

```

/*
Problem Statement: Design suitable data structures and implement pass-I of a two-pass assembler for
pseudo-
machine in Java using object oriented feature. Implementation should consist of a few
instructions from each category and few assembler directives.
*/
import java.io.*;
class SymTab
{
    public static void main(String args[])throws Exception
    {
        FileReader FP=new FileReader(args[0]);
        BufferedReader bufferedReader = new BufferedReader(FP);

        String line=null;
        int line_count=0,LC=0,symTabLine=0,opTabLine=0,litTabLine=0,poolTabLine=0;

        //Data Structures
        final int MAX=100;
        String SymbolTab[][]=new String[MAX][3];
        String OpTab[][]=new String[MAX][3];
        String LitTab[][]=new String[MAX][2];
        int PoolTab[]=new int[MAX];
        int litTabAddress=0;

/*-----*/

        System.out.println("_____");
        while((line = bufferedReader.readLine()) != null)
        {
            String[] tokens = line.split("\\t");
            if(line_count==0)
            {
                LC=Integer.parseInt(tokens[2]);
                //set LC to operand of START
                for(int i=0;i<tokens.length;i++) //for printing the input program
                    System.out.print(tokens[i]+"\\t");
                System.out.println("");
            }
            else
            {
                for(int i=0;i<tokens.length;i++) //for printing the input program
                    System.out.print(tokens[i]+"\\t");
            }
        }
    }
}

```

```

        System.out.println("");
        if(!tokens[0].equals(""))
        {

            //Inserting into Symbol Table
            SymbolTab[symTabLine][0]=tokens[0];
            SymbolTab[symTabLine][1]=Integer.toString(LC);
            SymbolTab[symTabLine][2]=Integer.toString(1);
            symTabLine++;
        }
        else
        if(tokens[1].equalsIgnoreCase("DS") || tokens[1].equalsIgnoreCase("DC"))
        {

            //Entry into symbol table for declarative statements
            SymbolTab[symTabLine][0]=tokens[0];
            SymbolTab[symTabLine][1]=Integer.toString(LC);
            SymbolTab[symTabLine][2]=Integer.toString(1);
            symTabLine++;
        }

        if(tokens.length==3 && tokens[2].charAt(0)==' ')
        {

            //Entry of literals into literal table
            LitTab[litTabLine][0]=tokens[2];
            LitTab[litTabLine][1]=Integer.toString(LC);
            litTabLine++;
        }

        else if(tokens[1]!=null)
        {

            //Entry of Mnemonic in opcode table
            OpTab[opTabLine][0]=tokens[1];

            if(tokens[1].equalsIgnoreCase("START") || tokens[1].equalsIgnoreCase("END") || tokens[1].equalsIgnoreCase("ORIGIN") || tokens[1].equalsIgnoreCase("EQU") || tokens[1].equalsIgnoreCase("LTORG"))
            //if Assembler Directive
            {

                OpTab[opTabLine][1]="AD";
                OpTab[opTabLine][2]="R11";
            }
        }
    
```

```

        else
if(tokens[1].equalsIgnoreCase("DS") || tokens[1].equalsIgnoreCase("DC"))
    {
        OpTab[opTabLine][1]="DL";
        OpTab[opTabLine][2]="R7";

    }
    else
    {
        OpTab[opTabLine][1]="IS";
        OpTab[opTabLine][2]="(04,1)";

    }
    opTabLine++;
}
}
line_count++;
LC++;
}

```

```

System.out.println("_____");

```

```

//print symbol table
System.out.println("\n\n      SYMBOL TABLE      ");
System.out.println("-----");
System.out.println("SYMBOL\tADDRESS\tLENGTH");
System.out.println("-----");
for(int i=0;i<symTabLine;i++)

```

```

System.out.println(SymbolTab[i][0]+"\\t"+SymbolTab[i][1]+"\\t"+SymbolTab[i][2]);
System.out.println("-----");

```

```

//print opcode table
System.out.println("\n\n      OP CODE TABLE      ");
System.out.println("-----");
System.out.println("MNEMONIC\tCLASS\tINFO");
System.out.println("-----");
for(int i=0;i<opTabLine;i++)
    System.out.println(OpTab[i][0]+"\\t\\t"+OpTab[i][1]+"\\t"+OpTab[i][2]);
System.out.println("-----");

```

```

//print literal table
System.out.println("\n\n LITERAL TABLE          ");
System.out.println("-----");
System.out.println("LITERAL\tADDRESS");
System.out.println("-----");
for(int i=0;i<litTabLine;i++)
    System.out.println(LitTab[i][0]+"\\t"+LitTab[i][1]);
System.out.println("-----");

//initialization of POOLTAB
for(int i=0;i<litTabLine;i++)
{
    if(LitTab[i][0]!=null && LitTab[i+1][0]!=null ) //if literals are present
    {
        if(i==0)
        {
            PoolTab[poolTabLine]=i+1;
            poolTabLine++;
        }
        else
        if(Integer.parseInt(LitTab[i][1])<(Integer.parseInt(LitTab[i+1][1]))-1)
        {
            PoolTab[poolTabLine]=i+2;
            poolTabLine++;
        }
    }
}
//print pool table
System.out.println("\n\n POOL TABLE          ");
System.out.println("-----");
System.out.println("LITERAL NUMBER");
System.out.println("-----");
for(int i=0;i<poolTabLine;i++)
    System.out.println(PoolTab[i]);
System.out.println("-----");

// Always close files.
bufferedReader.close();
}
}

```

/*

OUTPUT-

neha@neha-1011PX:~/neha_SPOS\$ javac SymTab.java

neha@neha-1011PX:~/neha_SPOS\$ java SymTab input.txt

```
      START 100
      READ  A
LABEL MOVER A,B
      LTORG
          ='5'
          ='1'
          ='6'
          ='7'
      MOVEM      A,B
      LTORG
          ='2'
LOOP  READ  B
A     DS    1
B     DC    '1'
          ='1'
      END
```

SYMBOL TABLE

SYMBOL	ADDRESS	LENGTH

LABLE	102	1
LOOP	111	1
A	112	1
B	113	1

OPCODE TABLE

MNEMONIC	CLASS	INFO

READ	IS	(04,1)
MOVER	IS	(04,1)

LTORG	AD	R11	
MOVEM		IS	(04,1)
LTORG	AD	R11	
READ	IS	(04,1)	
DS	DL	R7	
DC	DL	R7	
END	AD	R11	

LITERAL TABLE

LITERAL ADDRESS

= '5'	104
= '1'	105
= '6'	106
= '7'	107
= '2'	110
= '1'	114

POOL TABLE

LITERAL NUMBER

1
5
6

*/

```
/*
```

Problem Statement: Implement Pass-II of two pass assembler for pseudo-machine in Java using object oriented

features. The output of assignment-1 (intermediate file and symbol table) should be input for this assignment.

```
*/
```

```
import java.io.BufferedReader;
```

```
import java.io.FileReader;
```

```
import java.io.FileWriter;
```

```
import java.io.IOException;
```

```
import java.util.HashMap;
```

```
public class Pass2 {
```

```
    public static void main(String[] Args) throws IOException{
```

```
        BufferedReader b1 = new BufferedReader(new FileReader("intermediate.txt"));
```

```
        BufferedReader b2 = new BufferedReader(new FileReader("symtab.txt"));
```

```
        BufferedReader b3 = new BufferedReader(new FileReader("littab.txt"));
```

```
        FileWriter f1 = new FileWriter("Pass2.txt");
```

```
        HashMap<Integer, String> symSymbol = new HashMap<Integer, String>();
```

```
        HashMap<Integer, String> litSymbol = new HashMap<Integer, String>();
```

```
        HashMap<Integer, String> litAddr = new HashMap<Integer, String>();
```

```
        String s;
```

```
        int symtabPointer=1,littabPointer=1,offset;
```

```
        while((s=b2.readLine())!=null){
```

```
            String word[]=s.split("\t\t");
```

```
            symSymbol.put(symtabPointer++,word[1]);
```

```
        }
```

```
        while((s=b3.readLine())!=null){
```

```
            String word[]=s.split("\t\t");
```

```
            litSymbol.put(littabPointer,word[0]);
```

```
            litAddr.put(littabPointer++,word[1]);
```

```
        }
```

```
        while((s=b1.readLine())!=null){
```

```
            if(s.substring(1,6).compareToIgnoreCase("IS,00")==0){
```

```
                f1.write("+ 00 0 000\n");
```

```
            }
```

```
            else if(s.substring(1,3).compareToIgnoreCase("IS")==0){
```

```
                f1.write("+ "+s.substring(4,6)+" ");
```

```
                if(s.charAt(9)==' '){
```

```
                    f1.write(s.charAt(8)+" ");
```

```
                    offset=3;
```

```
                }
```

```

        else{
            f1.write("0 ");
            offset=0;
        }
        if(s.charAt(8+offset)=='S')

f1.write(symSymbol.get(Integer.parseInt(s.substring(10+offset,s.length()-1))+"\n");
        else
            f1.write(litAddr.get(Integer.parseInt(s.substring(10+offset,s.length()-
1))+"\n");
    }
    else if(s.substring(1,6).compareToIgnoreCase("DL,01")==0){
        String s1=s.substring(10,s.length()-1),s2="";
        for(int i=0;i<3-s1.length();i++)
            s2+="0";
        s2+=s1;
        f1.write("+ 00 0 "+s2+"\n");
    }
    else{
        f1.write("\n");
    }
}
f1.close();
b1.close();
b2.close();
b3.close();
}
}

```

/*

OUTPUT:

neha@neha-1011PX:~/Desktop/neha_SPOS/Turn1/A2\$ javac Pass2.java

neha@neha-1011PX:~/Desktop/neha_SPOS/Turn1/A2\$ java Pass2

neha@neha-1011PX:~/Desktop/neha_SPOS/Turn1/A2\$ cat Pass2.txt

intermediate code -

(AD,01)(C,200)

(IS,04)(1)(L,1)

(IS,05)(1)(S,1)

(IS,04)(1)(S,1)

(IS,04)(3)(S,3)

(IS,01)(3)(L,2)

(IS,07)(6)(S,4)
 (DL,01)(C,5)
 (DL,01)(C,1)
 (IS,02)(1)(L,3)
 (IS,07)(1)(S,5)
 (IS,00)
 (AD,03)(S,2)+2
 (IS,03)(3)(S,3)
 (AD,03)(S,6)+1
 (DL,02)(C,1)
 (DL,02)(C,1)
 (AD,02)
 (DL,01)(C,1)

Symbol Table --

A	211	1
LOOP	202	1
B	212	1
NEXT	208	1
BACK	202	1
LAST	210	1

literal table --

5	206
1	207
1	213

machine code --

+ 04 1 206
 + 05 1 211
 + 04 1 211
 + 04 3 212
 + 01 3 207
 + 07 6 208
 + 00 0 005
 + 00 0 001
 + 02 1 213
 + 07 1 202
 + 00 0 000
 + 03 3 212 */

/* Problem Statement: Write a JAVA program (using oop features) to implement following

1. FCFS
2. SJF(Preemptive)
3. Priority(Non- Preemptive)
4. Round Robin(Preemptive)

1.FCFS

```
*/
import java.io.*;
import java.util.Scanner;
public class FCFS
{
    public static void main(String args[])
    {
        int i,no_p,burst_time[],TT[],WT[];
        float avg_wait=0,avg_TT=0;
        burst_time=new int[50];
        TT=new int[50];
        WT=new int[50];
        WT[0]=0;
        Scanner s=new Scanner(System.in);
        System.out.println("Enter the number of process: ");
        no_p=s.nextInt();
        System.out.println("\nEnter Burst Time for processes:");
        for(i=0;i<no_p;i++)
        {
            System.out.print("\tP"+(i+1)+" : ");
            burst_time[i]=s.nextInt();
        }

        for(i=1;i<no_p;i++)
        {
            WT[i]=WT[i-1]+burst_time[i-1];
            avg_wait+=WT[i];
        }
        avg_wait/=no_p;

        for(i=0;i<no_p;i++)
        {
            TT[i]=WT[i]+burst_time[i];
            avg_TT+=TT[i];
        }
    }
}
```

```

        avg_TT/=no_p;

        System.out.println("\n*****
        ****");
        System.out.println("\tProcesses:");

        System.out.println("*****
        **");
        System.out.println("  Process\tBurst Time\tWaiting Time\tTurn Around Time");
        for(i=0;i<no_p;i++)
        {
            System.out.println("\tP"+(i+1)+"\t "+burst_time[i]+\t\t "+WT[i]+\t\t "+TT[i]);

        }
        System.out.println("\n-----");
        System.out.println("\nAverage waiting time : "+avg_wait);
        System.out.println("\nAverage Turn Around time : "+avg_TT+"\n");
    }
}

```

/*Output:

Enter the number of process:

3

Enter Burst Time for processes:

P1: 24

P2: 3

P3: 3

Processes:

Process	Burst Time	Waiting Time	Turn Around Time
P1	24	0	24
P2	3	24	27
P3	3	27	30

Average waiting time : 17.0

Average Turn Around time : 27.0 */

```

/*Round Robin(Preemptive)*/
import java.util.*;
import java.io.*;
class RoundR
{
    public static void main(String args[])
    {
        int Process[]=new int[10];
        int a[]=new int[10];
        int Arrival_time[]=new int[10];
        int Burst_time[]=new int[10];
        int WT[]=new int[10];
        int TAT[]=new int[10];
        int Pno,sum=0;;
        int TimeQuantum;

System.out.println("\nEnter the no. of Process::");
        Scanner sc=new Scanner(System.in);
        Pno=sc.nextInt();
        System.out.println("\nEnter each process::");
        for(int i=0;i<Pno;i++)
        {
            Process[i]=sc.nextInt();
        }

System.out.println("\nEnter the Burst Time of each process::");
        for(int i=0;i<Pno;i++)
        {
            Burst_time[i]=sc.nextInt();
        }
System.out.println("\nEnter the Time Quantum::");
        TimeQuantum=sc.nextInt();
        do{
            for(int i=0;i<Pno;i++)
            {
                if(Burst_time[i]>TimeQuantum)
                {
                    Burst_time[i]-=TimeQuantum;
                    for(int j=0;j<Pno;j++)
                    {
                        if((j!=i)&&(Burst_time[j]!=0))
                            WT[j]+=TimeQuantum;
                    }
                }
            }
        } while (sum<Pno);
    }
}

```

```

        }
    }
    else
    {
        for(int j=0;j<Pno;j++)
        {
            if((j!=i)&&(Burst_time[j]!=0))
                WT[j]+=Burst_time[i];
        }
        Burst_time[i]=0;
    }
}

sum=0;
for(int k=0;k<Pno;k++)
    sum=sum+Burst_time[k];
} while(sum!=0);

for(int i=0;i<Pno;i++)
    TAT[i]=WT[i]+a[i];
System.out.println("process\t\tBT\tWT\tTAT");
for(int i=0;i<Pno;i++)
{
    System.out.println("process"+(i+1)+"\t"+a[i]+\t"+WT[i]+\t"+TAT[i]);
}

float avg_wt=0;
float avg_tat=0;
for(int j=0;j<Pno;j++)
{
    avg_wt+=WT[j];
}
for(int j=0;j<Pno;j++)
{
    avg_tat+=TAT[j];
}

System.out.println("average waiting time "+(avg_wt/Pno)+"\n Average turn around
time" +(avg_tat/Pno));
}
}

```

/*OUTPUT::

unix@unix-HP-280-G1-

MT:~/TEA33\$ java RoundR

Enter the no. of Process::

5

Enter each process::

1

2

3

4

5

Enter the Burst Time of each process::

2

1

8

4

5

Enter the Time Quantum::

2

process	BT	WT	TAT
process1	0	0	0
process2	0	2	2
process3	0	12	12
process4	0	9	9
process5	0	13	13

average waiting time 7.2

Average turn around time7.2 */

```

/*          2. SJF(Non-Preemptive)          */
import java.util.Scanner;
class SJF1{
public static void main(String args[]){
int burst_time[],process[],waiting_time[],tat[],i,j,n,total=0,pos,temp;
float wait_avg,TAT_avg;
Scanner s = new Scanner(System.in);

System.out.print("Enter number of process: ");
n = s.nextInt();

process = new int[n];
burst_time = new int[n];
waiting_time = new int[n];
tat = new int[n];

System.out.println("\nEnter Burst time:");
for(i=0;i<n;i++)
{
System.out.print("\nProcess["+(i+1)+"]: ");
burst_time[i] = s.nextInt();
process[i]=i+1; //Process Number
}

//Sorting
for(i=0;i<n;i++)
{
pos=i;
for(j=i+1;j<n;j++)
{
if(burst_time[j]<burst_time[pos])
pos=j;
}

temp=burst_time[i];
burst_time[i]=burst_time[pos];
burst_time[pos]=temp;

temp=process[i];
process[i]=process[pos];
process[pos]=temp;
}
}

```

```

//First process has 0 waiting time
waiting_time[0]=0;
//calculate waiting time
for(i=1;i<n;i++)
{
    waiting_time[i]=0;
    for(j=0;j<i;j++)
        waiting_time[i]+=burst_time[j];
    total+=waiting_time[i];
}

//Calculating Average waiting time
wait_avg=(float)total/n;
total=0;

System.out.println("\nProcess\tBurst Time \tWaiting Time\tTurnaround Time");
for(i=0;i<n;i++)
{
    tat[i]=burst_time[i]+waiting_time[i]; //Calculating Turnaround Time
    total+=tat[i];
    System.out.println("\n p"+process[i]+" \t\t "+burst_time[i]+" \t\t "+waiting_time[i]+" \t\t "+tat[i]);
}

//Calculation of Average Turnaround Time
TAT_avg=(float)total/n;
System.out.println("\n\nAverage Waiting Time: "+wait_avg);
System.out.println("\n\nAverage Turnaround Time: "+TAT_avg);

}
}

```



```

/* 2. SJF(Preemptive)*/
import java.util.Scanner;

class sjf_swap1{
public static void main(String args[])

{
int
burst_time[],process[],waiting_time[],tat[],arr_time[],completion_time[],i,j,n,total=0,total_comp=0,pos,
temp;
float wait_avg,TAT_avg;
Scanner s = new Scanner(System.in);
System.out.print("Enter number of process: ");
n = s.nextInt();
process = new int[n];
burst_time = new int[n];
waiting_time = new int[n];
arr_time=new int[n];
tat = new int[n];
completion_time=new int[n];

//burst time
System.out.println("\nEnter Burst time:");
for(i=0;i<n;i++)
{
System.out.print("\nProcess["+(i+1)+"]: ");
burst_time[i] = s.nextInt();
process[i]=i+1; //Process Number
}

//arrival time
System.out.println("\nEnter arrival time:");
for(i=0;i<n;i++)
{
System.out.print("\nProcess["+(i+1)+"]: ");
arr_time[i] = s.nextInt();
process[i]=i+1; //Process Number
}

//Sorting
for(i=0;i<n;i++)
{

```

```

pos=i;
for(j=i+1;j<n;j++)
{
if(burst_time[j]<burst_time[pos])
pos=j;
}

temp=burst_time[i];
burst_time[i]=burst_time[pos];
burst_time[pos]=temp;

temp=process[i];
process[i]=process[pos];
process[pos]=temp;

System.out.println("process"+process[i]);
}
//completion
time new
for(i=1;i<n;i++)
{
completion_time[i]=0;
for(j=0;j<i;j++)
completion_time[i]+=burst_time[j];
total_comp+=completion_time[i];
}

//First process has 0 waiting
time
waiting_time[0]=0;
//calculate

waiting time
for(i=1;i<n;i++)
{
waiting_time[i]=0;
for(j=0;j<i;j++)
waiting_time[i]+=burst_time[j];
total+=waiting_time[i];
}

```

```

//Calculating Average waiting time
wait_avg=(float)total/n;
total=0;

System.out.println("\nPro_number\t Burst Time \tcompletion_time\tWaiting Time\tTurnaround Time");
for(i=0;i<n;i++)
{
tat[i]=burst_time[i]+waiting_time[i];
//Calculating Turnaround Time
total+=tat[i];
System.out.println("\n"+process[i]+" \t\t "+burst_time[i]+" \t\t "
"+completion_time[i]+" \t\t "+waiting_time[i]+" \t\t "+tat[i]);
}

//Calculation of Average Turnaround Time
TAT_avg=(float)total/n;
System.out.println("\n\nAWT: "+wait_avg);
System.out.println("\n\nATAT: "+TAT_avg);

}
}

```

```
/*
```

Problem Statement :

Write a Java Program (using OOP features) to implement paging simulation using

1. Least Recently Used (LRU)
2. Optimal algorithm

****Optimal****

```
*/
```

```
import java.util.*;
```

```
import java.io.*;
```

```
class Optimal
```

```
{
```

```
    public static void main(String args[])throws IOException
```

```
    {
```

```
        BufferedReader br = new BufferedReader(new InputStreamReader(System.in));
```

```
        int numberOfFrames, numberOfPages, flag1, flag2, flag3, i, j, k, pos = 0, max;
```

```
        int faults = 0;
```

```
        int temp[] = new int[10];
```

```
        System.out.println("Enter number of Frames: ");
```

```
        numberOfFrames = Integer.parseInt(br.readLine());
```

```
        int frame[] = new int[numberOfFrames];
```

```
        System.out.println("Enter number of Pages: ");
```

```
        numberOfPages = Integer.parseInt(br.readLine());
```

```
        int pages[] = new int[numberOfPages];
```

```
        System.out.println("Enter the pages: ");
```

```
        for(i=0; i<numberOfPages; i++)
```

```
            pages[i] = Integer.parseInt(br.readLine());
```

```
        for(i = 0; i < numberOfFrames; i++)
```

```
            frame[i] = -1;
```

```
        for(i = 0; i < numberOfPages; ++i){
```

```
            flag1 = flag2 = 0;
```

```
            for(j = 0; j < numberOfFrames; ++j){
```

```

        if(frame[j] == pages[i]){
            flag1 = flag2 = 1;
            break;
        }
    }

    if(flag1 == 0){
        for(j = 0; j < numberOfFrames; ++j){
            if(frame[j] == -1){
                faults++;
                frame[j] = pages[i];
                flag2 = 1;
                break;
            }
        }
    }

    if(flag2 == 0){
        flag3 = 0;

        for(j = 0; j < numberOfFrames; ++j){
            temp[j] = -1;

            for(k = i + 1; k < numberOfPages; ++k){
                if(frame[j] == pages[k]){
                    temp[j] = k;
                    break;
                }
            }
        }

        for(j = 0; j < numberOfFrames; ++j){
            if(temp[j] == -1){
                pos = j;
                flag3 = 1;
                break;
            }
        }

        if(flag3 == 0){
            max = temp[0];
            pos = 0;

```

```

        for(j = 1; j < numberOfFrames; ++j){
            if(temp[j] > max){
                max = temp[j];
                pos = j;
            }
        }

        frame[pos] = pages[i];
        faults++;
    }

//      System.out.print();

    for(j = 0; j < numberOfFrames; ++j){
        System.out.print("\t" + frame[j]);
    }
}

System.out.println("\n\nTotal Page Faults: " + faults);

}

}

//7 0 1 2 0 3 0 4 2 3 0 3 2

```

Practical 5

Understanding the connectivity of raspberry-pi/Arduino with IR sensor. Write an application to detect obstacle and notify user using leds.

```
int obstaclePin=13;
```

```
int hasObstacle=HIGH;
```

```
void setup() {
```

```
    pinMode(obstaclePin,INPUT);
```

```
    pinMode(12,OUTPUT)
```

```
    Serial.begin(9600);
```

```
}
```

```
void loop() {
```

```
    hasObstacle=digitalRead(obstaclePin);
```

```
    if(hasObstacle==LOW){
```

```
        Serial.println("Stop Something is ahead!!");
```

```
        digitalWrite(12,HIGH);
```

```
    }else{
```

```
        Serial.println("Path is clear");
```

```
        digitalWrite(12,LOW);
```

```
    }
```

```
    delay(2000);
```

```
}
```

Practical 6

Understanding the connectivity of raspberry-pi/Arduino with DHT11/22 sensor. Write an application to notify different levels using LEDs

```
#include <dht.h>
#define outPin 8

dht DHT;

void setup(){
  Serial.begin(9600);

  pinMode(12,OUTPUT);
}

void loop(){
  int readData=DHT.read11(outPin);

  float t = DHT.temperature;
  float h = DHT.humidity;

  if(t > 31){
    digitalWrite(12,HIGH);
  }
  else{
    digitalWrite(12,LOW);
  }
  Serial.print("Temperature = ");
  Serial.print(t);
  Serial.print("C | ");
  Serial.print((t*9.0)/5.0+32.0);
  Serial.println("F");
  Serial.print("Humidity = ");
  Serial.print(h);
  Serial.println("%");
  Serial.println("");

  delay(2000);
}
```


Practical 7

Understanding the connectivity of raspberry-pi/Arduino with Ultrasonic sensor. Write an application for distance measurement and notify it on the serial monitor.

```
const int pingPin = 7; // Trigger Pin of Ultrasonic Sensor
const int echoPin = 6; // Echo Pin of Ultrasonic Sensor
```

```
void setup() {
  Serial.begin(9600);
}
```

```
void loop() {
  long duration, inches, cm;
  pinMode(pingPin, OUTPUT);
  digitalWrite(pingPin, LOW);
  delayMicroseconds(2);
  digitalWrite(pingPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(pingPin, LOW);
  pinMode(echoPin, INPUT);
  duration = pulseIn(echoPin, HIGH);
  inches = microsecondsToInches(duration);
  cm = microsecondsToCentimeters(duration);
  Serial.print(inches);
  Serial.print("in, ");
  Serial.print(cm);
  Serial.print("cm");
  Serial.println();
  delay(1000);
}
```

```
long microsecondsToInches(long microseconds) {
  return microseconds / 74 / 2;
}
```

```
long microsecondsToCentimeters(long microseconds) {
  return microseconds / 29 / 2;
}
```

Practical 8

**Understanding the Understanding the connectivity of raspberry-pi/Arduino with water level sensor.
Write an application to detect water level and notify user using leds and monitor.**

```
#define sensorPin A0
#define buzzer 6
// Value for storing water level
int val = 0;

void setup() {
  pinMode(buzzer, OUTPUT);
  digitalWrite(buzzer, LOW);
}

void loop() {

  int level = analogRead(sensorPin);
  if(level > 450)
  {
    digitalWrite(buzzer, HIGH);
  }
  else
  {
    digitalWrite(buzzer, LOW);
  }
  delay(1000);
}
```

Practical 9

Understanding the connectivity of raspberry-pi/Arduino with temperature sensor. Write an application to read the environment temperature. If temperature crosses a threshold value, generate alerts using leds.

```
#include <dht.h>
#define outPin 8

dht DHT;

void setup(){
  Serial.begin(9600);

  pinMode(12,OUTPUT);
}

void loop(){
  int readData=DHT.read11(outPin);

  float t = DHT.temperature;
  float h = DHT.humidity;

  if(t > 31){
    digitalWrite(12,HIGH);
  }
  else{
    digitalWrite(12,LOW);
  }
  Serial.print("Temperature = ");
  Serial.print(t);
  Serial.print("C|");
  Serial.print((t*9.0)/5.0+32.0);
  Serial.println("F");
  Serial.print("Humidity = ");
  Serial.print(h);
  Serial.println("%");
  Serial.println("");

  delay(2000);
}
```

Practical 10

**Understanding the connectivity of raspberry-pi/Arduino with water level and soil moisture sensor.
Write an application to implement a smart gardening system.**

```
void setup() {  
  pinMode(A0,INPUT);  
  pinMode(A1,INPUT);  
  Serial.begin(9600);  
}  
  
void loop() {  
  int val1=analogRead(A0);  
  int val2=analogRead(A1);  
  Serial.print("Water Level= ");  
  Serial.print(val1);  
  Serial.print("Soil Moisture= ");  
  Serial.print(val2);  
  delay(2000);  
}
```