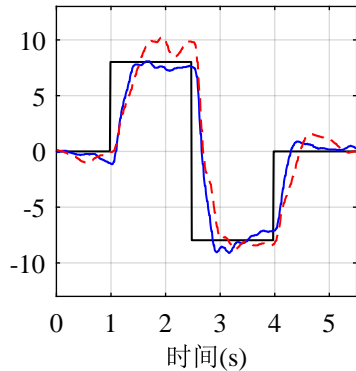


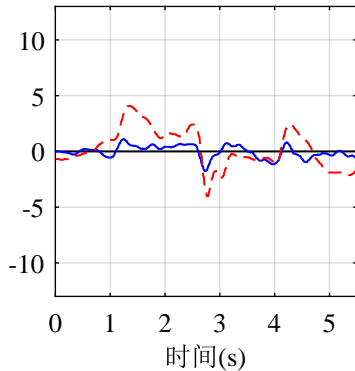
— 参考值 — INDI - - PID

横滚角($^{\circ}$)



— 参考值 — INDI - - PID

俯仰角($^{\circ}$)



— 参考值 — INDI - - PID

偏航角($^{\circ}$)

