## **QA** report of frames.py

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QA performed by: Sanket Chirame

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- 1. Latlon function:
  - a. Changed all numbers to float.
  - b. 180 degree longitude was returned as pi instead of 180
- 2. Ecif2ecef:
  - a. There was mistake in calculation of time. The variable 't' denotes the time since the launch of satellite. But ecif and ecef frames are aligned at equinox. Thus time from equinox to launch needs to be added in 't'
- 3. Import statement was importing entire constants file. Changed it to import only required variables.
- 4. Added comments for better explanation.