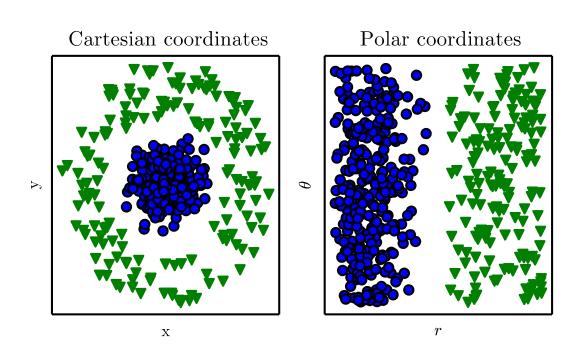
# Introduction to Deep Learning CMPT 733

Steven Bergner

#### Overview

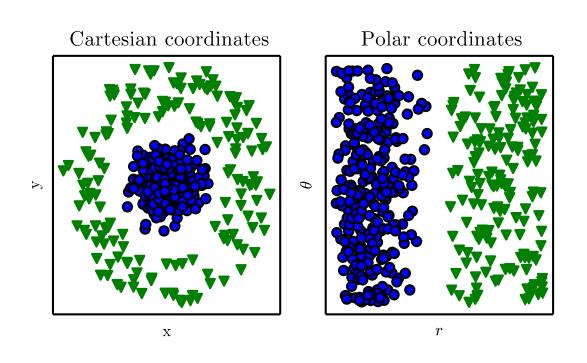
- Renaissance of artificial neural networks
  - Representation learning vs feature engineering
- Background
  - Linear Algebra, Optimization
  - Regularization
- Construction and training of layered learners
- Frameworks for deep learning

#### Representations matter



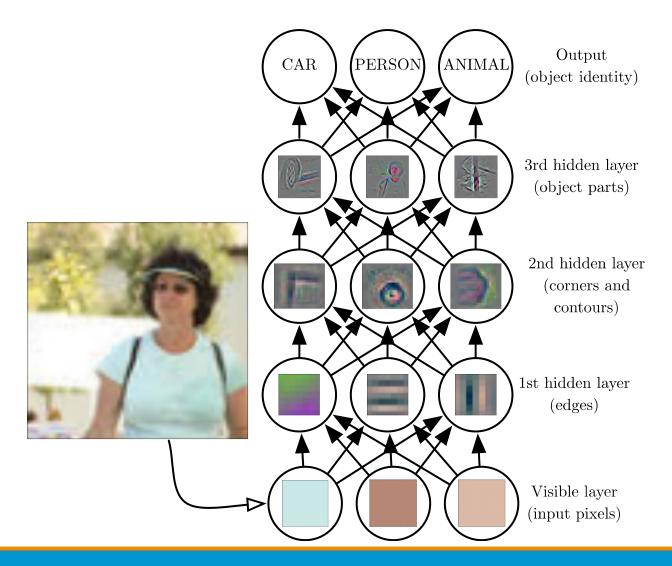
- Transform into the right representation
- Classify points simply by threshold on radius axis

#### Representations matter

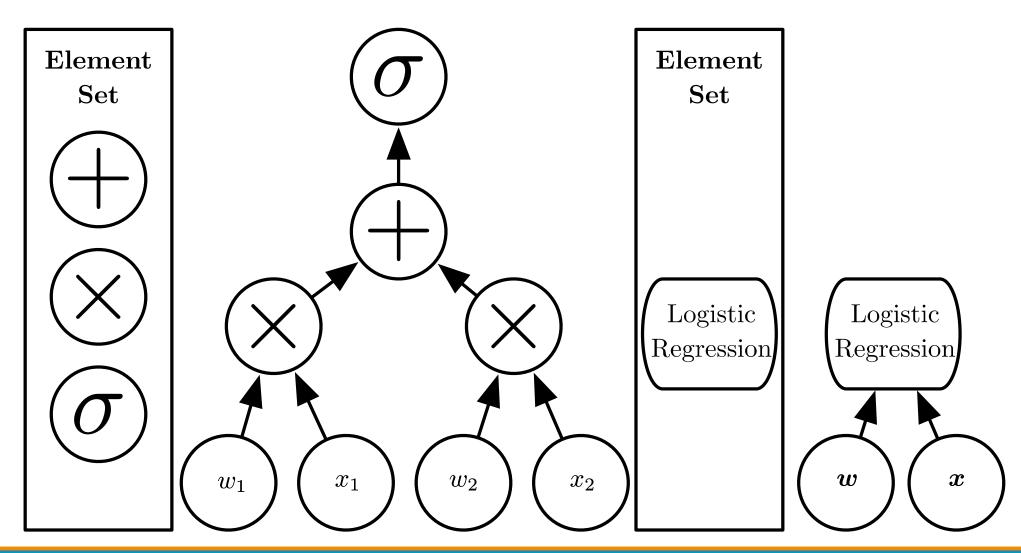


- Transform into the right representation
- Classify points simply by threshold on radius axis
- Single neuron with nonlinearity can do this

## Depth: layered composition

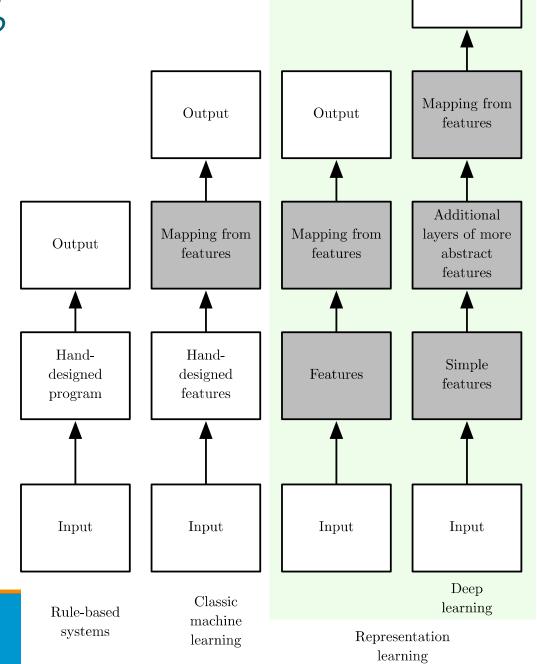


## Computational graph



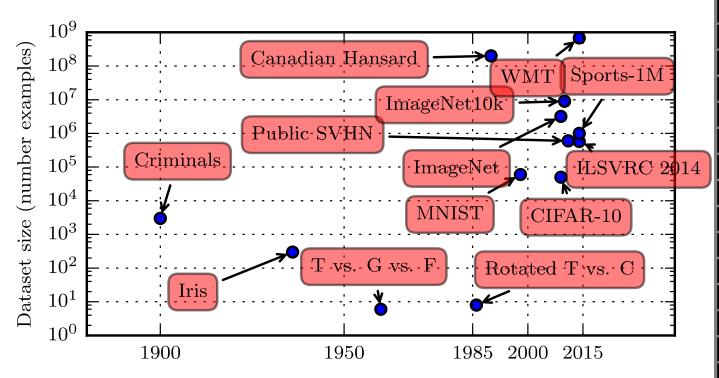
#### Components of learning

- Hand designed program
  - Input → Output
- Increasingly automated
  - Simple features
  - Abstract features
  - Mapping from features



Output

#### Growing Dataset Size



4265554341530830627 1817138542097674168 7512671980694996237

MNIST dataset

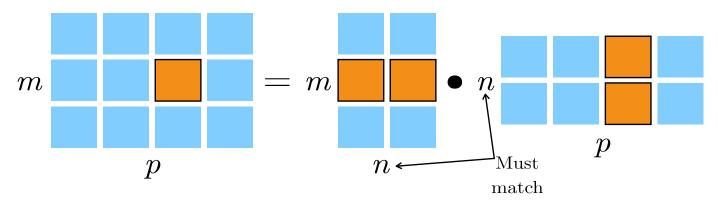
#### Basics

Linear Algebra and Optimization

- Tensor is an array of numbers
  - Multi-dim: 0d scalar, 1d vector, 2d matrix/image, 3d RGB image
- Matrix (dot) product C = AB  $C_{i,j} = \sum_k A_{i,k} B_{k,j}$

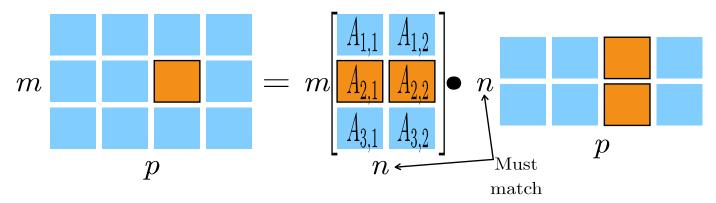
Dot product of vectors A and B

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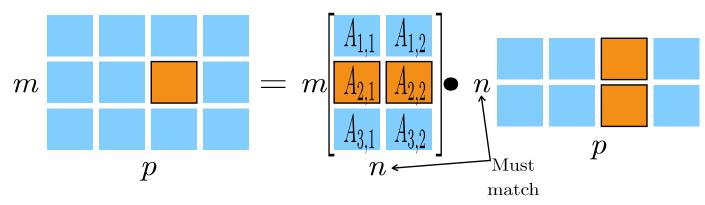


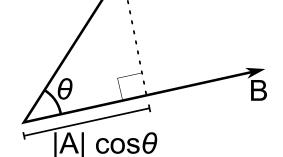
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$$C = AB$$

$$C_{i,j} = \sum_{k} A_{i,k} B_{k,j}$$





Dot product of vectors A and B

#### Linear algebra: Norms

•  $L^p$  norm

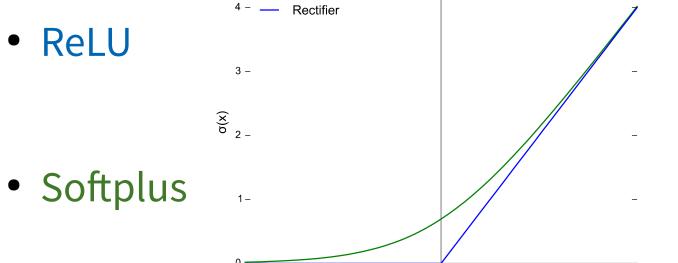
$$||\boldsymbol{x}||_p = \left(\sum_i |x_i|^p\right)^{\frac{1}{p}}$$

- Most popular norm: L2 norm, p=2
- L1 norm, p=1:  $||x||_1 = \sum_i |x_i|$ .
- Max norm, infinite  $p: ||\mathbf{x}||_{\infty} = \max_{i} |x_{i}|$ .

#### Nonlinearities

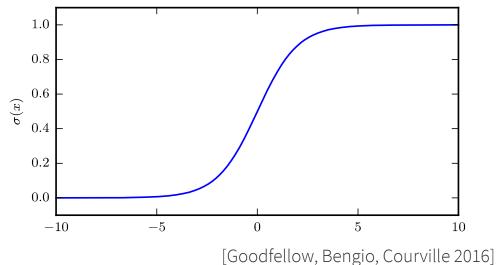
[(c) public domain]



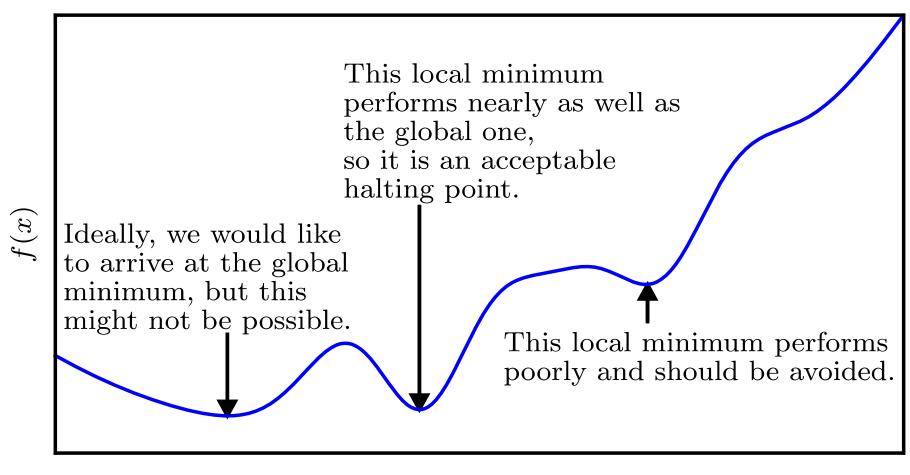


Softplus

Logistic Sigmoid

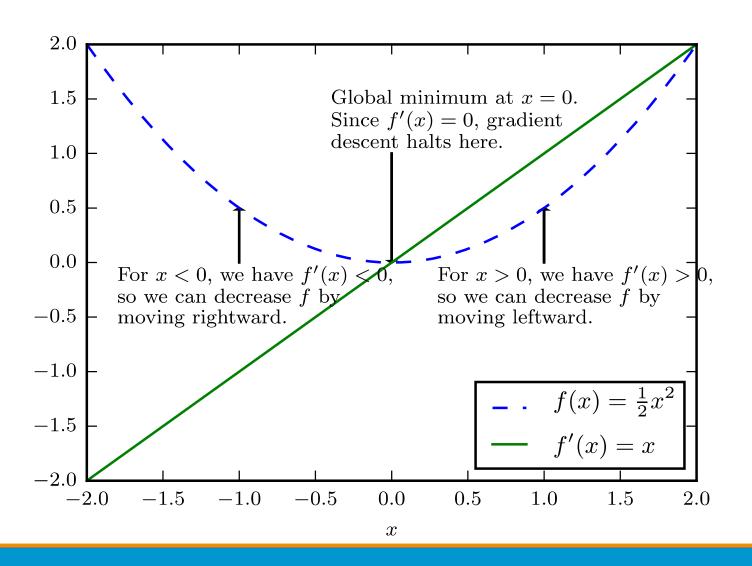


#### Approximate Optimization

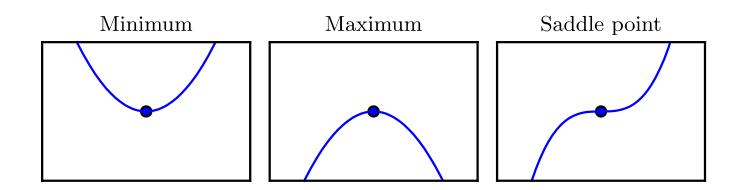


 $\boldsymbol{x}$ 

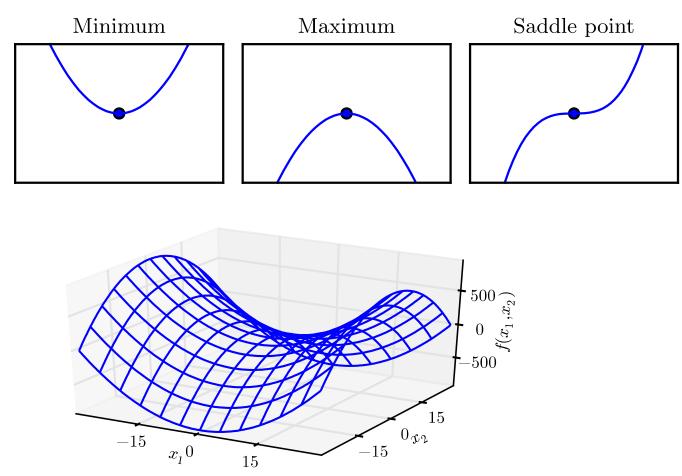
#### Gradient descent



## Critical points

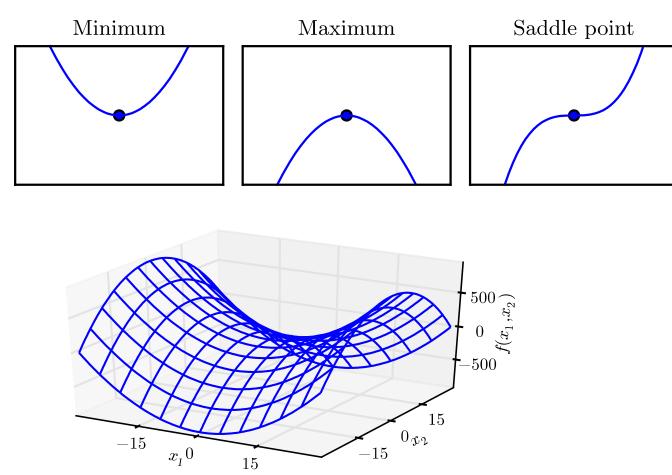


#### Critical points

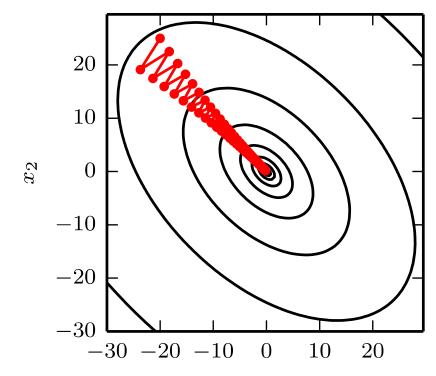


Saddle point – 1<sup>st</sup> and 2<sup>nd</sup> derivative vanish

#### Critical points



Saddle point – 1<sup>st</sup> and 2<sup>nd</sup> derivative vanish



Poor conditioning:  $x_1$ 1<sup>st</sup> deriv large in one and small in another direction

## Tensorflow Playground

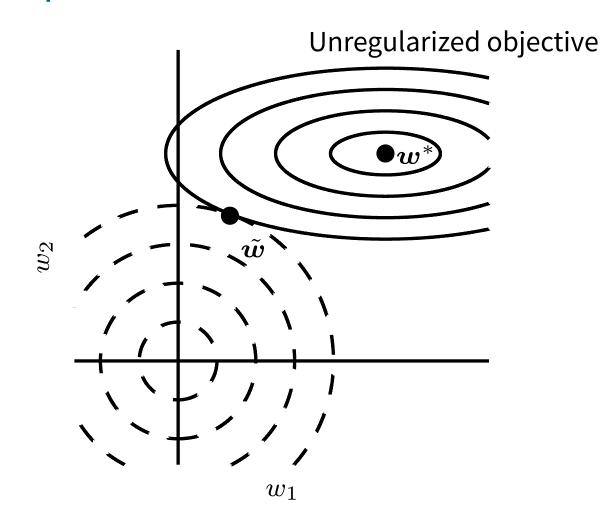
- http://playground.tensorflow.org/
  - Try out simple network configurations

- https://cs.stanford.edu/people/karpathy/convnetjs/demo/cla ssify2d.html
  - Visualize linear and non-linear mappings

#### Regularization

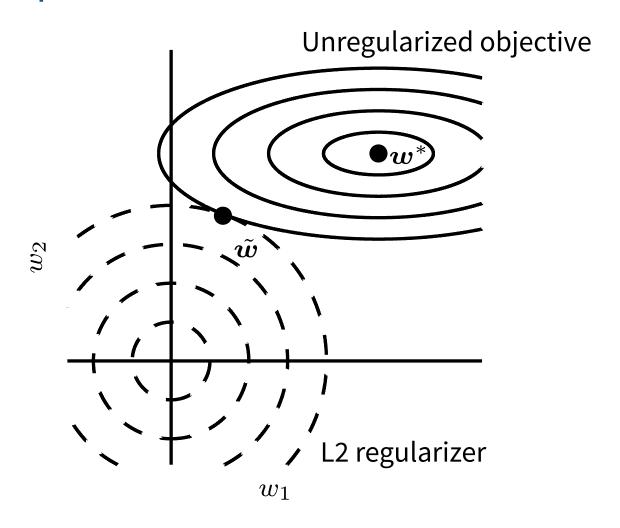
Reduced generalization error without impacting training error

#### Constrained optimization



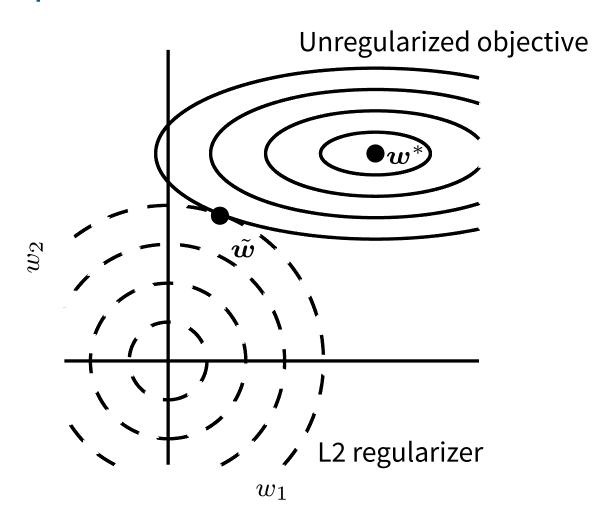
#### Constrained optimization

Squared L2 encourages small weights

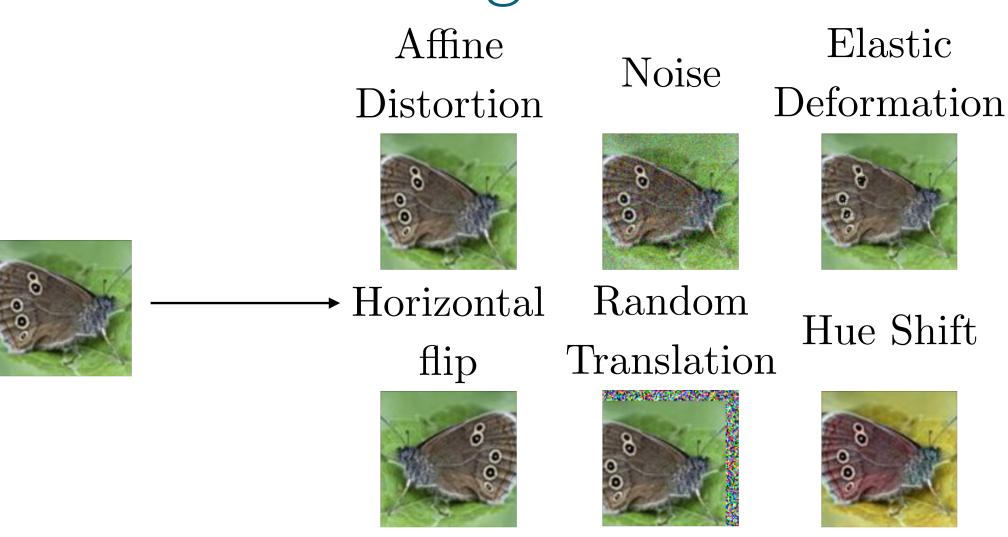


#### Constrained optimization

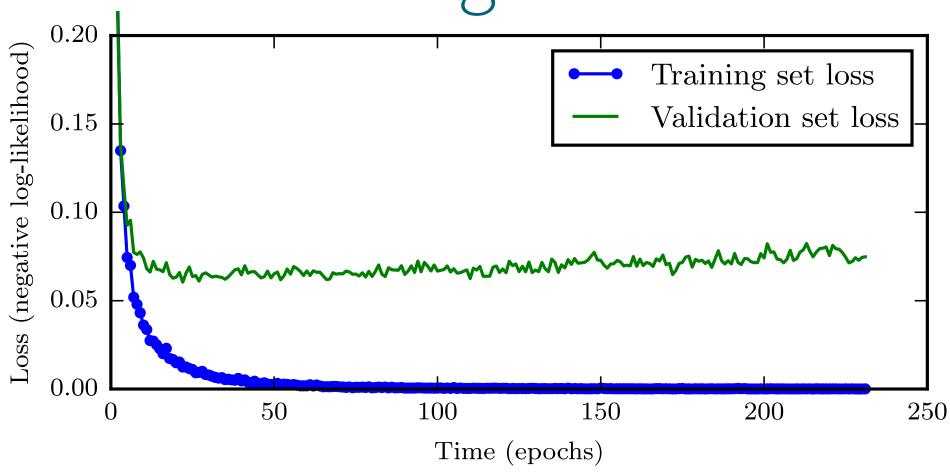
- Squared L2 encourages small weights
- L1 encourages sparsity of model parameters (weights)



#### Dataset augmentation



## Learning curves



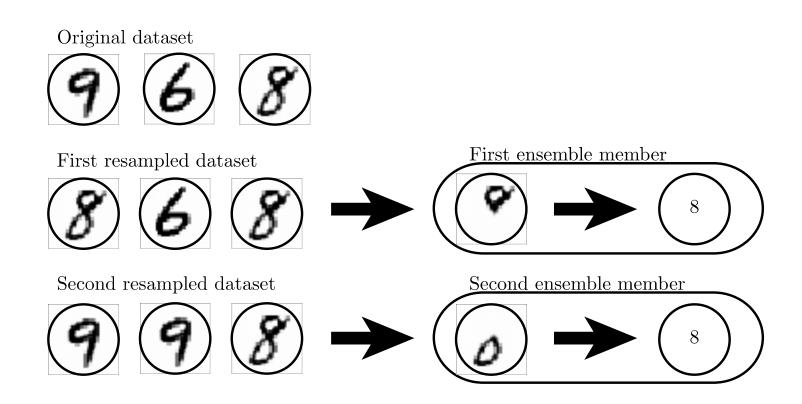
#### Learning curves 0.20Loss (negative log-likelihood) Training set loss Validation set loss 0.15 0.10 0.050.00 50 100 200 150 250

Time (epochs)

Early stopping before validation error starts to increase

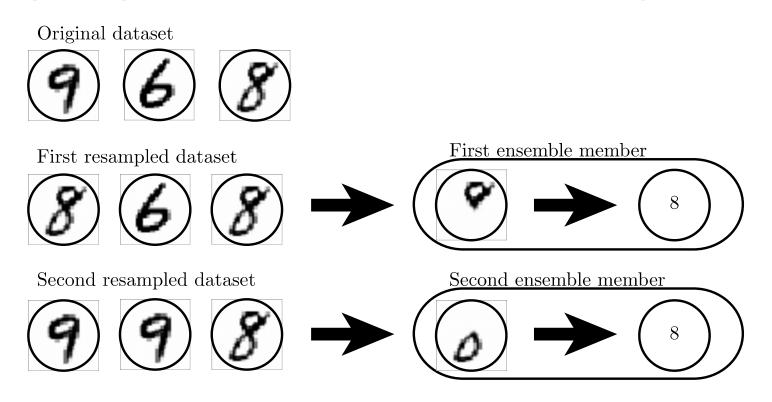
#### Bagging

Average multiple models trained on subsets of the data



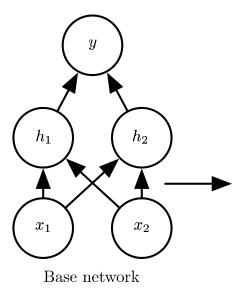
#### Bagging

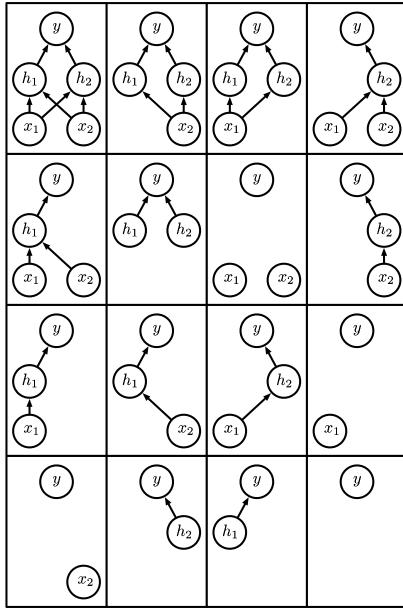
- Average multiple models trained on subsets of the data
- First subset: learns top loop, Second subset: bottom loop



#### Dropout

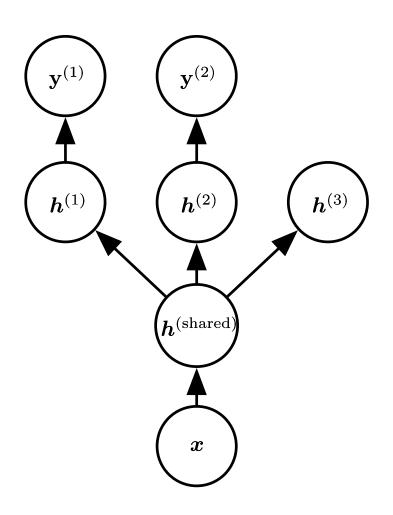
- Random sample of connection weights is set to zero
- Train different network model each time
- Learn more robust, generalizable features





Ensemble of subnetworks

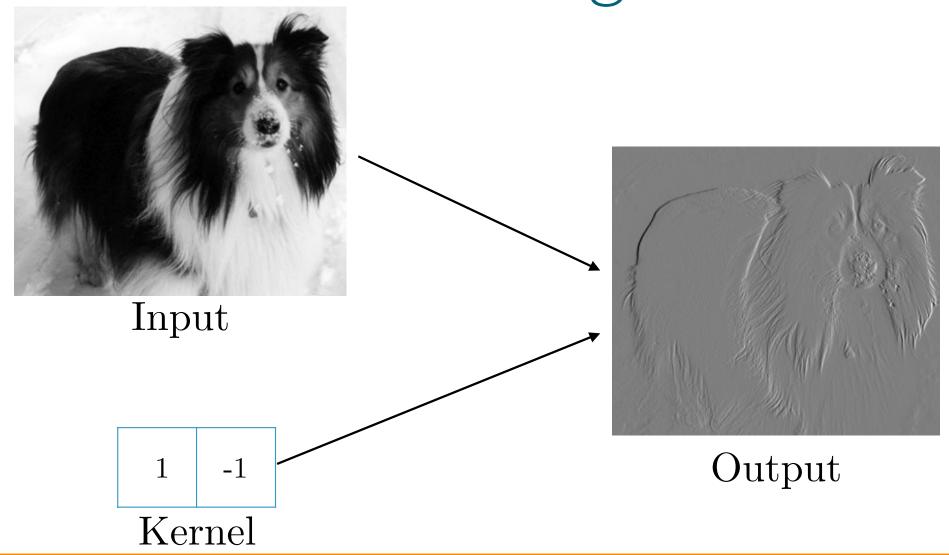
#### Multitask learning



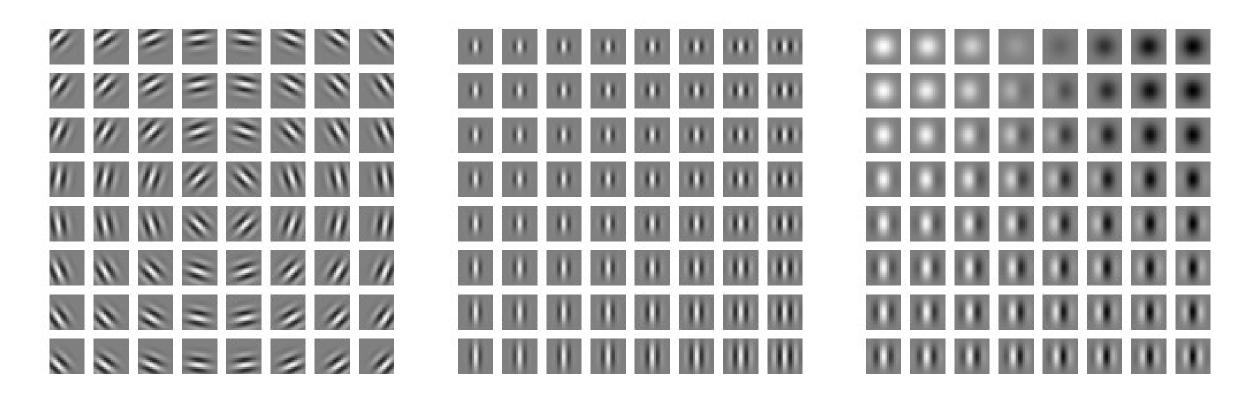
- Shared parameters are trained with more data
- Improved generalization error due to increased statistical strength

## Components of popular architectures

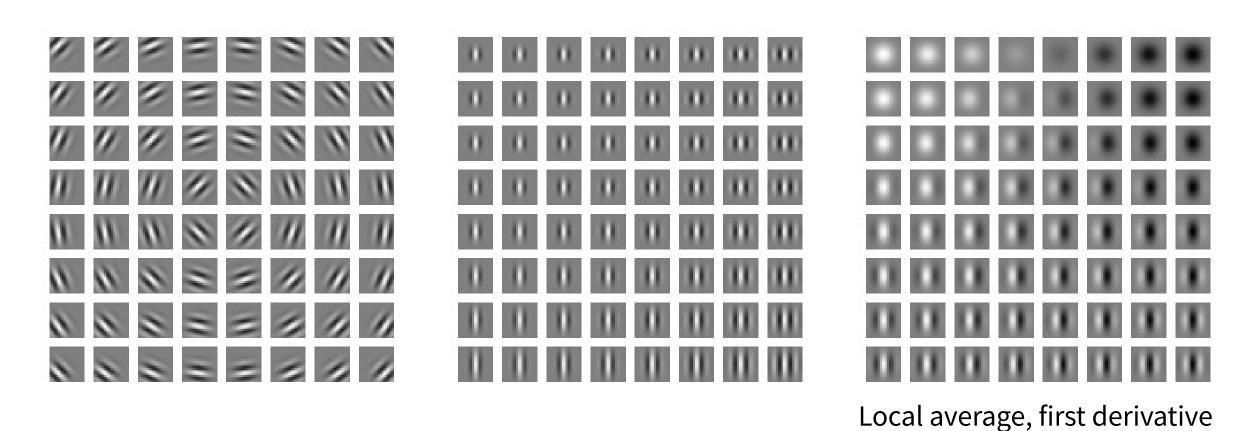
## Convolution as edge detector



#### Gabor wavelets (kernels)

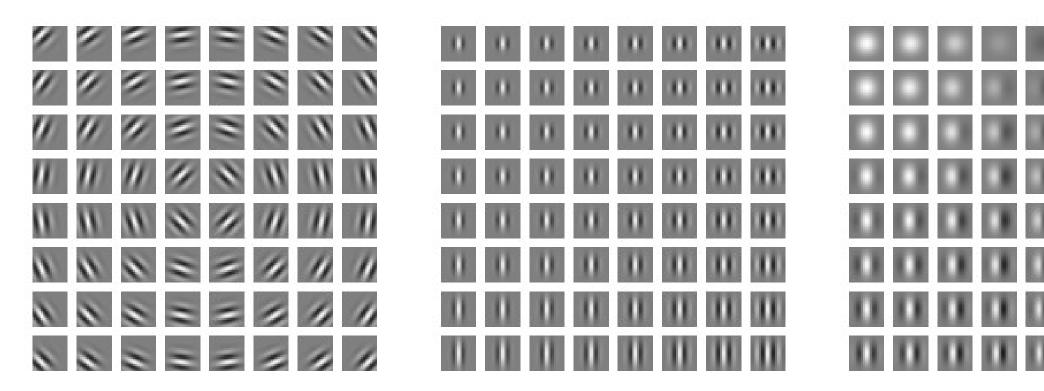


#### Gabor wavelets (kernels)



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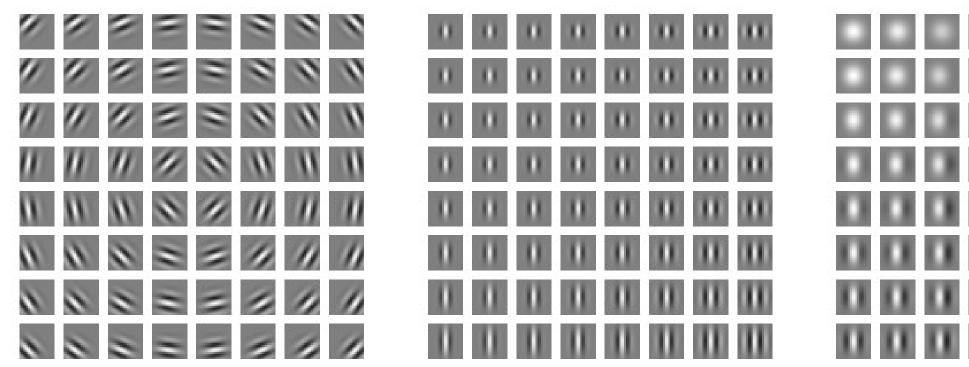
Second derivative (curvature)



Local average, first derivative

#### Gabor wavelets (kernels)

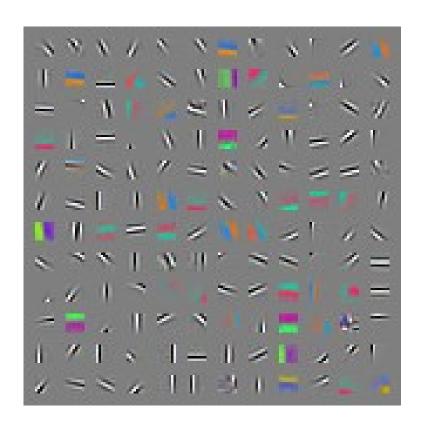
Second derivative (curvature)

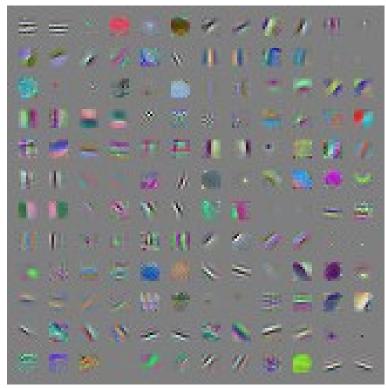


Local average, first derivative

Directional second derivative

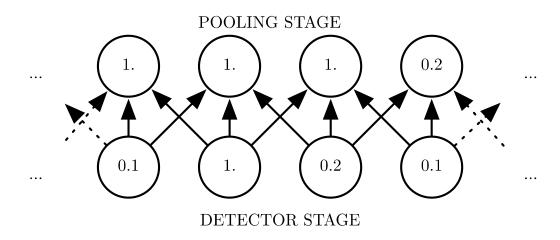
#### Gabor-like learned kernels



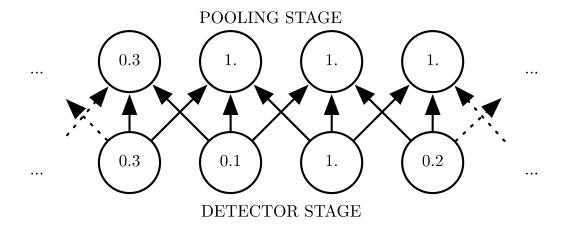


Features extractors provided by pretrained networks

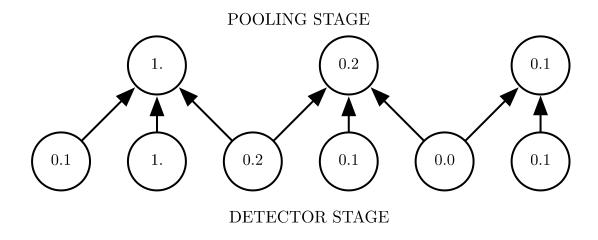
### Max pooling translation invariance



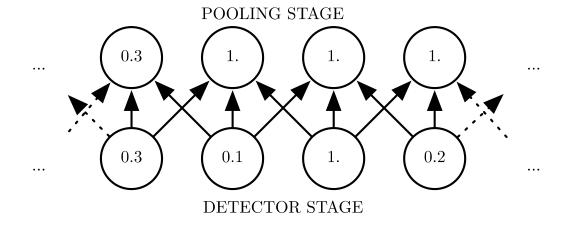
 Take max of certain neighbourhood



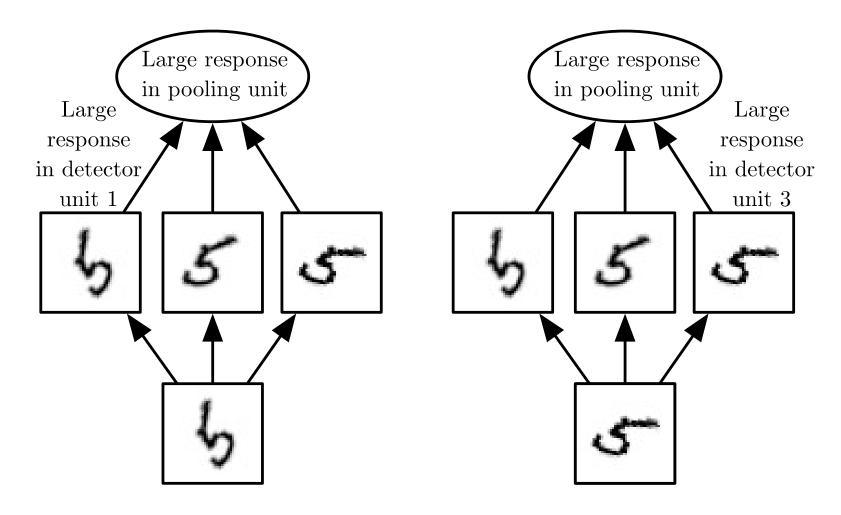
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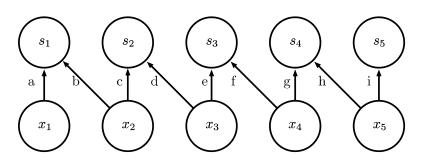
- Take max of certain neighbourhood
- Often combined followed by downsampling



### Max pooling transform invariance

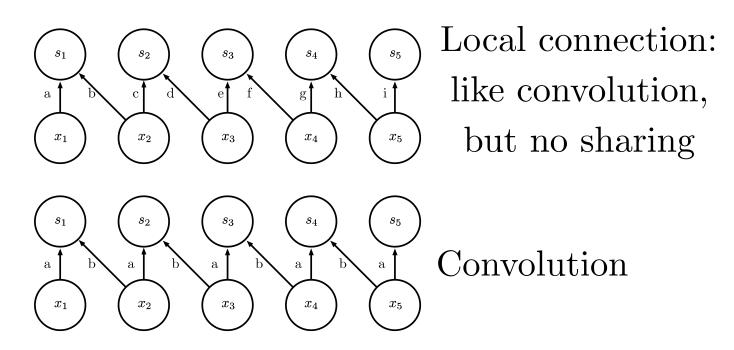


# Types of connectivity

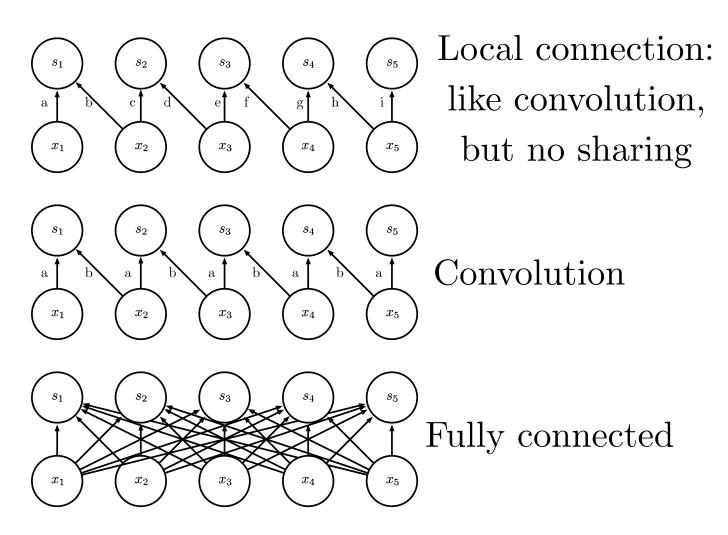


Local connection: like convolution, but no sharing

# Types of connectivity



# Types of connectivity



No structure → fully connected

- No structure → fully connected
- Spatial structure  $\rightarrow$  convolutional

- No structure → fully connected
- Spatial structure  $\rightarrow$  convolutional
- Sequential structure  $\rightarrow$  recurrent

## Optimization Algorithm

- Lots of variants address choice of learning rate
- See Visualization of Algorithms
- AdaDelta and RMSprop often work well

#### Software for Deep Learning

#### Current Frameworks

- Tensorflow / Keras
- Pytorch
- DL4J
- Caffe
- And many more
- Most have CPU-only mode but much faster on NVIDIA GPU

### Development strategy

- Identify needs: High accuracy or low accuracy?
- Choose metric
  - Accuracy (% of examples correct), Coverage (% examples processed)
  - Precision TP/(TP+FP), Recall TP/(TP+FN)
  - Amount of error in case of regression
- Build end-to-end system
  - Start from baseline, e.g. initialize with pre-trained network
- Refine driven by data

#### Sources

• I. Goodfellow, Y. Bengio, A. Courville "Deep Learning" MIT Press 2016 [link]