Student Satellite Project
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Website: www.aero.iitb.ac.in/satlab

Readme file for default_blocks.py
Attitude Determination and Control Subsystem

sensor

Author: Riya
Date: 28 September, 2018
Default models of sensor : (ideal sensor) measured output = actual output (no noise or bias)

controller

Author: Riya
Date: 28 September, 2018
Default models of controller: (no controller)

environment

Author: Riya
Date: 28 September, 2018
Default models of environment: (no disturbance)

estimator

Author: Riya
Date: 28 September, 2018
Default models of estimator: (returns qBO obtained by integrator)