

AUTOMATIC NUMBER PLATE RECOGNITION (ANPR) -- By Mayank Vajpayee

```
In [32]: #installing Opencv Library  
pip install opencv-python
```

Requirement already satisfied: opencv-python in c:\users\mayan\anaconda4\envs\tf_env\lib\site-packages (4.11.0.86)
Requirement already satisfied: numpy>=1.21.2 in c:\users\mayan\anaconda4\envs\tf_env\lib\site-packages (from opencv-python) (2.1.3)
Note: you may need to restart the kernel to use updated packages.

```
In [5]: import cv2
```

its a separate command

```
import zipfile  
zip_ref = zipfile.ZipFile('/content/archive.zip', 'r')  
zip_ref.extractall('/content')  
zip_ref.close()
```

```
In [6]: #importing tensor flow  
#earlier was getting error to import tensor fow, so created a new environment "tf_e  
#and the running jupyter notebbok and the libraries in the new environment  
import tensorflow as tf  
print(tf.__version__)
```

2.19.0

```
In [7]: import tensorflow as tf  
from tensorflow import keras  
from keras import Sequential  
from keras.layers import Dense,Conv2D,MaxPooling2D,Flatten,BatchNormalization,Dropo
```

```
In [8]: # Loads the data required for detecting the license plates from cascade classifier.  
plate_cascade = cv2.CascadeClassifier(r'C:\Users\mayan\Full_Stack_Data_Science_Cour
```

```
In [9]: def detect_plate(img, text=''): # the function detects and perfors blurring on the  
    plate_img = img.copy()  
    roi = img.copy()  
    plate_rect = plate_cascade.detectMultiScale(plate_img, scaleFactor = 1.2, minNe  
    for (x,y,w,h) in plate_rect:  
        roi_ = roi[y:y+h, x:x+w, :] # extracting the Region of Interest of license  
        plate = roi[y:y+h, x:x+w, :]  
        cv2.rectangle(plate_img, (x+2,y), (x+w-3, y+h-5), (51,181,155), 3) # final  
    if text!='':  
        plate_img = cv2.putText(plate_img, text, (x-w//2,y-h//2),  
                                cv2.FONT_HERSHEY_COMPLEX_SMALL, 0.5, (51,181,155),  
    return plate_img, plate # returning the processed image.
```

```
In [11]: import matplotlib.pyplot as plt
```

```
In [12]: # Testing the above function
def display(img_, title=''):
    img = cv2.cvtColor(img_, cv2.COLOR_BGR2RGB)
    fig = plt.figure(figsize=(10,6))
    ax = plt.subplot(111)
    ax.imshow(img)
    plt.axis('off')
    plt.title(title)
    plt.show()

img = cv2.imread(r'C:\Users\mayan\Full_Stack_Data_Science_Course_IIT_Guwahati\Final
display(img, 'input image')
```

input image



```
In [13]: # Getting plate from the processed image
output_img, plate = detect_plate(img)
```

```
In [14]: display(output_img, 'detected license plate in the input image')
```

detected license plate in the input image



```
In [15]: display(plate, 'extracted license plate from the image')
```

extracted license plate from the image



```
In [16]: # Match contours to license plate or character template
def find_contours(dimensions, img) :

    # Find all contours in the image
    cntrs, _ = cv2.findContours(img.copy(), cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE)

    # Retrieve potential dimensions
    lower_width = dimensions[0]
    upper_width = dimensions[1]
    lower_height = dimensions[2]
    upper_height = dimensions[3]

    # Check largest 5 or 15 contours for license plate or character respectively
    cntrs = sorted(cntrs, key=cv2.contourArea, reverse=True)[:15]

    ii = cv2.imread('contour.jpg')
```

```

x_cntr_list = []
img_res = []
for cntr in cntrs :
    # detects contour in binary image and returns the coordinates of rectangle
    intX, intY, intWidth, intHeight = cv2.boundingRect(cntr)

    # checking the dimensions of the contour to filter out the characters by co
    if intWidth > lower_width and intWidth < upper_width and intHeight > lower_
        x_cntr_list.append(intX) #stores the x coordinate of the character's co

    char_copy = np.zeros((44,24))
    # extracting each character using the enclosing rectangle's coordinates
    char = img[intY:intY+intHeight, intX:intX+intWidth]
    char = cv2.resize(char, (20, 40))

    cv2.rectangle(img, (intX,intY), (intWidth+intX, intY+intHeight), (75,30
plt.imshow(img, cmap='gray')

    # Make result formatted for classification: invert colors
    char = cv2.subtract(255, char)

    # Resize the image to 24x44 with black border
    char_copy[2:42, 2:22] = char
    char_copy[0:2, :] = 0
    char_copy[:, 0:2] = 0
    char_copy[42:44, :] = 0
    char_copy[:, 22:24] = 0

    img_res.append(char_copy) # List that stores the character's binary ima

# Return characters on ascending order with respect to the x-coordinate (most-L

plt.show()
# arbitrary function that stores sorted list of character indeces
indices = sorted(range(len(x_cntr_list)), key=lambda k: x_cntr_list[k])
img_res_copy = []
for idx in indices:
    img_res_copy.append(img_res[idx])# stores character images according to the
img_res = np.array(img_res_copy)

return img_res

```

In [18]: `import numpy as np`

In [19]: `# Find characters in the resulting images`

```

def segment_characters(image) :

    # Preprocess cropped license plate image
    img_lp = cv2.resize(image, (333, 75))
    img_gray_lp = cv2.cvtColor(img_lp, cv2.COLOR_BGR2GRAY)
    _, img_binary_lp = cv2.threshold(img_gray_lp, 200, 255, cv2.THRESH_BINARY+cv2.T
    img_binary_lp = cv2.erode(img_binary_lp, (3,3))
    img_binary_lp = cv2.dilate(img_binary_lp, (3,3))

```

```

LP_WIDTH = img_binary_lp.shape[0]
LP_HEIGHT = img_binary_lp.shape[1]

# Make borders white
img_binary_lp[0:3,:] = 255
img_binary_lp[:,0:3] = 255
img_binary_lp[72:75,:] = 255
img_binary_lp[:,330:333] = 255

# Estimations of character contours sizes of cropped license plates
dimensions = [LP_WIDTH/6,
              LP_WIDTH/2,
              LP_HEIGHT/10,
              2*LP_HEIGHT/3]

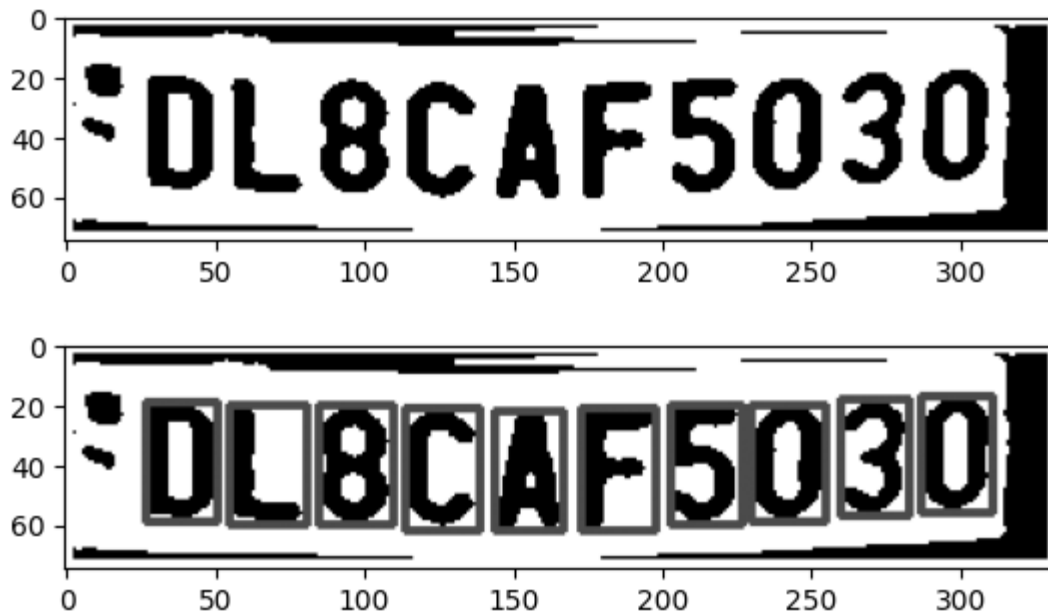
plt.imshow(img_binary_lp, cmap='gray')
plt.show()
cv2.imwrite('contour.jpg',img_binary_lp)

# Get contours within cropped license plate
char_list = find_contours(dimensions, img_binary_lp)

return char_list

```

In [20]: `char = segment_characters(plate)`



In [21]: `for i in range(10):
 plt.subplot(1, 10, i+1)
 plt.imshow(char[i], cmap='gray')
 plt.axis('off')`



```
In [22]: import tensorflow.keras.backend as K
from tensorflow.keras.preprocessing.image import ImageDataGenerator
train_datagen = ImageDataGenerator(rescale=1./255, width_shift_range=0.1, height_sh
path = 'C:/Users/mayan/Full_Stack_Data_Science_Course_IIT_Guwahati/Final_Notebooks/
train_generator = train_datagen.flow_from_directory(
    path+'/train', # this is the target directory
    target_size=(28,28), # all images will be resized to 28x28
    batch_size=1,
    class_mode='sparse')

validation_generator = train_datagen.flow_from_directory(
    path+'/val', # this is the target directory
    target_size=(28,28), # all images will be resized to 28x28 batch_size=1,
    class_mode='sparse')
```

Found 864 images belonging to 36 classes.

Found 216 images belonging to 36 classes.

```
In [23]: from tensorflow.keras import optimizers
K.clear_session()
model = Sequential()
model.add(Conv2D(16, kernel_size=(22,22), padding='same', activation='relu', input_shape=(28,28,3)))
model.add(Conv2D(32, kernel_size=(16,16), padding='same', activation='relu'))
model.add(Conv2D(64, kernel_size=(8,8), padding='same', activation='relu'))
model.add(Conv2D(64, kernel_size=(4,4), padding='same', activation='relu'))
model.add(MaxPooling2D(pool_size=(4, 4)))
model.add(Dropout(0.4))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dense(36, activation='softmax'))

model.compile(loss='sparse_categorical_crossentropy', optimizer=optimizers.Adam(learning_rate=0.001))
```

WARNING:tensorflow:From C:\Users\mayan\anaconda4\envs\tf_env\lib\site-packages\keras\src\backend\common\global_state.py:82: The name tf.reset_default_graph is deprecated. Please use tf.compat.v1.reset_default_graph instead.

C:\Users\mayan\anaconda4\envs\tf_env\lib\site-packages\keras\src\layers\convolutional\base_conv.py:107: UserWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When using Sequential models, prefer using an `Input(shape)` object as the first layer in the model instead.
super().__init__(activity_regularizer=activity_regularizer, **kwargs)

```
In [24]: model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	
conv2d (Conv2D)	(None, 28, 28, 16)	
conv2d_1 (Conv2D)	(None, 28, 28, 32)	
conv2d_2 (Conv2D)	(None, 28, 28, 64)	
conv2d_3 (Conv2D)	(None, 28, 28, 64)	
max_pooling2d (MaxPooling2D)	(None, 7, 7, 64)	
dropout (Dropout)	(None, 7, 7, 64)	
flatten (Flatten)	(None, 3136)	
dense (Dense)	(None, 128)	
dense_1 (Dense)	(None, 36)	

Total params: 757,268 (2.89 MB)

Trainable params: 757,268 (2.89 MB)

Non-trainable params: 0 (0.00 B)

```
In [25]: class stop_training_callback(tf.keras.callbacks.Callback):
         def on_epoch_end(self, epoch, logs={}):
             if(logs.get('val_accuracy') > 0.999):
                 self.model.stop_training = True
```

```
In [1]: pip install Pillow
```

Requirement already satisfied: Pillow in c:\users\mayan\anaconda4\envs\tf_env\lib\site-packages (11.2.1)

Note: you may need to restart the kernel to use updated packages.

```
In [26]: from PIL import Image

         img = Image.new('RGB', (100, 100), color='red')
         img.show()
```

```
In [28]: pip install scipy
```

Collecting scipy

Downloading scipy-1.15.3-cp310-cp310-win_amd64.whl.metadata (60 kB)

Requirement already satisfied: numpy<2.5,>=1.23.5 in c:\users\mayan\anaconda4\envs\tf_env\lib\site-packages (from scipy) (2.1.3)

Downloading scipy-1.15.3-cp310-cp310-win_amd64.whl (41.3 MB)

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```

Installing collected packages: scipy

Successfully installed scipy-1.15.3


Note: you may need to restart the kernel to use updated packages.

```
In [29]: batch_size = 1
         callbacks = [stop_training_callback()]
         model.fit(
             train_generator,
             steps_per_epoch = train_generator.samples // batch_size,
```



```
validation_data = validation_generator,  
epochs = 80, verbose=1, callbacks=callbacks)
```

Epoch 1/80

864/864  **0s** 34ms/step - accuracy: 0.0728 - loss: 3.4810

C:\Users\mayan\anaconda4\envs\tf_env\lib\site-packages\keras\src\trainers\data_adapters\py_dataset_adapter.py:121: UserWarning: Your `PyDataset` class should call `super().__init__(**kwargs)` in its constructor. `**kwargs` can include `workers`, `use_multiprocessing`, `max_queue_size`. Do not pass these arguments to `fit()`, as they will be ignored.

```
self._warn_if_super_not_called()
```

864/864 ————— 34s 36ms/step - accuracy: 0.0729 - loss: 3.4805 - val_accuracy: 0.4954 - val_loss: 1.7115
Epoch 2/80

864/864 ————— 27s 32ms/step - accuracy: 0.4947 - loss: 1.6275 - val_accuracy: 0.6944 - val_loss: 0.8638
Epoch 3/80

864/864 ————— 23s 26ms/step - accuracy: 0.7226 - loss: 0.8709 - val_accuracy: 0.8657 - val_loss: 0.4835
Epoch 4/80

864/864 ————— 22s 25ms/step - accuracy: 0.8645 - loss: 0.4502 - val_accuracy: 0.8981 - val_loss: 0.3588
Epoch 5/80

864/864 ————— 23s 26ms/step - accuracy: 0.8960 - loss: 0.3751 - val_accuracy: 0.9444 - val_loss: 0.1943
Epoch 6/80

864/864 ————— 22s 25ms/step - accuracy: 0.9132 - loss: 0.2895 - val_accuracy: 0.9167 - val_loss: 0.2671
Epoch 7/80

864/864 ————— 22s 25ms/step - accuracy: 0.9366 - loss: 0.1950 - val_accuracy: 0.9583 - val_loss: 0.2184
Epoch 8/80

864/864 ————— 25s 29ms/step - accuracy: 0.9412 - loss: 0.1914 - val_accuracy: 0.9398 - val_loss: 0.1827
Epoch 9/80

864/864 ————— 24s 27ms/step - accuracy: 0.9527 - loss: 0.1308 - val_accuracy: 0.9537 - val_loss: 0.1273
Epoch 10/80

864/864 ————— 23s 26ms/step - accuracy: 0.9607 - loss: 0.1048 - val_accuracy: 0.9444 - val_loss: 0.1178
Epoch 11/80

864/864 ————— 23s 27ms/step - accuracy: 0.9561 - loss: 0.1805 - val_accuracy: 0.9676 - val_loss: 0.1172
Epoch 12/80

864/864 ————— 22s 26ms/step - accuracy: 0.9589 - loss: 0.1162 - val_accuracy: 0.9722 - val_loss: 0.1254
Epoch 13/80

864/864 ————— 22s 25ms/step - accuracy: 0.9522 - loss: 0.1545 - val_accuracy: 0.9815 - val_loss: 0.0601
Epoch 14/80

864/864 ————— 23s 27ms/step - accuracy: 0.9727 - loss: 0.0769 - val_accuracy: 0.9861 - val_loss: 0.0499
Epoch 15/80




















864/864 ————— 27s 31ms/step - accuracy: 0.9685 - loss: 0.0947 - val_accuracy: 0.9861 - val_loss: 0.0362
Epoch 16/80



















864/864 ————— 25s 29ms/step - accuracy: 0.9662 - loss: 0.1125 - val_accuracy: 0.9676 - val_loss: 0.1380
Epoch 17/80

864/864 ————— 25s 29ms/step - accuracy: 0.9580 - loss: 0.1296 - val_accuracy: 0.9722 - val_loss: 0.0931
Epoch 18/80

864/864 ————— 24s 28ms/step - accuracy: 0.9719 - loss: 0.0770 - val_accuracy: 0.9815 - val_loss: 0.0694
Epoch 19/80

864/864 ————— 24s 28ms/step - accuracy: 0.9820 - loss: 0.0502 - val_accuracy: 0.9954 - val_loss: 0.0236

Epoch 20/80
864/864  **24s** 28ms/step - accuracy: 0.9739 - loss: 0.0696 - val_accuracy: 0.9815 - val_loss: 0.0888
Epoch 21/80
864/864  **24s** 28ms/step - accuracy: 0.9885 - loss: 0.0403 - val_accuracy: 0.9769 - val_loss: 0.0741
Epoch 22/80
864/864  **24s** 28ms/step - accuracy: 0.9455 - loss: 0.1863 - val_accuracy: 0.9815 - val_loss: 0.0653
Epoch 23/80
864/864  **22s** 26ms/step - accuracy: 0.9769 - loss: 0.0710 - val_accuracy: 0.9722 - val_loss: 0.0516
Epoch 24/80
864/864  **24s** 27ms/step - accuracy: 0.9808 - loss: 0.0693 - val_accuracy: 0.9722 - val_loss: 0.1093
Epoch 25/80
864/864  **26s** 30ms/step - accuracy: 0.9778 - loss: 0.0726 - val_accuracy: 0.9583 - val_loss: 0.1501
Epoch 26/80
864/864  **25s** 29ms/step - accuracy: 0.9652 - loss: 0.0859 - val_accuracy: 0.9630 - val_loss: 0.0551
Epoch 27/80
864/864  **27s** 31ms/step - accuracy: 0.9852 - loss: 0.0370 - val_accuracy: 0.9815 - val_loss: 0.0650
Epoch 28/80
864/864  **26s** 30ms/step - accuracy: 0.9813 - loss: 0.0529 - val_accuracy: 0.9444 - val_loss: 0.1772
Epoch 29/80
864/864  **25s** 29ms/step - accuracy: 0.9666 - loss: 0.0799 - val_accuracy: 0.9722 - val_loss: 0.0854
Epoch 30/80
864/864  **26s** 30ms/step - accuracy: 0.9690 - loss: 0.1111 - val_accuracy: 0.9722 - val_loss: 0.0691
Epoch 31/80
864/864  **26s** 30ms/step - accuracy: 0.9701 - loss: 0.0649 - val_accuracy: 0.9769 - val_loss: 0.0457
Epoch 32/80
864/864  **25s** 29ms/step - accuracy: 0.9911 - loss: 0.0237 - val_accuracy: 0.9815 - val_loss: 0.0452
Epoch 33/80
864/864  **25s** 29ms/step - accuracy: 0.9816 - loss: 0.0407 - val_accuracy: 0.9815 - val_loss: 0.0687
Epoch 34/80
864/864  **25s** 29ms/step - accuracy: 0.9631 - loss: 0.1492 - val_accuracy: 0.9907 - val_loss: 0.0550
Epoch 35/80
864/864  **25s** 28ms/step - accuracy: 0.9641 - loss: 0.1375 - val_accuracy: 0.9861 - val_loss: 0.0301
Epoch 36/80
864/864  **25s** 29ms/step - accuracy: 0.9816 - loss: 0.0431 - val_accuracy: 0.9769 - val_loss: 0.0361
Epoch 37/80
864/864  **23s** 27ms/step - accuracy: 0.9672 - loss: 0.0837 - val_accuracy: 0.9722 - val_loss: 0.0481
Epoch 38/80
864/864  **22s** 26ms/step - accuracy: 0.9873 - loss: 0.0378 - val_accuracy: 0.9873 - val_loss: 0.0378

ccuracy: 0.9907 - val_loss: 0.0235
Epoch 39/80
864/864  25s 29ms/step - accuracy: 0.9706 - loss: 0.0889 - val_a
ccuracy: 0.9815 - val_loss: 0.0462
Epoch 40/80
864/864  26s 30ms/step - accuracy: 0.9936 - loss: 0.0166 - val_a
ccuracy: 0.9861 - val_loss: 0.0307
Epoch 41/80
864/864  23s 27ms/step - accuracy: 0.9922 - loss: 0.0407 - val_a
ccuracy: 0.9491 - val_loss: 0.1452
Epoch 42/80
864/864  25s 28ms/step - accuracy: 0.9809 - loss: 0.0520 - val_a
ccuracy: 0.9861 - val_loss: 0.0315
Epoch 43/80
864/864  21s 24ms/step - accuracy: 0.9904 - loss: 0.0328 - val_a
ccuracy: 0.9491 - val_loss: 0.1898
Epoch 44/80
864/864  21s 24ms/step - accuracy: 0.9616 - loss: 0.1107 - val_a
ccuracy: 0.9861 - val_loss: 0.0703
Epoch 45/80
864/864  26s 30ms/step - accuracy: 0.9878 - loss: 0.0290 - val_a
ccuracy: 0.9769 - val_loss: 0.0994
Epoch 46/80
864/864  23s 27ms/step - accuracy: 0.9883 - loss: 0.0261 - val_a
ccuracy: 0.9815 - val_loss: 0.0604
Epoch 47/80
864/864  23s 27ms/step - accuracy: 0.9737 - loss: 0.0606 - val_a
ccuracy: 0.9537 - val_loss: 0.2130
Epoch 48/80
864/864  22s 25ms/step - accuracy: 0.9725 - loss: 0.0991 - val_a
ccuracy: 0.9630 - val_loss: 0.0908
Epoch 49/80
864/864  21s 25ms/step - accuracy: 0.9806 - loss: 0.0684 - val_a
ccuracy: 0.9815 - val_loss: 0.0758
Epoch 50/80
864/864  21s 25ms/step - accuracy: 0.9869 - loss: 0.0248 - val_a
ccuracy: 0.9815 - val_loss: 0.0421
Epoch 51/80
864/864  21s 25ms/step - accuracy: 0.9896 - loss: 0.0264 - val_a
ccuracy: 0.9815 - val_loss: 0.0482
Epoch 52/80
864/864  21s 25ms/step - accuracy: 0.9825 - loss: 0.0418 - val_a
ccuracy: 0.9954 - val_loss: 0.0251
Epoch 53/80
864/864  21s 25ms/step - accuracy: 0.9863 - loss: 0.0350 - val_a
ccuracy: 0.9861 - val_loss: 0.0442
Epoch 54/80
864/864  22s 25ms/step - accuracy: 0.9954 - loss: 0.0206 - val_a
ccuracy: 0.9954 - val_loss: 0.0307
Epoch 55/80
864/864  21s 24ms/step - accuracy: 0.9919 - loss: 0.0267 - val_a
ccuracy: 0.9954 - val_loss: 0.0212
Epoch 56/80
864/864  21s 24ms/step - accuracy: 0.9731 - loss: 0.0626 - val_a
ccuracy: 0.9676 - val_loss: 0.0668
Epoch 57/80

864/864 ————— 22s 26ms/step - accuracy: 0.9811 - loss: 0.0605 - val_accuracy: 0.9907 - val_loss: 0.0332
Epoch 58/80

864/864 ————— 22s 26ms/step - accuracy: 0.9788 - loss: 0.0622 - val_accuracy: 0.9583 - val_loss: 0.2134
Epoch 59/80

864/864 ————— 21s 24ms/step - accuracy: 0.9810 - loss: 0.0659 - val_accuracy: 0.9815 - val_loss: 0.0403
Epoch 60/80

864/864 ————— 22s 25ms/step - accuracy: 0.9922 - loss: 0.0312 - val_accuracy: 0.9815 - val_loss: 0.1006
Epoch 61/80

864/864 ————— 23s 27ms/step - accuracy: 0.9878 - loss: 0.0355 - val_accuracy: 0.9722 - val_loss: 0.0631
Epoch 62/80

864/864 ————— 23s 27ms/step - accuracy: 0.9819 - loss: 0.0428 - val_accuracy: 0.9769 - val_loss: 0.0679
Epoch 63/80

864/864 ————— 24s 28ms/step - accuracy: 0.9889 - loss: 0.0319 - val_accuracy: 0.9769 - val_loss: 0.0352
Epoch 64/80

864/864 ————— 23s 27ms/step - accuracy: 0.9862 - loss: 0.0345 - val_accuracy: 0.9954 - val_loss: 0.0185
Epoch 65/80

864/864 ————— 22s 26ms/step - accuracy: 0.9877 - loss: 0.0593 - val_accuracy: 0.9769 - val_loss: 0.1113
Epoch 66/80

864/864 ————— 22s 25ms/step - accuracy: 0.9795 - loss: 0.0365 - val_accuracy: 0.9861 - val_loss: 0.0479
Epoch 67/80

864/864 ————— 22s 25ms/step - accuracy: 0.9840 - loss: 0.0311 - val_accuracy: 0.9907 - val_loss: 0.0188
Epoch 68/80

864/864 ————— 26s 30ms/step - accuracy: 0.9869 - loss: 0.0276 - val_accuracy: 0.9954 - val_loss: 0.0194
Epoch 69/80

864/864 ————— 22s 26ms/step - accuracy: 0.9947 - loss: 0.0259 - val_accuracy: 0.9907 - val_loss: 0.0162
Epoch 70/80

864/864 ————— 25s 28ms/step - accuracy: 0.9908 - loss: 0.0214 - val_accuracy: 0.9954 - val_loss: 0.0147
Epoch 71/80

864/864 ————— 25s 29ms/step - accuracy: 0.9569 - loss: 0.1041 - val_accuracy: 0.9861 - val_loss: 0.0862
Epoch 72/80

864/864 ————— 21s 25ms/step - accuracy: 0.9884 - loss: 0.0306 - val_accuracy: 0.9954 - val_loss: 0.0160
Epoch 73/80

864/864 ————— 21s 24ms/step - accuracy: 0.9812 - loss: 0.0409 - val_accuracy: 0.9769 - val_loss: 0.0379
Epoch 74/80

864/864 ————— 21s 24ms/step - accuracy: 0.9823 - loss: 0.0505 - val_accuracy: 0.9815 - val_loss: 0.0866
Epoch 75/80

864/864 ————— 21s 25ms/step - accuracy: 0.9768 - loss: 0.0483 - val_accuracy: 0.9954 - val_loss: 0.0108

Epoch 76/80

864/864 ————— **21s** 24ms/step - accuracy: 0.9858 - loss: 0.0259 - val_accuracy: 0.9907 - val_loss: 0.0191

Epoch 77/80

864/864 ————— **25s** 29ms/step - accuracy: 0.9932 - loss: 0.0170 - val_accuracy: 0.9722 - val_loss: 0.2631

Epoch 78/80

864/864 ————— **22s** 26ms/step - accuracy: 0.9794 - loss: 0.0597 - val_accuracy: 0.9769 - val_loss: 0.0514

Epoch 79/80

864/864 ————— **26s** 30ms/step - accuracy: 0.9837 - loss: 0.0566 - val_accuracy: 0.9954 - val_loss: 0.0134

Epoch 80/80

864/864 ————— **24s** 28ms/step - accuracy: 0.9898 - loss: 0.0197 - val_accuracy: 0.9907 - val_loss: 0.0192

Out[29]: <keras.src.callbacks.history.History at 0x14428d0dc0>

```
In [30]: # Predicting the output
def fix_dimension(img):
    new_img = np.zeros((28,28,3))
    for i in range(3):
        new_img[:, :, i] = img
    return new_img

def show_results():
    dic = {}
    characters = '0123456789ABCDEFGHIJKLMNOPQRSTUVWXYZ'
    for i, c in enumerate(characters):
        dic[i] = c

    output = []
    for i, ch in enumerate(char): #iterating over the characters
        img_ = cv2.resize(ch, (28,28), interpolation=cv2.INTER_AREA)
        img = fix_dimension(img_)
        img = img.reshape(1,28,28,3) #preparing image for the model
        y_ = model.predict(img)[0] #predicting the class
        # Get the index of the predicted class (class with highest probability)
        character_index = np.argmax(y_)
        character = dic[character_index] # Use character_index as key to access dic
        output.append(character) #storing the result in a list

    plate_number = ''.join(output)

    return plate_number

print(show_results())
```

1/1 _____ 0s 115ms/step
1/1 _____ 0s 33ms/step
1/1 _____ 0s 51ms/step
1/1 _____ 0s 33ms/step
1/1 _____ 0s 40ms/step
1/1 _____ 0s 37ms/step
1/1 _____ 0s 31ms/step
1/1 _____ 0s 36ms/step
1/1 _____ 0s 33ms/step
1/1 _____ 0s 39ms/step
DL8CAF5030

```
In [31]: # Segmented characters and their predicted value.
plt.figure(figsize=(10,6))
for i,ch in enumerate(char):
    img = cv2.resize(ch, (28,28), interpolation=cv2.INTER_AREA)
    plt.subplot(3,4,i+1)
    plt.imshow(img,cmap='gray')
    plt.title(f'predicted: {show_results()[i]}')
    plt.axis('off')
plt.show()
```


1/1	_____	0s	43ms/step
1/1	_____	0s	31ms/step
1/1	_____	0s	38ms/step
1/1	_____	0s	32ms/step
1/1	_____	0s	29ms/step
1/1	_____	0s	50ms/step
1/1	_____	0s	31ms/step
1/1	_____	0s	30ms/step
1/1	_____	0s	36ms/step
1/1	_____	0s	30ms/step
1/1	_____	0s	42ms/step
1/1	_____	0s	32ms/step
1/1	_____	0s	40ms/step
1/1	_____	0s	34ms/step
1/1	_____	0s	36ms/step
1/1	_____	0s	52ms/step
1/1	_____	0s	35ms/step
1/1	_____	0s	46ms/step
1/1	_____	0s	38ms/step
1/1	_____	0s	39ms/step
1/1	_____	0s	32ms/step
1/1	_____	0s	50ms/step
1/1	_____	0s	41ms/step
1/1	_____	0s	38ms/step
1/1	_____	0s	47ms/step
1/1	_____	0s	35ms/step
1/1	_____	0s	41ms/step
1/1	_____	0s	43ms/step
1/1	_____	0s	37ms/step
1/1	_____	0s	39ms/step
1/1	_____	0s	42ms/step
1/1	_____	0s	40ms/step
1/1	_____	0s	34ms/step
1/1	_____	0s	37ms/step
1/1	_____	0s	38ms/step
1/1	_____	0s	39ms/step
1/1	_____	0s	47ms/step
1/1	_____	0s	38ms/step
1/1	_____	0s	38ms/step
1/1	_____	0s	36ms/step
1/1	_____	0s	39ms/step
1/1	_____	0s	34ms/step
1/1	_____	0s	50ms/step
1/1	_____	0s	34ms/step
1/1	_____	0s	39ms/step
1/1	_____	0s	35ms/step
1/1	_____	0s	66ms/step
1/1	_____	0s	42ms/step
1/1	_____	0s	36ms/step
1/1	_____	0s	49ms/step
1/1	_____	0s	36ms/step
1/1	_____	0s	44ms/step
1/1	_____	0s	37ms/step
1/1	_____	0s	44ms/step
1/1	_____	0s	39ms/step
1/1	_____	0s	43ms/step

1/1	—————	0s	38ms/step
1/1	—————	0s	47ms/step
1/1	—————	0s	42ms/step
1/1	—————	0s	41ms/step
1/1	—————	0s	50ms/step
1/1	—————	0s	38ms/step
1/1	—————	0s	35ms/step
1/1	—————	0s	41ms/step
1/1	—————	0s	37ms/step
1/1	—————	0s	39ms/step
1/1	—————	0s	36ms/step
1/1	—————	0s	39ms/step
1/1	—————	0s	47ms/step
1/1	—————	0s	49ms/step
1/1	—————	0s	40ms/step
1/1	—————	0s	34ms/step
1/1	—————	0s	41ms/step
1/1	—————	0s	35ms/step
1/1	—————	0s	35ms/step
1/1	—————	0s	36ms/step
1/1	—————	0s	49ms/step
1/1	—————	0s	35ms/step
1/1	—————	0s	49ms/step
1/1	—————	0s	34ms/step
1/1	—————	0s	41ms/step
1/1	—————	0s	50ms/step
1/1	—————	0s	34ms/step
1/1	—————	0s	36ms/step
1/1	—————	0s	48ms/step
1/1	—————	0s	51ms/step
1/1	—————	0s	49ms/step
1/1	—————	0s	37ms/step
1/1	—————	0s	53ms/step
1/1	—————	0s	39ms/step
1/1	—————	0s	40ms/step
1/1	—————	0s	38ms/step
1/1	—————	0s	49ms/step
1/1	—————	0s	46ms/step
1/1	—————	0s	40ms/step
1/1	—————	0s	39ms/step
1/1	—————	0s	39ms/step
1/1	—————	0s	41ms/step
1/1	—————	0s	41ms/step
1/1	—————	0s	38ms/step

predicted: D



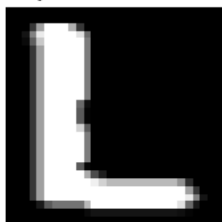
predicted: A



predicted: 3



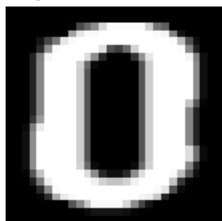
predicted: L



predicted: F



predicted: 0



predicted: 8



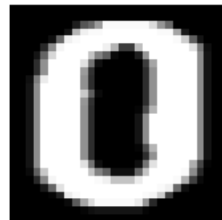
predicted: 5



predicted: C



predicted: 0



In []: