

# PROJECTIVE INTEGRATION FOR INELASTIC BOLTZMANN EQUATION

## 1. BOLTZMANN EQUATION WITH INELASTIC COLLISION

**1.1. The inelastic collision operator.** Assume two particles with velocities  $v$  and  $v_*$  are going to collide. During the collision, there is some loss of momentum in the impact direction  $\omega \in S^{d-1}$  ( $S^{d-1}$  is the unit sphere in  $\mathbb{R}^d$ ), resulting in the post-collisional velocities  $v'$  and  $v'_*$ . Let  $e$  stand for the restitution coefficient or inelasticity parameter, then

$$(v' - v'_*) \cdot \omega = -e[(v - v_*) \cdot \omega], \quad 0 \leq e \leq 1. \quad (1)$$

Using (1),  $v'$  and  $v'_*$  can be represented as

$$\begin{cases} v' = v - \frac{1+e}{2}[(v - v_*) \cdot \omega]\omega, \\ v'_* = v_* + \frac{1+e}{2}[(v - v_*) \cdot \omega]\omega. \end{cases} \quad (2)$$

which is  $\omega$ -representation. One can easily verify the conservation of momentum and dissipation of energy:

$$v' + v'_* = v + v_*; \quad |v'|^2 + |v'_*|^2 - |v|^2 - |v_*|^2 = -\frac{1-e^2}{2}[(v - v_*) \cdot \omega]^2 \leq 0. \quad (3)$$

For numerical purpose, it is convenient to consider  $\sigma$ -representation:

$$\begin{cases} v' = \frac{v + v_*}{2} + \frac{1-e}{4}(v - v_*) + \frac{1+e}{4}|v - v_*|\sigma, \\ v'_* = \frac{v + v_*}{2} - \frac{1-e}{4}(v - v_*) - \frac{1+e}{4}|v - v_*|\sigma, \end{cases} \quad (4)$$

where  $\sigma$  is another unit vector on  $S^{d-1}$  and is related to  $\omega$  as

$$(g \cdot \omega)\omega = \frac{1}{2}(g - |g|\sigma). \quad (5)$$

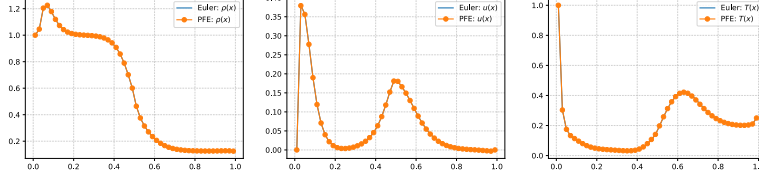
Then the collision has the following weak form:

$$\int_{\mathbb{R}^d} Q(f, f)(v) \varphi(v) \, dv = \frac{1}{2} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \int_{S^{d-1}} B_\sigma(|g|, \sigma \cdot \hat{g}) f f_* (\varphi' + \varphi'_* - \varphi - \varphi_*) \, d\sigma \, dv \, dv_*, \quad (6)$$

where  $g = v - v_*$ , and  $(v', v'_*)$  are given by (4). The collision kernel  $B_\sigma$  may take various forms depending on the types of interactions. The most commonly used form is the variable hard sphere (VHS) model:

$$B_\sigma(|g|, \sigma \cdot \hat{g}) = C_\lambda |g|^\lambda, \quad 0 \leq \lambda \leq 1, \quad (7)$$

where  $C_\lambda > 0$  is some constant. Two special cases are: Maxwell molecules ( $\lambda = 0$ ) and hard spheres ( $\lambda = 1$ ).

FIGURE 1. Solutions with  $e = 0.2$ . PFE vs. Euler

**1.2. The inelastic Boltzmann equation.** The inelastic Boltzmann equation reads:

$$\partial_t f + v \cdot \nabla_x f = \frac{1}{\varepsilon} Q_{\text{in}}(f) \quad (8)$$

## 2. PROJECTIVE INTEGRATOR

Consider an ODE system:

$$\begin{cases} \frac{du}{dt} = g(u(t)), & t > 0 \\ u(0) = u_0. \end{cases} \quad (9)$$

where the dynamic has a scale separation, that is, the eigenvalues of  $\frac{dg}{du}$  are clustered into two groups separated by a gap.

### 2.1. The scheme.

- Inner integrator: forward Euler method with small time step  $\delta t$ :

$$u^{k+1} = u^k + \delta t g(u^k).$$

- Extrapolate in time:

$$u^{n+1} = u^{n,K+1} + (\Delta t - (K+1)\delta t) \frac{u^{n,K+1} - u^{n,K}}{\delta t}.$$

## 3. NUMERICAL

We consider the Riemann problem (Sod shock tube problem) as test.

**3.1. Example.** The initial data are given by the Maxwellian distributions computed from the macroscopic quantities

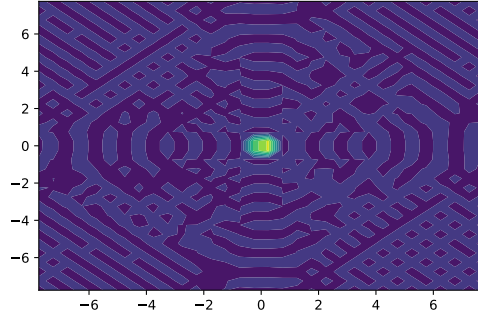
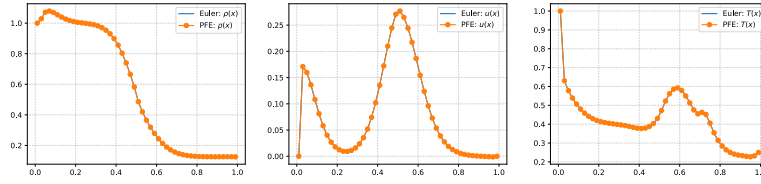
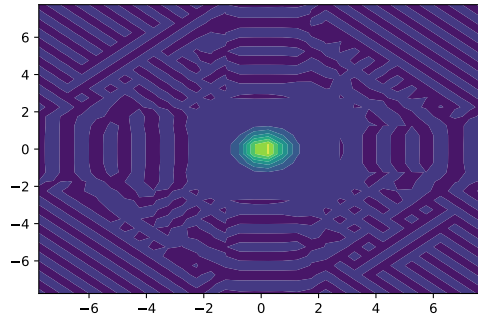
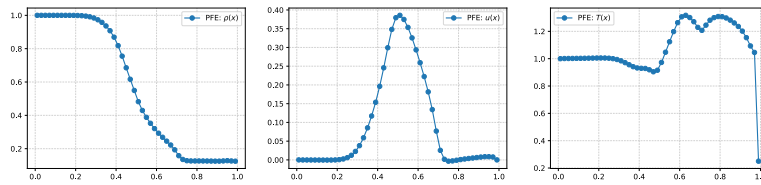
$$(\rho_l, u_l, T_l) = (1, 0, 1), \quad \text{if } 0 \leq x \leq 0.5, \quad (10)$$

$$(\rho_r, u_r, T_r) = (0.125, 0, 0.25) \quad \text{if } 0.5 < x \leq 1. \quad (11)$$

We solve the  $1D_x \times 2D_v$  inelastic Boltzmann equation with different  $\varepsilon$ s and  $e$ s.

**3.1.1.  $\varepsilon = 10^{-2}$ .** We test the PFE (projective forward euler) scheme compared with the explicite Euler scheme.  $\Delta x = 0.02$ , for PFE scheme  $\Delta t = 0.004$ ,  $\delta t = 10^{-3}$  and for Euler scheme  $\Delta t = 0.002$ . The macroscopic quantities and solution at  $T = 0.1$  are shown in Figure 1.

**3.1.2.  $\varepsilon = 10^{-4}$ .** We perform the same numerical experiment as above. However, since  $\Delta t$  of the Euler scheme is restricted by  $\varepsilon$  which is very small in this case. We can only run the PFE with a bigger time step  $\Delta t = 0.002$ .

FIGURE 2. Solution  $f$  in  $v$  when  $e = 0.2$ .FIGURE 3. Solutions with  $e = 0.8$ . PFE vs. EulerFIGURE 4. Solution  $f$  in  $v$  when  $e = 0.8$ .FIGURE 5. Solutions with  $e = 1.0$ . PFE

## REFERENCES