

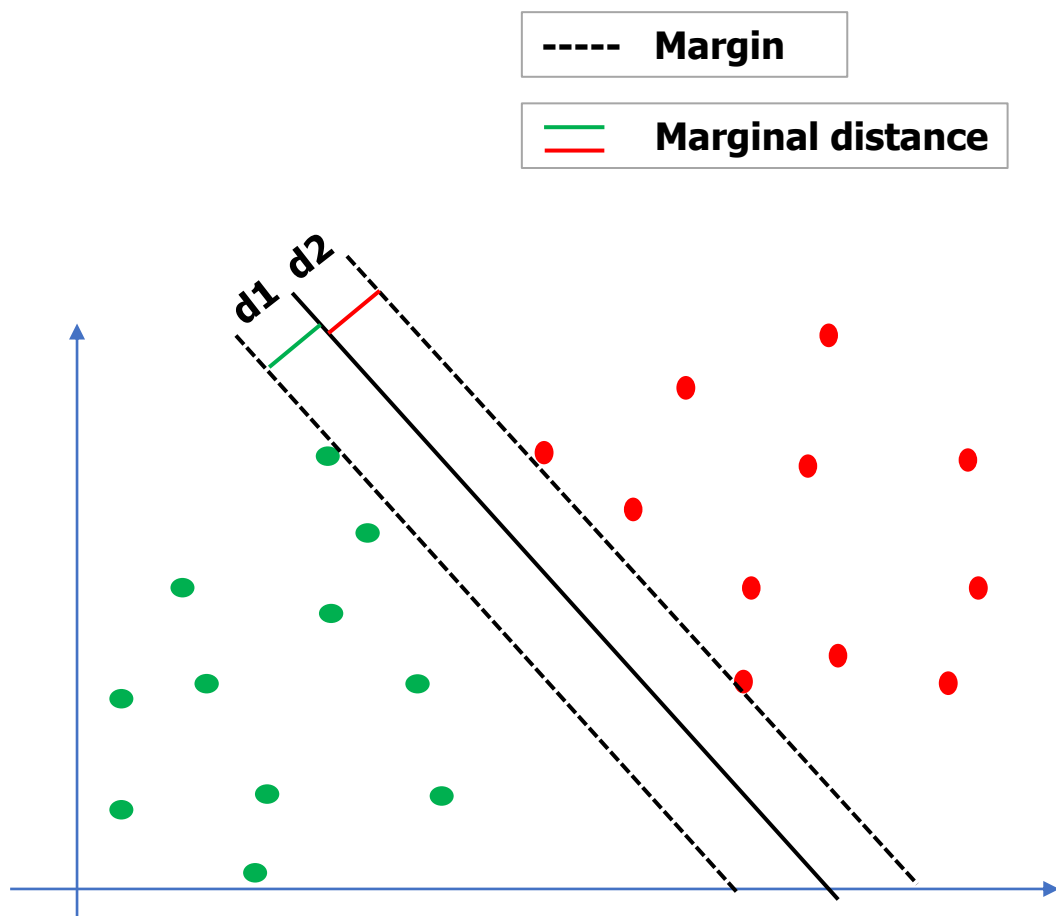
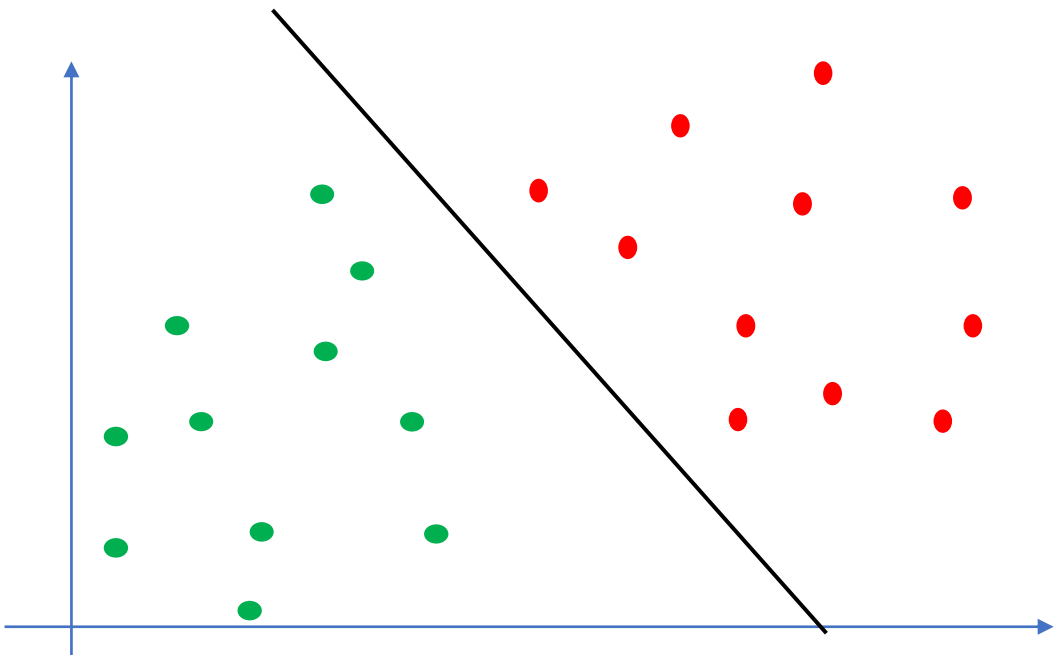
SVM

Support Vector Machines

SVM – Support Vector Machine

- Supervised machine learning algorithm
- Classification technique for **linear and non-linear** separable classes
- Alternate to Logistic regression
- Classification based on finding a **hyperplane** that maximises the margin between two classes
 - Mathematically speaking, SVM's are co-ordinates of the data/observations
- Mainly used in binary classification
 - Can be used in multiclass classification by implementing 'One-Vs-All' method
- SVM algorithm has a feature to ignore outliers
- Complex algorithm, computing resources high, but SVM performs very well

**Let us consider a
Binary Classification
Problem that is
Linearly separable**

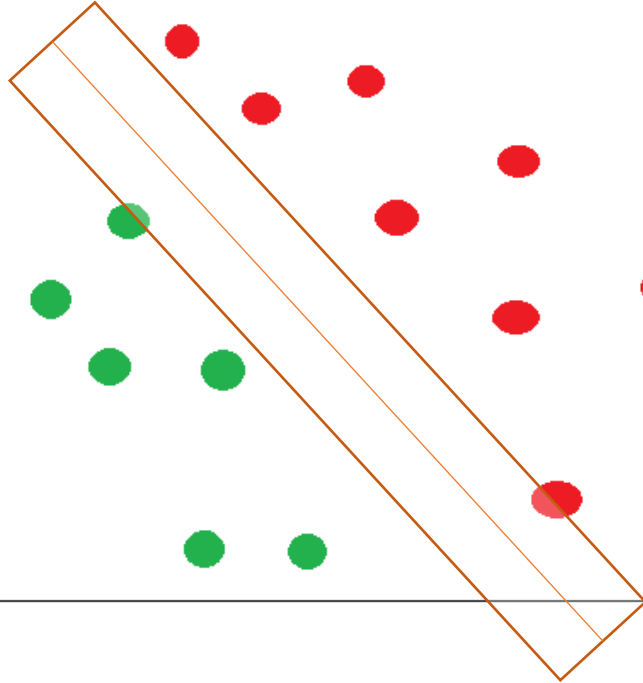


The goal of SVM

- Find a hyperplane that maximises the distance between the 2 nearest opposite classes
- The margin signifies a generalised model that would give a more accurate model
- The hyperplane leaves the widest possible "cushion" between input points from two classes. Trade-off between
 - "narrow cushion, little / no mistakes"
 - "wide cushion, quite a few mistakes"
- A narrow margin may do a good job at separating the training classes, but it is prone to misclassifications of the test data

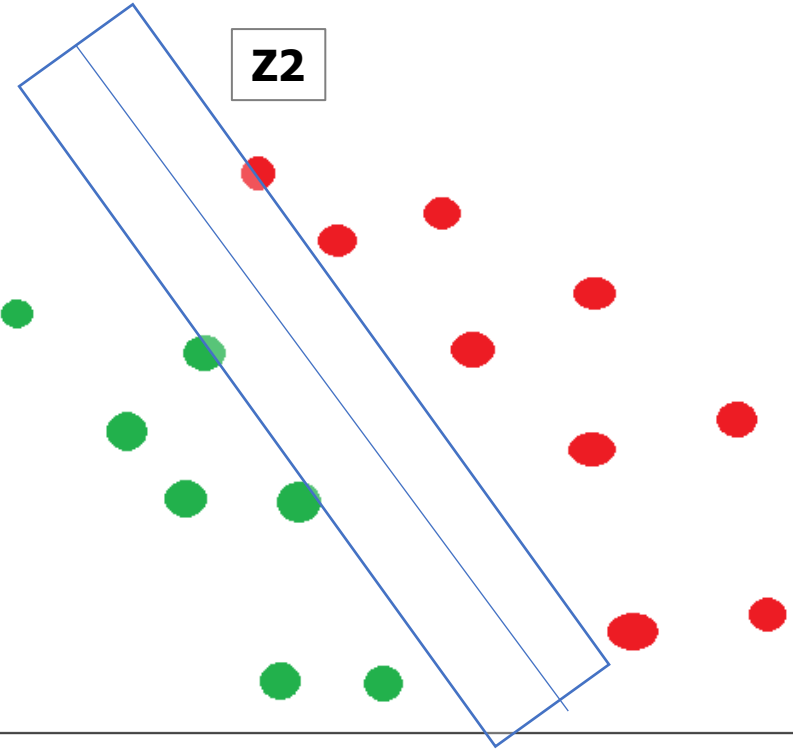
$$z_2 > z_1$$

z1



$w^T \cdot x + b \leq -1$ for *Green* classes

z2



$w^T \cdot x + b \geq 1$ for *Red* classes

What are Support Vectors ?

- Support Vectors are the data points through which the marginal lines passes
- The number of SV's can vary depending upon the data

General equation

$$y = w_1x_1 + w_2x_2 + \dots + b$$

Where

w : weight associated with feature x

$Y > +1$: Positive Class

$Y < -1$: Negative Class

We can generalise the equation as

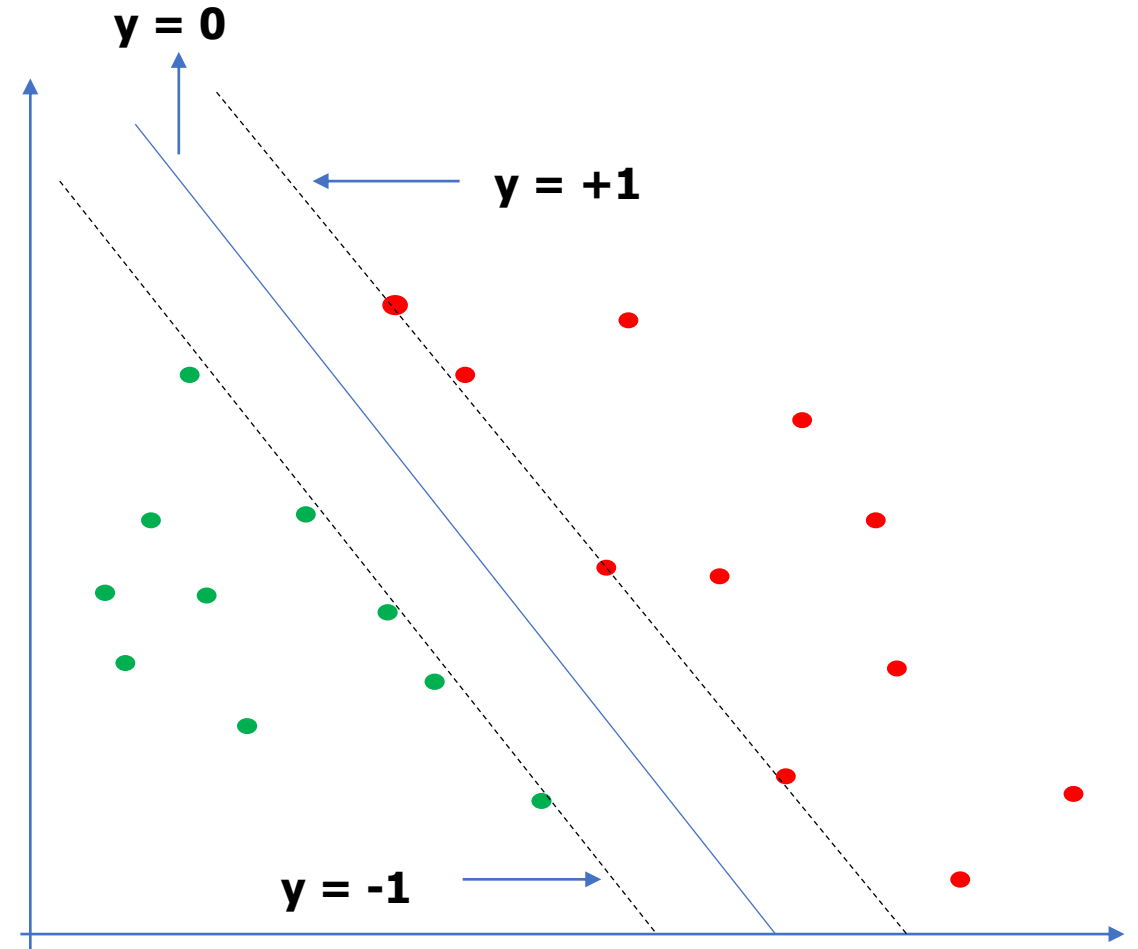
$$y = w^T x + b$$

where

w : weights of the features

x : input features

b : constant



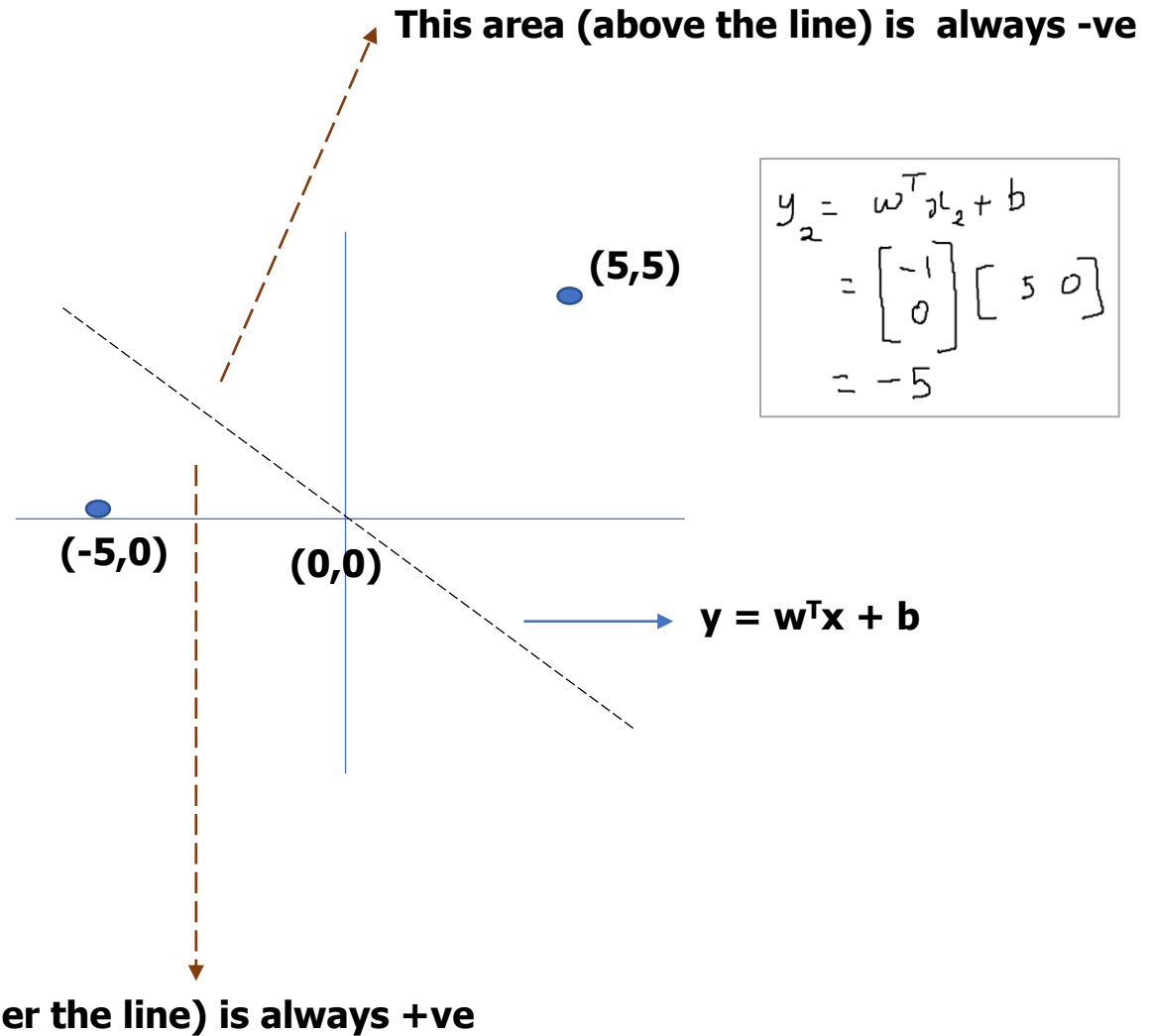
Assume $m=-1$
 $b=0$ (since line passes through the origin)

$$y = mx + b$$

Here, weights (w) are m (**-1**) and b (**0**)
 $w = [-1, 0]$

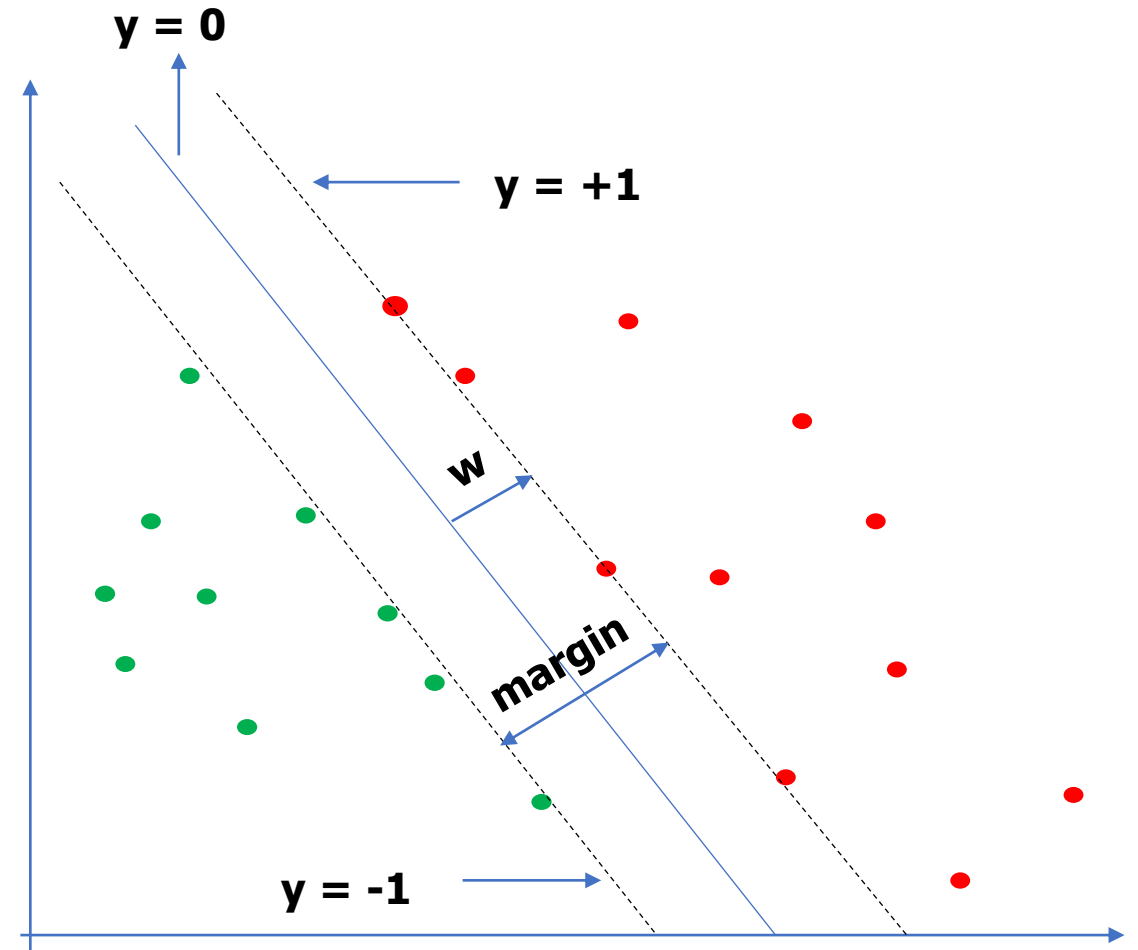
Consider 2 data points
 $X_1 = [-5, 0]$, $X_2 = [5, 5]$

$$\begin{aligned} y_1 &= w^T x_1 + b \\ &= \begin{bmatrix} -1 \\ 0 \end{bmatrix} \begin{bmatrix} -5 & 0 \end{bmatrix} \\ &= 5 \end{aligned}$$

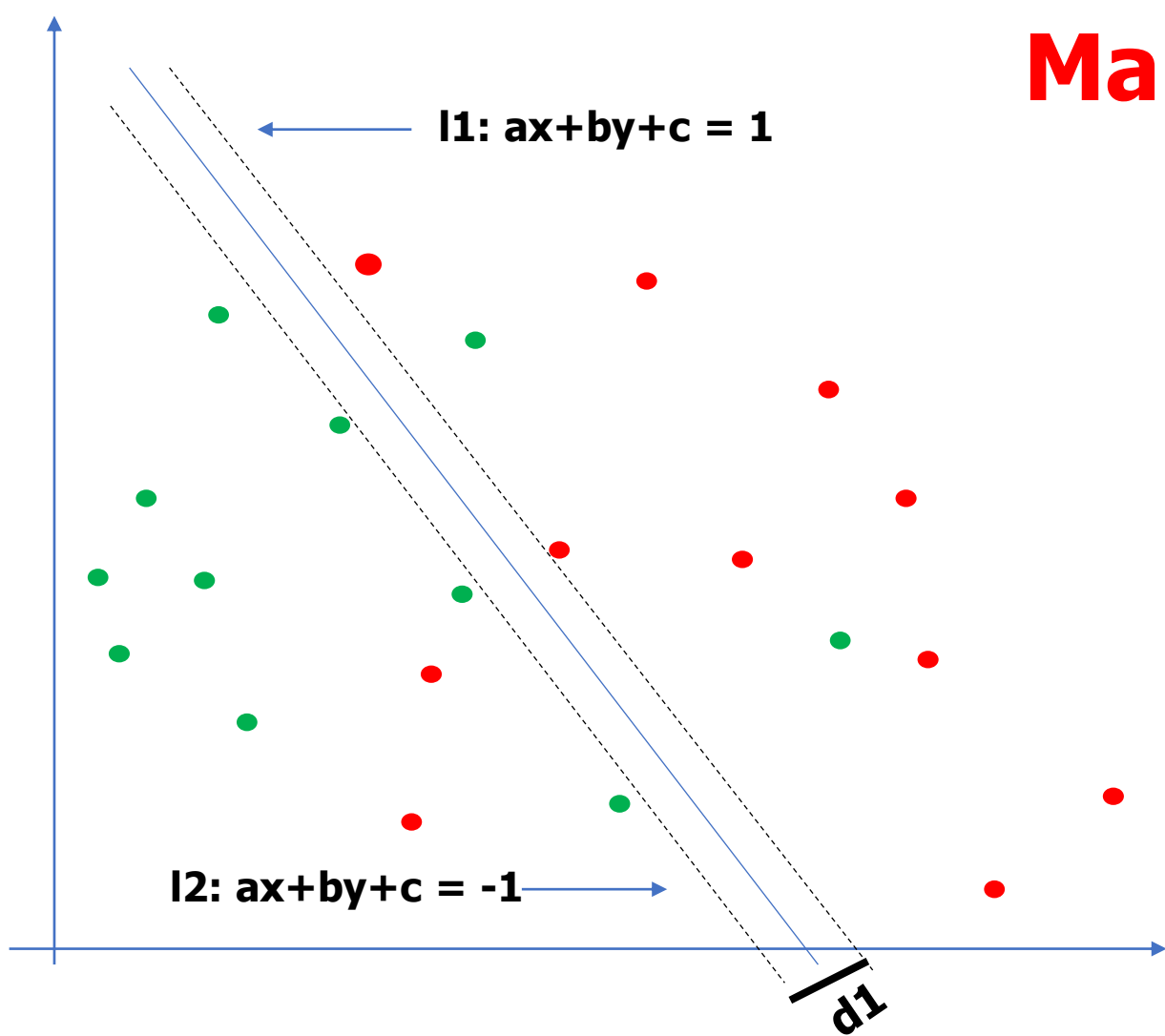


$$\begin{aligned} y_2 &= w^T x_2 + b \\ &= \begin{bmatrix} -1 \\ 0 \end{bmatrix} \begin{bmatrix} 5 & 0 \end{bmatrix} \\ &= -5 \end{aligned}$$

- Vector $w = (w_1, w_2, \dots)$ is perpendicular to the decision boundary
- $w \rightarrow$ normal vector
- $b \rightarrow$ scalar



Margin Error



Let the equations of the lines be

$$l1: ax+by+c = 1$$

$$l2: ax+by+c = -1$$

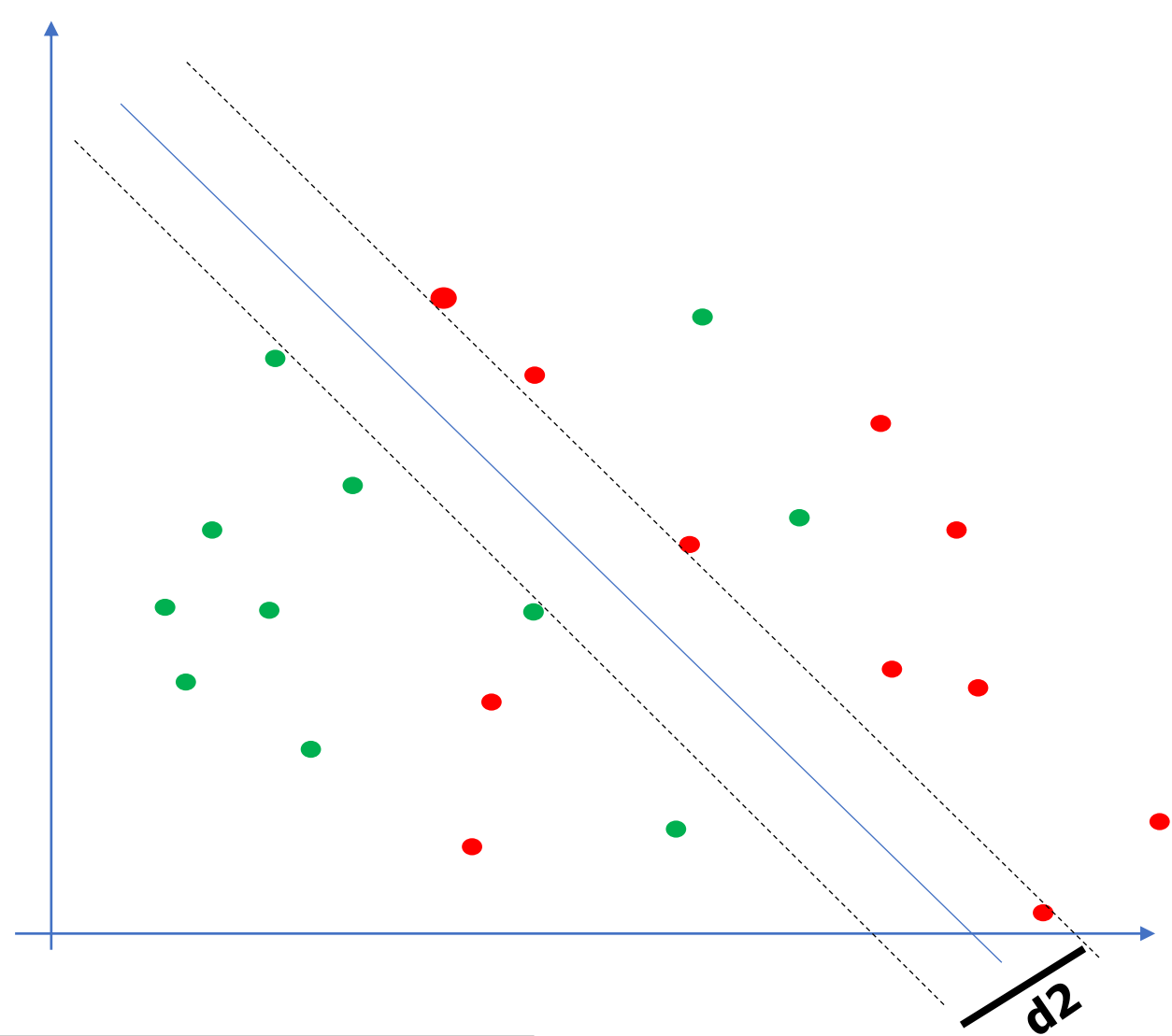
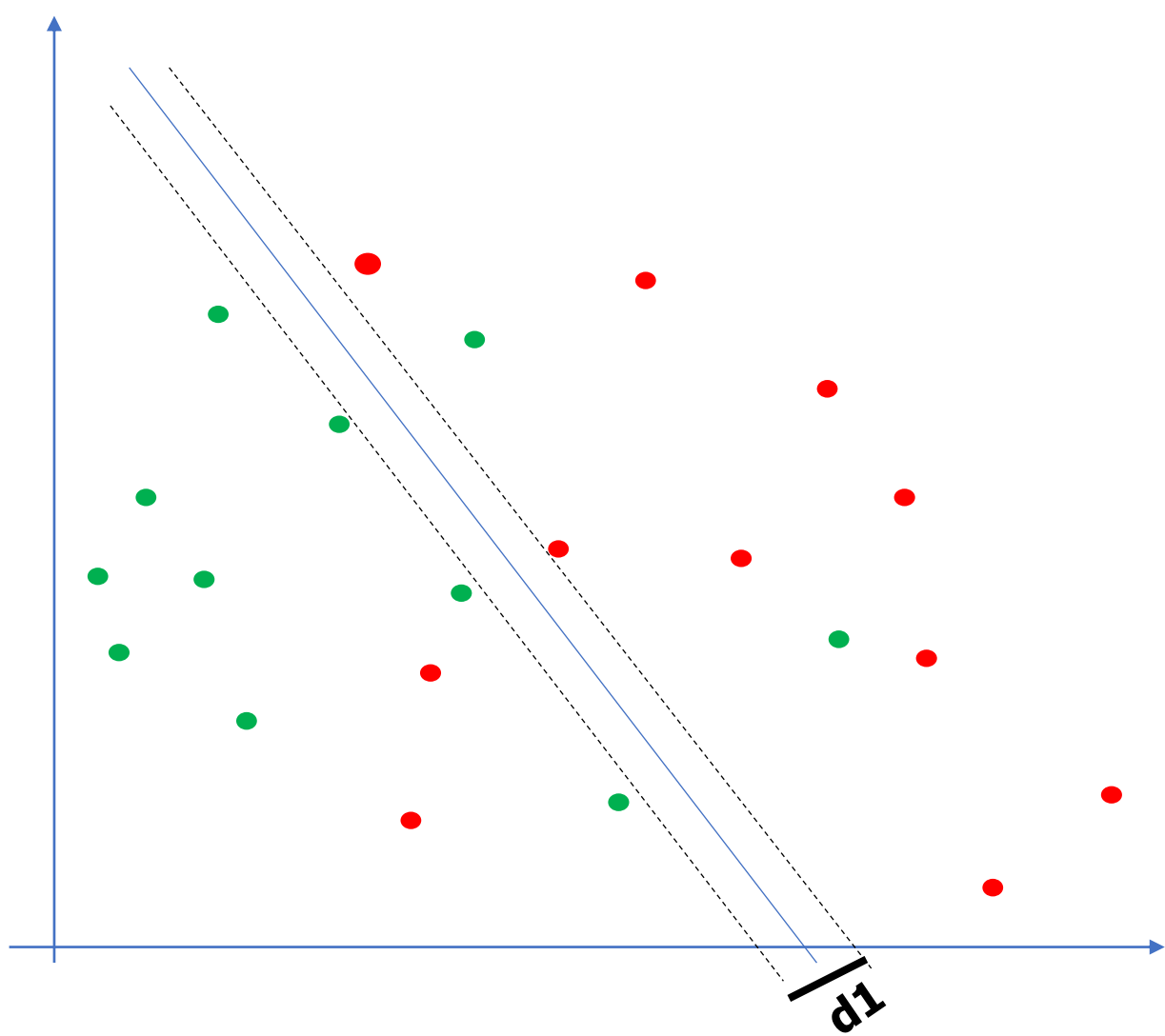
Margin (d1) = Perpendicular distance joining each line

$$\text{Formula (d1)} = 2 / \sqrt{a^2 + b^2}$$

$$\text{Margin Error: } a^2 + b^2$$

Goal of SVM is to minimise this error

Which line is better depends on whether we need too many classification errors or too many margin errors



Which line is better ?

Margin Error defines the best line

Larger distance (d) means less margin error; Smaller distance (d) means larger margin error

To find the **marginal distance**

$$\mathbf{w}^T \mathbf{x}_1 + \mathbf{b} = 1 \rightarrow (1)$$

$$\mathbf{w}^T \mathbf{x}_2 + \mathbf{b} = -1 \rightarrow (2)$$

Subtracting (2) from (1)

$$\mathbf{w}^T (\mathbf{x}_2 - \mathbf{x}_1) = 2$$

Dividing both sides by $||\mathbf{w}||$ (length of the normal vector)

$$\mathbf{w}^T (\mathbf{x}_2 - \mathbf{x}_1) / ||\mathbf{w}|| = 2 / ||\mathbf{w}||$$

SVM Optimisation function

subject to the constraint

$$\begin{aligned} y &= +1 \text{ when } \mathbf{w}^T \mathbf{x} + \mathbf{b} \geq +1 \\ &= -1 \text{ when } \mathbf{w}^T \mathbf{x} + \mathbf{b} \leq -1 \end{aligned}$$

The goal is to maximise $||\mathbf{w}||$

This is done by changing the **(w,b)** values

Multiplying the constraints with the class labels, we can rewrite the condition as

$$Y * \mathbf{w}^T \mathbf{x} + \mathbf{b} \geq +1$$

$$Y * \mathbf{w}^T \mathbf{x} + \mathbf{b} \geq +1$$

This indicates correct classification

Rewriting the maximisation problem into a minimisation problem, we get

$$\max 2 / ||\mathbf{w}|| \rightarrow \min \frac{1}{2} (||\mathbf{w}||)^2$$

Subject to the condition

$$Y (\mathbf{w}^T \mathbf{x} + \mathbf{b}) - 1 \geq 0$$

Solving this will give the value for \mathbf{w} and \mathbf{b}

- Real life scenario does not usually have such linearly separable points
- Prone to misclassifications and errors
- Errors doesn't mean change the margin

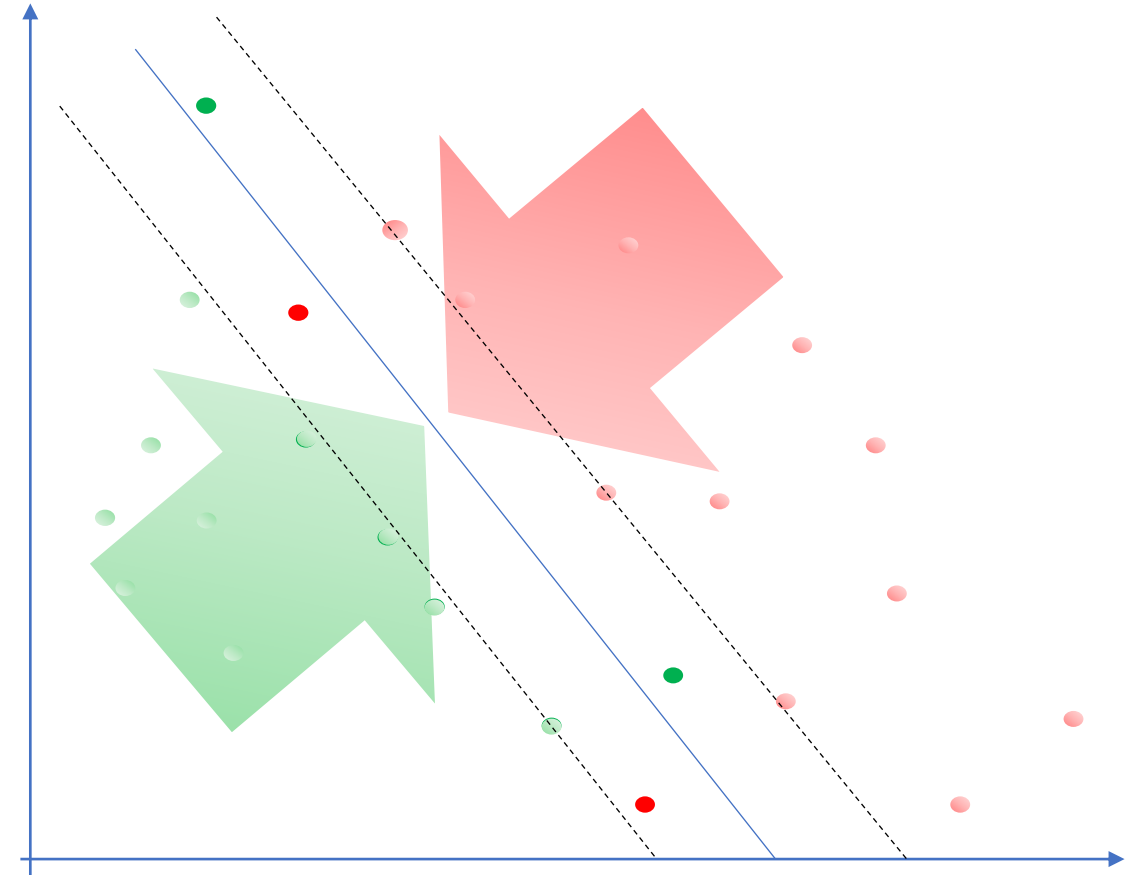
Rewriting the equation, we get

$$\min \frac{1}{2} (||\mathbf{w}'||^2) + c \sum \zeta$$

where

C = number of errors

ζ = value of the errors



Cost Parameter

- C controls the cost of misclassification on the training data
- $C \rightarrow$ how many errors are there
- $(C * \text{Classification Error}) + (\text{Margin Error})$
- Value of C
 - ✓ **Small C**
 - Cost of misclassification low ("too strict")
 - Large Margin Error
 - ✓ **Large C**
 - Cost of misclassification high and potentially overfit ("too loose")
 - Low Margin Error
- The goal is to find the balance between "not too strict" and "not too loose"
- Cross-validation and resampling are good ways to finding the best C

C and Gamma

- For linear models, only C needs to be optimized
- For RBF models, both C and Gamma parameters need to be optimized
- C and Gamma values can change based on the dataset / problem dataset
- For starters, the estimates could range from
 - C -> 0.1 – 100
 - Gamma -> 0.0001 - 10

Find the best Kernel and other parameters

Cost

- Known as the Penalty parameter (**C**)
- Controls the cost of misclassification on the training data
- **High C** → more data points chosen as support vectors
 - High variance : Low Bias → Overfit
- **Low C** → less data points chosen as support vectors
 - Low variance : High Bias → Underfit

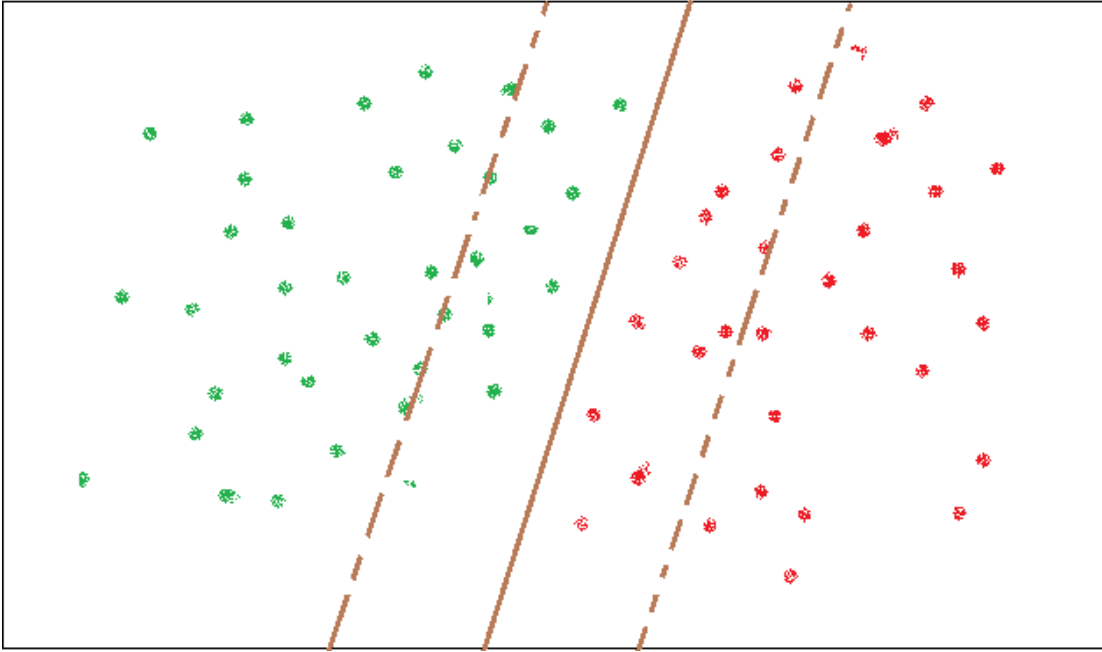
Gamma

- Influence of data points on the decision boundary
- Shape of the decision boundary line depends on gamma
 - **High Gamma** → decision boundary depends on data points near the decision boundary
 - **Low Gamma** → decision boundary depends on far away points

- The goal of SVM is to find a hyperplane that would leave the widest possible "cushion" between input points from two classes.
- There is a trade-off between "narrow cushion, little / no mistakes" and "wide cushion, quite a few mistakes".

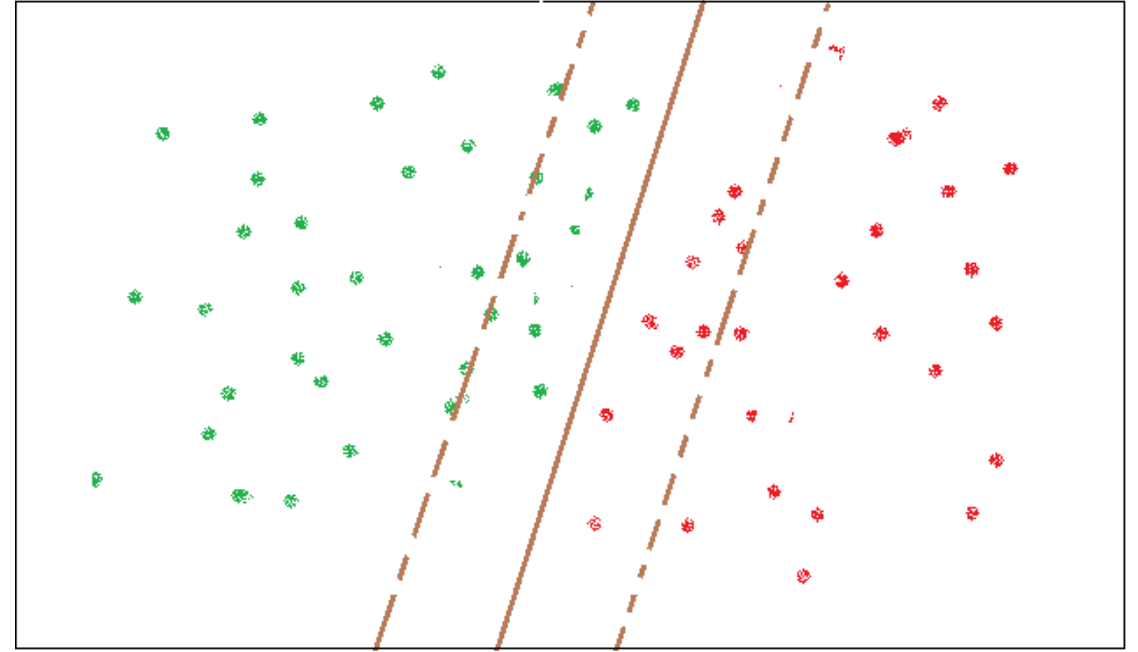
C Parameter

Predictions with $C=0.1$



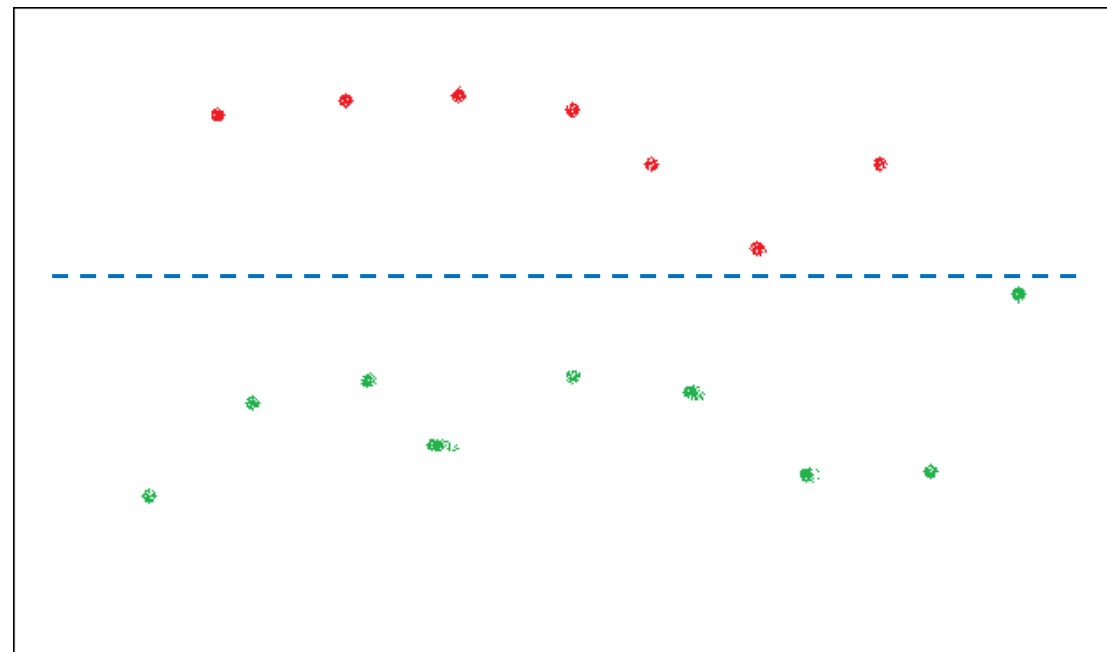
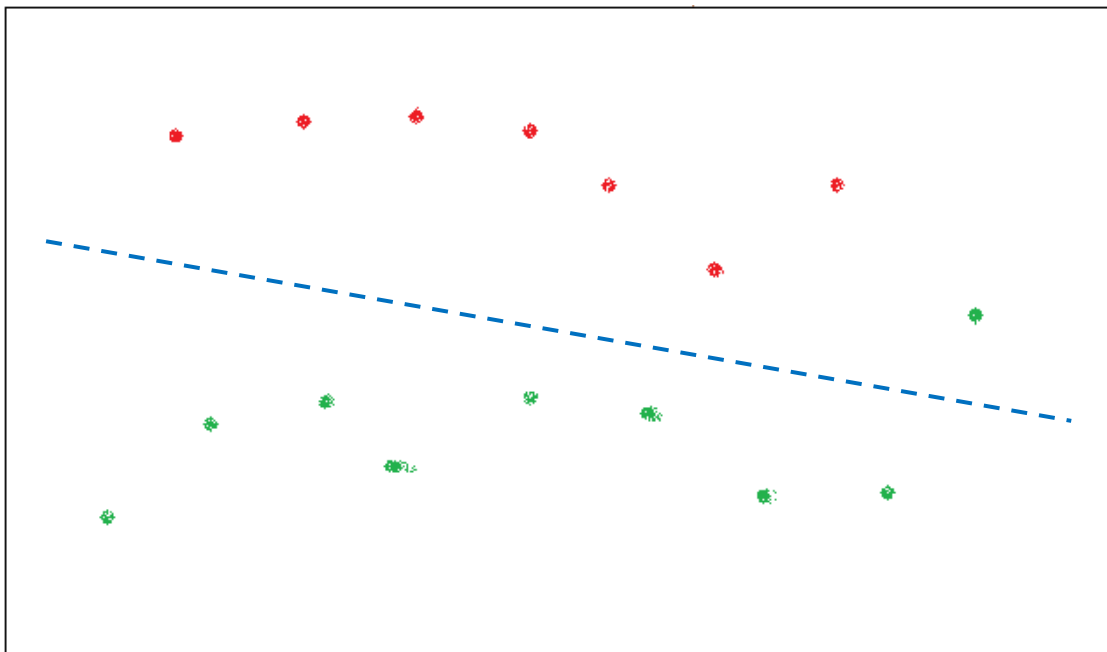
- Large margin
- More generalised model
- May have classification errors

Predictions with $C=100$



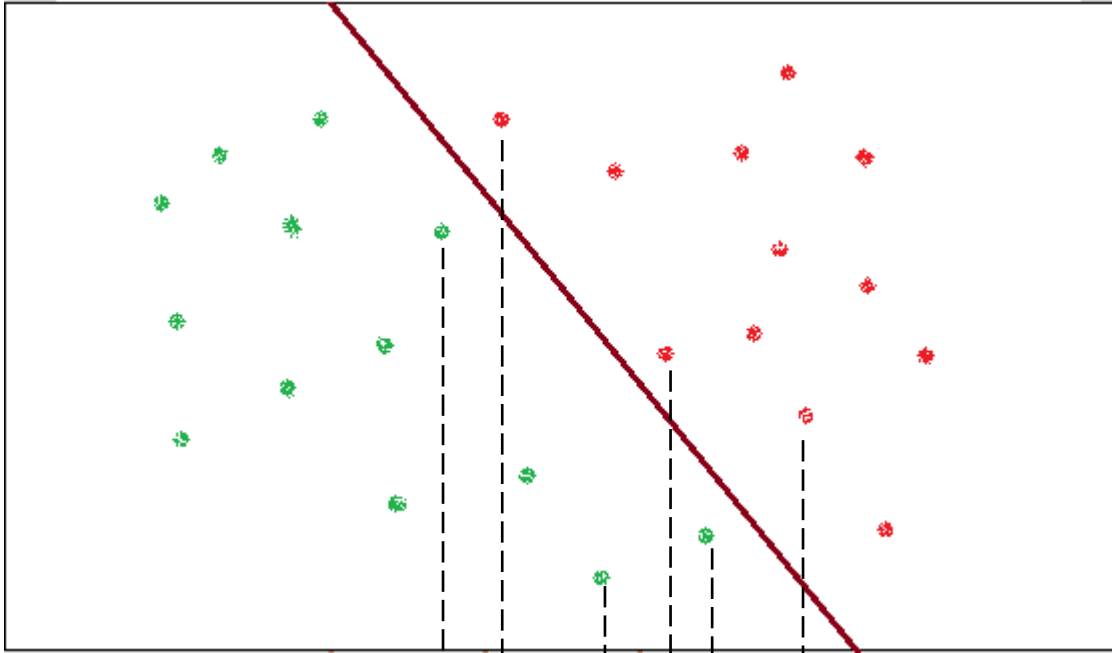
- Smaller margin
- May not have any classification errors

- Given 2 models, assume there are 2 boundary lines
- Which separating line is better ?



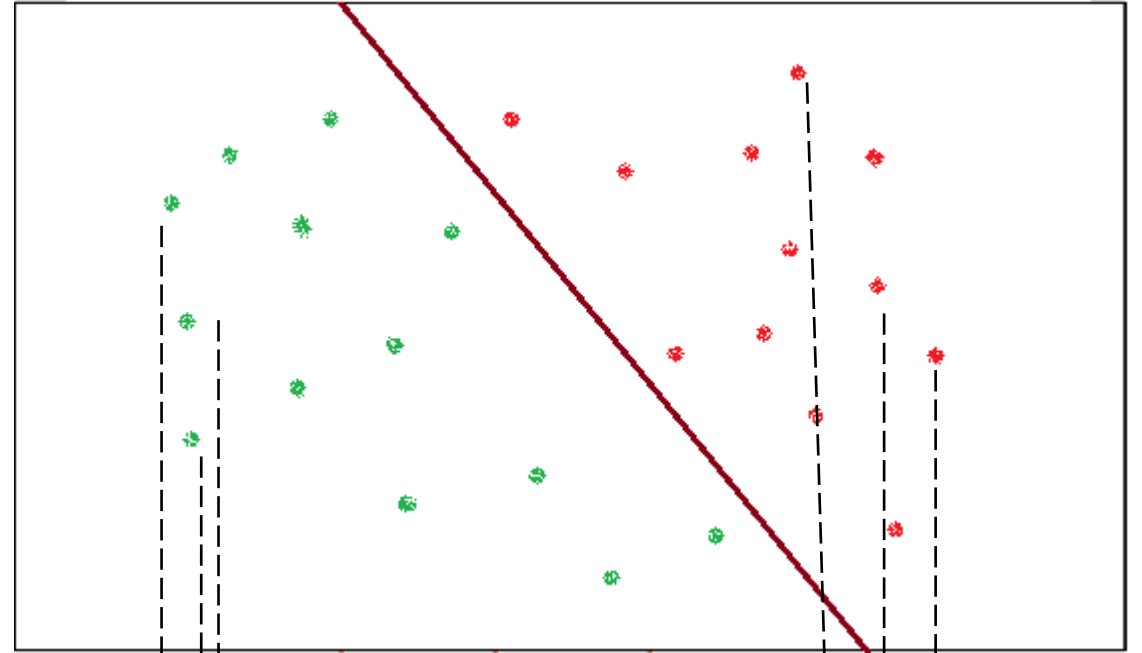
Gamma Parameter

- Used mainly with non-linear SVM (where data cannot be linearly separated due to high dimensions)
- RBF (Radial Basis Function) – most commonly used non-linear kernel in SVM
- Influence of a single training example (definition according to SVM documentation)
- Low Gamma
 - Training data has a far reach
 - Large similarity radius that groups more points
- High Gamma
 - Training data has a close reach
 - Points need to be very close to group them in the same class
 - Models with high gamma values usually overfits



- **High Gamma**

Decision boundary depends on these closest points



- **Low Gamma**

Decision boundary depends on these far away points

Find the best Kernel and other parameters

Kernel

- Kernels are mathematical functions
- Measures the similarity between 2 data points
- Sometimes, it is difficult to draw decision boundary
- This kernel technique is black-box

Kernel types

- RBF (Radial Basis Kernel Function) (observations > features)
- Linear Kernel (features > observations)

Non-Linear classification / Kernel Trick

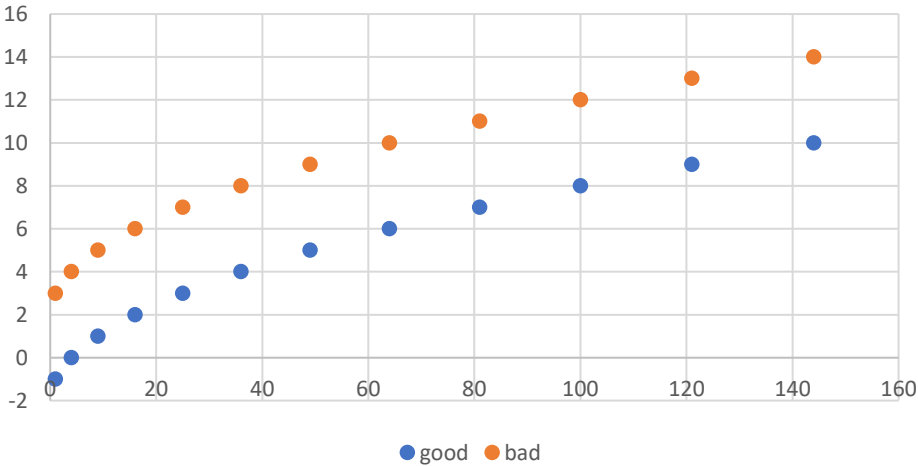
- Uses “kernel” technique to convert non-linear classes to linear classes to fit multi-classes
 - Quite efficient in multi-class prediction
- Uses higher dimension feature space for calculation (i.e. converting non-linear separable classes to separable classes)
- SVM is popular as it works efficiently in large datasets having multi-classes
- Algorithm to arrive at an optimum hyperplane can be computationally expensive and time consuming
- More features and more observations complicate the algorithm
- Choice of Kernel for non-linear datasets
 - A big challenge
 - Black-box performance
 - Uses complex data transformation techniques

x	good	bad
1	-1	3
4	0	4
9	1	5
16	2	6
25	3	7
36	4	8
49	5	9
64	6	10
81	7	11
100	8	12
121	9	13
144	10	14

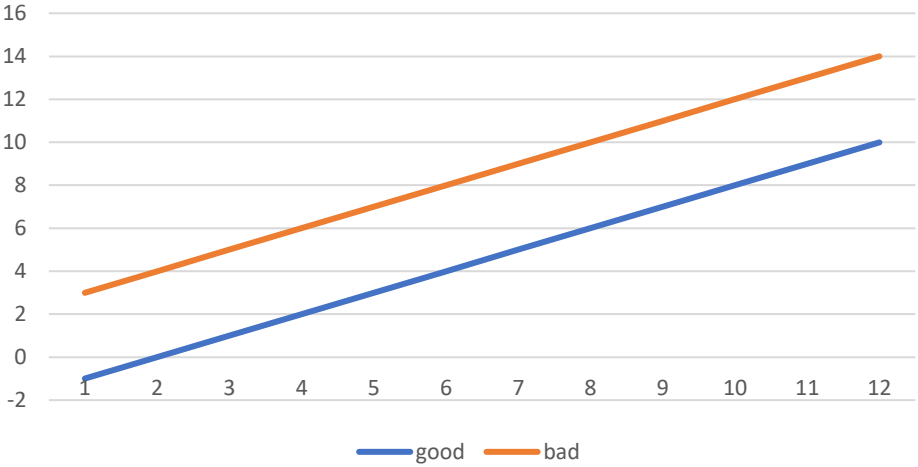
Square root of x

x	good	bad
1	-1	3
2	0	4
3	1	5
4	2	6
5	3	7
6	4	8
7	5	9
8	6	10
9	7	11
10	8	12
11	9	13
12	10	14

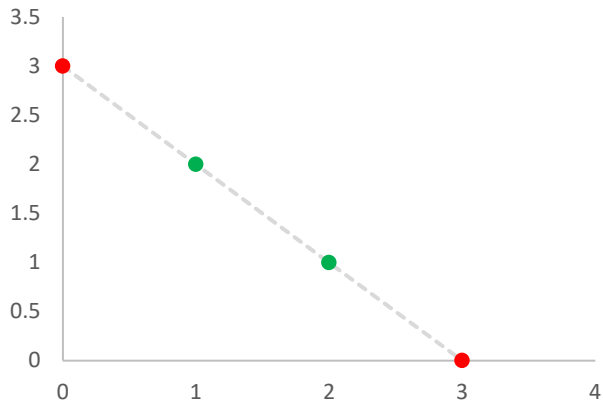
Non-Linear



Linear



x	y
0	3
1	2
2	1
3	0

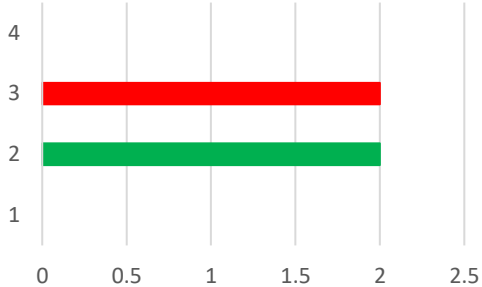


How to separate
the **Red** Class
from **Green** ?

transformation →

x	y	x+y	x*y	x ²
0	3	3	0	0
1	2	3	2	1
2	1	3	2	4
3	0	3	0	9

x * y



x	y	x*y	(x,y,x*y)
0	3	0	(0,3,0)
1	2	2	(1,2,2)
2	1	2	(2,1,2)
3	0	0	(3,0,0)

