## **SERVIR's Applied Deep Learning Handbook**

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#### Introduction

Knuth (1984) says some interesting stuff...

Todo: Make some reference to Flores-Anderson et al. (2019)

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# Part I Curriculum

### 1 Data Preparation

```
# Print out the Python version used by this environment.
import sys
print(f'{sys.version=}')
```

sys.version='3.11.0 | packaged by conda-forge | (main, Jan 14 2023, 12:26:40) [Clang 14.0.6]

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## 2 Semantic Segmentation (Crop Mapping)

## 2.1 Rice mapping in Bhutan with U-Net using high resolution satellite imagery



This notebook is also available in this github repo: https://github.com/SERVIR/servir-aces. Navigate to the notebooks folder.

#### 2.2 Setup environment

```
from google.colab import drive
drive.mount("/content/drive")
```

Downloading servir\_aces-0.0.14-py2.py3-none-any.whl (32 kB)

!pip install servir-aces

```
Collecting servir-aces
```

```
Requirement already satisfied: numpy in /usr/local/lib/python3.10/dist-packages (from servir Requirement already satisfied: tensorflow>=2.9.3 in /usr/local/lib/python3.10/dist-packages Requirement already satisfied: earthengine-api in /usr/local/lib/python3.10/dist-packages (from servir-aces)

Downloading python_dotenv-1.0.1-py3-none-any.whl (19 kB)

Requirement already satisfied: matplotlib in /usr/local/lib/python3.10/dist-packages (from servir-aces)

Requirement already satisfied: absl-py>=1.0.0 in /usr/local/lib/python3.10/dist-packages (from servir-aces)

Requirement already satisfied: astunparse>=1.6.0 in /usr/local/lib/python3.10/dist-packages Requirement already satisfied: flatbuffers>=23.5.26 in /usr/local/lib/python3.10/dist-packages Requirement already satisfied: gast!=0.5.0,!=0.5.1,!=0.5.2,>=0.2.1 in /usr/local/lib/python3.10/dist-packages Requirement already satisfied: google-pasta>=0.1.1 in /usr/local/lib/python3.10/dist-packages Requirement already satisfied: h5py>=2.9.0 in /usr/local/lib/python3.10/dist-packages (from servir-aces)
```

Requirement already satisfied: libclang>=13.0.0 in /usr/local/lib/python3.10/dist-packages (

```
Requirement already satisfied: ml-dtypes~=0.2.0 in /usr/local/lib/python3.10/dist-packages (
Requirement already satisfied: opt-einsum>=2.3.2 in /usr/local/lib/python3.10/dist-packages
Requirement already satisfied: packaging in /usr/local/lib/python3.10/dist-packages (from temperature)
Requirement already satisfied: protobuf!=4.21.0,!=4.21.1,!=4.21.2,!=4.21.3,!=4.21.4,!=4.21.5
Requirement already satisfied: setuptools in /usr/local/lib/python3.10/dist-packages (from to
Requirement already satisfied: six>=1.12.0 in /usr/local/lib/python3.10/dist-packages (from
Requirement already satisfied: termcolor>=1.1.0 in /usr/local/lib/python3.10/dist-packages (
Requirement already satisfied: typing-extensions>=3.6.6 in /usr/local/lib/python3.10/dist-pa
Requirement already satisfied: wrapt<1.15,>=1.11.0 in /usr/local/lib/python3.10/dist-package
Requirement already satisfied: tensorflow-io-gcs-filesystem>=0.23.1 in /usr/local/lib/pythom
Requirement already satisfied: grpcio<2.0,>=1.24.3 in /usr/local/lib/python3.10/dist-package
Requirement already satisfied: tensorboard<2.16,>=2.15 in /usr/local/lib/python3.10/dist-pac
Requirement already satisfied: tensorflow-estimator<2.16,>=2.15.0 in /usr/local/lib/python3.
Requirement already satisfied: keras<2.16,>=2.15.0 in /usr/local/lib/python3.10/dist-package
Requirement already satisfied: google-cloud-storage in /usr/local/lib/python3.10/dist-package
Requirement already satisfied: google-api-python-client>=1.12.1 in /usr/local/lib/python3.10
Requirement already satisfied: google-auth>=1.4.1 in /usr/local/lib/python3.10/dist-packages
Requirement already satisfied: google-auth-httplib2>=0.0.3 in /usr/local/lib/python3.10/dist
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Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.10/dist-packages
Requirement already satisfied: kiwisolver>=1.0.1 in /usr/local/lib/python3.10/dist-packages
Requirement already satisfied: pillow>=6.2.0 in /usr/local/lib/python3.10/dist-packages (from
Requirement already satisfied: pyparsing>=2.3.1 in /usr/local/lib/python3.10/dist-packages (
Requirement already satisfied: python-dateutil>=2.7 in /usr/local/lib/python3.10/dist-package
Requirement already satisfied: wheel<1.0,>=0.23.0 in /usr/local/lib/python3.10/dist-packages
Requirement already satisfied: google-api-core!=2.0.*,!=2.1.*,!=2.2.*,!=2.3.0,<3.0.0dev,>=1.5
Requirement already satisfied: uritemplate<5,>=3.0.1 in /usr/local/lib/python3.10/dist-package
Requirement already satisfied: cachetools<6.0,>=2.0.0 in /usr/local/lib/python3.10/dist-pack
Requirement already satisfied: pyasn1-modules>=0.2.1 in /usr/local/lib/python3.10/dist-packa
Requirement already satisfied: rsa<5,>=3.1.4 in /usr/local/lib/python3.10/dist-packages (from
Requirement already satisfied: google-auth-oauthlib<2,>=0.5 in /usr/local/lib/python3.10/dis
Requirement already satisfied: markdown>=2.6.8 in /usr/local/lib/python3.10/dist-packages (fi
Requirement already satisfied: tensorboard-data-server<0.8.0,>=0.7.0 in /usr/local/lib/pythos
Requirement already satisfied: werkzeug>=1.0.1 in /usr/local/lib/python3.10/dist-packages (fi
Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.10/dist-pa
Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.10/dist-packages (from
Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.10/dist-packages
Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.10/dist-packages
Requirement already satisfied: google-cloud-core<3.0dev,>=2.3.0 in /usr/local/lib/python3.10
Requirement already satisfied: google-resumable-media>=2.3.2 in /usr/local/lib/python3.10/dia
```

```
Requirement already satisfied: googleapis-common-protos<2.0.dev0,>=1.56.2 in /usr/local/lib/PRequirement already satisfied: requests-oauthlib>=0.7.0 in /usr/local/lib/Python3.10/dist-package Requirement already satisfied: google-crc32c<2.0dev,>=1.0 in /usr/local/lib/Python3.10/dist-Package Requirement already satisfied: pyasn1<0.7.0,>=0.4.6 in /usr/local/lib/Python3.10/dist-package Requirement already satisfied: MarkupSafe>=2.1.1 in /usr/local/lib/Python3.10/dist-packages Requirement already satisfied: oauthlib>=3.0.0 in /usr/local/lib/Python3.10/dist-packages (f: Installing collected packages: python-dotenv, servir-aces Successfully installed python-dotenv-1.0.1 servir-aces-0.0.14
```

```
# !git clone https://github.com/SERVIR/servir-aces
```

```
Cloning into 'servir-aces'...
remote: Enumerating objects: 740, done.
remote: Counting objects: 100% (116/116), done.
remote: Compressing objects: 100% (78/78), done.
remote: Total 740 (delta 46), reused 68 (delta 38), pack-reused 624
Receiving objects: 100% (740/740), 5.07 MiB | 16.12 MiB/s, done.
Resolving deltas: 100% (468/468), done.
```

#### 2.2.1 Download datasets

For this chapter, we have already prepared and exported the training datasets. They can be found at the google cloud storage and we will use gsutil to get the dataset in our workspace. The dataset has training, testing, and validation subdirectory. Let's start by downloading these datasets in our workspace.

If you're looking to produce your own datasets, you can follow this notebook which was used to produce these training, testing, and validation datasets provided in this notebook.

```
!mkdir -p content/datasets
!gsutil -m cp -r gs://dl-book/chapter-1 content/datasets/
```

If you experience problems with multiprocessing on MacOS, they might be related to https://bu Copying gs://dl-book/chapter-1/.DS\_Store...

```
Copying gs://dl-book/chapter-1/dnn_planet_wo_indices/testing/testing.tfrecord.gz...

Copying gs://dl-book/chapter-1/dnn_planet_wo_indices/training/training.tfrecord.gz...

Copying gs://dl-book/chapter-1/dnn_planet_wo_indices/validation/validation.tfrecord.gz...

Copying gs://dl-book/chapter-1/images/image_202100000.tfrecord.gz...
```

```
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Copying gs://dl-book/chapter-1/images/image_202100002.tfrecord.gz...
Copying gs://dl-book/chapter-1/images/image_202100003.tfrecord.gz...
Copying gs://dl-book/chapter-1/models/dnn_v1/config.env...
Copying gs://dl-book/chapter-1/images/image_202100004.tfrecord.gz...
Copying gs://dl-book/chapter-1/images/image_202100005.tfrecord.gz...
Copying gs://dl-book/chapter-1/images/image_2021mixer.json...
Copying gs://dl-book/chapter-1/models/dnn_v1/aces/keras_metadata.pb...
Copying gs://dl-book/chapter-1/models/dnn_v1/aces/fingerprint.pb...
Copying gs://dl-book/chapter-1/models/dnn_v1/aces/saved_model.pb...
Copying gs://dl-book/chapter-1/models/dnn v1/aces/variables/variables.data-00000-of-00001...
Copying gs://dl-book/chapter-1/models/dnn_v1/aces/variables/variables.index...
Copying gs://dl-book/chapter-1/models/dnn_v1/config.json...
Copying gs://dl-book/chapter-1/models/dnn_v1/evaluation.txt...
Copying gs://dl-book/chapter-1/models/dnn_v1/logs/train/events.out.tfevents.1713307528.b5c4c
Copying gs://dl-book/chapter-1/models/dnn_v1/logs/validation/events.out.tfevents.1713307537.
Copying gs://dl-book/chapter-1/models/dnn_v1/model.png...
Copying gs://dl-book/chapter-1/models/dnn_v1/model.txt...
Copying gs://dl-book/chapter-1/models/dnn_v1/modelCheckpoint/fingerprint.pb...
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Copying gs://dl-book/chapter-1/models/dnn_v1/modelCheckpoint/keras_metadata.pb...
Copying gs://dl-book/chapter-1/models/unet_v1/aces/fingerprint.pb...
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Copying gs://dl-book/chapter-1/models/dnn_v1/trained-model/fingerprint.pb...
Copying gs://dl-book/chapter-1/models/dnn_v1/modelCheckpoint/saved_model.pb...
==> NOTE: You are downloading one or more large file(s), which would
run significantly faster if you enabled sliced object downloads. This
feature is enabled by default but requires that compiled crcmod be
installed (see "gsutil help crcmod").
Copying gs://dl-book/chapter-1/models/unet_v1/aces/saved_model.pb...
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Copying gs://dl-book/chapter-1/models/dnn_v1/trained-model/saved_model.pb...
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```
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Copying gs://dl-book/chapter-1/models/unet_v1/evaluation.txt...
Copying gs://dl-book/chapter-1/models/unet_v1/config.json...
Copying gs://dl-book/chapter-1/models/unet v1/model.txt...
Copying gs://dl-book/chapter-1/models/unet_v1/logs/validation/events.out.tfevents.1713299558
Copying gs://dl-book/chapter-1/models/unet_v1/aces/variables/variables.index...
Copying gs://dl-book/chapter-1/models/unet_v1/modelCheckpoint/fingerprint.pb...
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Copying gs://dl-book/chapter-1/models/unet_v1/modelCheckpoint/variables/variables.data-00000
Copying gs://dl-book/chapter-1/models/unet_v1/modelCheckpoint/variables/variables.index...
Copying gs://dl-book/chapter-1/models/unet_v1/prediction/prediction_unet_v1.TFRecord...
Copying gs://dl-book/chapter-1/models/unet_v1/parameters.txt...
Copying gs://dl-book/chapter-1/models/unet_v1/trained-model/fingerprint.pb...
Copying gs://dl-book/chapter-1/models/unet_v1/trained-model/keras_metadata.pb...
Copying gs://dl-book/chapter-1/models/unet_v1/trained-model/saved_model.pb...
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/ [187/192 files] [ 16.3 GiB/ 16.3 GiB] 99% Done 43.1 MiB/s ETA 00:00:00
```

#### 2.2.2 Setup config file variables

Now the repo is downloaded. We will create an environment file file to place point to our training data and customize parameters for the model. To do this, we make a copy of the .env.example file provided.

Under the hood, all the configuration provided via the environment file are parsed as a config object and can be accessed programatically.

Note current version does not expose all the model intracacies through the environment file but future version may include those depending on the need.

```
!cp servir-aces/.env.example servir-aces/config.env
```

Okay, now we have the config.env file, we will use this to provide our environments and parameters.

Note there are several parameters that can be changed. Let's start by changing the BASEDIR and OUTPUT\_DIR as below.

```
BASEDIR = "/content/"
OUTPUT_DIR = "/content/drive/MyDrive/Colab Notebooks/DL_Book/Chapter_1/output"
```

We will start by training a U-Net model using the dl-book/chapter-1/unet\_256x256\_planet\_wo\_indices dataset inside the dataset folder for this exercise. Let's go ahead and change our DATADIR in the config.env file as below.

```
DATADIR = "datasets/unet_256x256_planet_wo_indices"
```

These datasets have RGBN from Planetscope mosiac. Since we are trying to map the rice fields, we use growing season and pre-growing season information. Thus, we have 8 optical bands, namely red\_before, green\_before, blue\_before, nir\_before, red\_during, green\_during, blue\_during, and nir\_during. In addition, you can use USE\_ELEVATION and USE\_S1 config to include the topographic and radar information. Since this datasets have toppgraphic and radar features, so we won't be settling these config values. Similarly, these datasets are tiled to 256x256 pixels, so let's also change that.

```
# For model training, USE_ELEVATION extends FEATURES with "elevation" & "slope"
# USE_S1 extends FEATURES with "vv_asc_before", "vh_asc_before", "vv_asc_during", "vh_asc_during"
# "vv_desc_before", "vh_desc_before", "vv_desc_during", "vh_desc_during"
# In case these are not useful and you have other bands in your training data, you can do se
# USE_ELEVATION and USE_S1 to False and update FEATURES to include needed bands
USE_ELEVATION = False
USE_S1 = False
```

 $PATCH_SHAPE = (256, 256)$ 

Next, we need to calculate the size of the training, testing and validation dataset. For this, we know our size before hand. But aces also provides handful of functions that we can use to calculate this. See this notebook to learn more about how to do it. We will also change the BATCH\_SIZE to 32; if you have larger memory available, you can increase the BATCH\_SIZE. You can run for longer EPOCHS by changing the EPOCHS paramter; we will keep it to 5 for now.

```
# Sizes of the training and evaluation datasets.
TRAIN_SIZE = 8531
TEST_SIZE = 1222
VAL_SIZE = 2404
BATCH_SIZE = 32
EPOCHS = 30
```

#### 2.2.3 Update the config file programtically

We can also make a dictionary so we can change these config settings programatically.

```
BASEDIR = "/content/" # @param {type:"string"}

OUTPUT_DIR = "/content/drive/MyDrive/Colab Notebooks/DL_Book/Chapter_1/output" # @param {type
DATADIR = "datasets/unet_256x256_planet_wo_indices" # @param {type:"string"}
# PATCH_SHAPE, USE_ELEVATION, USE_S1, TRAIN_SIZE, TEST_SIZE, VAL_SIZE
# BATCH_SIZE, EPOCHS are converted to their appropriate type.

USE_ELEVATION = "False" # @param {type:"string"}

USE_S1 = "False" # @param {type:"string"}

PATCH_SHAPE = "(256, 256)" # @param {type:"string"}

TRAIN_SIZE = "8531" # @param {type:"string"}

TEST_SIZE = "1222" # @param {type:"string"}

VAL_SIZE = "2404" # @param {type:"string"}

BATCH_SIZE = "32" # @param {type:"string"}

EPOCHS = "30" # @param {type:"string"}

MODEL_DIR_NAME = "unet_v1" # @param {type:"string"}
```

```
unet_config_settings = {
    "BASEDIR" : BASEDIR,
    "OUTPUT_DIR": OUTPUT_DIR,
    "DATADIR": DATADIR,
    "USE_ELEVATION": USE_ELEVATION,
    "USE_S1": USE_S1,
    "PATCH_SHAPE": PATCH_SHAPE,
    "TRAIN_SIZE": TRAIN_SIZE,
    "TEST_SIZE": TEST_SIZE,
    "VAL_SIZE": VAL_SIZE,
    "BATCH_SIZE": BATCH_SIZE,
    "BATCH_SIZE": BATCH_SIZE,
    "EPOCHS": EPOCHS,
    "MODEL_DIR_NAME": MODEL_DIR_NAME,
}
```

#### 2.3 U-Net Model

#### 2.3.1 Load config file variables

```
from aces import Config, DataProcessor, ModelTrainer, EEUtils
```

Let's load our config file through the Config class.

```
unet_config = Config(config_file=config_file)
```

```
BASEDIR: /content

DATADIR: /content/datasets/unet_256x256_planet_wo_indices

using features: ['red_before', 'green_before', 'blue_before', 'nir_before', 'red_during', 'green_before']

using labels: ['class']
```

Most of the config in the config.env is now available via the config instance. Let's check few of them here.

#### 2.3.2 Load ModelTrainer class

Next, let's make an instance of the ModelTrainer object. The ModelTrainer class provides various tools for training, building, compiling, and running specified deep learning models.

```
unet_model_trainer = ModelTrainer(unet_config, seed=42)
```

Using seed: 42

#### 2.3.3 Train and Save U-Net model

ModelTrainer class provides various functionality. We will use train\_model function that helps to train the model using the provided configuration settings.

This method performs the following steps: - Configures memory growth for TensorFlow. - Creates TensorFlow datasets for training, testing, and validation. - Builds and compiles the model. - Prepares the output directory for saving models and results. - Starts the training process. - Evaluates and prints validation metrics. - Saves training parameters, plots, and models.

```
unet_model_trainer.train_model()
**************************
************************************
> Found 1 GPUs
*************************************
Loading dataset from /content/datasets/unet_256x256_planet_wo_indices/training/*
randomly transforming data
Loading dataset from /content/datasets/unet_256x256_planet_wo_indices/validation/*
Loading dataset from /content/datasets/unet_256x256_planet_wo_indices/testing/*
Printing dataset info:
Training
inputs: float32 (32, 256, 256, 8)
tf.Tensor(
[[[[0.073075 0.063275 0.0411
                        ... 0.050625 0.0274
                                         0.23925 ]
  [0.084775 0.067375 0.047025 ... 0.057675 0.032075 0.242375]
  [0.083625 0.068575 0.045075 ... 0.059275 0.0332
                                         0.2409 ]
  [0.0702
          0.06825
                 0.04495 ... 0.055025 0.028325 0.26305 ]
  [0.064475 0.066
                 0.043575 ... 0.0524
                                  0.027075 0.26705 ]
  [0.0676
          0.06355
                0.04535
                        ... 0.05375 0.02875 0.263275]]
 [[0.071475 0.062225 0.0388
                        ... 0.0496
                                  0.025375 0.24155 ]
  [0.07815 0.065025 0.044225 ... 0.0545
                                  0.02905
                                         0.24175 ]
  [0.086025 0.069125 0.046175 ... 0.05855
                                  0.0326
                                         0.2355 ]
  [0.060775 0.0627
                 0.041875 ... 0.051575 0.029725 0.267475]
                 0.04225
                       ... 0.0513
                                  0.02685 0.268375]
  [0.061375 0.06225
  [0.06845  0.064075  0.043925  ...  0.052925  0.028575  0.267975]]
```

```
[[0.0677
                   0.038625 ... 0.04835 0.024825 0.236075]
           0.0605
 [0.078375 0.0629
                   0.04215 ... 0.0524
                                        0.02855 0.237375]
          0.065725 0.04635 ... 0.05705 0.030975 0.235375]
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 . . .
           0.062775 0.04485 ... 0.053425 0.0292
 Γ0.07
                                                0.27015 ]
 [0.0607
           0.060675 0.041175 ... 0.053075 0.026275 0.27025 ]
 Γ0.068
           0.0667  0.045375  ...  0.055475  0.029375  0.26272511
. . .
[[0.083525 0.06785 0.044125 ... 0.06365 0.0331
                                                0.234825]
 [0.097825 0.07235 0.047925 ... 0.06675 0.03365 0.2363 ]
          0.082125 0.05385 ... 0.072125 0.036225 0.2486 ]
 Γ0.1092
 [0.08935  0.088725  0.067575  ...  0.079675  0.042425  0.38085 ]
 [0.093725 0.0875
                   0.06355 ... 0.07565 0.04185 0.344525]
 [0.0937  0.089675  0.066775  ...  0.07465  0.043025  0.330925]]
[[0.0893
          0.0732
                   0.04715 ... 0.065
                                        0.0351
                                                0.2335251
 [0.091325 0.073425 0.047475 ... 0.0653
                                        0.032675 0.238325]
 [0.096775 0.07645 0.051625 ... 0.06875 0.0344
                                                0.252825]
 . . .
          0.084875 0.061975 ... 0.07825 0.042875 0.38785 ]
 Γ0.0836
 [0.08865 0.083825 0.060675 ... 0.0765 0.042525 0.3522 ]
 [0.0909 0.084475 0.061975 ... 0.0769
                                        0.043275 0.342625]]
[[0.092075 0.078
                   0.050925 ... 0.06565 0.03555 0.235275]
                   0.043325 ... 0.063925 0.03215 0.243875]
           0.0705
 [0.0805
 [0.086925 0.074025 0.0495 ... 0.067475 0.03345 0.26095 ]
 [0.081075 0.078725 0.056425 ... 0.07505 0.0398
                                                0.37805]
 [0.0865 0.079375 0.05845 ... 0.076175 0.0439
                                                0.3619
 [[[0.076525 0.0703
                   0.04595 ... 0.055225 0.028025 0.25075 ]
 [0.072025 0.0658
                   0.0446 ... 0.05555 0.02795 0.24755 1
 [0.0669 0.06225 0.038125 ... 0.05245 0.027125 0.241425]
 [0.054175 0.050575 0.029475 ... 0.04845 0.022375 0.23045 ]
 [0.05465  0.052375  0.031125  ...  0.04935  0.024375  0.2282 ]
 [0.052525 0.052725 0.029275 ... 0.048325 0.02325 0.229475]]
```

```
[[0.0784  0.065975  0.0441  ...  0.0594  0.031425  0.241175]
 [0.075475 0.066225 0.044975 ... 0.05505 0.02915 0.2405 ]
 [0.073375 0.063225 0.044475 ... 0.05435 0.029375 0.243575]
 [0.047325 0.05035 0.027125 ... 0.04535 0.022275 0.2235 ]
[0.046475 0.051075 0.026425 ... 0.047025 0.021025 0.2348 ]
 [0.04295 0.050275 0.02575 ... 0.044525 0.01955 0.240875]]
[[0.065825 0.0619 0.04045 ... 0.053225 0.026425 0.236775]
 [0.07745 0.062725 0.040725 ... 0.0573
                                         0.030725 0.2439 ]
[0.075525 0.063775 0.0434 ... 0.05595 0.030125 0.25005 ]
 [0.046675 0.048325 0.02605 ... 0.0475 0.0219 0.23165 ]
 [0.046825 0.04955 0.026425 ... 0.0471 0.02055 0.243125]
 [0.04435  0.0498  0.0253  ... 0.04675  0.020775  0.239925]]
[[0.028025 0.041275 0.01945 ... 0.039375 0.015675 0.22205 ]
[0.0245  0.040675  0.018025  ...  0.039575  0.016475  0.2187 ]
[0.02185 0.03435 0.01665 ... 0.034025 0.015
                                               0.20335 ]
 . . .
 [0.1155  0.09395  0.0714  ...  0.058625  0.0275  0.335675]
 [0.117225 0.09435 0.0699 ... 0.05885 0.028175 0.34795 ]
 [0.1168  0.093275  0.06865  ...  0.0585  0.02895  0.353275]]
[[0.032025 0.04075 0.020675 ... 0.04025 0.015525 0.2328 ]
 [0.024525 0.038175 0.018025 ... 0.03785 0.015075 0.21255 ]
[0.0227 0.03625 0.016425 ... 0.035 0.015075 0.204675]
 . . .
 [0.11625  0.093825  0.071275  ...  0.058625  0.02685  0.34765 ]
 [0.115325 0.092175 0.06915 ... 0.05855 0.02745 0.3572 ]
[0.1143  0.091225  0.067325  ...  0.05835  0.028925  0.357825]]
[[0.033325 0.04015 0.0212
                            ... 0.037875 0.015575 0.220525]
[0.027225 \ 0.038525 \ 0.01925 \ \dots \ 0.03625 \ 0.014825 \ 0.207775]
 [0.02625 0.03785 0.01885 ... 0.035675 0.015175 0.209825]
 . . .
 [0.1132
          0.09225 0.0699
                            ... 0.057875 0.027175 0.352875]
[0.1116 0.090575 0.0685
                            ... 0.0585 0.027325 0.36045 ]
[0.110325 0.089725 0.06665 ... 0.059425 0.02975 0.35485 ]]]
```

```
[[[0.076325 0.0714
                    0.0511 ... 0.05685 0.027375 0.3285 ]
 [0.078825 0.066725 0.044825 ... 0.05665 0.03155 0.3196 ]
         0.0806
                   0.060575 ... 0.07545 0.048225 0.2805 ]
 [0.1038
  . . .
 [0.02885    0.040825    0.022125    ...    0.037725    0.016275    0.17815 ]
 [0.0286 0.0422
                    0.02355 ... 0.039625 0.016675 0.191225]
 [0.02775 0.04375 0.022175 ... 0.043325 0.0181 0.203775]]
 [[0.06785 0.062075 0.04025 ... 0.04975 0.026175 0.31845 ]
 [0.07785  0.06515  0.041575  ...  0.055275  0.033675  0.29555 ]
                    0.062 ... 0.076125 0.047775 0.27305 ]
 [0.099375 0.0823
 [0.026425 0.040625 0.021825 ... 0.037175 0.0163 0.180075]
 [0.0283
           0.04245 0.02205 ... 0.04045 0.017175 0.192025]
 [0.02925 0.0436 0.022975 ... 0.043725 0.0179 0.20435 ]]
 [[0.064725 0.0621
                    0.0413 ... 0.05105 0.02655 0.30515 ]
 [0.08075 0.067625 0.0489 ... 0.0599 0.033625 0.28425 ]
 [0.1018  0.078725  0.060025 ...  0.0735  0.043225  0.2772  ]
 . . .
                    0.020975 ... 0.03765 0.01625 0.184425]
 [0.0277
           0.0412
 [0.02835 0.043125 0.021675 ... 0.040175 0.017375 0.19335 ]
 [0.030575 0.043325 0.023375 ... 0.04225 0.0173 0.200575]]
 . . .
 [[0.06545 0.054525 0.034075 ... 0.05745 0.028325 0.244075]
 [0.06275 0.053075 0.03125 ... 0.055625 0.027675 0.247475]
 [0.060875 0.05235 0.030725 ... 0.053875 0.026575 0.247275]
  . . .
 [0.04905 0.0508
                    0.031375 ... 0.039275 0.018625 0.184025]
 [0.047775 \ 0.04855 \ 0.03135 \ \dots \ 0.038075 \ 0.017725 \ 0.173025]
 [0.048475 0.052025 0.0336 ... 0.0377 0.018625 0.172875]]
 [[0.061575 0.051675 0.03085 ... 0.052975 0.02525 0.244675]
 [0.056875 0.050975 0.027025 ... 0.051675 0.023125 0.243075]
 [0.051075 0.05215 0.027025 ... 0.052125 0.022625 0.2422 ]
  . . .
 [0.051525 0.05075 0.031625 ... 0.039625 0.021775 0.1806 ]
 [0.0485  0.049475  0.031275  ...  0.03685  0.01885  0.181675]
 [0.054275 \ 0.054875 \ 0.036125 \ \dots \ 0.037525 \ 0.0198 \ 0.171425]]
```

```
[[0.055875 0.051075 0.02745 ... 0.04885 0.02285 0.2407 ]
 [0.056  0.052725  0.0285  ...  0.053175  0.02415  0.24375 ]
 [0.0544 0.05275 0.02815 ... 0.0555 0.0232 0.24885 ]
 [0.05005 0.051775 0.031 ... 0.03915 0.019525 0.1762 ]
 [0.048825 0.051275 0.0324 ... 0.036175 0.018375 0.18395 ]
  \begin{bmatrix} [[0.059125\ 0.0521 \ 0.0284 \ \dots \ 0.046025\ 0.019975\ 0.234825] \end{bmatrix} 
 [0.06905 0.055875 0.0304 ... 0.04825 0.021725 0.237375]
          [0.0699
 . . .
 [0.034575 \ 0.04225 \ 0.0247 \ \dots \ 0.03785 \ 0.019175 \ 0.157225]
 [0.029975 \ 0.038475 \ 0.023925 \ \dots \ 0.034475 \ 0.014425 \ 0.175175]
 [0.025325 0.03555 0.02115 ... 0.0325 0.0144 0.157 ]]
[[0.04895 0.051125 0.02935 ... 0.04475 0.0215 0.2242 ]
          0.05555 0.032025 ... 0.04655 0.0231
 [0.0563
                                              0.224225]
 [0.055875 0.0564 0.032875 ... 0.04815 0.023 0.232925]
 . . .
 [0.0347 0.0392 0.0209 ... 0.035425 0.015675 0.17295 ]
 [0.031875 0.0362
                  0.02055 ... 0.029625 0.013925 0.14845 ]
 [0.028125 0.03385 0.020825 ... 0.026825 0.01315 0.13235 ]]
[[0.0486
          [0.05655 0.053425 0.028925 ... 0.047275 0.022825 0.219525]
 [0.0573  0.055525  0.0294  ...  0.0482  0.022275  0.2325 ]
 . . .
 [0.031925 0.033875 0.0206 ... 0.03015 0.014075 0.169075]
 [0.0316  0.032025  0.019625  ...  0.0268  0.012925  0.136325]]
. . .
[[0.067175 0.0628  0.039875 ... 0.052775 0.0307  0.2282 ]
 [0.080275 \ 0.071475 \ 0.050425 \ \dots \ 0.0566 \ 0.0342 \ 0.217525]
 [0.07215  0.068375  0.045875  ...  0.056375  0.034375  0.2167 ]
 [0.03785  0.041425  0.023875  ...  0.043775  0.019575  0.213625]
```

```
[0.03475 0.0394
                    0.02255 ... 0.04455 0.02
                                                  0.217375]
 [0.032625 0.039025 0.02305 ... 0.043425 0.01985 0.229575]]
 [[0.07875 0.068475 0.0437
                             ... 0.056175 0.0339
                                                  0.22795]
 [0.08205 0.073825 0.0498 ... 0.057775 0.035225 0.2253 ]
 [0.08115 0.07405 0.0505
                             ... 0.059475 0.03475 0.2217 ]
 . . .
 [0.03895 0.043275 0.026075 ... 0.044775 0.021
                                                  0.2286 ]
 [0.03795  0.038525  0.02265  ...  0.04295  0.018625  0.22255 ]
 [0.03365 0.038425 0.02355 ... 0.042
                                         0.0189 0.225125]]
 [[0.089
           0.076325 0.0531 ... 0.05915 0.0333 0.228925]
 [0.084925 0.075775 0.050825 ... 0.05925 0.0363
                                                  0.236375]
 [0.08475 0.077325 0.050925 ... 0.0591 0.03615 0.225875]
 [0.040075 0.0416
                    0.025975 ... 0.044 0.020425 0.234125]
 [0.038075 0.036475 0.022375 ... 0.042175 0.01925 0.21895 ]
 [0.0349  0.036575  0.0241  ...  0.041525  0.0202  0.223625]]]
[[[0.039875 0.055875 0.031825 ... 0.046725 0.0206
                                                  0.2473 1
  [0.041225 0.053475 0.031675 ... 0.04425 0.01995 0.2442 ]
 [0.038
           0.0509
                   0.030125 ... 0.04345 0.018975 0.252075]
  . . .
 [0.079575 0.068025 0.048175 ... 0.0623
                                         0.0347 0.275575]
 [0.093775 0.08395 0.063975 ... 0.12865 0.096575 0.214425]
 [0.102475 0.09315 0.07065 ... 0.124725 0.11835 0.17915 ]]
 [[0.039875 0.055025 0.034025 ... 0.0453
                                         0.020225 0.25715 ]
 [0.039625 \ 0.053725 \ 0.032925 \ \dots \ 0.0437 \ 0.01945 \ 0.250625]
 [0.03925 0.051775 0.031525 ... 0.0442 0.018825 0.2608 ]
 [0.080175 0.073025 0.052975 ... 0.06945 0.0391
                                                  0.219825]
 [0.09105 0.0811
                    0.05875 ... 0.09675 0.067
                                                  0.133375]
 [0.08775 0.0791
                    0.053775 ... 0.097075 0.066325 0.1061 ]]
 [[0.04015 0.05545 0.0358
                           ... 0.046
                                         0.020325 0.2604 ]
 Γ0.0386
           0.053425 0.035075 ... 0.04415 0.0186 0.259075]
 [0.038875 0.0541
                    0.035
                            ... 0.04585 0.0204
                                                  0.2731 ]
 [0.09545 0.086025 0.06205 ... 0.08275 0.050225 0.117975]
 [0.07805 0.07245 0.05015
                            ... 0.08905 0.06075 0.088825]
 [0.075975 0.07035 0.04505 ... 0.09075 0.064575 0.082325]]
```

```
[[0.041475 0.041475 0.021175 ... 0.03885 0.015775 0.209025]
 [0.039625 0.040275 0.021525 ... 0.0381 0.01435 0.199925]
 [0.034975 0.040175 0.020375 ... 0.0356 0.014575 0.1891 ]
 [0.0552
           0.048575 0.034275 ... 0.037725 0.020475 0.150825]
 [0.046975 0.04565 0.03075 ... 0.0352
                                          0.01815 0.137475]
 [0.049075 0.04705 0.031375 ... 0.03935 0.02075 0.1534 ]]
           0.04265 0.024375 ... 0.039125 0.0159
 [[0.0475
                                                   0.2042
 [0.048075 0.042075 0.0262 ... 0.039575 0.015975 0.1975 ]
 [0.0455 0.041725 0.02305 ... 0.0391
                                          0.0166
                                                   0.203425]
 [0.054875 0.04825 0.0329 ... 0.036975 0.020325 0.14335 ]
 [0.04635 0.0461
                    0.0307
                             ... 0.0349
                                          0.018575 0.1444 ]
 Γ0.0477
           0.045825 0.030225 ... 0.038175 0.0193 0.14945 ]]
 [[0.047625 0.042275 0.025025 ... 0.039375 0.016775 0.2007 ]
 [0.04795 0.043
                    0.02435 ... 0.039425 0.01655 0.198825]
 [0.057725 0.04625 0.03155
                             ... 0.0416
                                          0.0185
                                                   0.20395]
  . . .
 [0.0496  0.04615  0.03035  ...  0.036125  0.01925  0.138325]
 [0.0501
           0.047175 0.030225 ... 0.0391
                                          0.0216
                                                   0.158675]
 [0.04975  0.048025  0.030475  ...  0.038725  0.021075  0.1527 ]]]
[[[0.09655 0.074775 0.050975 ... 0.0516
                                          0.023025 0.261275]
 [0.092725 \ 0.072675 \ 0.0496 \ \dots \ 0.058225 \ 0.0292 \ 0.208175]
 [0.080925 0.064725 0.04845 ... 0.08235 0.050425 0.170475]
 [0.047575 \ 0.051725 \ 0.026375 \ \dots \ 0.044925 \ 0.017175 \ 0.256825]
 [0.055575 0.052925 0.030125 ... 0.048075 0.018
                                                   0.27485]
 [0.055525 0.0531
                    0.0318 ... 0.04635 0.01725 0.256675]]
 [[0.095525 0.07545 0.05235 ... 0.053225 0.022625 0.271925]
 [0.0957
           0.075225 0.05265
                             ... 0.057725 0.02675 0.219325]
           0.071825 0.05245
                                        0.05045 0.18085 ]
 Γ0.0937
                             ... 0.0824
 [0.042775 0.048825 0.02565 ... 0.043875 0.016375 0.257325]
                    0.028075 ... 0.04785 0.017925 0.282775]
 [0.050625 0.051
 [0.0558 0.052
                    0.029675 ... 0.046875 0.017275 0.268275]]
```

```
[[0.09525 0.076025 0.0528 ... 0.0533
                                       0.021625 0.2891 ]
  [0.09735 0.0765
                   0.053
                           ... 0.055425 0.024675 0.244825]
  [0.09475  0.075125  0.05085  ...  0.071575  0.040575  0.1881 ]
  [0.038275 0.0477
                           ... 0.043325 0.016
                   0.0243
                                               0.2494 ]
  [0.04245 0.050225 0.0255
                           ... 0.046025 0.01685 0.259525]
  [0.0483 \quad 0.052175 \quad 0.02775 \quad \dots \quad 0.04545 \quad 0.017225 \quad 0.249375]]
 . . .
 [[0.033875 0.045775 0.029025 ... 0.0404
                                       0.018975 0.2029 ]
  [0.036975 0.046825 0.02825 ... 0.04005 0.018575 0.19235 ]
  [0.116775 0.0982
                   0.080175 ... 0.08415 0.06735 0.2857 ]
  [0.104525 0.09055 0.071025 ... 0.0795
                                       0.0627
                                               0.310825]
  [[0.035775 0.042825 0.02835 ... 0.039125 0.0173
                                               0.20685 1
                   0.028275 ... 0.0397 0.017525 0.2041 ]
  [0.03505 0.0427
  [0.03665 0.0459
                   0.027125 ... 0.041575 0.0189
                                               0.20055]
  [0.10555  0.088325  0.06645  ...  0.081425  0.059475  0.288725]
  [0.10945 0.091575 0.072325 ... 0.084475 0.057925 0.306175]
  [[0.0381
                   0.027175 ... 0.0385
           0.0465
                                       0.0179
                                              0.199175]
  [0.036325 0.04335 0.027625 ... 0.037975 0.016925 0.1999 ]
  [0.036475 0.047725 0.029125 ... 0.043325 0.019775 0.21835 ]
  . . .
                   0.0796
  [0.1108 0.1004
                           ... 0.0981
                                       0.084725 0.291575]
  [0.0959 0.0824
                   0.06165 ... 0.07685 0.0528 0.318575]
  [0.093025 0.07815 0.0585 ... 0.06915 0.0448 0.32745 ]]]], shape=(32, 256, 256, 8),
outputs: float32 (32, 256, 256, 5)
tf.Tensor(
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  [0. 0. 1. 0. 0.]
  [0. 0. 1. 0. 0.]
  [0. 0. 1. 0. 0.]]
```

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- [0. 0. 1. 0. 0.]

- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]]
- [[0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]

. . .

- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]]

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- [0. 1. 0. 0. 0.]

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- [1. 0. 0. 0. 0.]
- [0. 1. 0. 0. 0.]]
- [[1. 0. 0. 0. 0.]
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- [1. 0. 0. 0. 0.]

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- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]
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- [1. 0. 0. 0. 0.]

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- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]]

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  - [0. 0. 1. 0. 0.]
  - [0. 0. 1. 0. 0.]]
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  - [1. 0. 0. 0. 0.]
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  - [0. 0. 1. 0. 0.]
  - [0. 0. 1. 0. 0.]]
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  - [1. 0. 0. 0. 0.]
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  - [0. 0. 1. 0. 0.]
  - [0. 0. 1. 0. 0.]]
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  - [[1. 0. 0. 0. 0.]
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  - . . .
  - [0. 1. 0. 0. 0.]
  - [0. 1. 0. 0. 0.]
  - [0. 1. 0. 0. 0.]]
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  - [1. 0. 0. 0. 0.]
  - . . .
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  - [0. 1. 0. 0. 0.]
  - [0. 1. 0. 0. 0.]]

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- [1. 0. 0. 0. 0.]

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- [0. 1. 0. 0. 0.]
- [0. 1. 0. 0. 0.]]]
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  - [0. 0. 1. 0. 0.]

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- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]
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- [0. 0. 1. 0. 0.]

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- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]
- [[1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [0. 1. 0. 0. 0.]

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- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]

. . .

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- [0. 1. 0. 0. 0.]

- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]]

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[[0. 0. 1. 0. 0.]
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- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]]
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- [0. 0. 1. 0. 0.]

. . .

- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]]]

. . .

- [[[0. 0. 1. 0. 0.]
  - [0. 0. 1. 0. 0.]
  - [0. 0. 1. 0. 0.]

. . .

- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]
- [[0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]

. . .

- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]
- [[0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]

- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]

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[[0. 0. 1. 0. 0.]
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- [0. 0. 1. 0. 0.]

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- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]
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- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]
- [[0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]

. . .

. . .

- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]]
- [[[0. 0. 1. 0. 0.]
  - [0. 0. 1. 0. 0.]
  - [0. 0. 1. 0. 0.]

. . .

- [1. 0. 0. 0. 0.]
- [0. 0. 0. 1. 0.]
- [0. 0. 0. 1. 0.]]
- [[0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]

- [1. 0. 0. 0. 0.]
- [0. 0. 0. 0. 1.]
- [0. 0. 0. 0. 1.]]

- [[0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]

- [0. 0. 0. 0. 1.]
- [0. 0. 0. 0. 1.]
- [0. 0. 0. 0. 1.]]

. . .

- [[0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- ... [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]
- [[0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]

. . .

- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]
- [[0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]
- [0. 0. 1. 0. 0.]

. . .

- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]]

[[[0. 0. 1. 0. 0.]

- [0. 1. 0. 0. 0.]
- [0. 0. 0. 0. 1.]

- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]
- [1. 0. 0. 0. 0.]]

```
[[0. 0. 1. 0. 0.]
   [0. 1. 0. 0. 0.]
   [0. 0. 0. 0. 1.]
   . . .
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]]
  [[0. 0. 1. 0. 0.]
   [0. 1. 0. 0. 0.]
   [0. 0. 1. 0. 0.]
   . . .
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]]
  [[0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   . . .
   [0. 0. 0. 1. 0.]
   [0. 1. 0. 0. 0.]
   [1. 0. 0. 0. 0.]]
  [[0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   . . .
   [0. 0. 0. 1. 0.]
   [0. 1. 0. 0. 0.]
   [1. 0. 0. 0. 0.]]
  [[0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   . . .
   [0. 0. 0. 1. 0.]
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]]]], shape=(32, 256, 256, 5), dtype=float32)
Testing
```

```
inputs: float32 (1, 256, 256, 8)
tf.Tensor(
[[[[0.0853
            0.0767
                     0.052625 ... 0.084725 0.048225 0.266675]
   [0.08645 0.076725 0.05415 ... 0.0815
                                            0.049725 0.256475]
   Γ0.0881
            0.07945 0.05675 ... 0.0833
                                            0.049725 0.267
   [0.041725 0.046875 0.027925 ... 0.04645 0.019175 0.2598 ]
   [0.03835 0.044725 0.024125 ... 0.04525 0.018175 0.2606 ]
   [0.0354 0.03985 0.021875 ... 0.044
                                            0.017925 0.260925]]
  [[0.08945  0.072675  0.047475  ...  0.084925  0.045675  0.253325]
            0.07225   0.048375   ...   0.088875   0.049475   0.25065 ]
   [0.096
                             ... 0.088175 0.050675 0.269075]
   [0.10235 0.0735
                     0.0509
   . . .
   [0.042225 0.0459
                     0.026575 ... 0.04655 0.01875 0.265025]
   [0.040375 0.044525 0.02595 ... 0.04585 0.0186
                                                     0.26045 ]
   [0.03615  0.041075  0.022125  ...  0.044825  0.017775  0.263675]]
  [[0.087625 0.0762
                     0.0522 ... 0.084775 0.0459
                                                     0.243175
   [0.09235 0.07215 0.048425 ... 0.0871
                                            0.04725 0.243725]
   [0.104925 0.074375 0.05205 ... 0.0889
                                            0.048275 0.25105 ]
   . . .
   [0.04065 0.041975 0.023275 ... 0.043425 0.018075 0.25435 ]
            0.04225 0.02305 ... 0.0432
                                            0.017725 0.254725]
   [0.0382
   [0.037025 0.042925 0.022875 ... 0.046575 0.018425 0.259875]]
  . . .
                     0.03945 ... 0.05635 0.03315 0.198025]
  [[0.074575 0.06
            0.06205  0.040675  ...  0.058675  0.033075  0.198625]
   [0.080225 0.06355 0.0416
                              ... 0.059775 0.03395 0.206025]
   . . .
   [0.09965 0.082725 0.06805 ... 0.067325 0.05815 0.27725 ]
   [0.0889
            0.0679
                     0.0468
                               ... 0.0563
                                            0.034875 0.29495 ]
   [0.07205 0.059575 0.04125 ... 0.05235 0.03185 0.3116 ]]
            0.06205 0.039975 ... 0.058175 0.0334
  [[0.0768
                                                     0.197525
   Γ0.0797
            0.0638
                      0.041675 ... 0.060425 0.035925 0.1993 ]
   [0.08345 0.063725 0.04135 ... 0.0606
                                            0.03585 0.2044 1
   [0.110425 0.089975 0.071475 ... 0.083225 0.07175 0.261625]
            0.076725 0.053175 ... 0.060975 0.043725 0.29315 ]
   [0.0995
   [0.07945  0.06385  0.0462  ...  0.059675  0.038375  0.32095 ]]
```

```
[[0.074075 0.0615
                     0.0395
                              ... 0.0591
                                           0.03185 0.200825]
            [0.0771
  [0.0835
            0.063125 0.0417
                             ... 0.059825 0.034325 0.2
  . . .
  [0.118575 0.0944
                     0.070325 ... 0.09795 0.078
  [0.11975 0.0899
                     0.063575 ... 0.077975 0.05495 0.306325]
            0.068475 \ 0.049775 \ \dots \ 0.063225 \ 0.039625 \ 0.3163 ]]]], shape=(1, 256, 256, 8), d
outputs: float32 (1, 256, 256, 5)
tf.Tensor(
[[[[1. 0. 0. 0. 0.]
  [0. 0. 1. 0. 0.]
  [0. 1. 0. 0. 0.]
   . . .
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]]
  [[0. 0. 1. 0. 0.]
  [0. 0. 0. 1. 0.]
  [0. 0. 0. 1. 0.]
  . . .
  [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]]
  [[0. 1. 0. 0. 0.]
  [0. 0. 1. 0. 0.]
  [0. 0. 1. 0. 0.]
   . . .
  [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]]
  . . .
  [[1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]
  [0. 0. 1. 0. 0.]
  [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]]
```

```
[[1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]
  [0. 0. 0. 1. 0.]
  [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]]
 [[1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]
  [1. 0. 0. 0. 0.]
  [0. 0. 0. 1. 0.]
  [0. 0. 1. 0. 0.]
  [1. 0. 0. 0. 0.]]]], shape=(1, 256, 256, 5), dtype=float32)
Validation
inputs: float32 (1, 256, 256, 8)
tf.Tensor(
[[[[0.053275 0.043025 0.0284 ... 0.042575 0.01925 0.2313 ]
  [0.0535
            0.04265 0.0293
                             ... 0.043975 0.0191
                                                 0.2464251
  [0.049125 0.042675 0.027125 ... 0.042275 0.019325 0.228225]
  [0.0724
            0.064525 0.044325 ... 0.0504
                                         0.0264
                                                 0.202325]
  [0.07395 0.0651
                    0.04495 ... 0.05235 0.02625 0.211175]
  [0.075975 0.0647
                    0.04615 ... 0.0523
                                         0.027625 0.2079 ]]
  [[0.053025 0.042325 0.02895
                            ... 0.041625 0.018475 0.239625]
  [0.051225 0.0413
                    0.029
                             ... 0.042
                                         0.018375 0.238775]
  [0.04785 0.04345 0.02785
                            ... 0.042625 0.019825 0.21835 ]
   . . .
  [0.067
            0.059125 0.042375 ... 0.049375 0.023475 0.18365 ]
            [0.0679
                                                 0.197125]
  [0.066575 0.062775 0.041925 ... 0.049875 0.0247
                                                 0.199775]]
                             ... 0.040925 0.01785 0.243675]
  [[0.04975 0.03945 0.0265
  [0.050625 0.040725 0.027925 ... 0.040825 0.018625 0.236075]
  [0.0546]
            . . .
  [0.069075 0.0611
                    0.0435
                             ... 0.050075 0.02435 0.186325]
  [0.07345 0.063225 0.0452
                             ... 0.052325 0.02595 0.19745 ]
  [0.068175 0.06035 0.04155 ... 0.04985 0.023925 0.1912 ]]
```

. . .

```
[[0.064425 0.062275 0.037175 ... 0.0576 0.027975 0.265325]
   [0.058075 0.059925 0.03495 ... 0.05475 0.02585 0.26375 ]
   [0.040675 0.053675 0.028975 ... 0.0482
                                           0.02065 0.250575]
   [0.0937
            0.09025 0.072
                              ... 0.0486
                                           0.02375 0.2789 ]
   [0.094125 0.091525 0.072925 ... 0.04795 0.02335 0.273275]
   [0.09135  0.08855  0.067875 ... 0.04985  0.023425  0.282475]]
  [[0.063175 0.05715 0.03525 ... 0.054475 0.0265
                                                    0.2553 ]
   [0.0581
            0.0556
                     0.032875 ... 0.0511
                                           0.0242
                                                    0.246625]
                     0.027975 ... 0.0464
   [0.0396
            0.0509
                                           0.020075 0.23445 ]
   . . .
                     0.076275 ... 0.048725 0.0235
   [0.09535 0.0905
                                                    0.289175]
   [0.093725 0.09015 0.0717
                             ... 0.048325 0.02345 0.279575]
   [0.09145 0.088125 0.068475 ... 0.0493
                                          0.023075 0.290275]]
  [[0.04605 0.05285 0.0288
                              ... 0.048925 0.021625 0.2413 ]
   [0.03955 0.051625 0.028325 ... 0.046975 0.020875 0.2319 ]
                                                    0.221325]
   [0.0431
            0.052225 0.03135 ... 0.042275 0.02
   . . .
   [0.099075 0.085075 0.06545 ... 0.051925 0.02575 0.298475]
   [0.100175 0.08775 0.0678
                              ... 0.05005 0.024175 0.28905 ]
   [0.09685 0.0912
                     0.07425 ... 0.049975 0.023375 0.290425]]]], shape=(1, 256, 256, 8), d
outputs: float32 (1, 256, 256, 5)
tf.Tensor(
[[[[0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   . . .
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]]
  [[0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   . . .
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]]
```

```
[[0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]
   [1. 0. 0. 0. 0.]]
  [[0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   . . .
   [0. 1. 0. 0. 0.]
   [0. 1. 0. 0. 0.]
   [0. 1. 0. 0. 0.]]
  [[0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   . . .
   [0. 1. 0. 0. 0.]
   [0. 1. 0. 0. 0.]
   [0. 1. 0. 0. 0.]]
  [[0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   [0. 0. 1. 0. 0.]
   . . .
   [0. 1. 0. 0. 0.]
   [0. 1. 0. 0. 0.]
   [0. 1. 0. 0. 0.]]]], shape=(1, 256, 256, 5), dtype=float32)
***********************************
******************* building and compiling model... *************
DERIVE_FEATURES: False
Model: "unet"
```

<pre>batch_normalization (Batch Normalization)</pre>	(None, N	None,	None,	32)	128	['conv2d[0][0]']
activation (Activation)	(None, N	None,	None,	32)	0	['batch_normalization[0]
activation_1 (Activation)	(None, N	None,	None,	32)	0	['activation[0][0]']
<pre>separable_conv2d (Separabl eConv2D)</pre>	(None, N	None,	None,	64)	2400	['activation_1[0][0]']
<pre>batch_normalization_1 (Bat chNormalization)</pre>	(None, N	None,	None,	64)	256	['separable_conv2d[0][0]
activation_2 (Activation)	(None, N	None,	None,	64)	0	['batch_normalization_1[(
<pre>separable_conv2d_1 (Separa bleConv2D)</pre>	(None, N	None,	None,	64)	4736	['activation_2[0][0]']
<pre>batch_normalization_2 (Bat chNormalization)</pre>	(None, N	None,	None,	64)	256	['separable_conv2d_1[0][(
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, N	None,	None,	64)	0	['batch_normalization_2[0]
conv2d_1 (Conv2D)	(None, N	None,	None,	64)	2112	['activation[0][0]']
add (Add)	(None, N	None,	None,	64)	0	['max_pooling2d[0][0]', 'conv2d_1[0][0]']
activation_3 (Activation)	(None, N	None,	None,	64)	0	['add[0][0]']
<pre>separable_conv2d_2 (Separa bleConv2D)</pre>	(None, N	None,	None,	128)	8896	['activation_3[0][0]']
<pre>batch_normalization_3 (Bat chNormalization)</pre>	(None, N	None,	None,	128)	512	['separable_conv2d_2[0][0
activation_4 (Activation)	(None, N	None,	None,	128)	0	['batch_normalization_3[(
separable_conv2d_3 (Separa	(None, N	None,	None,	128)	17664	['activation_4[0][0]']

# bleConv2D)

<pre>batch_normalization_4 (Bat chNormalization)</pre>	(None, None, Non	e, 128)	512	['separable_conv2d_3[0][
<pre>max_pooling2d_1 (MaxPoolin g2D)</pre>	(None, None, Non	e, 128)	0	['batch_normalization_4[0]
conv2d_2 (Conv2D)	(None, None, None	e, 128)	8320	['add[0][0]']
add_1 (Add)	(None, None, Non	e, 128)	0	['max_pooling2d_1[0][0]' 'conv2d_2[0][0]']
activation_5 (Activation)	(None, None, None	e, 128)	0	['add_1[0][0]']
<pre>separable_conv2d_4 (Separa bleConv2D)</pre>	(None, None, Non	e, 256)	34176	['activation_5[0][0]']
<pre>batch_normalization_5 (Bat chNormalization)</pre>	(None, None, Non	e, 256)	1024	['separable_conv2d_4[0][0
activation_6 (Activation)	(None, None, Non	e, 256)	0	['batch_normalization_5[0]
<pre>separable_conv2d_5 (Separa bleConv2D)</pre>	(None, None, Non	e, 256)	68096	['activation_6[0][0]']
<pre>batch_normalization_6 (Bat chNormalization)</pre>	(None, None, Non	e, 256)	1024	['separable_conv2d_5[0][0
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, None, Non	e, 256)	0	['batch_normalization_6[0]
conv2d_3 (Conv2D)	(None, None, Non	e, 256)	33024	['add_1[0][0]']
add_2 (Add)	(None, None, Non	e, 256)	0	['max_pooling2d_2[0][0]' 'conv2d_3[0][0]']
activation_7 (Activation)	(None, None, Non	e, 256)	0	['add_2[0][0]']
<pre>conv2d_transpose (Conv2DTr anspose)</pre>	(None, None, None	e, 256)	590080	['activation_7[0][0]']

<pre>batch_normalization_7 (Bat chNormalization)</pre>	(None, None, None, 256)	1024	['conv2d_transpose[0][0]
activation_8 (Activation)	(None, None, None, 256)	0	<pre>['batch_normalization_7[0]</pre>
<pre>conv2d_transpose_1 (Conv2D Transpose)</pre>	(None, None, None, 256)	590080	['activation_8[0][0]']
<pre>batch_normalization_8 (Bat chNormalization)</pre>	(None, None, None, 256)	1024	['conv2d_transpose_1[0][0
<pre>up_sampling2d_1 (UpSamplin g2D)</pre>	(None, None, None, 256)	0	['add_2[0][0]']
<pre>up_sampling2d (UpSampling2 D)</pre>	(None, None, None, 256)	0	['batch_normalization_8[0]
conv2d_4 (Conv2D)	(None, None, None, 256)	65792	['up_sampling2d_1[0][0]']
add_3 (Add)	(None, None, None, 256)	0	['up_sampling2d[0][0]', 'conv2d_4[0][0]']
activation_9 (Activation)	(None, None, None, 256)	0	['add_3[0][0]']
<pre>conv2d_transpose_2 (Conv2D Transpose)</pre>	(None, None, None, 128)	295040	['activation_9[0][0]']
<pre>batch_normalization_9 (Bat chNormalization)</pre>	(None, None, None, 128)	512	['conv2d_transpose_2[0][0
activation_10 (Activation)	(None, None, None, 128)	0	['batch_normalization_9[0]
<pre>conv2d_transpose_3 (Conv2D Transpose)</pre>	(None, None, None, 128)	147584	['activation_10[0][0]']
<pre>batch_normalization_10 (Ba tchNormalization)</pre>	(None, None, None, 128)	512	['conv2d_transpose_3[0][(
up_sampling2d_3 (UpSamplin g2D)	(None, None, None, 256)	0	['add_3[0][0]']

<pre>up_sampling2d_2 (UpSamplin g2D)</pre>	(None, None,	None, 128)	0	<pre>['batch_normalization_10 ']</pre>
conv2d_5 (Conv2D)	(None, None,	None, 128)	32896	['up_sampling2d_3[0][0]']
add_4 (Add)	(None, None,	None, 128)	0	['up_sampling2d_2[0][0]' 'conv2d_5[0][0]']
activation_11 (Activation)	(None, None,	None, 128)	0	['add_4[0][0]']
<pre>conv2d_transpose_4 (Conv2D Transpose)</pre>	(None, None,	None, 64)	73792	['activation_11[0][0]']
<pre>batch_normalization_11 (Ba tchNormalization)</pre>	(None, None,	None, 64)	256	['conv2d_transpose_4[0][0
activation_12 (Activation)	(None, None,	None, 64)	0	['batch_normalization_11 ']
<pre>conv2d_transpose_5 (Conv2D Transpose)</pre>	(None, None,	None, 64)	36928	['activation_12[0][0]']
<pre>batch_normalization_12 (Ba tchNormalization)</pre>	(None, None,	None, 64)	256	['conv2d_transpose_5[0][
up_sampling2d_5 (UpSamplin g2D)	(None, None,	None, 128)	0	['add_4[0][0]']
up_sampling2d_4 (UpSamplin g2D)	(None, None,	None, 64)	0	['batch_normalization_12
conv2d_6 (Conv2D)	(None, None,	None, 64)	8256	['up_sampling2d_5[0][0]']
add_5 (Add)	(None, None,	None, 64)	0	['up_sampling2d_4[0][0]' 'conv2d_6[0][0]']
activation_13 (Activation)	(None, None,	None, 64)	0	['add_5[0][0]']
<pre>conv2d_transpose_6 (Conv2D Transpose)</pre>	(None, None,	None, 32)	18464	['activation_13[0][0]']
<pre>batch_normalization_13 (Ba tchNormalization)</pre>	(None, None,	None, 32)	128	['conv2d_transpose_6[0][0

```
activation_14 (Activation)
                  (None, None, None, 32)
                                     0
                                            ['batch_normalization_13
                                            וי
conv2d_transpose_7 (Conv2D
                  (None, None, None, 32)
                                     9248
                                            ['activation_14[0][0]']
Transpose)
                                            ['conv2d_transpose_7[0][
batch_normalization_14 (Ba (None, None, None, 32)
                                     128
tchNormalization)
                                            ['add_5[0][0]']
up_sampling2d_7 (UpSamplin (None, None, None, 64)
                                     0
g2D)
up_sampling2d_6 (UpSamplin (None, None, None, 32)
                                            ['batch_normalization_14
g2D)
conv2d_7 (Conv2D)
                                     2080
                                            ['up_sampling2d_7[0][0]']
                  (None, None, None, 32)
add_6 (Add)
                   (None, None, None, 32)
                                     0
                                            ['up_sampling2d_6[0][0]'
                                             'conv2d_7[0][0]']
final_conv (Conv2D)
                  (None, None, None, 5)
                                     1445
                                            ['add_6[0][0]']
Total params: 2060997 (7.86 MB)
Trainable params: 2057221 (7.85 MB)
Non-trainable params: 3776 (14.75 KB)
******************** preparing output directory... **************
> Saving models and results at /content/drive/MyDrive/Colab Notebooks/DL_Book/Chapter_1/outp
Epoch 1: val_loss improved from inf to 2.63403, saving model to /content/drive/MyDrive/Colab
Epoch 2/30
Epoch 2: val_loss improved from 2.63403 to 1.23879, saving model to /content/drive/MyDrive/C
```

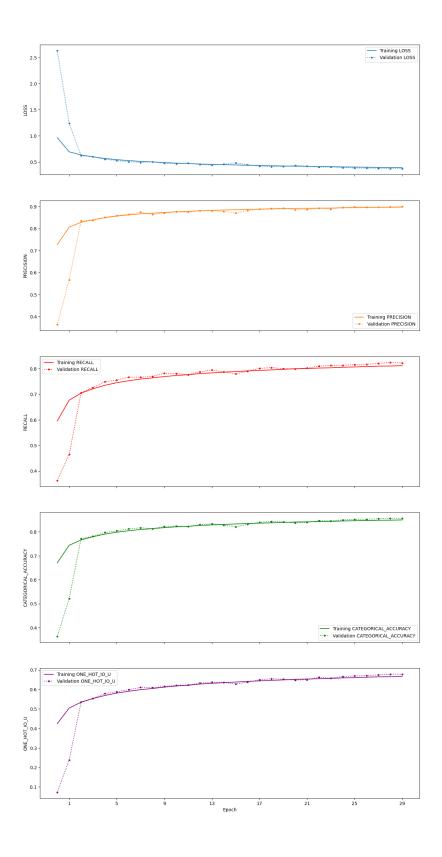
Epoch 3/30

```
Epoch 3: val_loss improved from 1.23879 to 0.62282, saving model to /content/drive/MyDrive/C
Epoch 4: val_loss improved from 0.62282 to 0.60250, saving model to /content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/M
Epoch 5/30
Epoch 5: val_loss improved from 0.60250 to 0.55160, saving model to /content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/M
Epoch 6: val loss improved from 0.55160 to 0.52872, saving model to /content/drive/MyDrive/C
Epoch 7/30
Epoch 7: val loss improved from 0.52872 to 0.50506, saving model to /content/drive/MyDrive/C
Epoch 8/30
Epoch 8: val_loss improved from 0.50506 to 0.49242, saving model to /content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/M
Epoch 9/30
Epoch 9: val_loss did not improve from 0.49242
Epoch 10/30
Epoch 10: val_loss improved from 0.49242 to 0.47591, saving model to /content/drive/MyDrive/
Epoch 11/30
Epoch 11: val_loss improved from 0.47591 to 0.46856, saving model to /content/drive/MyDrive/
Epoch 12/30
Epoch 12: val_loss did not improve from 0.46856
Epoch 13/30
Epoch 13: val loss improved from 0.46856 to 0.45125, saving model to /content/drive/MyDrive/
```

```
Epoch 14/30
Epoch 14: val loss improved from 0.45125 to 0.44229, saving model to /content/drive/MyDrive/
Epoch 15/30
Epoch 15: val loss did not improve from 0.44229
Epoch 16/30
Epoch 16: val_loss did not improve from 0.44229
Epoch 17/30
Epoch 17: val_loss did not improve from 0.44229
Epoch 18/30
Epoch 18: val_loss improved from 0.44229 to 0.42199, saving model to /content/drive/MyDrive/
Epoch 19/30
Epoch 19: val_loss improved from 0.42199 to 0.41151, saving model to /content/drive/MyDrive/
Epoch 20/30
Epoch 20: val_loss did not improve from 0.41151
Epoch 21/30
Epoch 21: val_loss did not improve from 0.41151
Epoch 22/30
Epoch 22: val loss did not improve from 0.41151
Epoch 23/30
Epoch 23: val_loss improved from 0.41151 to 0.40218, saving model to /content/drive/MyDrive/
Epoch 24/30
Epoch 24: val_loss did not improve from 0.40218
```

```
Epoch 25/30
Epoch 25: val_loss improved from 0.40218 to 0.39190, saving model to /content/drive/MyDrive/
Epoch 26/30
Epoch 26: val_loss improved from 0.39190 to 0.38542, saving model to /content/drive/MyDrive/
Epoch 27/30
Epoch 27: val loss improved from 0.38542 to 0.38379, saving model to /content/drive/MyDrive/
Epoch 28/30
Epoch 28: val_loss improved from 0.38379 to 0.37968, saving model to /content/drive/MyDrive/
Epoch 29/30
Epoch 29: val_loss improved from 0.37968 to 0.37328, saving model to /content/drive/MyDrive/
Epoch 30/30
Epoch 30: val_loss improved from 0.37328 to 0.37270, saving model to /content/drive/MyDrive/
*********************************
**************
****************
Validation
loss: 0.3722515106201172
precision: 0.9008649587631226
recall: 0.8225432634353638
categorical_accuracy: 0.8566350340843201
one_hot_io_u: 0.6780571341514587
******************************
**********************************
******* saving model config and history object... *************
***********************************
```

*********************
Saving plots and model visualization at /content/drive/MyDrive/Colab Notebooks/DL_Book/Chapt
*******************
************************** saving models *******************
*******************



#### 2.3.4 Save the config file

```
from pathlib import Path
import shutil

config_file = Path(config_file)
drive_config_file = Path(unet_config.MODEL_DIR / f"{str(config_file).split('/')[-1]}")

# Create the target directory if it doesn't exist
drive_config_file.parent.mkdir(parents=True, exist_ok=True)

# Copy the file
shutil.copy(config_file, drive_config_file)

print(f"File copied from {config_file} to {drive_config_file}")
```

File copied from servir-aces/config.env to /content/drive/MyDrive/Colab Notebooks/DL\_Book/Characteristics.

## 2.3.5 Load the logs files via TensorBoard

Tensorboard provides a unique way to view and interact with the logs while the model is being trained. Learn more here. Here we only show you how you can load them to tensorboard with our training logs.

```
# Load the TensorBoard notebook extension
%load_ext tensorboard

log_dir_unet = f"{str(unet_config.MODEL_DIR)}/logs"
log_dir_unet
```

'/content/drive/MyDrive/Colab Notebooks/DL\_Book/Chapter\_1/output/unet\_v1/logs'

```
%tensorboard --logdir "{log_dir_unet}"
```

Reusing TensorBoard on port 6007 (pid 5630), started 0:02:00 ago. (Use '!kill 5630' to kill

<IPython.core.display.Javascript object>

# 2.3.6 Load the Saved U-Net Model

Load the saved model

```
import tensorflow as tf
```

unet\_model = tf.keras.models.load\_model(f"{str(unet\_config.MODEL\_DIR)}/trained-model")

print(unet\_model.summary())

Model: "unet"

	- · · I · · · · · · I ·		Connected to
input_1 (InputLayer)	[(None, None, None, 8)]	0	[]
conv2d (Conv2D)	(None, None, None, 32)	2336	['input_1[0][0]']
batch_normalization (Batch Normalization)	(None, None, None, 32)	128	['conv2d[0][0]']
activation (Activation)	(None, None, None, 32)	0	['batch_normalization[0]
activation_1 (Activation)	(None, None, None, 32)	0	['activation[0][0]']
<pre>separable_conv2d (Separabl eConv2D)</pre>	(None, None, None, 64)	2400	['activation_1[0][0]']
<pre>batch_normalization_1 (Bat chNormalization)</pre>	(None, None, None, 64)	256	['separable_conv2d[0][0]
activation_2 (Activation)	(None, None, None, 64)	0	['batch_normalization_1[(
<pre>separable_conv2d_1 (Separa bleConv2D)</pre>	(None, None, None, 64)	4736	['activation_2[0][0]']
<pre>batch_normalization_2 (Bat chNormalization)</pre>	(None, None, None, 64)	256	['separable_conv2d_1[0][(
max_pooling2d (MaxPooling2	(None, None, None, 64)	0	['batch_normalization_2[

D)				1
conv2d_1 (Conv2D)	(None, None, N	None, 64)	2112	['activation[0][0]']
add (Add)	(None, None, N	None, 64)	0	['max_pooling2d[0][0]', 'conv2d_1[0][0]']
activation_3 (Activation)	(None, None, N	None, 64)	0	['add[0][0]']
<pre>separable_conv2d_2 (Separa bleConv2D)</pre>	(None, None, N	None, 128)	8896	['activation_3[0][0]']
<pre>batch_normalization_3 (Bat chNormalization)</pre>	(None, None, N	None, 128)	512	['separable_conv2d_2[0][0
activation_4 (Activation)	(None, None, N	None, 128)	0	['batch_normalization_3[0]
<pre>separable_conv2d_3 (Separa bleConv2D)</pre>	(None, None, N	None, 128)	17664	['activation_4[0][0]']
<pre>batch_normalization_4 (Bat chNormalization)</pre>	(None, None, N	None, 128)	512	['separable_conv2d_3[0][0
<pre>max_pooling2d_1 (MaxPoolin g2D)</pre>	(None, None, N	None, 128)	0	['batch_normalization_4[0]
conv2d_2 (Conv2D)	(None, None, N	None, 128)	8320	['add[0][0]']
add_1 (Add)	(None, None, N	None, 128)	0	['max_pooling2d_1[0][0]' 'conv2d_2[0][0]']
activation_5 (Activation)	(None, None, N	None, 128)	0	['add_1[0][0]']
<pre>separable_conv2d_4 (Separa bleConv2D)</pre>	(None, None, N	None, 256)	34176	['activation_5[0][0]']
<pre>batch_normalization_5 (Bat chNormalization)</pre>	(None, None, N	None, 256)	1024	['separable_conv2d_4[0][0
activation_6 (Activation)	(None, None, N	None, 256)	0	['batch_normalization_5[0]

<pre>separable_conv2d_5 (Separa bleConv2D)</pre>	(None, None	e, None,	256)	68096	['activation_6[0][0]']
<pre>batch_normalization_6 (Bat chNormalization)</pre>	(None, None	e, None,	256)	1024	['separable_conv2d_5[0][(
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, None	e, None,	256)	0	['batch_normalization_6[0]
conv2d_3 (Conv2D)	(None, None	e, None,	256)	33024	['add_1[0][0]']
add_2 (Add)	(None, None	e, None,	256)	0	['max_pooling2d_2[0][0]' 'conv2d_3[0][0]']
activation_7 (Activation)	(None, None	e, None,	256)	0	['add_2[0][0]']
<pre>conv2d_transpose (Conv2DTr anspose)</pre>	(None, None	e, None,	256)	590080	['activation_7[0][0]']
<pre>batch_normalization_7 (Bat chNormalization)</pre>	(None, None	e, None,	256)	1024	['conv2d_transpose[0][0]
activation_8 (Activation)	(None, None	e, None,	256)	0	['batch_normalization_7[0]
<pre>conv2d_transpose_1 (Conv2D Transpose)</pre>	(None, None	e, None,	256)	590080	['activation_8[0][0]']
<pre>batch_normalization_8 (Bat chNormalization)</pre>	(None, None	e, None,	256)	1024	['conv2d_transpose_1[0][
up_sampling2d_1 (UpSamplin g2D)	(None, None	e, None,	256)	0	['add_2[0][0]']
up_sampling2d (UpSampling2 D)	(None, None	e, None,	256)	0	['batch_normalization_8[6]
conv2d_4 (Conv2D)	(None, None	e, None,	256)	65792	['up_sampling2d_1[0][0]']
add_3 (Add)	(None, None	e, None,	256)	0	['up_sampling2d[0][0]', 'conv2d_4[0][0]']
activation_9 (Activation)	(None, None	e, None,	256)	0	['add_3[0][0]']

<pre>conv2d_transpose_2 (Conv2D Transpose)</pre>	(None, N	None,	None,	128)	295040	['activation_9[0][0]']
<pre>batch_normalization_9 (Bat chNormalization)</pre>	(None, N	None,	None,	128)	512	['conv2d_transpose_2[0][0
activation_10 (Activation)	(None, N	None,	None,	128)	0	['batch_normalization_9[0]
<pre>conv2d_transpose_3 (Conv2D Transpose)</pre>	(None, N	None,	None,	128)	147584	['activation_10[0][0]']
<pre>batch_normalization_10 (Ba tchNormalization)</pre>	(None, N	None,	None,	128)	512	['conv2d_transpose_3[0][0
up_sampling2d_3 (UpSamplin g2D)	(None, N	None,	None,	256)	0	['add_3[0][0]']
<pre>up_sampling2d_2 (UpSamplin g2D)</pre>	(None, N	None,	None,	128)	0	['batch_normalization_10']
conv2d_5 (Conv2D)	(None, N	None,	None,	128)	32896	['up_sampling2d_3[0][0]']
<b>=</b> '						
add_4 (Add)	(None, N	None,	None,	128)	0	['up_sampling2d_2[0][0]' 'conv2d_5[0][0]']
<del>-</del>	(None, N				0	
add_4 (Add)		None,	None,	128)		'conv2d_5[0][0]']
add_4 (Add)  activation_11 (Activation)  conv2d_transpose_4 (Conv2D	(None, N	None,	None,	128) 64)	0	'conv2d_5[0][0]'] ['add_4[0][0]']
add_4 (Add)  activation_11 (Activation)  conv2d_transpose_4 (Conv2D Transpose)  batch_normalization_11 (Ba	(None, N	None, None,	None, None,	128) 64) 64)	0 73792	'conv2d_5[0][0]'] ['add_4[0][0]'] ['activation_11[0][0]']
add_4 (Add)  activation_11 (Activation)  conv2d_transpose_4 (Conv2D Transpose)  batch_normalization_11 (Ba tchNormalization)	(None, None,	None, None, None,	None, None,	128) 64) 64)	0 73792 256	'conv2d_5[0][0]'] ['add_4[0][0]'] ['activation_11[0][0]'] ['conv2d_transpose_4[0][0][0][0][0][0][0][0][0][0][0][0][0][

tchNormalization)

up_sampling2d_5 (UpSamplin g2D)	(None, None,	None,	128)	0	['add_4[0][0]']
up_sampling2d_4 (UpSamplin g2D)	(None, None,	None,	64)	0	<pre>['batch_normalization_12 ']</pre>
conv2d_6 (Conv2D)	(None, None,	None,	64)	8256	['up_sampling2d_5[0][0]']
add_5 (Add)	(None, None,	None,	64)	0	['up_sampling2d_4[0][0]' 'conv2d_6[0][0]']
activation_13 (Activation)	(None, None,	None,	64)	0	['add_5[0][0]']
<pre>conv2d_transpose_6 (Conv2D Transpose)</pre>	(None, None,	None,	32)	18464	['activation_13[0][0]']
<pre>batch_normalization_13 (Ba tchNormalization)</pre>	(None, None,	None,	32)	128	['conv2d_transpose_6[0][0
activation_14 (Activation)	(None, None,	None,	32)	0	<pre>['batch_normalization_13 ']</pre>
<pre>conv2d_transpose_7 (Conv2D Transpose)</pre>	(None, None,	None,	32)	9248	['activation_14[0][0]']
<pre>batch_normalization_14 (Ba tchNormalization)</pre>	(None, None,	None,	32)	128	['conv2d_transpose_7[0][0
up_sampling2d_7 (UpSamplin g2D)	(None, None,	None,	64)	0	['add_5[0][0]']
up_sampling2d_6 (UpSamplin g2D)	(None, None,	None,	32)	0	['batch_normalization_14']
conv2d_7 (Conv2D)	(None, None,	None,	32)	2080	['up_sampling2d_7[0][0]']
add_6 (Add)	(None, None,	None,	32)	0	['up_sampling2d_6[0][0]' 'conv2d_7[0][0]']
final_conv (Conv2D)	(None, None,	None,	5)	1445	['add_6[0][0]']

\_\_\_\_\_\_

Total params: 2060997 (7.86 MB)
Trainable params: 2057221 (7.85 MB)
Non-trainable params: 3776 (14.75 KB)

\_\_\_\_\_\_

None

# 2.3.7 Inference using Saved U-Net Model

Now we can use the saved model to start the export of the prediction of the image. For prediction, you would need to first prepare your image data. We have already exported the image needed here, which we will use for now. See this notebook to understand how we did it.

In addition, this notebook shows how you can then use the image to predict from the saved Model.

In any case, you now have the prediction in the Earth Engine as image.

# 2.4 DNN Model

## 2.4.1 Setup any changes in the config file for DNN Model

There are few config variables that needs to be changed for running a DNN model. First would be the data itself so let's change the DATADIR. We also need to change our output directory using MODEL\_DIR\_NAME. This is the sub-directory inside the OUTPUT\_DIR for this model run. We also need to specify this is the DNN model that we want to run. We have MODEL\_TYPE parameter for that. Currently, it supports unet, dnn, and cnn (case sensitive) models; default being unet. Make other changes, as appropriate.

```
DATADIR = "datasets/dnn_planet_wo_indices"
MODEL_DIR_NAME = "dnn_v1"
MODEL TYPE = "dnn"
```

## 2.4.2 Update the config file programtically

```
DATADIR = "datasets/dnn_planet_wo_indices" # @param {type:"string"}
# PATCH_SHAPE, USE_ELEVATION, USE_S1, TRAIN_SIZE, TEST_SIZE, VAL_SIZE
# BATCH_SIZE, EPOCHS are converted to their appropriate type.
MODEL_DIR_NAME = "dnn_v1" # @param {type:"string"}
```

## 2.4.3 Load config file variables for DNN Model

```
dnn_config = Config(config_file=config_file, override=True)

BASEDIR: /content
DATADIR: /content/datasets/dnn_planet_wo_indices
using features: ['red_before', 'green_before', 'blue_before', 'nir_before', 'red_during', 'g.
using labels: ['class']

Most of the config in the config.env is now available via the config instance. Let's check few
of them here.

dnn_config.TRAINING_DIR, dnn_config.OUTPUT_DIR, dnn_config.BATCH_SIZE, dnn_config.MODEL_TYPE

(PosixPath('/content/datasets/dnn_planet_wo_indices/training'),
    PosixPath('/content/drive/MyDrive/Colab Notebooks/DL_Book/Chapter_1/output'),
    32,
    'dnn')
```

#### 2.4.4 Load ModelTrainer class

Next, let's make an instance of the ModelTrainer object. The ModelTrainer class provides various tools for training, building, compiling, and running specified deep learning models.

```
dnn_model_trainer = ModelTrainer(dnn_config, seed=42)
```

Using seed: 42

#### 2.4.5 Train and Save DNN model

```
dnn_model_trainer.train_model()
************************************
> Found 1 GPUs
Loading dataset from /content/datasets/dnn_planet_wo_indices/training/*
Loading dataset from /content/datasets/dnn_planet_wo_indices/validation/*
Loading dataset from /content/datasets/dnn_planet_wo_indices/testing/*
Printing dataset info:
Training
inputs: float32 (32, 1, 8)
tf.Tensor(
[[[0.06445 0.0383
             0.09815  0.06755  0.269975  0.207325  0.11135
 0.060025]]
[[0.075925 0.02705 0.08695 0.054775 0.235575 0.291625 0.1049
 0.0364 ]]
[[0.043625 0.025
             0.064175 0.04265 0.22
                              0.225
                                    0.062025
 0.03195 ]]
[[0.07915 0.05365 0.1054
                   0.093425 0.257325 0.28345 0.1119
 0.079675]]
[[0.06945  0.025825  0.10755  0.062125  0.245125  0.28365  0.116975
```

- 0.0485 ]]
- [[0.092425 0.07485 0.10285 0.09645 0.238575 0.252075 0.123025 0.094825]]

- [[0.072725 0.030975 0.10185 0.0666 0.26585 0.38635 0.11875 0.045725]]
- [[0.0713 0.0289 0.09355 0.06415 0.236675 0.2564 0.10215 0.049475]]
- [[0.086175 0.077875 0.10745 0.0709 0.263475 0.289175 0.1188 0.075975]]
- [[0.079575 0.027525 0.102325 0.054775 0.253875 0.2761 0.111325 0.03985 ]]
- [[0.08825 0.0803 0.1016 0.0862 0.265025 0.260925 0.115625 0.092325]]
- [[0.08025 0.10325 0.1034 0.13695 0.2283 0.246475 0.109975 0.124 ]]
- [[0.077775 0.029875 0.0953 0.0546 0.235325 0.266 0.122125 0.0469 ]]
- [[0.089475 0.070675 0.10515 0.09125 0.257725 0.254375 0.132675 0.09745 ]]

- [[0.0785 0.026275 0.105575 0.051025 0.2552 0.2522 0.120125 0.034825]]
- [[0.07945 0.045775 0.094475 0.0652 0.264175 0.335825 0.1147 0.059275]]
- [[0.04725 0.031125 0.08165 0.065325 0.23025 0.2299 0.0981 0.060525]]

- [[0.067125 0.026625 0.093575 0.05095 0.255925 0.231575 0.10545 0.0415 ]]
- [[0.076325 0.02685 0.10615 0.05585 0.25805 0.276325 0.116725 0.0417 ]]
- [[0.061275 0.023975 0.086025 0.041375 0.199425 0.255125 0.111 0.030825]]
- [[0.059725 0.0203 0.0877 0.0434 0.230125 0.251975 0.105675 0.027225]]
- [[0.07205 0.02285 0.094025 0.04865 0.2084 0.247225 0.119175 0.03225 ]]
- [[0.07005 0.023125 0.111925 0.0475 0.2716 0.2495 0.124725 0.0313 ]]], shape=(32, 1, 8), dtype=float32)

outputs: float32 (32, 1, 5)

tf.Tensor(

[[[0. 1. 0. 0. 0.]]

- [[0. 1. 0. 0. 0.]]
- [[0. 1. 0. 0. 0.]]
- [[0. 0. 0. 1. 0.]]
- [[0. 1. 0. 0. 0.]]
- [[0. 0. 0. 1. 0.]]
- [[0. 1. 0. 0. 0.]]
- [[1. 0. 0. 0. 0.]]
- [[0. 0. 1. 0. 0.]]
- [[0. 1. 0. 0. 0.]]
- [[0. 1. 0. 0. 0.]]
- [[0. 1. 0. 0. 0.]]
- [[0. 0. 0. 1. 0.]]
- [[0. 1. 0. 0. 0.]]
- [[0. 0. 0. 1. 0.]]
- [[0. 0. 0. 1. 0.]]
- [[0. 0. 0. 1. 0.]]
- [[0. 0. 0. 1. 0.]]
- [[0. 0. 0. 1. 0.]]
- [[0. 1. 0. 0. 0.]]
- [[0. 1. 0. 0. 0.]]
- [[0. 0. 1. 0. 0.]]
- [[0. 1. 0. 0. 0.]]

```
[[0. 1. 0. 0. 0.]]
 [[0. 1. 0. 0. 0.]]
 [[0. 1. 0. 0. 0.]]
 [[0. 1. 0. 0. 0.]]
 [[0. 1. 0. 0. 0.]]
 [[0. 1. 0. 0. 0.]]
 [[0. 0. 0. 0. 1.]]
 [[0. 0. 1. 0. 0.]]
 [[0. 1. 0. 0. 0.]]], shape=(32, 1, 5), dtype=float32)
Testing
inputs: float32 (1, 1, 8)
tf.Tensor(
[[[0.06205 0.0342 0.081075 0.0639
                                  0.24245 0.251675 0.086575
  0.054175]]], shape=(1, 1, 8), dtype=float32)
outputs: float32 (1, 1, 5)
tf.Tensor([[[1. 0. 0. 0. 0.]]], shape=(1, 1, 5), dtype=float32)
Validation
inputs: float32 (1, 1, 8)
tf.Tensor(
[[[0.067225 0.031725 0.092275 0.07245 0.23165 0.2267
                                                   0.103025
  0.05155 ]]], shape=(1, 1, 8), dtype=float32)
outputs: float32 (1, 1, 5)
tf.Tensor([[[0. 0. 0. 1. 0.]]], shape=(1, 1, 5), dtype=float32)
******************** building and compiling model... *************
INITIAL BIAS: None
Model: "model"
Layer (type)
              Output Shape Param #
 input_layer (InputLayer) [(None, None, 8)]
```

(None, None, 256)

2304

dense (Dense)

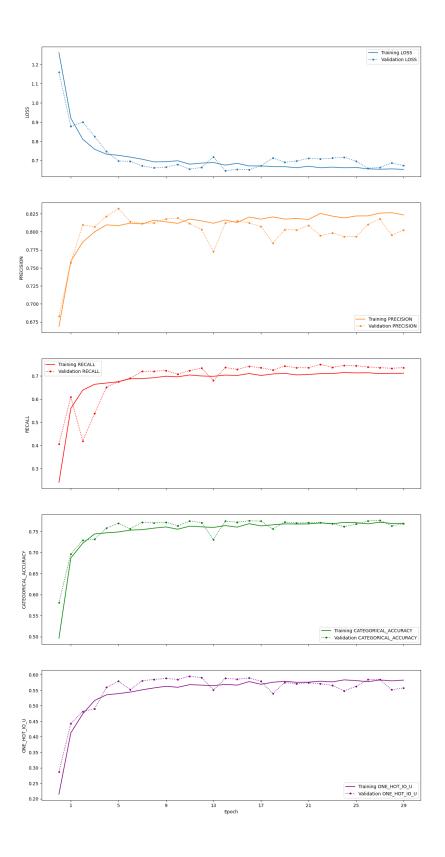
```
dropout (Dropout)
                                                                                                 0
                                                   (None, None, 256)
 dense_1 (Dense)
                                                                                                 32896
                                                   (None, None, 128)
 dropout_1 (Dropout)
                                                   (None, None, 128)
                                                                                                 0
 dense 2 (Dense)
                                                   (None, None, 64)
                                                                                                 8256
 dropout_2 (Dropout)
                                                   (None, None, 64)
                                                                                                 0
 dense_3 (Dense)
                                                                                                 2080
                                                   (None, None, 32)
 dropout_3 (Dropout)
                                                    (None, None, 32)
 dense_4 (Dense)
                                                    (None, None, 5)
                                                                                                 165
Total params: 45701 (178.52 KB)
Trainable params: 45701 (178.52 KB)
Non-trainable params: 0 (0.00 Byte)
None
***********************************
> Saving models and results at /content/drive/MyDrive/Colab Notebooks/DL_Book/Chapter_1/outp
************************************
****************************** training model... *******************
Epoch 1/30
Epoch 1: val_loss improved from inf to 1.15955, saving model to /content/drive/MyDrive/Colab
Epoch 2/30
Epoch 2: val_loss improved from 1.15955 to 0.87784, saving model to /content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive
Epoch 3/30
Epoch 3: val_loss did not improve from 0.87784
Epoch 4/30
```

```
Epoch 5/30
Epoch 5: val loss improved from 0.82494 to 0.74722, saving model to /content/drive/MyDrive/C
Epoch 6/30
Epoch 6: val loss improved from 0.74722 to 0.69727, saving model to /content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive
Epoch 7/30
Epoch 7: val loss improved from 0.69727 to 0.69563, saving model to /content/drive/MyDrive/C
Epoch 8/30
Epoch 8: val_loss improved from 0.69563 to 0.67199, saving model to /content/drive/MyDrive/C
Epoch 9/30
Epoch 9: val_loss improved from 0.67199 to 0.66129, saving model to /content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/Content/drive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive
Epoch 10/30
Epoch 10: val_loss did not improve from 0.66129
Epoch 11/30
Epoch 11: val_loss did not improve from 0.66129
Epoch 12/30
Epoch 12: val_loss improved from 0.66129 to 0.65464, saving model to /content/drive/MyDrive/
Epoch 13/30
Epoch 13: val loss did not improve from 0.65464
Epoch 14/30
Epoch 14: val_loss did not improve from 0.65464
Epoch 15/30
```

Epoch 15: val\_loss improved from 0.65464 to 0.64675, saving model to /content/drive/MyDrive/

```
Epoch 16/30
Epoch 16: val_loss did not improve from 0.64675
Epoch 17/30
Epoch 17: val_loss did not improve from 0.64675
Epoch 18/30
Epoch 18: val_loss did not improve from 0.64675
Epoch 19/30
Epoch 19: val_loss did not improve from 0.64675
Epoch 20/30
Epoch 20: val loss did not improve from 0.64675
Epoch 21/30
Epoch 21: val_loss did not improve from 0.64675
Epoch 22/30
Epoch 22: val_loss did not improve from 0.64675
Epoch 23/30
Epoch 23: val_loss did not improve from 0.64675
Epoch 24/30
Epoch 24: val_loss did not improve from 0.64675
Epoch 25/30
Epoch 25: val_loss did not improve from 0.64675
Epoch 26/30
```

```
Epoch 26: val_loss did not improve from 0.64675
Epoch 27/30
Epoch 27: val loss did not improve from 0.64675
Epoch 28/30
Epoch 28: val_loss did not improve from 0.64675
Epoch 29/30
Epoch 29: val_loss did not improve from 0.64675
Epoch 30/30
Epoch 30: val_loss did not improve from 0.64675
***********************************
******************************* evaluating model... *******************
**************
***************
Validation
loss: 0.6584734320640564
precision: 0.8037974834442139
recall: 0.7292863130569458
categorical_accuracy: 0.7735849022865295
one_hot_io_u: 0.5688682794570923
**********************************
****** saving model config and history object... ************
*******************************
*********************** saving plots... *****************
Saving plots and model visualization at /content/drive/MyDrive/Colab Notebooks/DL_Book/Chapt
***********************************
*********************** saving models... ******************
***********************************
```



## 2.4.6 Save the config file

```
drive_config_file = Path(dnn_config.MODEL_DIR / f"{str(config_file).split('/')[-1]}")
# Create the target directory if it doesn't exist
drive_config_file.parent.mkdir(parents=True, exist_ok=True)
# Copy the file
shutil.copy(config_file, drive_config_file)
print(f"File copied from {config_file} to {drive_config_file}")
```

File copied from servir-aces/config.env to /content/drive/MyDrive/Colab Notebooks/DL\_Book/Characteristics.

#### 2.4.7 Load the logs files via TensorBoard

```
log_dir_dnn = f"{str(dnn_config.MODEL_DIR)}/logs"
log_dir_dnn

'/content/drive/MyDrive/Colab Notebooks/DL_Book/Chapter_1/output/dnn_v1/logs'

%tensorboard --logdir "{log_dir_dnn}"

<IPython.core.display.Javascript object>
```

#### 2.4.8 Load the Saved DNN Model

```
dnn_model = tf.keras.models.load_model(f"{str(dnn_config.MODEL_DIR)}/trained-model")
print(dnn_model.summary())

Model: "model"

Layer (type) Output Shape Param #
```

<pre>input_layer (InputLayer)</pre>	[(None, None, 8)]	0
dense (Dense)	(None, None, 256)	2304
dropout (Dropout)	(None, None, 256)	0
dense_1 (Dense)	(None, None, 128)	32896
<pre>dropout_1 (Dropout)</pre>	(None, None, 128)	0
dense_2 (Dense)	(None, None, 64)	8256
<pre>dropout_2 (Dropout)</pre>	(None, None, 64)	0
dense_3 (Dense)	(None, None, 32)	2080
<pre>dropout_3 (Dropout)</pre>	(None, None, 32)	0
dense_4 (Dense)	(None, None, 5)	165

Total params: 45701 (178.52 KB)
Trainable params: 45701 (178.52 KB)
Non-trainable params: 0 (0.00 Byte)

\_\_\_\_\_

None

# 2.4.9 Inference using Saved DNN Model

Now we can use the saved model to start the export of the prediction of the image. For prediction, you would need to first prepare your image data. We have already exported the image needed here, which we will use for now. See this notebook to understand how we did it.

In addition, this notebook shows how you can then use the image to predict from the saved Model.

In any case, you now have the prediction in the Earth Engine as image.

# 2.5 Independent Validation

For independent validation, we will use a file that we have prepared. These files were collected using Collect Earth Online by SCO and NASA DEVELOP interns. We will be using GEE here. Before we do that, let's make changes in our config file.

We will make sure our GCS\_PROJECT is setup correctly.

```
GCS_PROJECT = "servir-ee"
```

## 2.5.1 Update the config file

#### 2.5.2 Load config file variable

```
config = Config(config_file=config_file, override=True)

BASEDIR: /content

DATADIR: /content/datasets/dnn_planet_wo_indices
using features: ['red_before', 'green_before', 'blue_before', 'nir_before', 'red_during', 'green_bels: ['class']
```

#### 2.5.3 Import earthengine and geemap for visualization

```
# Import, authenticate and initialize the Earth Engine library.
import ee
ee.Authenticate()
EEUtils.initialize_session(use_highvolume=True, project=config.GCS_PROJECT)
import geemap
Map = geemap.Map()
```

# 2.5.4 Class Information and Masking

```
# CLASS
# 0 - cropland etc.
# 1 - rice
# 2 - forest
# 3 - Built up
# 4 - Others (includes water body)
11 = ee.FeatureCollection("projects/servir-sco-assets/assets/Bhutan/BT_Admin_1")
paro = l1.filter(ee.Filter.eq("ADM1_EN", "Paro"))

# mask the rice growing zone
# in Paro, rice grows upto 2600 m asl (double check to make sure??)
dem = ee.Image("MERIT/DEM/v1_0_3") # ee.Image('USGS/SRTMGL1_003')
dem = dem.clip(paro)
rice_zone = dem.gte(0).And(dem.lte(2600))
```

<IPython.core.display.HTML object>

#### 2.5.5 Model: U-Net

# 2.5.5.1 Load and visualize the prediction output

```
UNET_RGBN = ee.Image("projects/servir-ee/assets/dl-book/chapter-1/prediction/prediction_unet_
UNET_RGBN = UNET_RGBN.updateMask(rice_zone)
Map.centerObject(UNET_RGBN, 11)
Map.addLayer(UNET_RGBN.clip(paro), {"bands": ["prediction"], "min":0, "max":4, "palette": ["]
Map
```

```
<IPython.core.display.HTML object>
```

Map(center=[27.378354616518475, 89.42005508391453], controls=(WidgetControl(options=['positions=])

#### 2.5.5.2 Calculate classification metrics

Remapping to rice and non-rice output

```
UNET_RGBN_remapped = UNET_RGBN.remap([0, 1, 2, 3, 4], [0, 1, 0, 0, 0], 0, "prediction")
Map.addLayer(UNET_RGBN_remapped, {"min": 0, "max": 1, "palette": ["cfcf00", "267300"]}, "UNE"
<IPython.core.display.HTML object>
Map(bottom=220961.0, center=[27.378354616518475, 89.42005508391453], controls=(WidgetControl
sampling_geom = ee.FeatureCollection("projects/servir-ee/assets/dl-book/chapter-1/data/sample
ceo_final_data = ee.FeatureCollection("projects/servir-ee/assets/dl-book/chapter-1/data/ceoDe
ceo_final_data = ee.FeatureCollection(ceo_final_data.filter(ee.Filter.bounds(sampling_geom).)
<IPython.core.display.HTML object>
prediction_unet = UNET_RGBN_remapped.sampleRegions(
    collection = ceo_final_data,
    scale = 10,
    geometries = True
# print("predictionOutputUnet", prediction_unet.getInfo())
<IPython.core.display.HTML object>
error_matrix_unet = prediction_unet.errorMatrix(actual="rice", predicted="remapped")
test_acc_unet = error_matrix_unet.accuracy()
test_kappa_unet = error_matrix_unet.kappa()
test_recall_producer_acc_unet = error_matrix_unet.producersAccuracy().get([1, 0])
test_precision_consumer_acc_unet = error_matrix_unet.consumersAccuracy().get([0, 1])
```

f1\_unet = error\_matrix\_unet.fscore().get([1])

```
<IPython.core.display.HTML object>
```

```
print("error_matrix_unet", error_matrix_unet.getInfo())
print("test_acc_unet", test_acc_unet.getInfo())
print("test_kappa_unet", test_kappa_unet.getInfo())
print("test_recall_producer_acc_unet", test_recall_producer_acc_unet.getInfo())
print("test_precision_consumer_acc_unet", test_precision_consumer_acc_unet.getInfo())
print("f1_unet", f1_unet.getInfo())

<pre
```

#### 2.5.5.3 Calculate Probability Distribution

```
prob_output_unet = UNET_RGBN.select(["prediction", "others_etc", "cropland_etc", "urban", "forename(["prediction_class", "others_prob", "cropland_prob", "urban", "urban", "cropland_prob", "cropland_prob", "urban", "cropland_prob", "urban", "cropland_prob", "cropland_prob", "urban", "cropland_prob", "cropland_prob", "urban", "cropland_prob", "cropland_p
```

<IPython.core.display.HTML object>

## 2.5.6 Model: DNN

#### 2.5.6.1 Load and visualize the prediction output

```
DNN_RGBN = ee.Image("projects/servir-ee/assets/dl-book/chapter-1/prediction/prediction_dnn_v
DNN_RGBN = DNN_RGBN.updateMask(rice_zone)
Map.centerObject(DNN_RGBN)
Map.addLayer(DNN_RGBN.clip(paro), {"bands": ["prediction"], "min":0, "max":4, "palette": ["Fi
Map
<IPython.core.display.HTML object>
Map(bottom=220961.0, center=[27.378354616518475, 89.42005508391453], controls=(WidgetControl
2.5.6.2 Calculate classification metrics
DNN_RGBN_remapped = DNN_RGBN.remap([0, 1, 2, 3, 4], [0, 1, 0, 0, 0], 0, "prediction")
Map.addLayer(DNN_RGBN_remapped, {"min": 0, "max": 1, "palette": ["cfcf00", "267300"]}, "DNN_I
Map
<IPython.core.display.HTML object>
Map(bottom=220961.0, center=[27.37845188654284, 89.42005507220328], controls=(WidgetControl(
prediction_dnn = DNN_RGBN_remapped.sampleRegions(
    collection = ceo_final_data,
    scale = 10,
    geometries = True
)
# print("predictionOutputDNN", prediction_dnn.getInfo())
<IPython.core.display.HTML object>
error_matrix_dnn = prediction_dnn.errorMatrix(actual="rice", predicted="remapped")
test_acc_dnn = error_matrix_dnn.accuracy()
test_kappa_dnn = error_matrix_dnn.kappa()
test_recall_producer_acc_dnn = error_matrix_dnn.producersAccuracy().get([1, 0])
test_precision_consumer_acc_dnn = error_matrix_dnn.consumersAccuracy().get([0, 1])
```

f1\_dnn = error\_matrix\_dnn.fscore().get([1])

```
<IPython.core.display.HTML object>
```

#### 2.5.6.3 Calculate Probability Distribution

<IPython.core.display.HTML object>

## 2.6 Figures and Plots

## 2.6.1 Training and Validation Plot

```
import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
import pickle

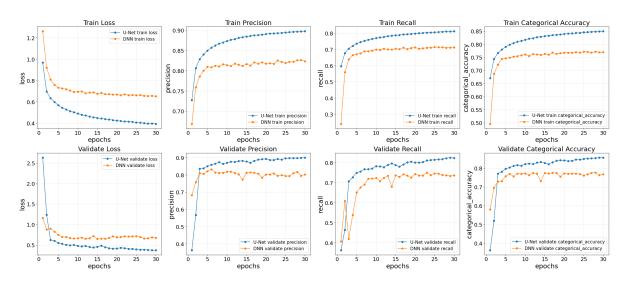
%matplotlib inline
```

```
with open(unet_config.MODEL_DIR / "model.pkl", "rb") as f:
    unet_model_metrics = pickle.load(f)

with open(dnn_config.MODEL_DIR / "model.pkl", "rb") as f:
    dnn_model_metrics = pickle.load(f)
```

```
# Create subplots for different metrics in a 3x4 grid
fig, axs = plt.subplots(2, 4, figsize=(4*7, 6*2))
colors = ["#1f77b4", "#ff7f0e", "#2ca02c", "#d62728"]
metrics = ["loss", "precision", "recall", "categorical_accuracy"]
metrics_name = ["Loss", "Precision", "Recall", "Categorical Accuracy"]
epochs = range(1, config.EPOCHS + 1)
title_fontsize = 22
label_fontsize = 22
legend_fontsize = 15
tick_fontsize = 18
lw=1.5
for i in range(2):
    for y in range(len(metrics)):
        if i == 1:
            axs[i][y].plot(epochs, unet_model_metrics[f"val_{metrics[y]}"], color=colors[0],
            axs[i][y].plot(epochs, dnn_model_metrics[f"val_{metrics[y]}"], color=colors[1],
            axs[i][y].set_title(f"Validate {metrics_name[y]}", fontsize=title_fontsize)
            axs[i][y].set_xlabel("epochs", fontsize=label_fontsize)
            axs[i][y].set_ylabel(f"{metrics[y]}", fontsize=label_fontsize)
```

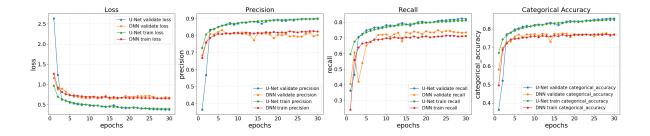
```
axs[i][y].grid(linestyle="dotted", alpha=0.7)
                                         axs[i][y].legend(fontsize=legend_fontsize)
                                         axs[i][y].tick_params(axis="both", which="major", labelsize=tick_fontsize)
                           else:
                                         axs[i][y].plot(epochs, unet_model_metrics[metrics[y]], color=colors[0], lw=lw, makes axs[i][y].plot(epochs, unet_model_metrics[metrics[y]], color=colors[0], lw=lw, makes axs[i][y].plot(epochs, unet_model_metrics[metrics[websites]]), color=colors[0], lw=lw, makes axs[i][y].plot(epochs, unet_model_metrics[websites]]), color=colors[0], lw=lw, makes axs[i][y].plot(epochs, unet_model_metrics[websites]]), color=colors[0], lw=lw, makes axs[i][y].plot(epochs, unet_model_metrics[websites]]), color=colors[0], lw=lw, unet_model_metrics[websites]]), color=colo
                                         axs[i][y].plot(epochs, dnn_model_metrics[metrics[y]], color=colors[1], lw=lw, max
                                         axs[i][y].set_title(f"Train {metrics_name[y]}", fontsize=title_fontsize)
                                         axs[i][y].set_xlabel("epochs", fontsize=label_fontsize)
                                         axs[i][y].set_ylabel(f"{metrics[y]}", fontsize=label_fontsize)
                                         axs[i][y].grid(linestyle="dotted", alpha=0.7)
                                         axs[i][y].legend(fontsize=legend_fontsize)
                                         axs[i][y].tick_params(axis="both", which="major", labelsize=tick_fontsize)
# Adjust layout and show the plot
plt.tight_layout()
# plt.savefig("metrics_plot_model_comparison.png", dpi=500, bbox_inches="tight")
plt.show()
```



```
# Create subplots for different metrics in a 3x4 grid
fig, axs = plt.subplots(1, 4, figsize=(4*7, 6*1))

colors = ["#1f77b4", "#ff7f0e", "#2ca02c", "#d62728"]
metrics = ["loss", "precision", "recall", "categorical_accuracy"]
```

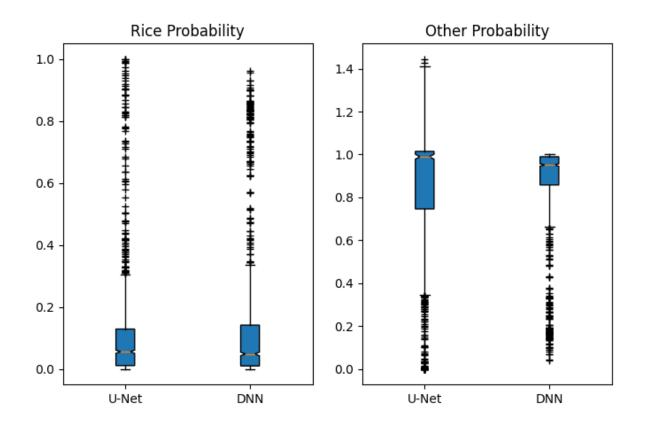
```
metrics name = ["Loss", "Precision", "Recall", "Categorical Accuracy"]
epochs = range(1, config.EPOCHS + 1)
title fontsize = 22
label_fontsize = 22
legend_fontsize = 15
tick_fontsize = 18
lw=1.5
for y in range(len(metrics)):
    axs[y].plot(epochs, unet_model_metrics[f"val_{metrics[y]}"], color=colors[0], marker="o"
    axs[y].plot(epochs, dnn_model_metrics[f"val_{metrics[y]}"], color=colors[1], lw=lw, mark
    axs[y].plot(epochs, unet_model_metrics[metrics[y]], color=colors[2], lw=lw, marker="o",
    axs[y].plot(epochs, dnn_model_metrics[metrics[y]], color=colors[3], lw=lw, marker="o", landametrics[y]], color=colors[3], lw=lw, marker="o", landametrics[y]]
    axs[y].set_title(f"{metrics_name[y]}", fontsize=title_fontsize)
    axs[y].set_xlabel("epochs", fontsize=label_fontsize)
    axs[y].set_ylabel(f"{metrics[y]}", fontsize=label_fontsize)
    axs[y].grid(linestyle="dotted", alpha=0.7)
    axs[y].legend(fontsize=legend_fontsize)
    axs[y].tick_params(axis="both", which="major", labelsize=tick_fontsize)
# Adjust layout and show the plot
plt.tight_layout()
# plt.savefig("metrics_plot_model_comparison.png", dpi=500, bbox_inches="tight")
plt.show()
```



## 2.6.2 Probability Distribution Plot

```
all_data = {}
unet_data = []
dnn_data = []
unet_rice_data = []
dnn_rice_data = []
unet_other_data = []
dnn_other_data = []
for i, feature in enumerate(prob_output_unet["features"]):
    unet_rice_prob = round(feature["properties"]["rice_prob"], 5)
    unet_other_prob = round(feature["properties"]["cropland_prob"] + round(feature["properties"])
    unet_data.append([unet_rice_prob, unet_other_prob])
    unet_rice_data.append(unet_rice_prob)
    unet_other_data.append(unet_other_prob)
    dnn_feature = prob_output_dnn["features"][i]
    dnn_rice_prob = round(dnn_feature["properties"]["rice_prob"], 5)
    dnn_other_prob = 1. - round(dnn_feature["properties"]["rice_prob"], 5)
    # dnn_other_prob = round(dnn_feature["properties"]["cropland_prob"] + dnn_feature["properties"]
    dnn_data.append([dnn_rice_prob, dnn_other_prob])
    dnn_rice_data.append(dnn_rice_prob)
    dnn_other_data.append(dnn_other_prob)
```

Text(0.5, 1.0, 'Other Probability')



# 3 Object Detection

```
# Print out the Python version used by this environment.
import sys
print(f'{sys.version=}')
```

sys.version='3.9.0 | packaged by conda-forge | (default, Nov 26 2020, 07:55:15) \n[Clang 11.

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Nunc ac dignissim magna. Vestibulum vitae egestas elit. Proin feugiat leo quis ante condimentum, eu ornare mauris feugiat. Pellentesque habitant morbi tristique senectus et netus et malesuada fames ac turpis egestas. Mauris cursus laoreet ex, dignissim bibendum est posuere iaculis. Suspendisse et maximus elit. In fringilla gravida ornare. Aenean id lectus pulvinar, sagittis felis nec, rutrum risus. Nam vel neque eu arcu blandit fringilla et in quam. Aliquam luctus est sit amet vestibulum eleifend. Phasellus elementum sagittis molestie. Proin tempor lorem arcu, at condimentum purus volutpat eu. Fusce et pellentesque ligula. Pellentesque id tellus at erat luctus fringilla. Suspendisse potenti.

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Duis ornare ex ac iaculis pretium. Maecenas sagittis odio id erat pharetra, sit amet consectetur quam sollicitudin. Vivamus pharetra quam purus, nec sagittis risus pretium at. Nullam feugiat, turpis ac accumsan interdum, sem tellus blandit neque, id vulputate diam quam semper nisl. Donec sit amet enim at neque porttitor aliquet. Phasellus facilisis nulla eget placerat eleifend. Vestibulum non egestas eros, eget lobortis ipsum. Nulla rutrum massa eget enim aliquam, id porttitor erat luctus. Nunc sagittis quis eros eu sagittis. Pellentesque dictum, erat at pellentesque sollicitudin, justo augue pulvinar metus, quis rutrum est mi nec felis. Vestibulum efficitur mi lorem, at elementum purus tincidunt a. Aliquam finibus enim magna, vitae pellentesque erat faucibus at. Nulla mauris tellus, imperdiet id lobortis et, dignissim condimentum ipsum. Morbi nulla orci, varius at aliquet sed, facilisis id tortor. Donec ut urna nisi.

## 4 Time Series

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Nunc ac dignissim magna. Vestibulum vitae egestas elit. Proin feugiat leo quis ante condimentum, eu ornare mauris feugiat. Pellentesque habitant morbi tristique senectus et netus et malesuada fames ac turpis egestas. Mauris cursus laoreet ex, dignissim bibendum est posuere iaculis. Suspendisse et maximus elit. In fringilla gravida ornare. Aenean id lectus pulvinar, sagittis felis nec, rutrum risus. Nam vel neque eu arcu blandit fringilla et in quam. Aliquam luctus est sit amet vestibulum eleifend. Phasellus elementum sagittis molestie. Proin tempor lorem arcu, at condimentum purus volutpat eu. Fusce et pellentesque ligula. Pellentesque id tellus at erat luctus fringilla. Suspendisse potenti.

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## 5 Ecological Processes Simulation

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# 6 Transfer Learning

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## 7 Fusion

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# 8 Downscaling

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Etiam maximus accumsan gravida. Maecenas at nunc dignissim, euismod enim ac, bibendum ipsum. Maecenas vehicula velit in nisl aliquet ultricies. Nam eget massa interdum, maximus arcu vel, pretium erat. Maecenas sit amet tempor purus, vitae aliquet nunc. Vivamus cursus urna velit, eleifend dictum magna laoreet ut. Duis eu erat mollis, blandit magna id, tincidunt ipsum. Integer massa nibh, commodo eu ex vel, venenatis efficitur ligula. Integer convallis lacus elit, maximus eleifend lacus ornare ac. Vestibulum scelerisque viverra urna id lacinia. Vestibulum ante ipsum primis in faucibus orci luctus et ultrices posuere cubilia curae; Aenean eget enim at diam bibendum tincidunt eu non purus. Nullam id magna ultrices, sodales metus viverra, tempus turpis.

# 9 Future of Deep Learning and Foundational Models

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# 10 Ethics and Artificial Intelligence

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## **Conclusions**

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