

* Dynamic Programming: half of idea of multiplying 2D

Exploding problem \rightarrow Polynomial Time (n^c)
Catalan No = $\frac{1}{n} \binom{2n-2}{n-1}$

Matrix Chain Multiplication Problem.

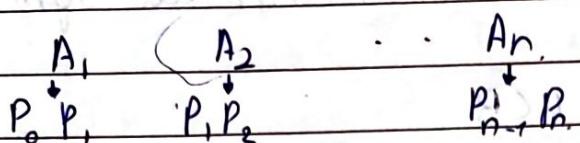
Memory element is used to keep records

It is parenthesization problem

Given: A_1, A_2, \dots, A_n (Input Matrices)

Parenthesize these matrices such that total no. of multiplications will be minimum for all possible parenthesization.

$A_i \rightarrow P_{i-1} \times P_i$



Function $M(i, j)$

```

if i=j then return M=0;
else min = +∞ (Very high Value)
    for k=i to j-1 do
        mult = M(i,k) + M(k+1,j) + P[i-1] * P[k] * P[j]
        if mult < min then
            min = mult ;
    end if
end for
end if

```

This algorithm is able to find : minimum no of multiplications

Complexity: $O(n^2)$ ($n \times n$ dimension of matrix)

$$T(n) = \sum_{k=1}^{n-1} (T(k) + T(n-k)) + O(n)$$

$$T(1) = \text{const} = 1.$$

$$\therefore T(n) = 2 \sum_{k=1}^{n-1} T(k) + O(n)$$

$$T(n) \geq U(n)$$

$$\text{let } U(n) = 2(U(n-1)) + 1.$$

$$U(n) \approx 2^n - 1$$

$$U(n) \approx 2^n$$

$$\therefore T(n) \geq 2^n$$

Thus Complexity of recursive approach is exponential

Procedure Matchchain (P)

for $i = 1$ to n do $M[i, i] = 0$; end for;

for $j = 2$ to n do

for $i = 1$ to $n-1+j$ do

$j = i + j - 1$; $M[i, j] = +\infty$;

for $k = i$ to $j-1$ do

$mult = M[i, k] + M[k+1, j] +$

$P[i-1] * P[k] * P[j]$;

if $mult < M[i, j]$ then

$M[i, j] = mult$; $S[i, j] = k$,

end if

end for.

end for

end for.

3 Nested Loops $\rightarrow O(n^3)$.

Trackpoint

MLS

$${}^6C_3 = \frac{1}{4} \left(\frac{6!}{3!3!} \right)$$

$$\frac{6 \times 5 \times 4}{3 \times 2}$$

$$P = [4 | 2 | 5 | 1 | 3]$$

$$A_1, \quad A_2, \quad A_3, \quad A_4$$

$$P_0 \times P_1, \quad P_1 \times P_2, \quad P_2 \times P_3, \quad P_3 \times P_4$$

$$4 \times 3 = 12$$

$$4 \times 5 \times 3$$

$$1 \quad ((A_1 A_2) (A_3 A_4))$$

$$4 \times 2 \times 2 \times 5 \\ 4 \times 2 \times 5 = 40$$

$$5 \times 1 \times 1 \times 3$$

$$55, 115$$

$$2 \quad (A_1, ((A_2 A_3) A_4))$$

$$2 \times 5 \times 1 \quad 2 \times 1 \times 6 = 12 = 10 \quad 40$$

$$3 \quad (((A_1 A_2) A_3) A_4)$$

$$72$$

$$4 \quad (A_1 (A_2 (A_3 A_4)))$$

$$69$$

$$5 \quad (((A_1 (A_2 A_3)) A_4))$$

$$30$$

$$253$$

$$15 + 30 + 24$$

$$4 \times 2 \times 1, \quad 2 \times 5 \times 1, \quad 2 \times 5 \times 1$$

$$4 \times 1 \times 3 \\ 4 \times 1 \times 3 = 12$$

1 2 3 4

1	0	$\infty \downarrow$ 40	18	(40)
2		0	$\infty \downarrow$ 10	45
3			0 + $\infty \downarrow$ 15	0
4				

1 2 3 4

1	1	1	1	3
2		2	3	3
3			3	3
4				

← Track Point.

$[A_1 (A_2 A_3) A_4]$

print_Parenth(s, i, j)

if i = j print ' A_i '.

- else

print "

print_Parenth(s, i, s[i][j]).

print_Parenth(s, s[i][j]+1, j)

print ")"

end if

Space Complexity $O(2^k)$

$A_1 A_2 A_3 A_4$

i = 1 0 = 4.

$(\underbrace{ }_{[1,3]} \quad \underbrace{ }_{[4,4]})$

$((\underbrace{ }_{[1,1]} \quad \underbrace{ }_{[2,3]}) \quad A_4)$

$((A_1 (\underbrace{ }_{[2,2]} \quad \underbrace{ }_{[3,3]}) A_4),$

* Rod Cutting Problem (without Dynamic Approach: $O(2^n)$,
with Dynamic Approach: $O(n^2)$)

Rod of length n and the table of prices
 p_i for $i = 1, 2, 3, \dots, n$

where p_i is the price of a rod of length i .

length ' i '	1	2	3	4	5	6	7	8	9	10
Price ' p_i '	1	5	8	9	10	17	17	20	24	30

The total possibilities of cuts are 2^{n-1} .

be $\frac{1}{2} \cdot 2^n + \frac{1}{2} \cdot 2^{n-1} + \dots + \frac{1}{2} \cdot 2^1 + \frac{1}{2} \cdot 2^0 = 2^n - 1$

A rod of length n can be cut in 2^{n-1} different ways Since we can choose cutting or not cutting at all distances i ($1 \leq i \leq n-1$) from left end

Dynamic programming is coming under bottom up approach

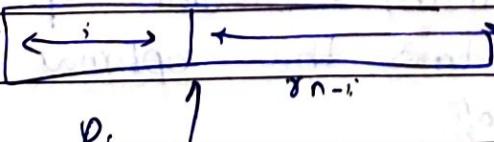
In case of recursive approach.

We can calculate the maximum values r_n terms of optimal values for shorter rods

$$r_n = \max (P_n, r_1 + r_{n-1}, r_2 + r_{n-2}, \dots, r_{n-1} + r_1)$$

Set $r_0 = 0$ and $r_n = \max (P_n + r_{n-1})$

$1 \leq i \leq n$.



$$P_i \quad | \quad r_{n-i}$$

Cut.

$\text{cut_Rod}(P, n)$

if $n=0$ then

return 0;

end

$q = -\infty$

For $i=1$ to n do

$q = \max(q, P[i] + \text{cut_Rod}(P, n-i))$

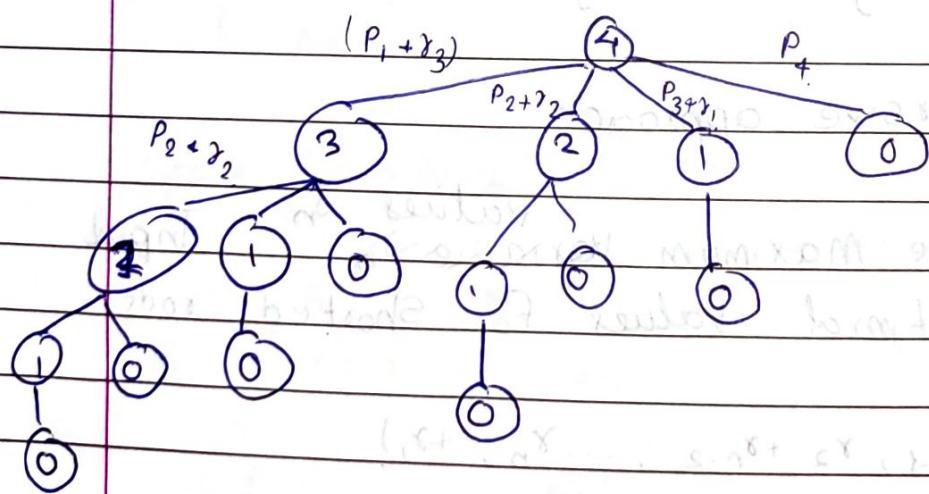
end

return q ;

$T(n) = \text{Total calls made to cut rod fn with rod length } n$

$$T(n) = \begin{cases} 1 + \sum_{0 \leq i \leq n-1} T(i), & \text{if } n > 1 \\ 1, & \text{if } n=0 \end{cases}$$

Complexity $O(2^n)$



- * Dynamic Programming using bottom up approach
// Array $S[0, 1, \dots, n]$ stores the optimal size of the first piece to cut off.

$\gamma[0] = 0;$

for $j = 1$ to n do

$q = -\infty$; //eg. 99999,

for $i = 1$ to j do

//Solve the problem of Size j

[if $q < p[i] + \gamma[j-i]$ then

$q = p[i] + \gamma[j-i]$;

$s[j] = i$; //Stores the size of 1st piece

end]

end.

$\gamma[j] = q$;

end

while $n > 0$ do

//Print sizes of pieces

print $s[n]$;

$n = n - s[n]$;

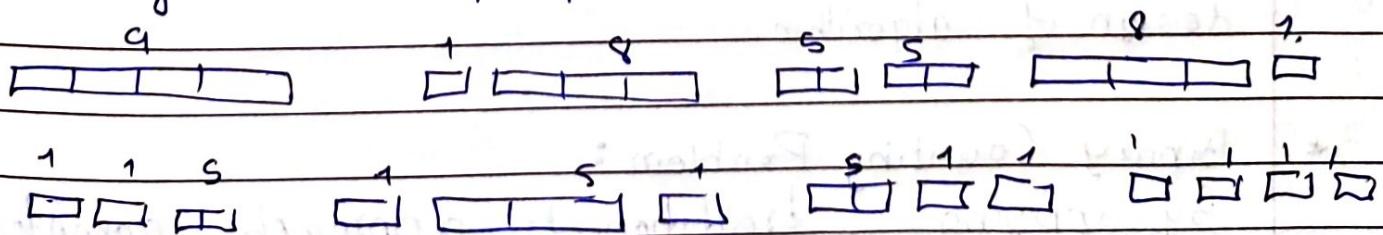
end

radford University

* Rod Cutting :

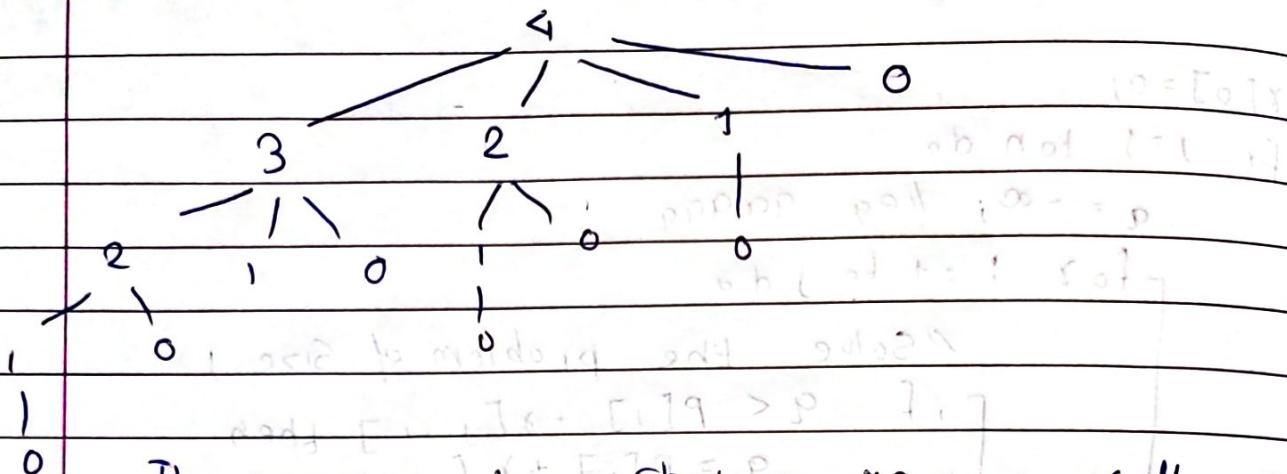
length. i	1	2	3	4	5	6	7	8	9	10
Price p_i	1	5	8	9	10	17	17	20	24	30

(Using bottom up approach)



The 8 possible ways of cutting up a rod of length

4.



The recursion tree showing recursive calls resulting from a call $CUT-ROD(p,n)$ for $n=4$.

Each node label gives the size n of the corresponding subproblem. So that an edge from a parent with label s to a child with label t corresponds to cutting off an initial piece.

length i	0	1	2	3	4	5	6	7	8	9	10
Prime P:	0	1	5	8	9	10	17	17	20	24	30
r[i]	0	1	5	8	10	13	17	18	22	25	30
s[i]	0	1	2	3	2	2	6	11	2	3	10

* Amortized Analysis:

Amortize - Gradually write off the initial cost over a period.

- It is an analysis technique which can influence the design of algorithm.

* Binary Counting Problem:

By applying traditional approach, complexity is $O(n \log n)$

- If trailing zero is obtained from left right to left, flip it to 1 and stop
- If trailing One is obtained flip it and next flip the first one that is obtained moving from right to left.
- If two consecutive trailing zero is obtained flip both to one and then flip the next zero to one.

* Procedure Increment.

$i = 0$

while $A[i] = P$ do

$A[i] = 0; i = i + 1;$

end while

$A[i] = 1;$

* Accounting Method

This analysis is based on a amortized cost. If the amortized cost exceeds the actual cost, the excess remains with data structure as a credit

$A[1]$	$A[3]$	$A[2]$	$A[1]$	$A[0]$
--------	--------	--------	--------	--------

0	0	0	0	0
0	0	0	1	2Rs

Assume

$0 \rightarrow 1$ 2Rs.

0	0	1	0
0	0	1	1

$1 \rightarrow 0$ 0Rs

0	1	0	0
0	1	0	1

At each step we are utilizing 2 Rs. and this goes till n so.
time Complexity = $O(2n) = O(n)$

0	1	1	0
0	1	1	1

If the amortized cost is small enough so that the actual cost cannot be covered then, it is paid by the credit. Each increment has amortized cost of $\frac{2}{k}$. So that there are almost $2n$ bit changes.

* Potential Method:

It is similar to accounting method the only difference is that no explicit credit is saved instead the credit is expressed as potential. This way potential is involved with the algorithm.

c_i = Actual Cost of i th Operation.

D_i = Data Structure after i th operation

$\phi(D_i)$ = Potential of D_i

$$a_i = c_i + \phi(D_i) - \phi(D_{i-1})$$

a_i = Amortized Cost of i th operation

$$\sum_{i=1}^n a_i = \sum_{i=1}^n (c_i + \phi(D_i) - \phi(D_{i-1}))$$

$$= \sum_{i=1}^n c_i + \phi(D_n) - \phi(D_0)$$

If we choose the potential function ϕ such that

$$\phi(D_0) = 0 \text{ and } \phi(D_n) = 0$$

$$\sum_{i=1}^n c_i \leq \sum_{i=1}^n a_i$$

\Rightarrow amortized cost is upper bounded for actual cost.

$$\phi(D_i) = b_i$$

b_i indicates how many total 1's are present in bit stream.

$$\begin{aligned} \phi(D_i) - \phi(D_{i-1}) &\leftarrow \text{No of 1's in prior stream.} \\ &= b_i - b_{i-1} \\ &= (b_{i-1} + 1) - b_{i-1} \end{aligned}$$

$$= 1 - t_{i-1}$$

$$= 1 - t_{i-1}$$

t = trailing ones

$$c_i = t_{i-1} + 1$$

$$q_i = c_i + \phi(D_i) - \phi(D_{i-1})$$

$$= t_{i-1} + 1 + b_i - b_{i-1}$$

$$= t_i + 1 - t_{i-1}$$

$$= \frac{2}{2}$$

Therefore: for no number of operation.

$$\sum_{i=1}^n q_i = 2n$$

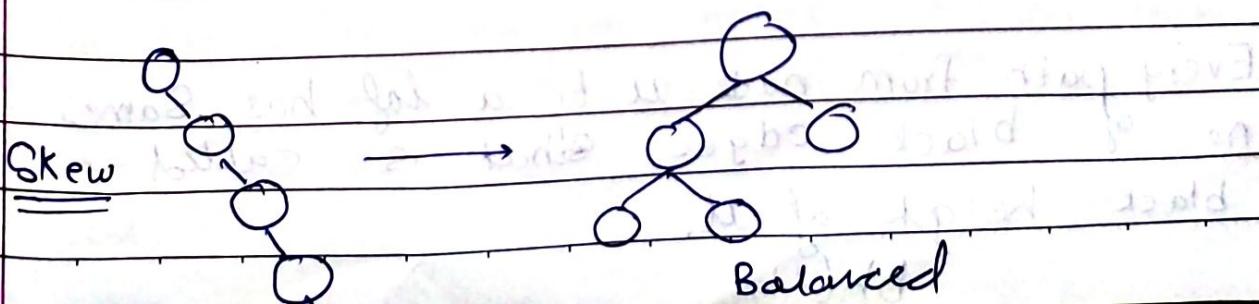
$\Rightarrow 2n$ is upper bound for actual cost

Binary Search Tree.

* Red Black Tree (Self Binary Tree).

It is also an advanced binary search tree.

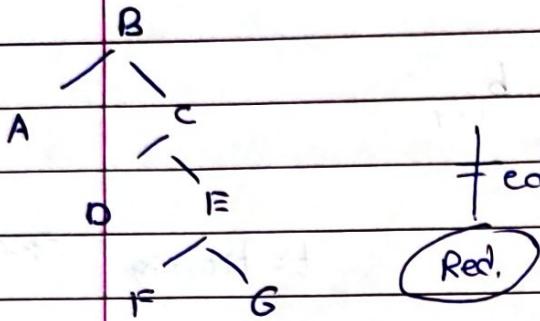
Also called RB Tree.



Rotation Operation.

Single

Double Rotation.

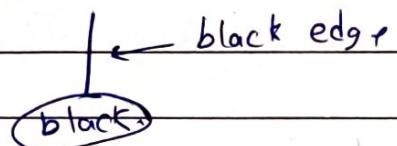


Left	Color	Key	Pointer to Parent	Right
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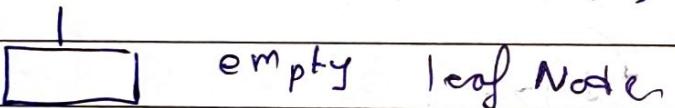
+ edge. we give color to edges.

If edge is black then node is black.

fixed

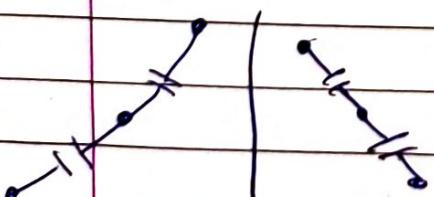
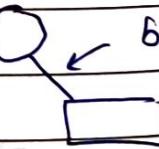


- Leaf Nodes will be empty pointer



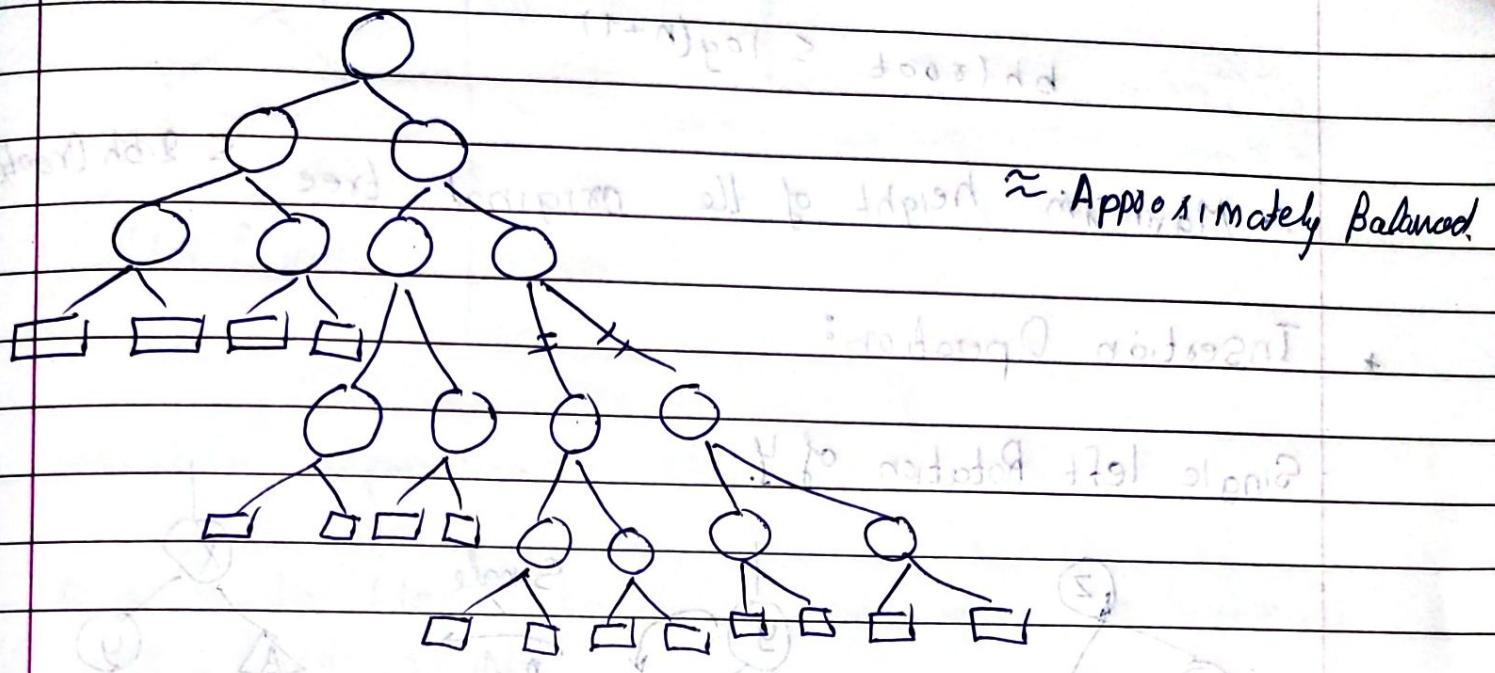
* Properties of R.B tree

- each edge has a color either red or black
- every edge to a leaf is black
- No path has two consecutive red edges.



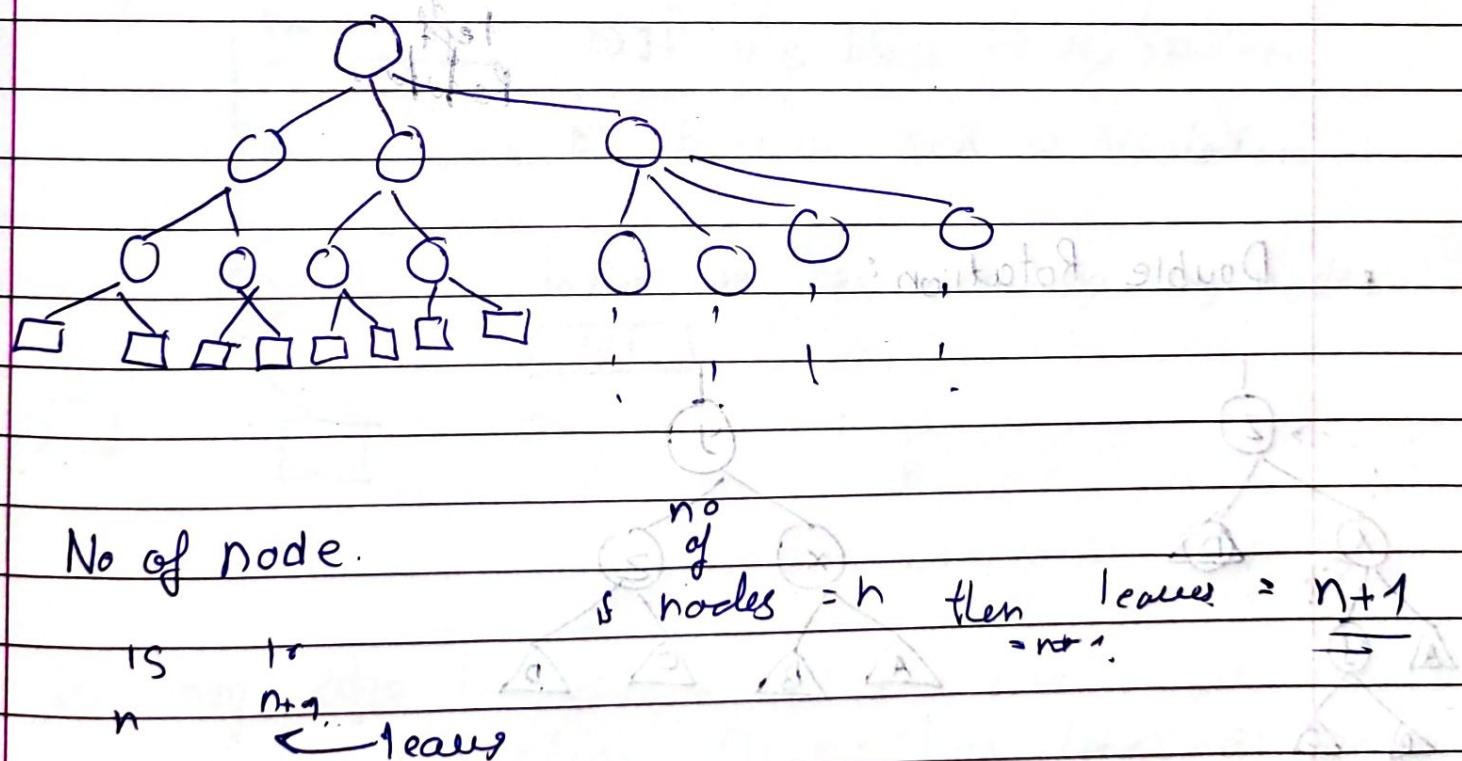
Consecutive red edges.

Every path from node u to a leaf has same no of black edges that is called as black height of u .



*Claim:

A red-black tree with N internal nodes has height at most $2 \log(n+1)$ or $\Theta(\log n)$.



In the contraction process, the tree nodes will have degree 2, 3, 4.

The contracted tree has leaves greater than or equal to $2^{bh(\text{root})}$ leaves $> 2^{bh(\text{root})}$

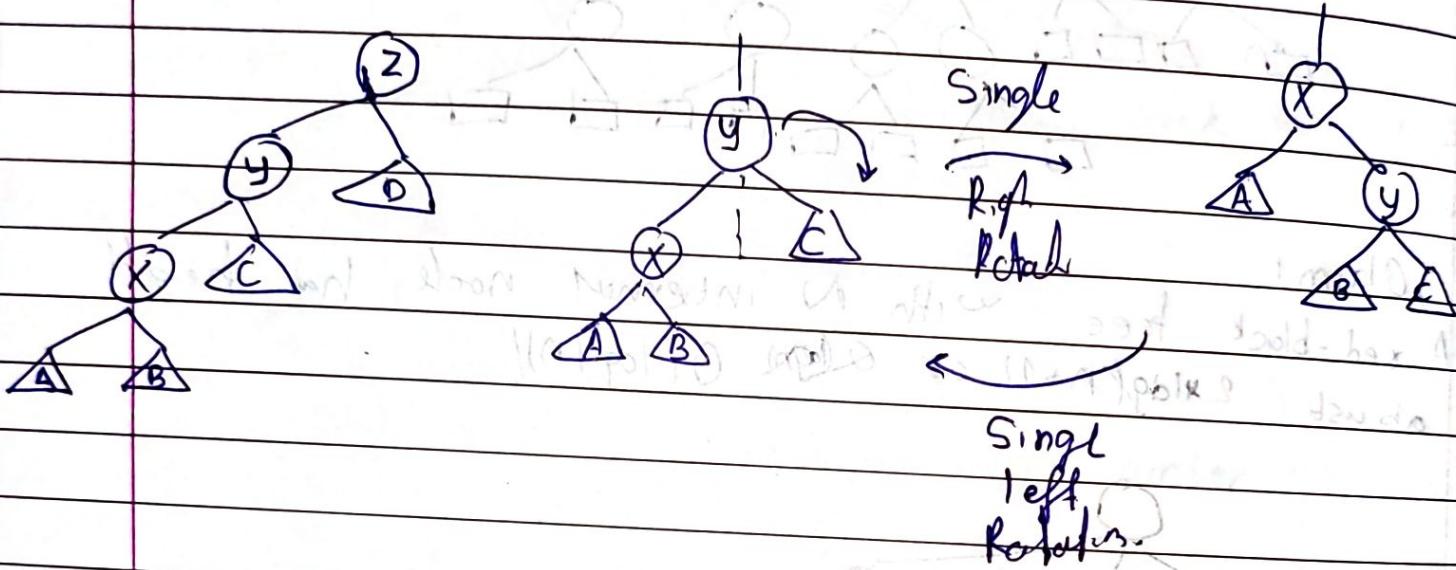
But $2^{bh(\text{root})} < n+1$

$$bh(\text{root}) \leq \log(n+1).$$

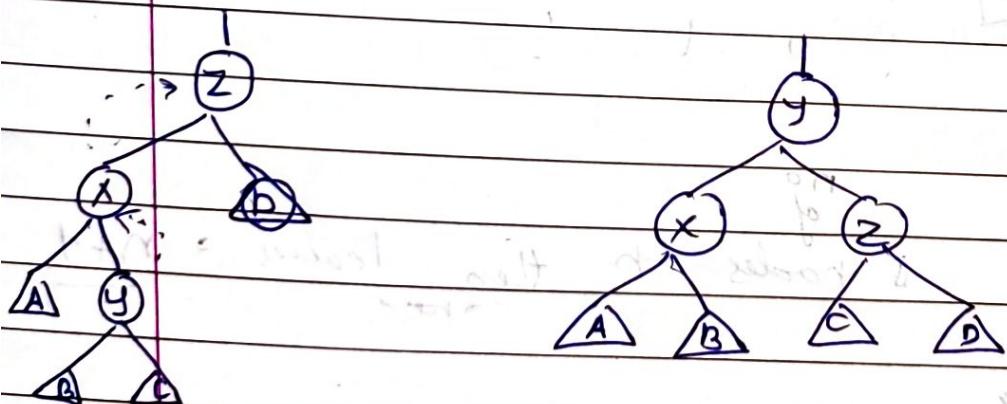
\therefore Maximum height of the original tree $\leq 2bh(\text{root})$

Insertion Operation:

Single left Rotation of Y.

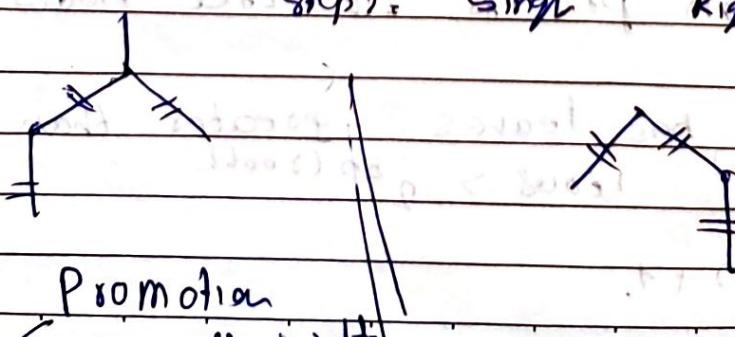


Double Rotation:



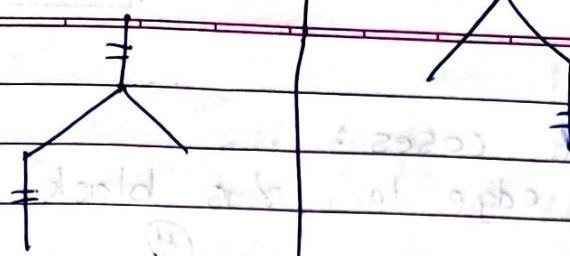
Step 1: Single Left Rotation of Y.

Step 2: Single Right Rotation of Y.



continued

M	T	W	T	F	S	S
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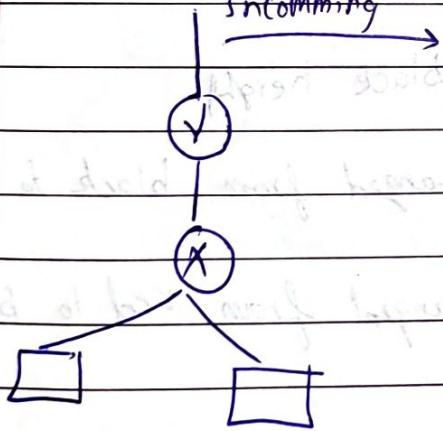
After Pruned.

* Insertion Operation:

1. At a node (leaf) both children empty or atleast one child empty.
2. Then Find Such node Where we can attach new node
3. Insert new node X

 a) If it is black \Rightarrow No problem

 b) If it is red \Rightarrow Violation



When we are attaching any node.

[X]

Incomming edge to root is black
(While inserting (If existing tree is not empty) incomming edge is red.)

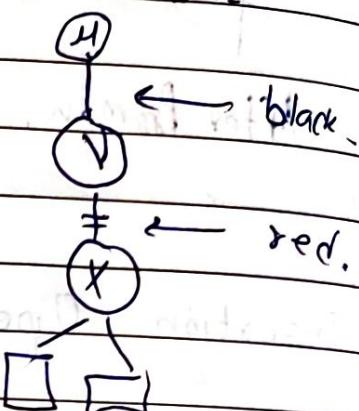
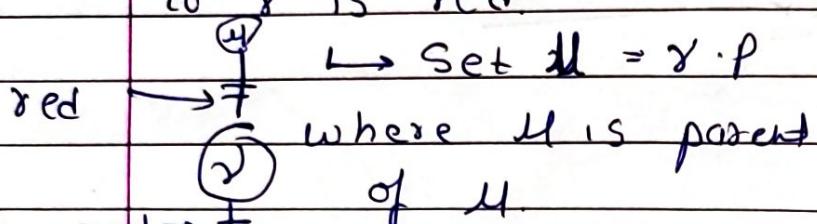
If Y has a red incomming edge and a red outgoing edge then this is the only violation of red black tree property.

- There are several cases:

* Case 1: Incoming edge to y is black.

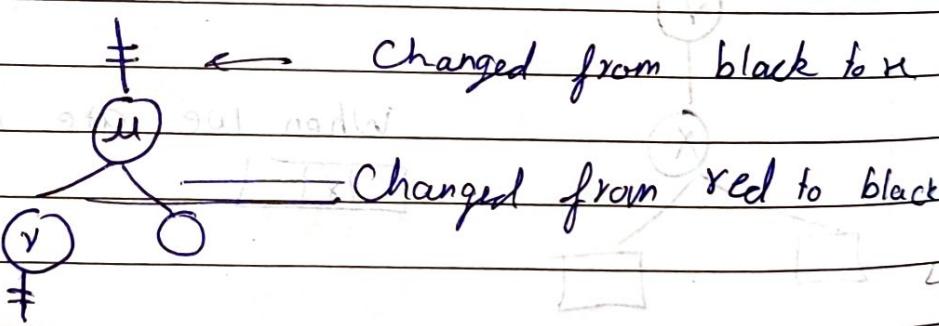
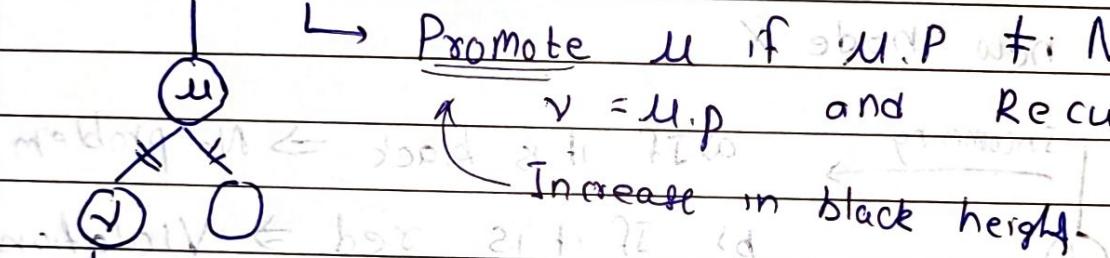
Stop \rightarrow Done.

* Case 2: If incoming edge to y is red.



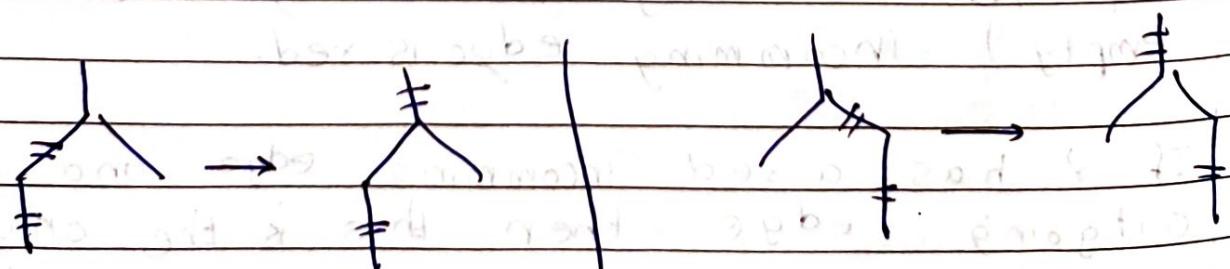
2.1: Both outgoing edges of u are red

\rightarrow Promote u if $u.p \neq \text{Nil}$, then
 $v = u.p$ and Recurse y .



Changed from red to black

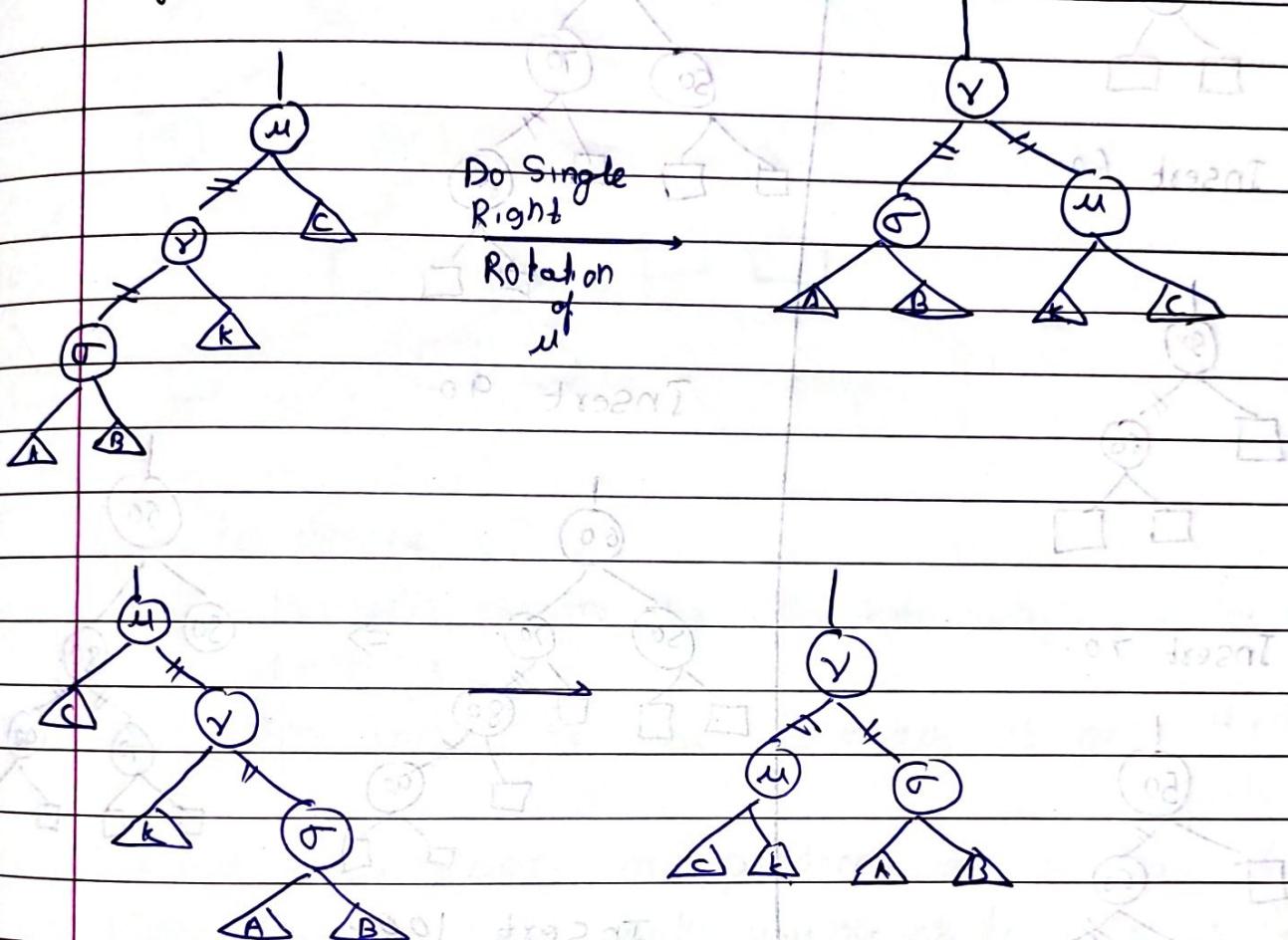
Making this change can lead to violation by $u.p$. So we set $y = u.p$ and recurse.



2.2:

Only one child of u is red.

v is the left child of u and left outgoing edge of v is red.



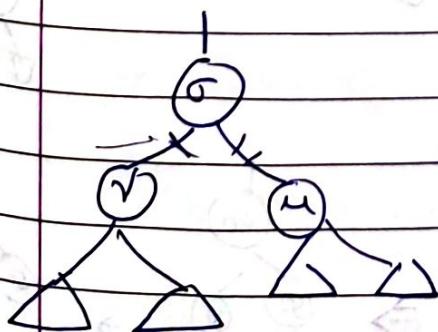
Case 2.3:

v is left child of u .

Double Rotation.

Symmetric write

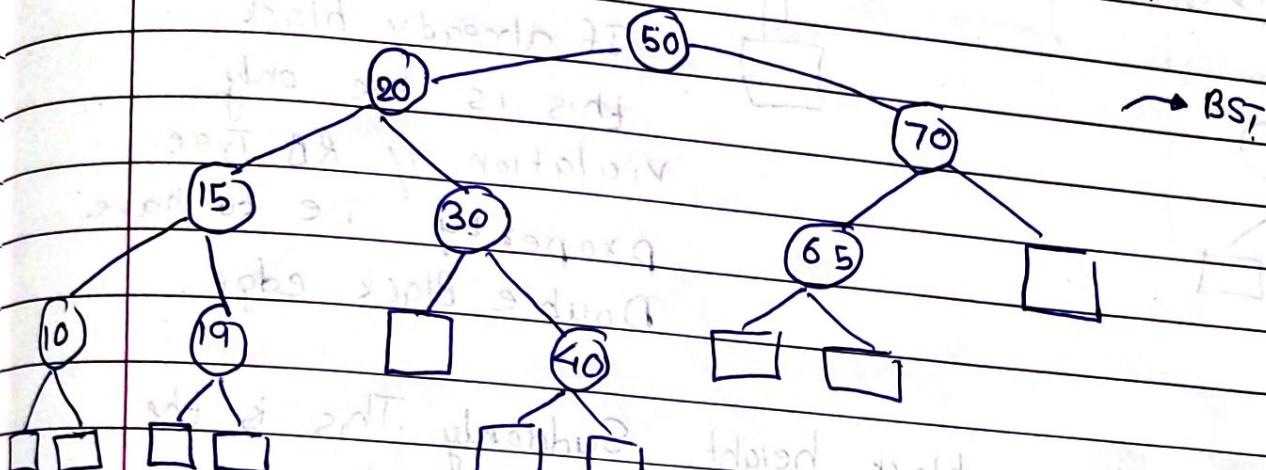
left is also applicable



* $O(\log n)$

Comp. bddy

* Delete Operation in Red-Black Tree :



Ways to delete

1. Provide pointer to the node, which is to be deleted

2. key value to be deleted, is provided.

S1: Find Successor or predecessor of Node X
repeatedly such that you reach to a node (leaf) where both sides are empty.

Colors

- red

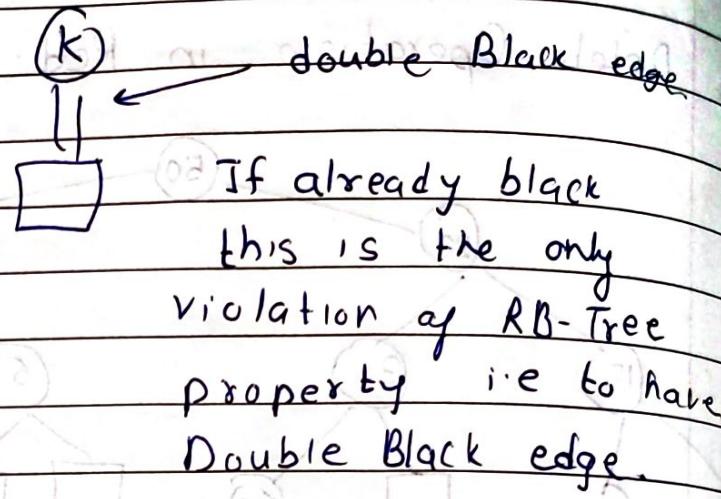
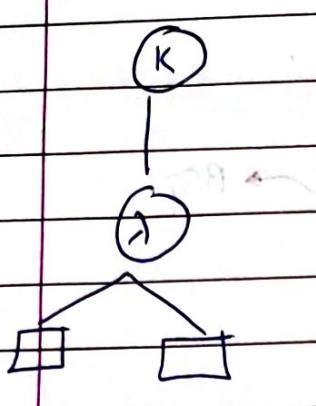
- black

- Double black.

Time Complexity - $O(h)$

λ be the node with two leaves

black
or
red



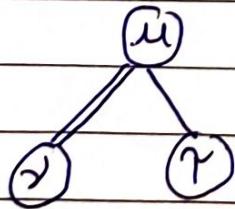
We can't change black height. Suddenly. This is the only violation to have double black edge.

Generic Situation

Below — γ

This node γ everything else is at fine (as per RB Tree Property)

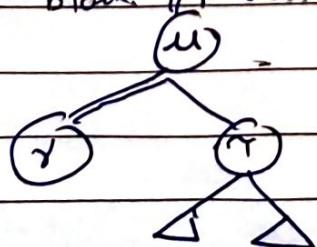
Case 1: Incoming edge of γ is not a double black. $\mu_1 = \gamma \cdot p$ τ is a sibling of γ .



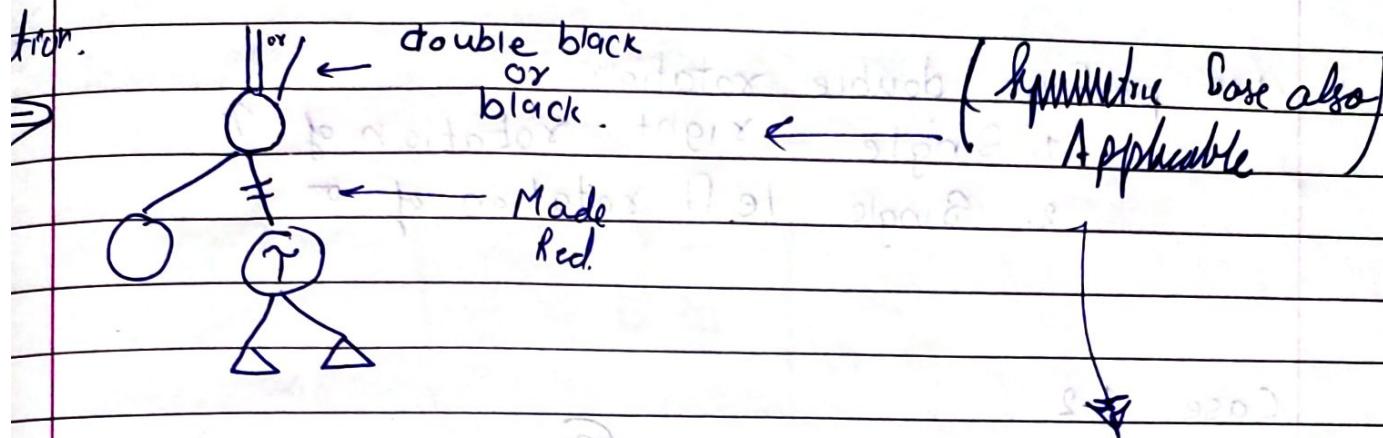
(Always there is a symmetric case)

Case 1.1. Tau is not a leaf.

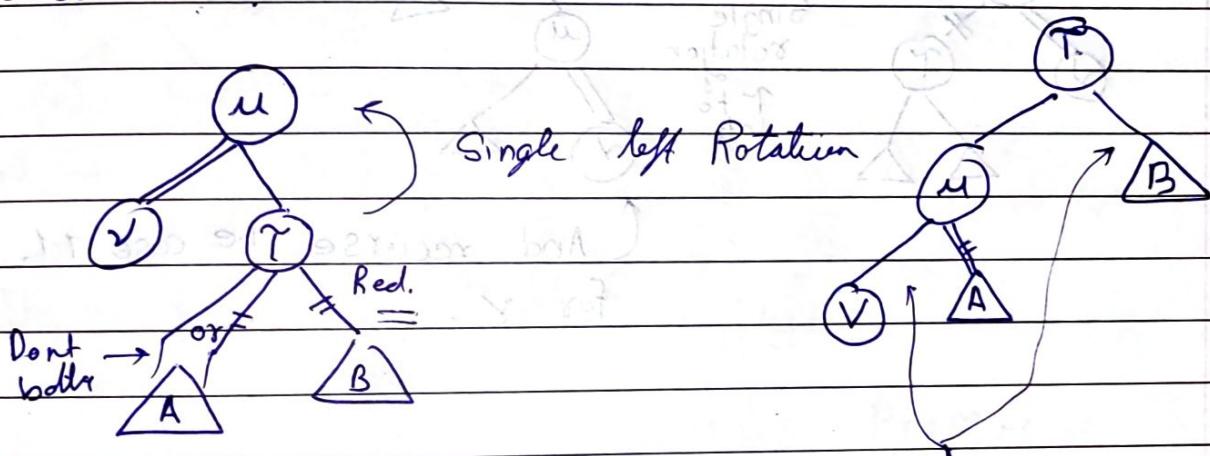
Case 1.1.1: Both outgoing edges of Tau are black. If red \rightarrow black.



\Rightarrow Demote μ_1 and recurse on
 $\gamma := \mu_1$ (γ is updated to μ_1)

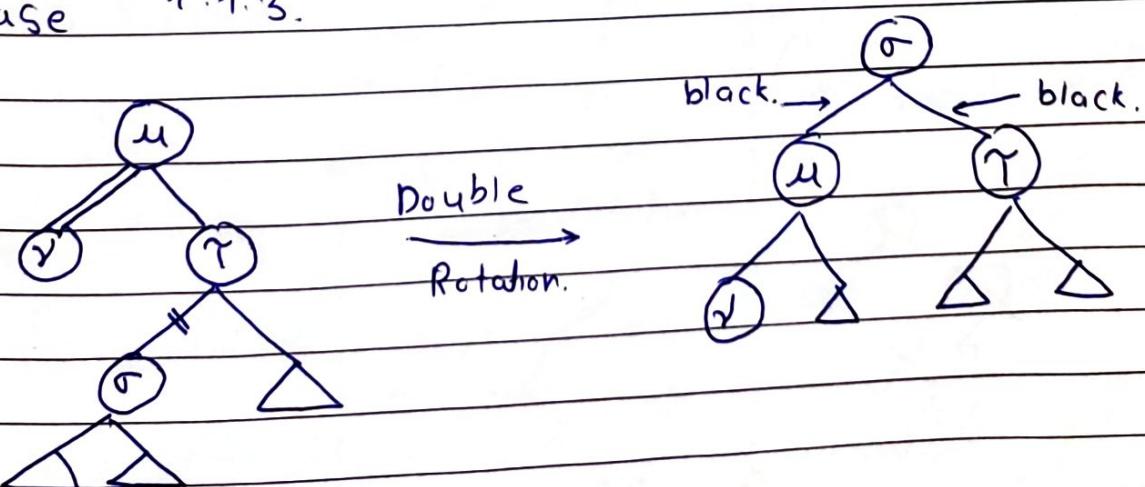


Case 1.1.2 :



γ is the left child of u and the right outgoing edge of γ is red.

Case 1.1.3.

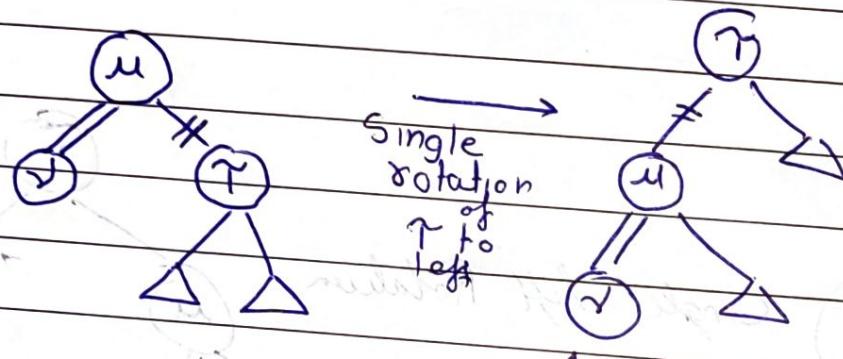


The left child of u and left outgoing edge of γ is red. The other one is black.

We perform double rotation

1. Single right rotation of γ
2. Single left rotation of α

Case 1.2



(And recurse i.e case 1.1 for γ .)

Case 2.

If incoming edge of γ is black \rightarrow
we have done STOP

* Flow Networks.

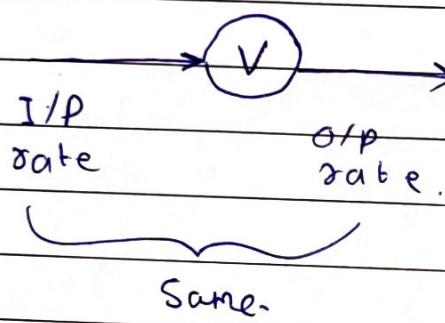
* Directed Graph $G(V, E)$ - V - Set of Vertices
 - E - Set of Edges.

s - Source - Where material is produced.

t - Sink - Where material is consumed.

Source produces material at some steady rate

Sink consumes the material at same rate



Flow Conservation Property:

* Maximum Flow Problem:

We wish to compute the greatest rate at which we can shift material from Source to Sink without violating any capacity constraints.

$$|F| = ?$$

(Flow Rate)

- For all $(u, v) \in E$

$$c(u, v) = 0.$$

- No Self loops

we assume G is connected.

Flow in G is Real Valued functions
 $f: V \times V \rightarrow \mathbb{R}$.

Capacity Constraints.
For $\forall u, v \in X$.

$$0 \leq f(u, v) \leq c(u, v)$$

Residual Capacity.

$$c(u, v) = 100 \text{ Units}$$

$$f(u, v) = 20 \text{ Units}$$

$$\text{Residual Capacity} = 100 - 20 \text{ Units}$$

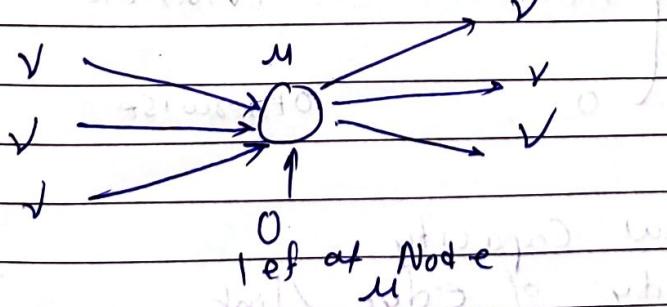
$$= 80 \text{ units}$$

$$2) \quad V_{u,v} \subset V_S \cap (u, S) \cap (v, S) \cap (v, u)$$

$$f(u, v) = -f(v, u)$$

$$3) \quad \text{for all } u \in V - \{s, t\}$$

$$\sum_{v \in V} f(u, v) = 0 \quad (\text{flow conservation})$$



The value of flow is $|f| = \sum_{v \in V} f(s, v)$

Max Flow Problem is to find $\max |f|$

$$|f| = \sum_{v \in V} f(s, v) - \sum_{v \in V} f(v, s)$$

or.

$$\sum_{v \in V} f(s, v) = \sum_{v \in V} f(v, s)$$

Max flow min cut theorem:

Some other properties of flow:

$$f(x, y) = \sum_{x \in X} \sum_{y \in Y} f(x, y)$$

for two sets $X, Y \subseteq V$

$$1. f(X, X) = 0$$

$$X \subseteq X$$

$$2. f(X, Y) = -f(Y, X)$$

$$3. f(X \cup Y, Z) = f(X, Z) + f(Y, Z)$$

$$4. f(Z, X \cup Y) = f(Z, X) + f(Z, Y)$$

* Ford Fulkerson Method:

uses the concept of residual capacity.

$$c_f(u, v) = \begin{cases} c(u, v) - f(u, v) & \text{if } (u, v) \in E \\ f(v, u) & \text{if } (v, u) \in E \\ 0 & \text{otherwise} \end{cases}$$

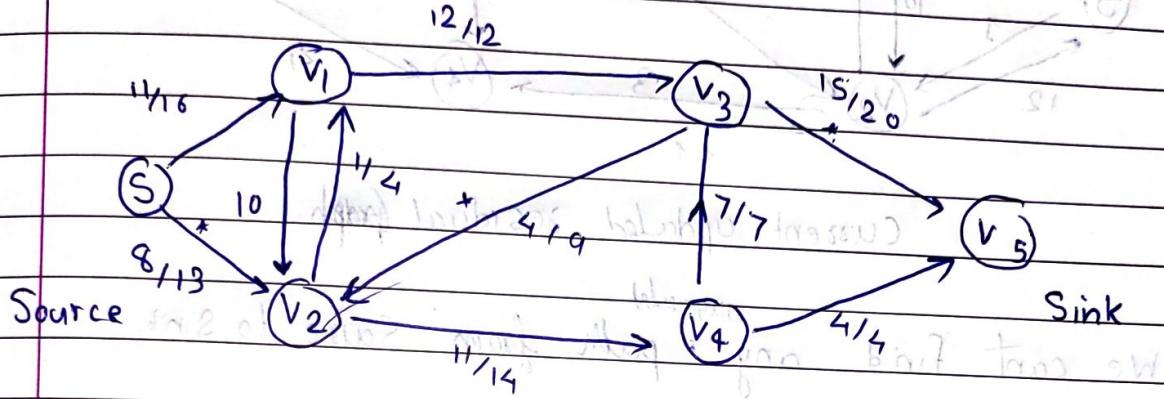
$c_f \rightarrow$ Residual Capacity.

$c \rightarrow$ Capacity of edge / link

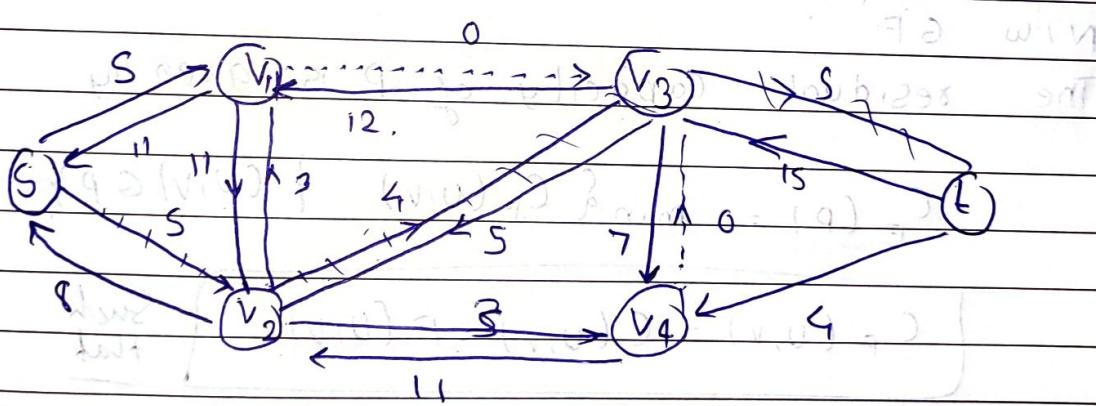
For the given N/W $G = (V, E)$ and a flow f ,
the residual N/W is $G_f = (V, E_f)$

where

$$E_F = \{(u, v) \in V \times V \mid C_F(u, v) > 0\}$$



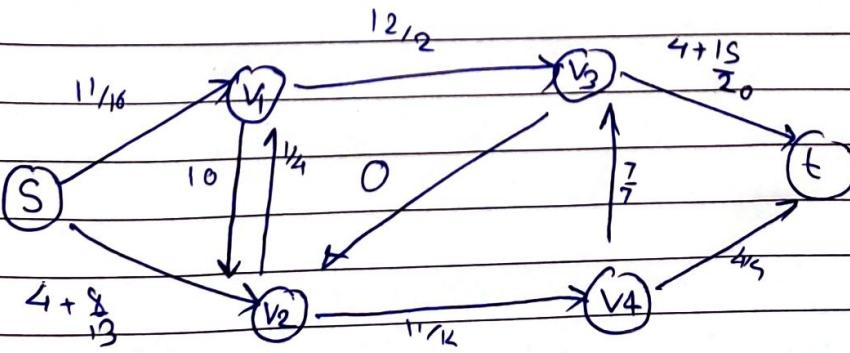
$$G = \{$$

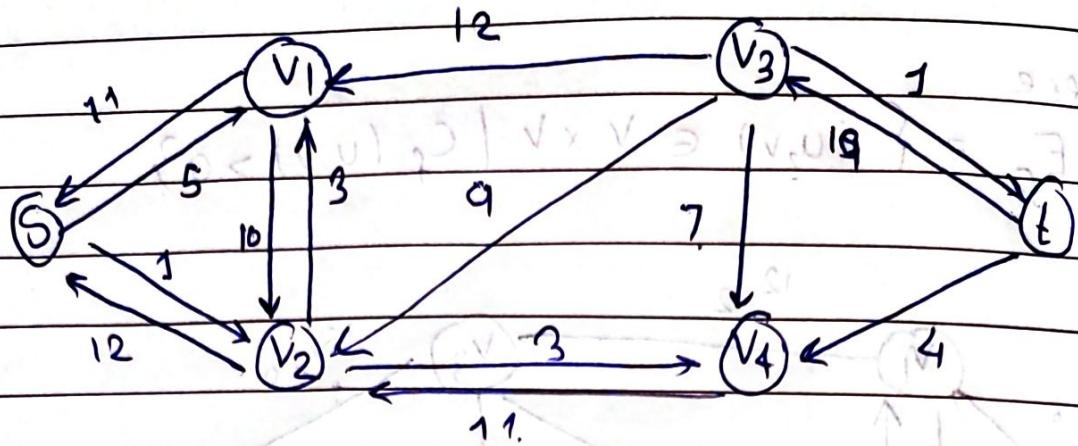


Lets Assume Sv_2v_3t path

This is the augmented path.

$$\min(5, 4, 5) = 4,$$





Current updated residual graph.

We can't find any ^{augmented} path from Source to Sink.

Augmenting Path:

A path p from 'S' to 't' in the residual graph.

The residual capacity of p is given by

$$C_F(p) = \min \{ C_F(u,v) \mid (u,v) \in p \}$$

$$C_F(u,v) = C(u,v) - f(u,v)$$

such that