text{conv}} f$  is the greatest convex lower semicontinuous function minorizing  $f$ .



## 3.5 Legendre-Fenchel transform

### 3.5.1 Definition

**Definition 18.** Let  $X$  be a Hilbert space and  $f : X \rightarrow \overline{\mathbb{R}}$  be an arbitrary function. The Legendre-Fenchel transform of  $f$  (or conjugate of  $f$ ) is the function  $f^* : X \rightarrow \overline{\mathbb{R}}$  defined by

$$f^*(p) = \sigma_{\text{epi } f}(p, -1) = \sup_{x \in X} \langle p, x \rangle - f(x).$$

**Remark.** The definition immediately shows, if  $A$  is an arbitrary nonempty subset of  $X$ , then

$$I_A^* = \sigma_A.$$

**Lemma 3.** Let  $f : X \rightarrow \overline{\mathbb{R}}$  be proper. If  $f$  admits an affine minorant then  $f^*$  is proper.

### 3.5.2 Fenchel-Moreau-Rockafellar theorem

**Theorem 11** (Fenchel-Moreau-Rockafellar). Let  $X$  be a Hilbert space and  $f : X \rightarrow \overline{\mathbb{R}}$  be a proper function with affine minorant. Then

$$f^{**} = \sup\{g, g \text{ affine minorant of } f\} = \overline{\text{conv}} f.$$

**Remark.** We have shown in the proof the equality

$$\text{epi} \overline{\text{conv}} f = \overline{\text{convepi } f},$$

i.e. the epigraph of the closed convex hull of a proper function with affine minorant is the closed convex hull of its epigraph.

**Corollary 3.** If  $f$  is convex, proper and lower semicontinuous then  $f^{**} = f$ .