

## Q2) Adiabatic shocks: numerical exercise

2.1) From class:  $\frac{\rho_1}{\rho_2} = \frac{\gamma-1}{\gamma+1} + \frac{2}{M_1^2(1+\gamma)}$

From plots:  $\rho_1 \sim 1 \text{ kg/m}^3$ ,  $\rho_2 \sim 0.5 \text{ kg/m}^3$ ,  $M_1 \sim 0.65$

$$\Rightarrow \frac{1}{0.5} \stackrel{?}{=} \frac{5/3-1}{5/3+1} + \frac{2}{(0.65)^2(1+5/3)}$$

$$2 \stackrel{?}{=} \frac{2/3}{8/3} + \frac{2}{(0.65)^2(8/3)}$$

$$2 \approx 2.03$$

Yes, this agrees with the shock jump conditions derived in class.

2.2) With a  $\Delta x = 0.4$  and  $\Delta t = 0.04$ , we have a shock with a width  $\sim 5$  grid points.

The value of  $\Delta x$  sets this width. A higher value of  $\Delta x$  results in a larger width. This is a result of having too much spatial discretization error which results in what is called artificial viscosity. This ends up smearing the numerically resolved shock. As we decrease  $\Delta x$ , we can see that the shock front is sharper as a result; approaching a width independent of  $\Delta x$  and  $\Delta t$ , i.e. a numerically converged solution. (see plots).