# Course 2: Supervised Learning



### **Summary**

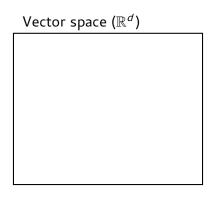
#### Last session

- What is not Al?
- Al definition
- 3 Applications
- Open issues

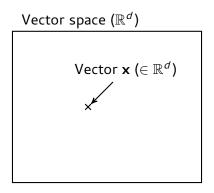
#### Today's session

- Learning from labeled examples
- Challenges of supervised learning

### **Notations**

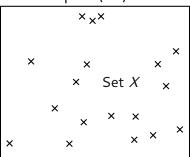


### **Notations**



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### Vector space ( $\mathbb{R}^d$ )



#### Machine learning

To learn is to **generalize** ( $\neq$  memorize),

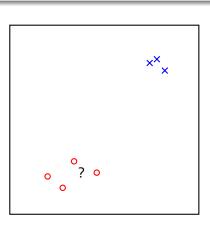
- Regression
- Classification
- Need of an expert
- Tons of applications:
  - Pattern recognition
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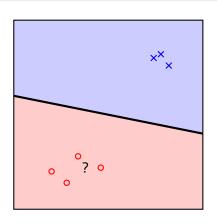
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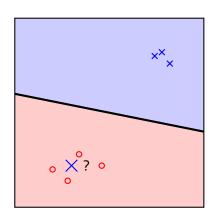
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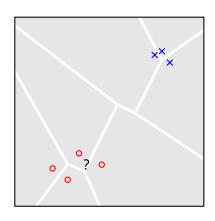
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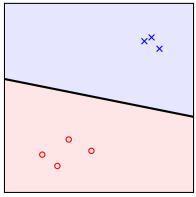
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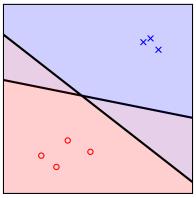
### An ill-defined problem

- An infinity of potential solutions, one must be the "best one" but is unreachable,
- ⇒ requires a priori, constraints.



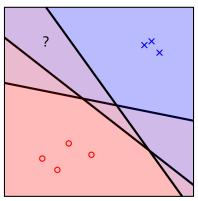
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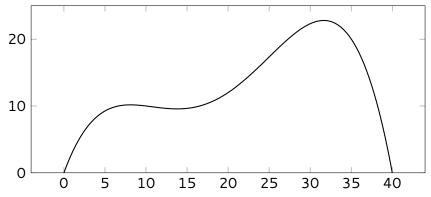


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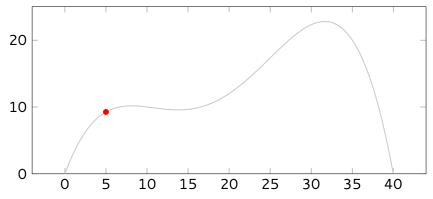
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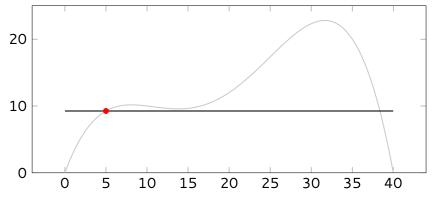
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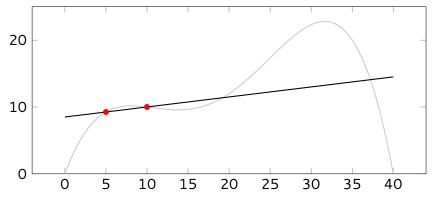
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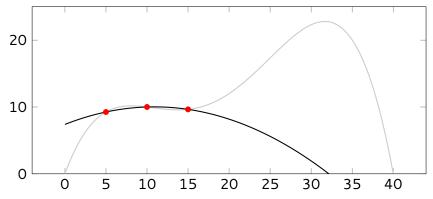
#### Bias/variance trade-off

IMT-Atlantique

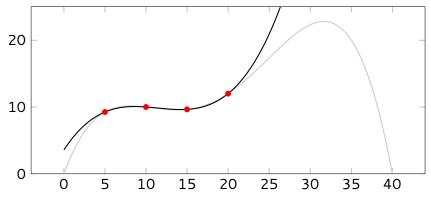
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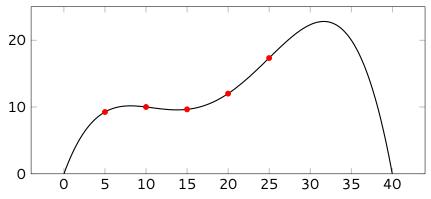
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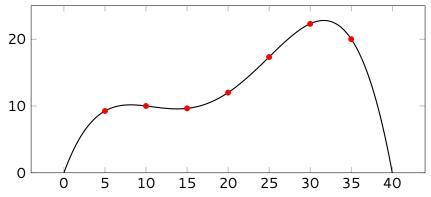
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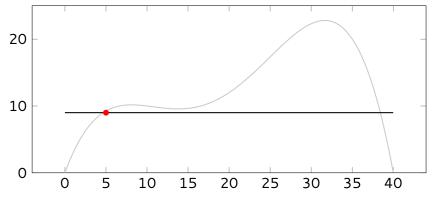
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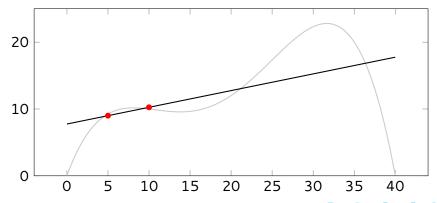
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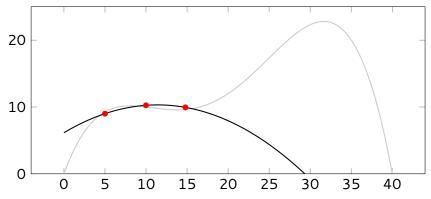
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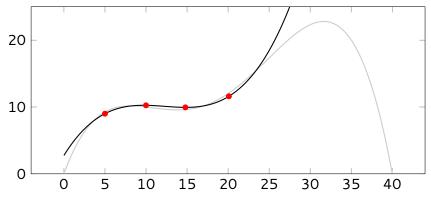
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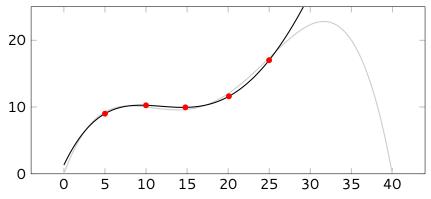
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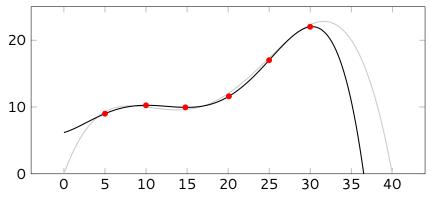
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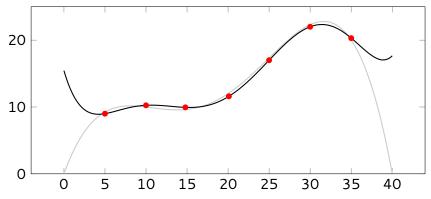
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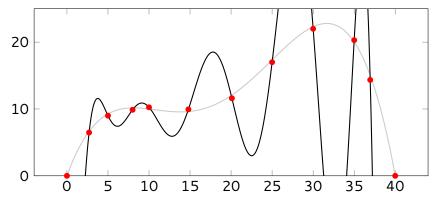
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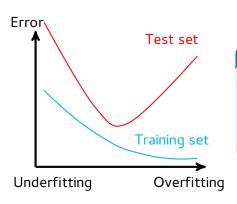


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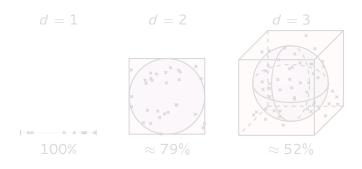


#### Crossvalidation

- To quantify overfitting, split training dataset in two parts:
  - A first part is used to train,
  - 2 A second part is used to validate,

#### Curse of dimensionality

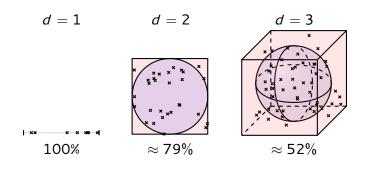
- Geometry is not intuitive in high dimension,
- Efficient methods in 2D are not necessarily still valid.

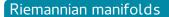


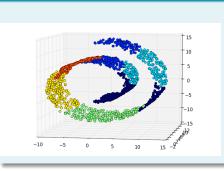
$$V_d^s = \frac{\pi^{d/2} R^d}{\Gamma(d/2+1)}$$
 versus  $V_d^c = (2R)^d$ 

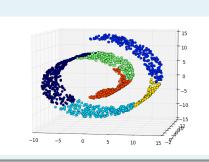
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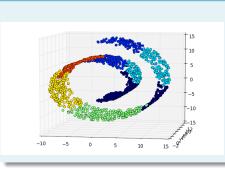


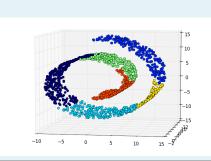






#### Riemannian manifolds





### Linear separability and need for embedding









### Computation time

Example on ImageNet, simply going through all images:

- $n = 10.000.000, d \approx 1.000.000,$
- ho pprox pprox pprox pprox elementary operations,
- $\sim$  2h45 on a modern processor.

#### Scalability

- Finding the best solution to a problem would be feasible with unlimited computation time,
- But searching through the space of possible functions is often untractable,
- Solutions must be computationally reasonable, which is the true challenge today.

#### Computation time

Example on ImageNet, simply going through all images:

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#### **Definition**

- Let us fix d,
- The VC dimension is a measure of the genericity of a method,
- It is the maximum cardinality of a set of vectors it is able to shatter in any possible way.

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Consider for example lines to shatter set of points with d = 2.



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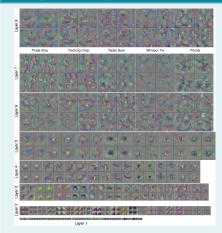


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# **Open Questions**

## Interpretability



Source: "Understanding Neural Networks Through Deep Visualization"

#### Few examples



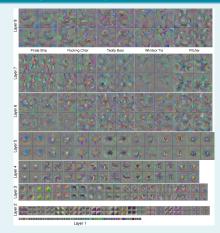
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### Other open questions

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- Irregular domains
- Choice of hyperparameters...

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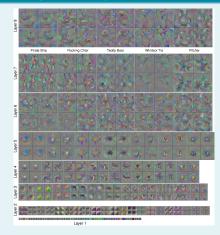
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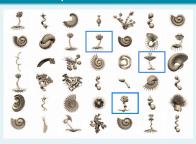
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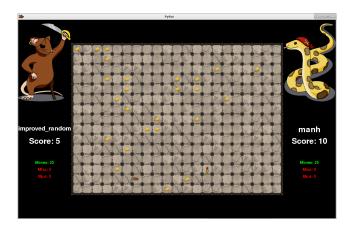


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# Non-symmetric PyRat without walls / mud



Both players follow a deterministic greedy algorithm.

Supervised learning - predict the outcome of a game from the start configuration.

Expected accuracy of a random classifier?

# Lab Session 2 and assignments for Session 3

# TP Supervised Learning (TP1)

- Generating PyRat Datasets
- Basics of machine learning using sklearn
- Tests on PyRat datasets using a naive approach

## Project 1 (P1)

You will be assigned a supervised learning method. You have to prepare a Jupyter Notebook on this method, including:

- A brief description of the theory behind the method,
- Basic tests on simulated data to show the influence of parameters and hyperparameters
- Advanced tests and analysis on your own PyRat Datasets

During Session 3 you will have 7 minutes to present your notebook.