

Nov 2021

First Term (Final Project 1)

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Mastering embedded system online diploma by Eng. Keroles Shenouda
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Case Study

A “client” expects to deliver the software of the following system:

- A pressure controller informs the crew of a cabin with an alarm when the pressure exceeds 20 bars in the cabin.
- The alarm duration equals 60 seconds.

Assumptions

- The controller set up and shutdown procedures are not modeled
- The controller maintenance is not modeled
- The pressure sensor never fails
- The alarm never fails
- The controller never faces power cut

Method

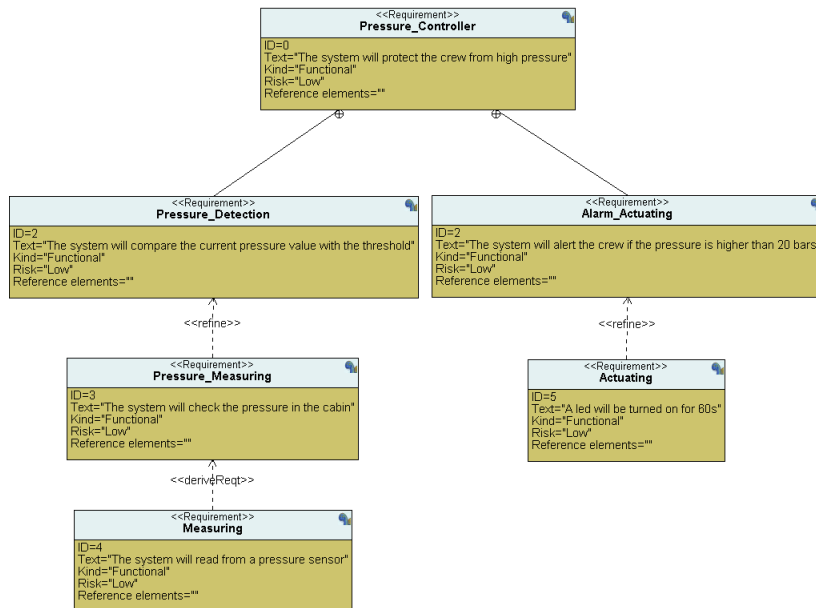
I will use the waterfall method which consists of

1. Requirements.
2. Analysis.
3. Design.
4. Coding.
5. Testing.
6. Deployment.

Idea

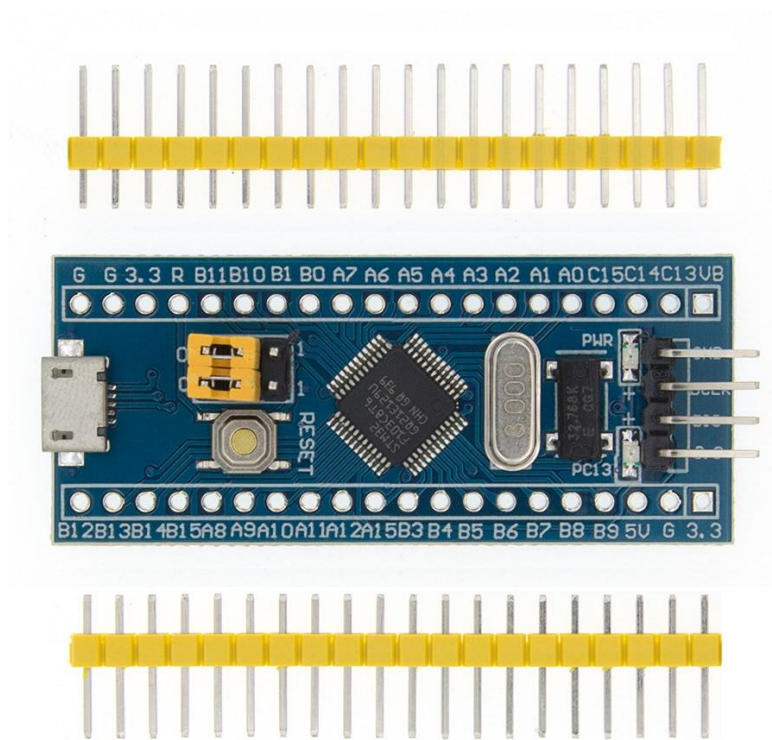
1. Get the pressure sensor data.
2. If the pressure is greater than or equal to the threshold = 20 bars.
 - a. Start the alarm for 60 seconds.
3. If the pressure is less than the threshold = 20 bars.
 - a. Continue.
4. Repeat.

Requirements Diagram



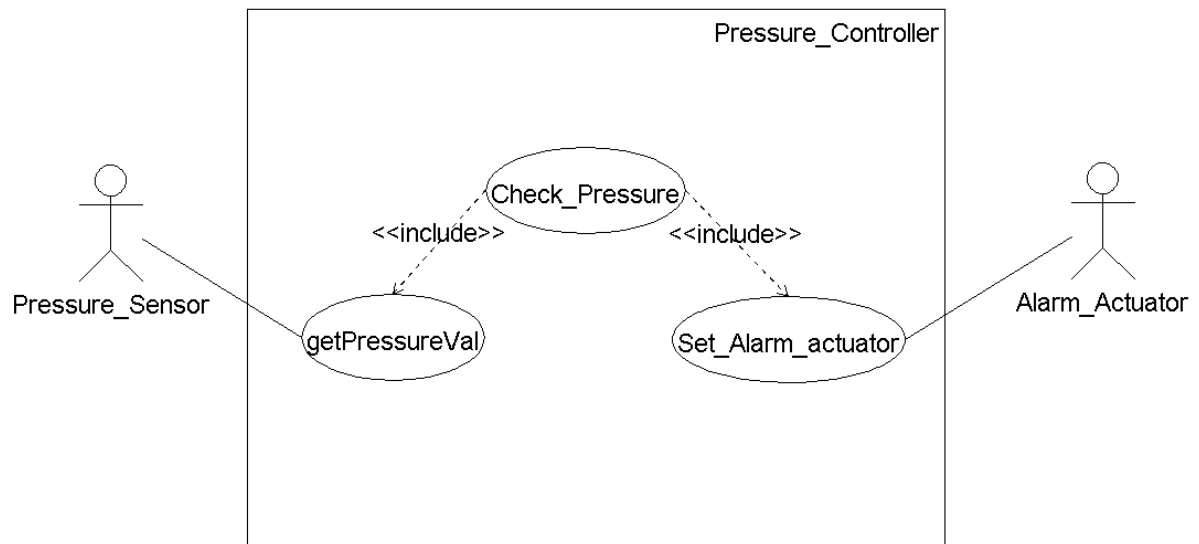
Space Exploration

We will use ARM STM32 board as it meets our requirements and available in stores.

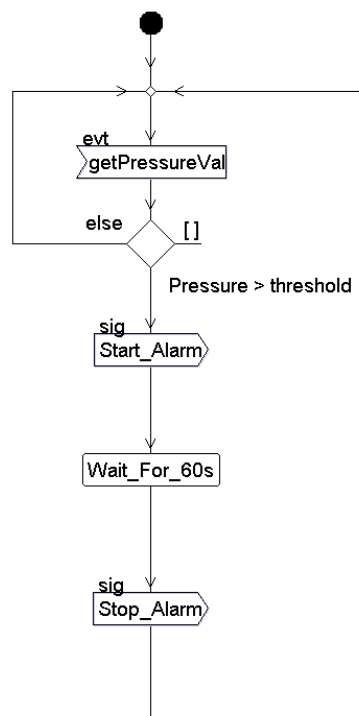


System Analysis

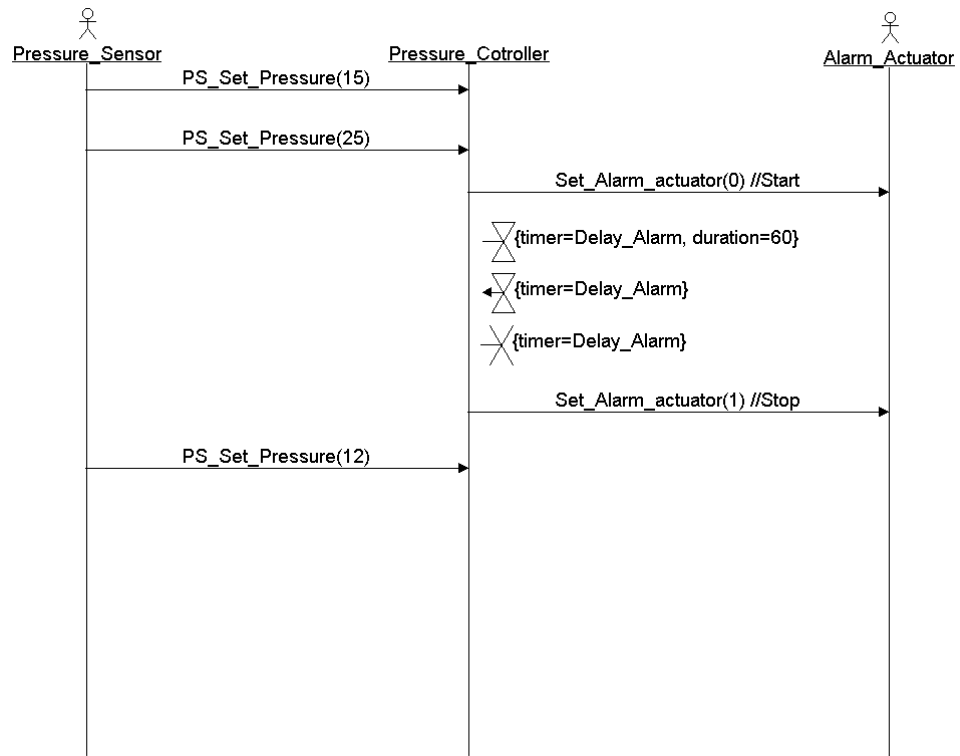
Use case diagram



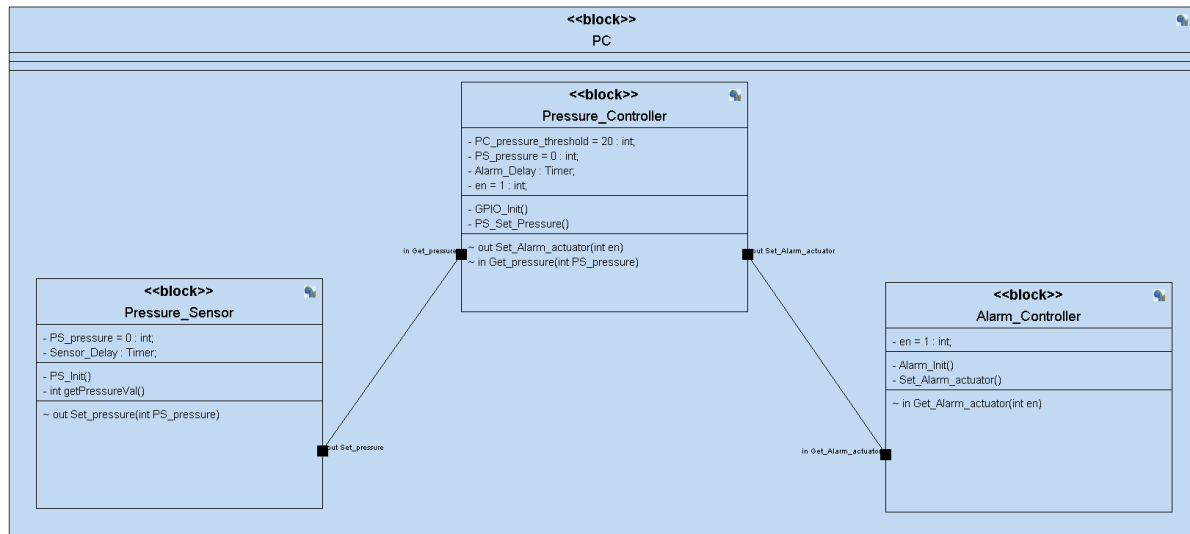
Activity diagram



Sequence diagram



Block Diagram



We will have 3 blocks:

1. Pressure sensor.
2. Pressure controller.
3. Alarm controller.

Pressure sensor

This block will have the pressure variable and will set it by the function `getPressureVal`.

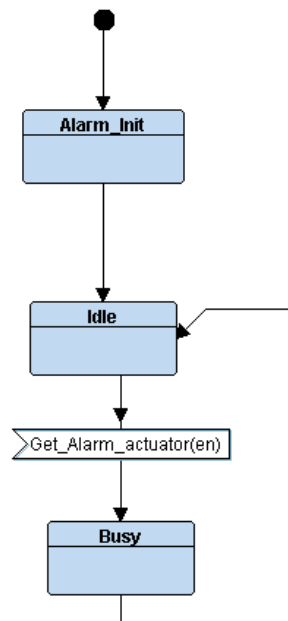
Alarm controller

This block will have the control over the alarm actuator using the function `Set_Alarm_actuator`.

Pressure controller

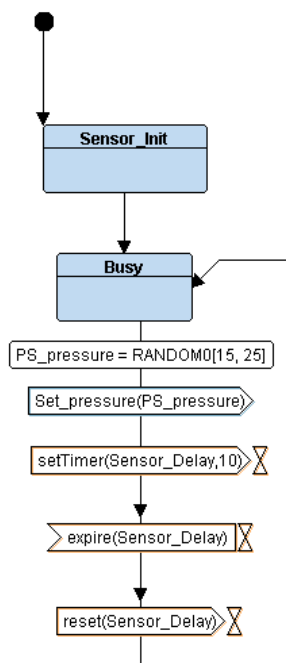
This block will have the control algorithm by retrieving, comparing and sending.

Alarm state machine



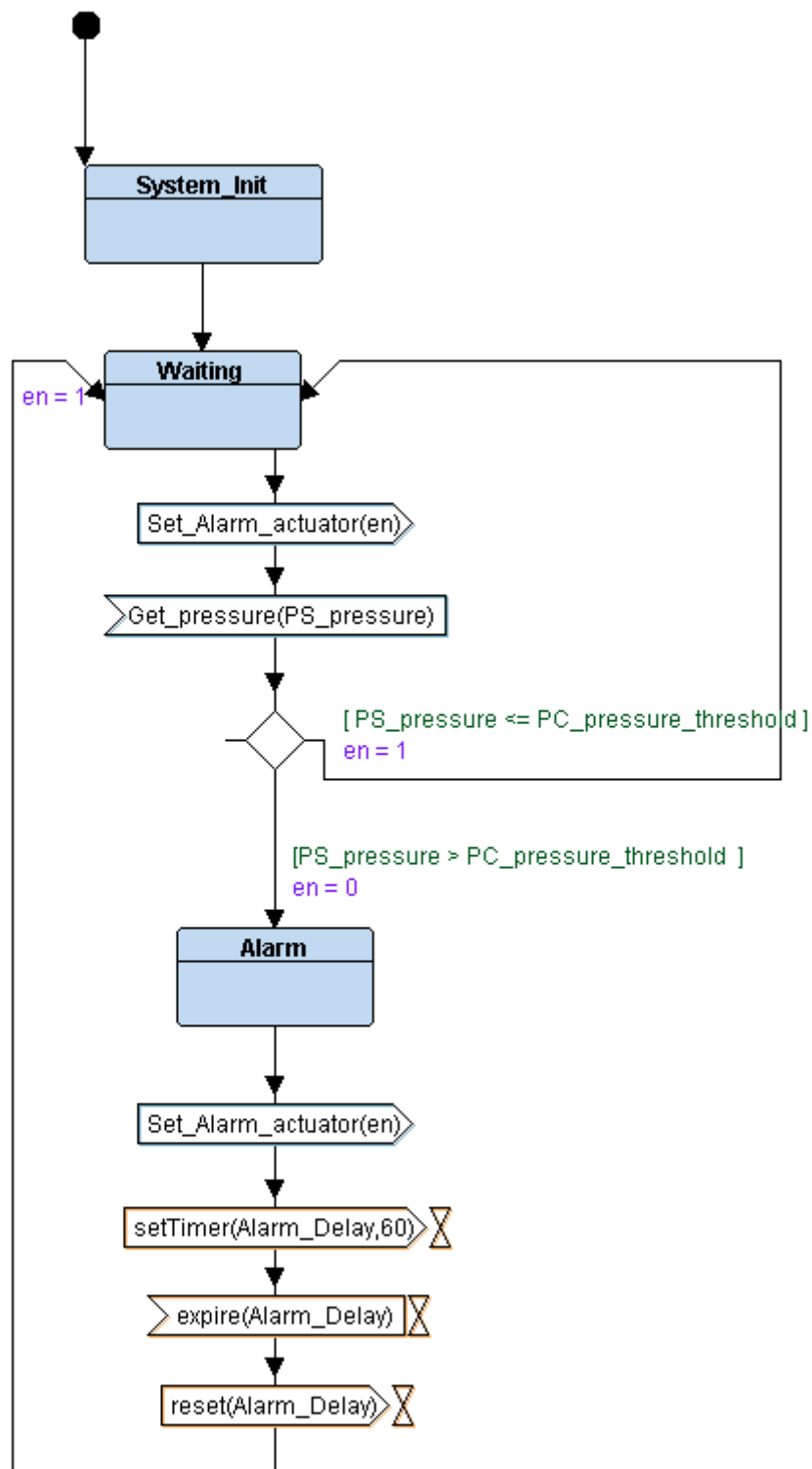
The alarm actuator will be initialized and begin at idle state and will start or stop depending on the “en” variable.

Pressure sensor state machine



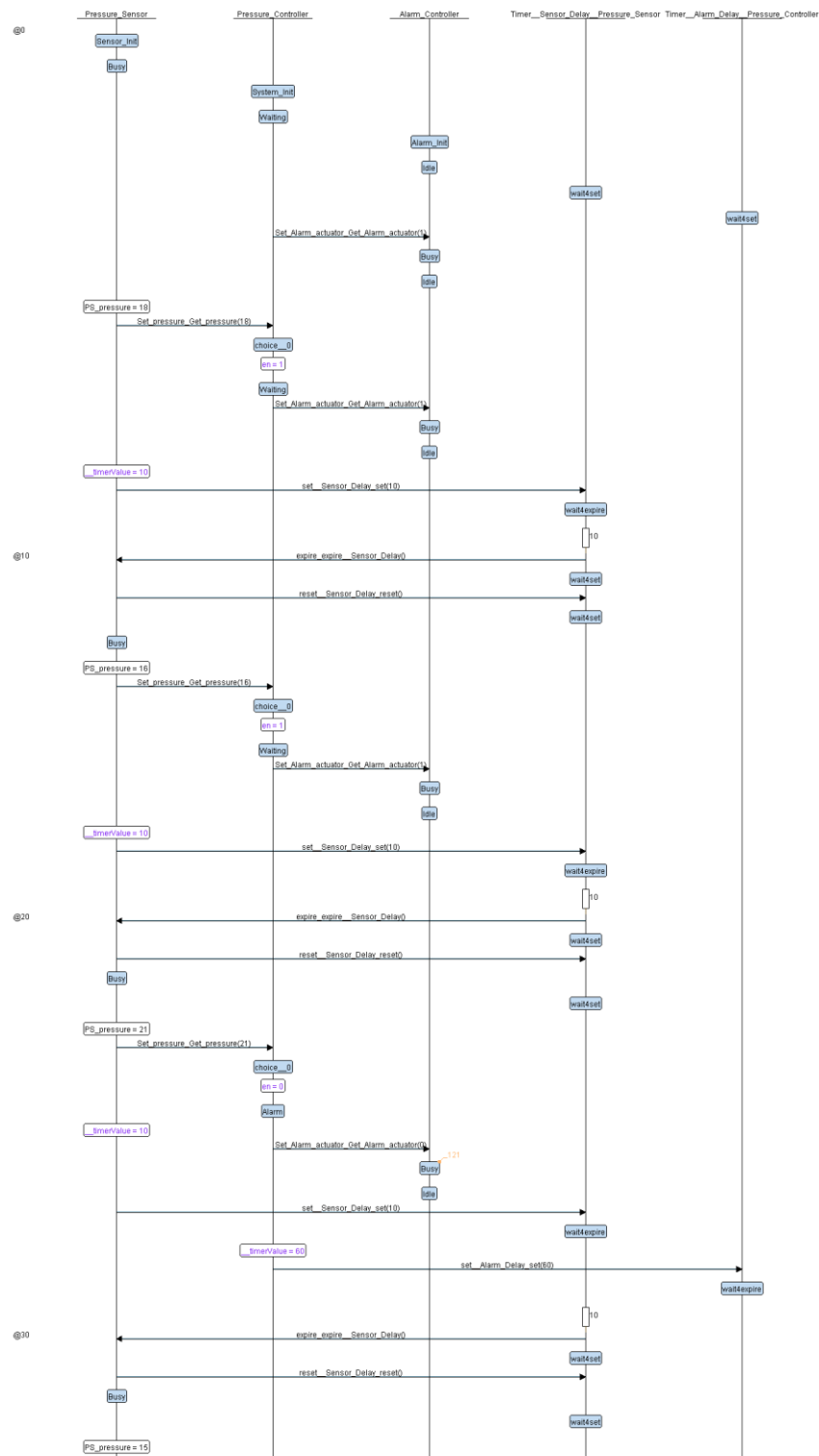
The pressure sensor will be initialized and begin at busy state and keep sending the pressure value every 10 sec.

Pressure controller state machine



The system will begin at the waiting state then sets the alarm off and get the pressure from the sensor then checks whether the pressure is greater than the threshold or not. If it is greater, it will switch to the alarm state and set the alarm on for 60 seconds then repeat the process.

Final Simulation



All blocks started with initializing, then busy for sensor, waiting for the controller and idle for the alarm.

Then, the controller sets the alarm off and get the pressure from the sensor which is equal to 18. It waits for 10 seconds to get the new pressure from sensor.

When the pressure is equal to 21, it switches to the alarm state and set the alarm on for 60 seconds, after that it will read from the sensor again.

Code

driver.h/c

```
1  #define uint32_t unsigned int
2
3  #define SET_BIT(ADDRESS,BIT)  ADDRESS |=  (1<<BIT)
4  #define RESET_BIT(ADDRESS,BIT) ADDRESS &= ~(1<<BIT)
5  #define TOGGLE_BIT(ADDRESS,BIT) ADDRESS ^=  (1<<BIT)
6  #define READ_BIT(ADDRESS,BIT) ((ADDRESS) &  (1<<(BIT)))
7
8
9  #define GPIO_PORTA 0x40010800
10 #define BASE_RCC   0x40021000
11
12 #define APB2ENR    *(volatile uint32_t *) (BASE_RCC + 0x18)
13
14 #define GPIOA_CRL  *(volatile uint32_t *) (GPIO_PORTA + 0x00)
15 #define GPIOA_CRH  *(volatile uint32_t *) (GPIO_PORTA + 0x04)
16 #define GPIOA_IDR  *(volatile uint32_t *) (GPIO_PORTA + 0x08)
17 #define GPIOA_ODR  *(volatile uint32_t *) (GPIO_PORTA + 0x0C)
18
19
20 void Delay(int nCount);
21 int  getPressureVal();
22 void Set_Alarm_actuator(int i);
23 void GPIO_INITIALIZATION();
```

```
1  #include "driver.h"
2
3  void Delay(int nCount)
4  {
5      for(; nCount != 0; nCount--);
6  }
7
8  int getPressureVal(){
9      return (GPIOA_IDR & 0xFF);
10 }
11
12 void Set_Alarm_actuator(int i){
13     if (i == 1){
14         SET_BIT(GPIOA_ODR,13);
15     }
16     else if (i == 0){
17         RESET_BIT(GPIOA_ODR,13);
18     }
19 }
20
21 void GPIO_INITIALIZATION (){
22     SET_BIT(APB2ENR, 2);
23     GPIOA_CRL &= 0xFF0FFFFFFF;
24     GPIOA_CRL |= 0x00000000;
25     GPIOA_CRH &= 0xFF0FFFFFFF;
26     GPIOA_CRH |= 0x22222222;
27 }
```

Pressure_Senor.h/c

```

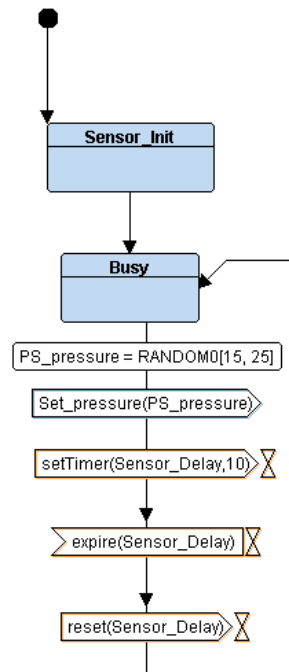
8  #include "Pressure_Sensor.h"
9
10 int PS_pressure = 0;
11
12 void (*P_PS_state) () = 0;
13
14 void PS_Init(){
15     /* Do some stuff */
16 }
17
18 STATE_Fn_Define(PS_Busy){
19     PS_State_ID = PS_Busy;
20     PS_pressure = getPressureVal();
21     PS_Set_Pressure(PS_pressure);
22     P_PS_state = STATE(PS_Busy);
23     Delay(100000);
24 }

```

```

8  #ifndef PRESSURE_SENSOR_H_
9  #define PRESSURE_SENSOR_H_
10
11 #define STATE_Fn_Define(_StatFunction_) void ST_##_StatFunction_()
12 #define STATE(_StatFunction_) ST_##_StatFunction_
13
14 /* States */
15 enum{
16     PS_Busy
17 }PS_State_ID;
18
19 /* State functions */
20 STATE_Fn_Define(PS_Busy);
21
22 /* Global pointer to fn */
23 extern void (*P_PS_state) ();
24
25 void PS_Init();
26
27 #endif /* PRESSURE_SENSOR_H_ */

```



Alarm_Controller.h/c

```

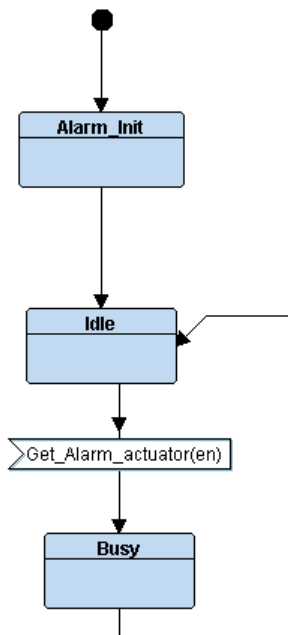
8  #include "Alarm_Controller.h"
9
10 void (*P_AC_state) () = 0;
11
12 void AC_Init() {
13     Set_Alarm_actuator(1);
14 }
15
16 STATE_Fn_Define(AC_Idle) {
17     AC_State_ID = AC_Idle;
18     P_AC_state = STATE(AC_Idle);
19 }
20
21 STATE_Fn_Define(AC_Busy) {
22     AC_State_ID = AC_Busy;
23     P_AC_state = STATE(AC_Idle);
24 }

```

```

8  #ifndef ALARM_CONTROLLER_H_
9  #define ALARM_CONTROLLER_H_
10
11 #define STATE_Fn_Define(_StatFunction_) void ST_##_StatFunction_()
12 #define STATE(_StatFunction_) ST_##_StatFunction_
13
14 /* States */
15 enum {
16     AC_Idle,
17     AC_Busy
18 } AC_State_ID;
19
20 /* State functions */
21 STATE_Fn_Define(AC_Idle);
22 STATE_Fn_Define(AC_Busy);
23
24 /* Global pointer to fn */
25 extern void (*P_AC_state) ();
26
27 void AC_Init();
28
29 #endif /* ALARM_CONTROLLER_H_ */

```



Pressure_Controller.h/c

```

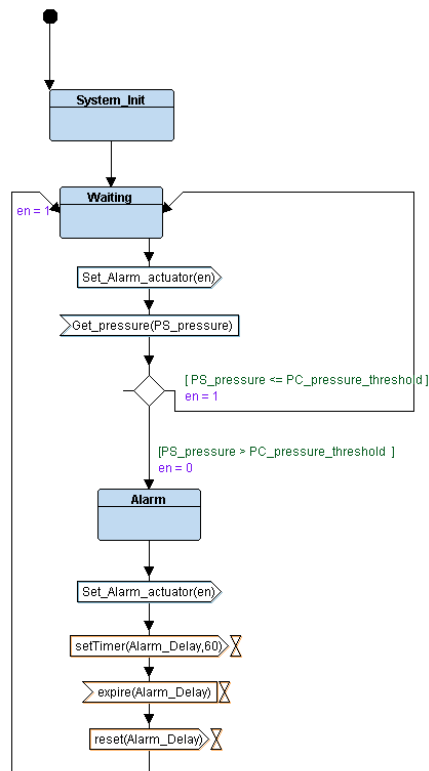
8  #include "Pressure_Controller.h"
9
10 /* Variables */
11 int PC_pressure = 0;
12 int PC_pressure_threshold = 20;
13
14 void (*P_PC_state)() = 0;
15
16 void PS_Set_Pressure(int p){
17     PC_pressure = p;
18     (PC_pressure <= PC_pressure_threshold) ? (P_PC_state = STATE(PC_Waiting)) : (P_PC_state = STATE(PC_Alarm));
19 }
20
21 STATE_Fn_Define(PC_Waiting){
22     PC_State_ID = PC_Waiting;
23     Set_Alarm_actuator(1);
24 }
25
26 STATE_Fn_Define(PC_Alarm){
27     PC_State_ID = PC_Alarm;
28     Set_Alarm_actuator(0);
29     /* Wait 60s */
30     Delay(6000000);
31     Set_Alarm_actuator(1);
32 }

```

```

8  #ifndef PRESSURE_CONTROLLER_H_
9  #define PRESSURE_CONTROLLER_H_
10
11 #define STATE_Fn_Define(_StatFunction_) void ST_##_StatFunction_()
12 #define STATE(_StatFunction_) ST_##_StatFunction_
13
14 /* States */
15 enum{
16     PC_Waiting,
17     PC_Alarm
18 }PC_State_ID;
19
20 /* State functions */
21 STATE_Fn_Define(PC_Waiting);
22 STATE_Fn_Define(PC_Alarm);
23
24 /* Global pointer to fn */
25 extern void (*P_PC_state)();
26
27 #endif /* PRESSURE_CONTROLLER_H_ */

```



main.c

```
1  /*
2  * main.c
3  *
4  * Created on: Nov 26, 2021
5  * Author: Mazen Talaat
6  */
7
8  #include "driver.h"
9  #include "Pressure_Controller.h"
10 #include "Alarm_Controller.h"
11 #include "Pressure_Sensor.h"
12
13 /* Pressure_Controller states: waiting, alarm *
14 * Pressure_Sensor      states: busy          *
15 * Alarm_Controller     states: idle, busy    */
16
17 void setup() {
18     AC_Init();
19     PS_Init();
20     P_PC_state = STATE(PC_Waiting);
21     P_AC_state = STATE(AC_Idle);
22     P_PS_state = STATE(PS_Busy);
23 }
24
25 int main () {
26     GPIO_INITIALIZATION();
27     setup();
28     while (1)
29     {
30         P_PS_state();
31         P_PC_state();
32         P_AC_state();
33         /* wait 10s */
34         Delay(100000);
35     }
36     return 0;
37 }
```

startup.c

```

6  #include <stdint.h>
7
8  /* Functions declaration */
9  extern int main();
10 void Reset_Handler();
11 void Default_Handler()
12 {
13     Reset_Handler();
14 }
15 void NMI_Handler      () __attribute__((weak, alias ("Default_Handler")));
16 void H_Fault_Handler  () __attribute__((weak, alias ("Default_Handler")));
17
18 /* Variables declaration */
19 static unsigned long Stack_top[256]; /*256*4 = 1024B */
20
21 extern unsigned int _S_data;
22 extern unsigned int _S_bss;
23 extern unsigned int _E_data;
24 extern unsigned int _E_bss;
25 extern unsigned int _E_text;
26
27 /* Vector table declaration */
28 /* Array of pointers to a function returns nothing */
29 void (* const g_p_fn_Vectors[])() __attribute__((section(".vectors"))) =
30 {
31     (void (*)( )) ((unsigned long)Stack_top + sizeof(Stack_top)),
32     &Reset_Handler,
33     &NMI_Handler,
34     &H_Fault_Handler
35 };
36
37 /* Reset function body */
38 void Reset_Handler(void)
39 {
40     unsigned int data_size = (unsigned char*)&_E_data - (unsigned char*)&_S_data;
41     unsigned char* P_src = (unsigned char*)&_E_text;
42     unsigned char* P_dst = (unsigned char*)&_S_data;
43     int i;
44     /* copying data from ROM to RAM */
45     for(i=0; i<data_size; i++){
46         *((unsigned char*)P_dst++) = *((unsigned char*)P_src++);
47     }
48     unsigned int bss_size = (unsigned char*)&_E_bss - (unsigned char*)&_S_bss;
49     /*Initializing .bss with zeros */
50     for(i=0; i<bss_size; i++){
51         *((unsigned char*)P_dst++) = (unsigned char)0;
52     }
53     main();
54 }

```

linker_script.ld

```

6  MEMORY
7  {
8      FLASH(RX) : o = 0x08000000 , l = 128K
9      SRAM(RWX) : o = 0x20000000 , l = 20K
10 }
11
12 SECTIONS
13 {
14     .text :
15     {
16         *(.vectors*)
17         *(.text*)
18         *(.rodata)
19         _E_text = . ;
20     }> FLASH
21
22     .data :
23     {
24         _S_data = . ;
25         *(.data)
26         . = ALIGN(4);
27         _E_data = . ;
28     }> SRAM AT > FLASH
29
30     .bss :
31     {
32         _S_bss = . ;
33         *(.bss*)
34         . = ALIGN(4);
35         _E_bss = . ;
36     }> SRAM
37 }

```


map_file.map

```

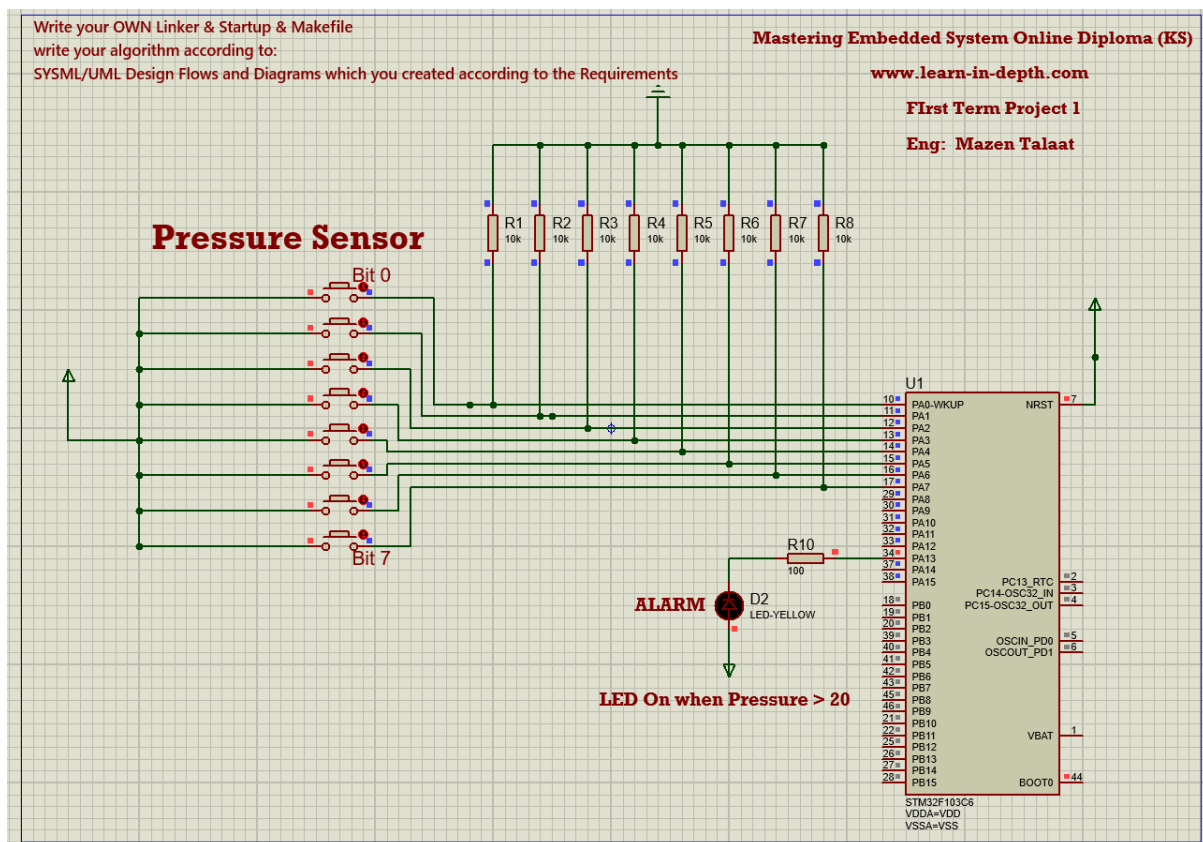
9  Memory Configuration
10
11 Name                Origin                Length                Attributes
12 FLASH                0x08000000            0x00020000            xr
13 SRAM                  0x20000000            0x00005000            xrw
14 *default*            0x00000000            0xffffffff
15
16 Linker script and memory map
17
18
19 .text                0x08000000            0x3b8
20 *(.vectors*)
21 .vectors              0x08000000            0x10 obj/startup.o
22                      0x08000000            g_p_fn_Vectors
23 *(.text*)
24 .text                0x08000010            0x68 obj/Alarm_Controller.o
25                      0x08000010            AC_Init
26                      0x08000020            ST_AC_Idle
27                      0x0800004c            ST_AC_Busy
28 .text                0x08000078            0x10c obj/driver.o
29                      0x08000078            Delay
30                      0x0800009c            getPressureVal
31                      0x080000b4            Set_Alarm_actuator
32                      0x08000104            GPIO_INITIALIZATION
33 .text                0x08000184            0x84 obj/main.o
34                      0x08000184            setup
35                      0x080001c8            main
36 .text                0x08000208            0xa8 obj/Pressure_Controller.o
37                      0x08000208            PS_Set_Pressure
38                      0x08000264            ST_PC_Waiting
39                      0x08000280            ST_PC_Alarm
40 .text                0x080002b0            0x54 obj/Pressure_Sensor.o
41                      0x080002b0            PS_Init
42                      0x080002bc            ST_PS_Busy
43 .text                0x08000304            0xb4 obj/startup.o
44                      0x08000304            H_Fault_Handler
45                      0x08000304            Default_Handler
46                      0x08000304            NMI_Handler
47                      0x08000310            Reset_Handler
48 *(.rodata)
49                      0x080003b8            _E_text = .
50
69 .data                0x20000000            0x4 load address 0x080003b8
70                      0x20000000            _S_data = .
71 *(.data)
72 .data                0x20000000            0x0 obj/Alarm_Controller.o
73 .data                0x20000000            0x0 obj/driver.o
74 .data                0x20000000            0x0 obj/main.o
75 .data                0x20000000            0x4 obj/Pressure_Controller.o
76                      0x20000000            PC_pressure_threshold
77 .data                0x20000004            0x0 obj/Pressure_Sensor.o
78 .data                0x20000004            0x0 obj/startup.o
79                      0x20000004            . = ALIGN (0x4)
80                      0x20000004            _E_data = .
81
82 .igot.plt            0x20000004            0x0 load address 0x080003bc
83 .igot.plt            0x00000000            0x0 obj/Alarm_Controller.o
84
85 .bss                 0x20000004            0x417 load address 0x080003bc
86                      0x20000004            _S_bss = .
87 *(.bss*)
88 .bss                 0x20000004            0x4 obj/Alarm_Controller.o
89                      0x20000004            P_AC_state
90 .bss                 0x20000008            0x0 obj/driver.o
91 .bss                 0x20000008            0x0 obj/main.o
92 .bss                 0x20000008            0x8 obj/Pressure_Controller.o
93                      0x20000008            PC_pressure
94                      0x2000000c            P_PC_state
95 .bss                 0x20000010            0x8 obj/Pressure_Sensor.o
96                      0x20000010            PS_pressure
97                      0x20000014            P_PS_state
98 .bss                 0x20000018            0x400 obj/startup.o
99                      0x20000018            . = ALIGN (0x4)
100                      0x20000018            _E_bss = .
101 COMMON               0x20000018            0x1 obj/Alarm_Controller.o
102                      0x20000018            AC_State_ID
103 COMMON               0x20000019            0x2 obj/main.o
104                      0x20000019            PC_State_ID
105                      0x2000001a            PS_State_ID

```

MakeFile

```
8 CC      = arm-none-eabi-
9 CFLAGS  = -mcpu=cortex-m3 -mthumb -gdwarf-2
10
11 SRCDIR  = src
12 OBJDIR  = obj
13 INCDIR  = include
14 BINDIR  = bin
15
16 LIBS=
17
18 INCS    = -I $(INCDIR)
19 SRC     = $(wildcard $(SRCDIR)/*.c)
20 OBJ     = $(SRC:$(SRCDIR)/%.c=$(OBJDIR)/%.o)
21
22 Project = Project1_Pressure_Controller
23 P_BIN_DIR = $(BINDIR)/$(Project)
24
25 all: $(P_BIN_DIR).bin $(P_BIN_DIR).hex
26     @echo "===== Everything Done ====="
27
28 $(OBJDIR)/%.o: $(SRCDIR)/%.c
29     $(CC) gcc.exe -c $(CFLAGS) $(INCS) $< -o $@
30     @echo "===== .C to .O Done ====="
31
32 $(P_BIN_DIR).elf: $(OBJ)
33     $(CC) ld.exe -T linker_script.ld $(LIBS) $^ -o $@ -Map=$(BINDIR)/map_file.map
34     @echo "===== Linking Done ====="
35
36 $(P_BIN_DIR).bin: $(P_BIN_DIR).elf
37     $(CC) objcopy.exe -O binary $< $@
38     @echo "===== Binary Out Done ====="
39
40 $(P_BIN_DIR).hex: $(P_BIN_DIR).elf
41     $(CC) objcopy.exe -O ihex $< $@
42     @echo "===== Hex Out Done ====="
43
44 clean_all:
45     rm -rf $(OBJDIR)/*.o $(BINDIR)/*.elf $(BINDIR)/*.bin $(BINDIR)/*.map $(BINDIR)/*.hex
46     @echo "===== Cleaned Everything ====="
47 clean:
48     rm -rf $(BINDIR)/*.elf $(BINDIR)/*.bin
49     @echo "===== Cleaned .elf and .bin ====="
```

Proteus Simulation



Name	Address	Value
PC_State_ID	20000419	PC_Waiting (0)
AC_State_ID	20000418	AC_Idle (0)
PS_State_ID	2000041A	PS_Busy (0)
PC_State_ID	20000419	PC_Waiting (0)
PC_pressure	20000008	0
PC_pressure_threshold	20000000	20
PS_State_ID	2000041A	PS_Busy (0)
PS_pressure	20000010	0
Stack_top	20000018	dword[256]
AC_State_ID	20000418	AC_Idle (0)
nCount	BP+12 = @200003E4	3827

Pressure = 0, LED Off



Name	Address	Value
PC_State_ID	20000419	PC_Alarm (1)
AC_State_ID	20000418	AC_Idle (0)
PS_State_ID	2000041A	PS_Busy (0)
PC_State_ID	20000419	PC_Alarm (1)
PC_pressure	20000008	32
PC_pressure_threshold	20000000	20
PS_State_ID	2000041A	PS_Busy (0)
PS_pressure	20000010	32
 Stack_top	20000018	dword[256]
AC_State_ID	20000418	AC_Idle (0)
nCount	BP+12 = @200003DC	5830478

Pressure = 32, LED On

Write your OWN Linker & Startup & Makefile

write your algorithm according to:

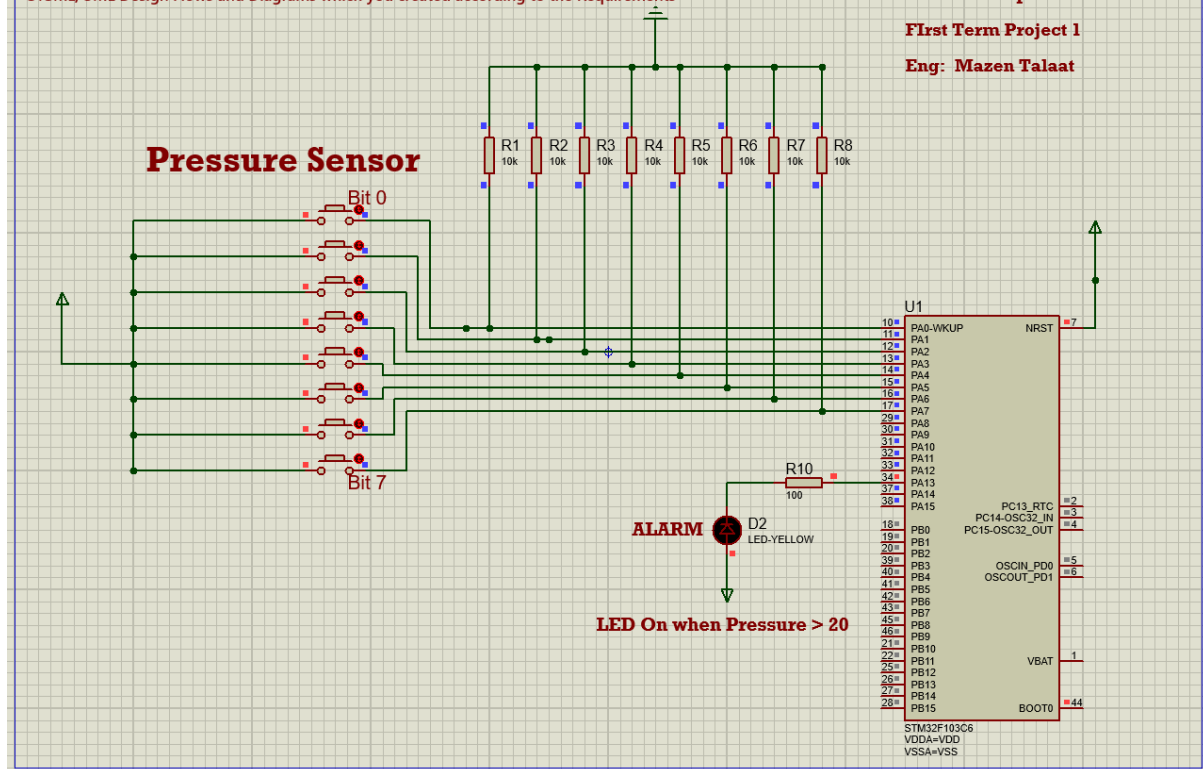
SYSML/UML Design Flows and Diagrams which you created according to the Requirements

Mastering Embedded System Online Diploma (KS)

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First Term Project 1

Eng: Mazen Talaat

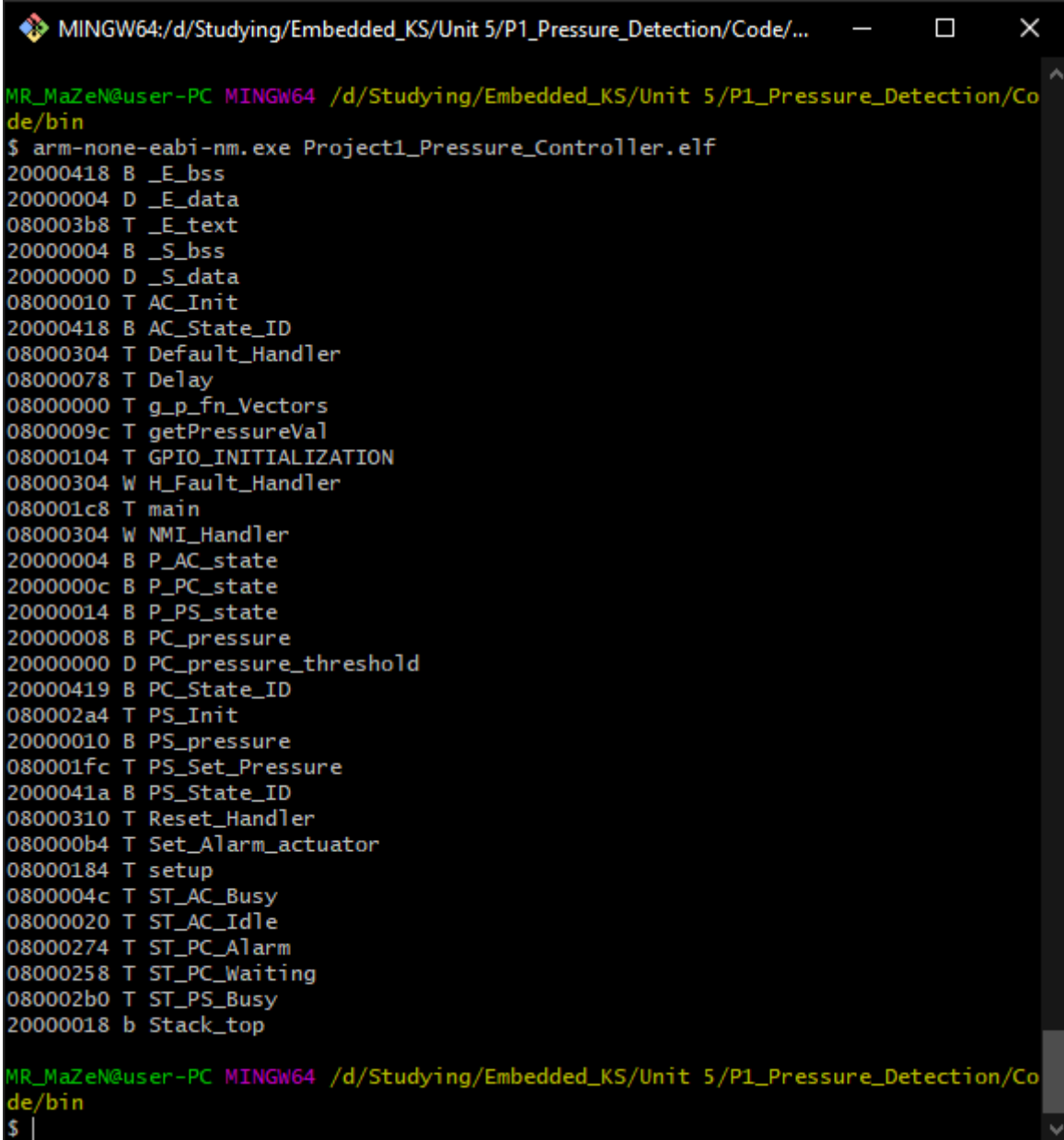


Name	Address	Value
PC_State_ID	20000419	PC_Waiting (0)
AC_State_ID	20000418	AC_Idle (0)
PS_State_ID	2000041A	PS_Busy (0)
PC_State_ID	20000419	PC_Waiting (0)
PC_pressure	20000008	0
PC_pressure_threshold	20000000	20
PS_State_ID	2000041A	PS_Busy (0)
PS_pressure	20000010	0
Stack_top	20000018	dword[256]
AC_State_ID	20000418	AC_Idle (0)
nCount	BP+12 = @200003E4	30505

Pressure = 0, LED Off

After some time (nCount)

Symbols table



```
MINGW64:/d/Studying/Embedded_KS/Unit 5/P1_Pressure_Detection/Code/...  
MR_MaZeN@user-PC MINGW64 /d/Studying/Embedded_KS/Unit 5/P1_Pressure_Detection/Code/bin  
$ arm-none-eabi-nm.exe Project1_Pressure_Controller.elf  
20000418 B _E_bss  
20000004 D _E_data  
080003b8 T _E_text  
20000004 B _S_bss  
20000000 D _S_data  
08000010 T AC_Init  
20000418 B AC_State_ID  
08000304 T Default_Handler  
08000078 T Delay  
08000000 T g_p_fn_Vectors  
0800009c T getPressureVal  
08000104 T GPIO_INITIALIZATION  
08000304 W H_Fault_Handler  
080001c8 T main  
08000304 W NMI_Handler  
20000004 B P_AC_state  
2000000c B P_PC_state  
20000014 B P_PS_state  
20000008 B PC_pressure  
20000000 D PC_pressure_threshold  
20000419 B PC_State_ID  
080002a4 T PS_Init  
20000010 B PS_pressure  
080001fc T PS_Set_Pressure  
2000041a B PS_State_ID  
08000310 T Reset_Handler  
080000b4 T Set_Alarm_actuator  
08000184 T setup  
0800004c T ST_AC_Busy  
08000020 T ST_AC_Idle  
08000274 T ST_PC_Alarm  
08000258 T ST_PC_Waiting  
080002b0 T ST_PS_Busy  
20000018 b Stack_top  
MR_MaZeN@user-PC MINGW64 /d/Studying/Embedded_KS/Unit 5/P1_Pressure_Detection/Code/bin  
$ |
```

Sections

main.o

```
$ arm-none-eabi-objdump.exe -h main.o

main.o:      file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
  0 .text          00000078  00000000  00000000  00000034  2**2
    CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE
  1 .data           00000000  00000000  00000000  000000ac  2**0
    CONTENTS, ALLOC, LOAD, DATA
  2 .bss            00000000  00000000  00000000  000000ac  2**0
    ALLOC
  3 .debug_info     000000fe  00000000  00000000  000000ac  2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
  4 .debug_abbrev   0000009a  00000000  00000000  000001aa  2**0
    CONTENTS, READONLY, DEBUGGING
  5 .debug_loc      00000058  00000000  00000000  00000244  2**0
    CONTENTS, READONLY, DEBUGGING
  6 .debug_aranges  00000020  00000000  00000000  0000029c  2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
  7 .debug_line     000000a3  00000000  00000000  000002bc  2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
  8 .debug_str      000000cd  00000000  00000000  0000035f  2**0
    CONTENTS, READONLY, DEBUGGING
  9 .comment        00000012  00000000  00000000  0000042c  2**0
    CONTENTS, READONLY
10 .ARM.attributes 00000033  00000000  00000000  0000043e  2**0
    CONTENTS, READONLY
11 .debug_frame     00000048  00000000  00000000  00000474  2**2
    CONTENTS, RELOC, READONLY, DEBUGGING
```

Alarm_Controller.o

```
$ arm-none-eabi-objdump.exe -h Alarm_Controller.o

Alarm_Controller.o:      file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
  0 .text          00000068  00000000  00000000  00000034  2**2
    CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE
  1 .data           00000000  00000000  00000000  0000009c  2**0
    CONTENTS, ALLOC, LOAD, DATA
  2 .bss            00000004  00000000  00000000  0000009c  2**2
    ALLOC
  3 .debug_info     000000c6  00000000  00000000  0000009c  2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
  4 .debug_abbrev   0000009a  00000000  00000000  00000162  2**0
    CONTENTS, READONLY, DEBUGGING
  5 .debug_loc      00000084  00000000  00000000  000001fc  2**0
    CONTENTS, READONLY, DEBUGGING
  6 .debug_aranges  00000020  00000000  00000000  00000280  2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
  7 .debug_line     0000006e  00000000  00000000  000002a0  2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
  8 .debug_str      000000b5  00000000  00000000  0000030e  2**0
    CONTENTS, READONLY, DEBUGGING
  9 .comment        00000012  00000000  00000000  000003c3  2**0
    CONTENTS, READONLY
10 .ARM.attributes 00000033  00000000  00000000  000003d5  2**0
    CONTENTS, READONLY
11 .debug_frame     0000005c  00000000  00000000  00000408  2**2
    CONTENTS, RELOC, READONLY, DEBUGGING
```


driver.o

```
$ arm-none-eabi-objdump.exe -h driver.o

driver.o:      file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
 0 .text          0000010c  00000000  00000000  00000034  2**2
                CONTENTS, ALLOC, LOAD, READONLY, CODE
 1 .data          00000000  00000000  00000000  00000140  2**0
                CONTENTS, ALLOC, LOAD, DATA
 2 .bss           00000000  00000000  00000000  00000140  2**0
                ALLOC
 3 .debug_info     000000ab  00000000  00000000  00000140  2**0
                CONTENTS, RELOC, READONLY, DEBUGGING
 4 .debug_abbrev   00000085  00000000  00000000  000001eb  2**0
                CONTENTS, READONLY, DEBUGGING
 5 .debug_loc      000000c8  00000000  00000000  00000270  2**0
                CONTENTS, READONLY, DEBUGGING
 6 .debug_aranges  00000020  00000000  00000000  00000338  2**0
                CONTENTS, RELOC, READONLY, DEBUGGING
 7 .debug_line     00000058  00000000  00000000  00000358  2**0
                CONTENTS, RELOC, READONLY, DEBUGGING
 8 .debug_str      00000096  00000000  00000000  000003b0  2**0
                CONTENTS, READONLY, DEBUGGING
 9 .comment        00000012  00000000  00000000  00000446  2**0
                CONTENTS, READONLY
10 .ARM.attributes 00000033  00000000  00000000  00000458  2**0
                CONTENTS, READONLY
11 .debug_frame    00000078  00000000  00000000  0000048c  2**2
                CONTENTS, RELOC, READONLY, DEBUGGING
```

Pressure_Controller.o

```
$ arm-none-eabi-objdump.exe -h Pressure_Controller.o

Pressure_Controller.o:      file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
 0 .text          000000a8  00000000  00000000  00000034  2**2
                CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE
 1 .data          00000004  00000000  00000000  000000dc  2**2
                CONTENTS, ALLOC, LOAD, DATA
 2 .bss           00000008  00000000  00000000  000000e0  2**2
                ALLOC
 3 .debug_info     00000123  00000000  00000000  000000e0  2**0
                CONTENTS, RELOC, READONLY, DEBUGGING
 4 .debug_abbrev   000000c0  00000000  00000000  00000203  2**0
                CONTENTS, READONLY, DEBUGGING
 5 .debug_loc      00000090  00000000  00000000  000002c3  2**0
                CONTENTS, READONLY, DEBUGGING
 6 .debug_aranges  00000020  00000000  00000000  00000353  2**0
                CONTENTS, RELOC, READONLY, DEBUGGING
 7 .debug_line     00000083  00000000  00000000  00000373  2**0
                CONTENTS, RELOC, READONLY, DEBUGGING
 8 .debug_str      000000f0  00000000  00000000  000003f6  2**0
                CONTENTS, READONLY, DEBUGGING
 9 .comment        00000012  00000000  00000000  000004e6  2**0
                CONTENTS, READONLY
10 .ARM.attributes 00000033  00000000  00000000  000004f8  2**0
                CONTENTS, READONLY
11 .debug_frame    00000064  00000000  00000000  0000052c  2**2
                CONTENTS, RELOC, READONLY, DEBUGGING
```


Pressure_Sensor.o

```
$ arm-none-eabi-objdump.exe -h Pressure_Sensor.o

Pressure_Sensor.o:      file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
 0 .text          00000060 00000000 00000000 00000034 2**2
    CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE
 1 .data          00000000 00000000 00000000 00000094 2**0
    CONTENTS, ALLOC, LOAD, DATA
 2 .bss           00000008 00000000 00000000 00000094 2**2
    ALLOC
 3 .debug_info     000000e3 00000000 00000000 00000094 2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
 4 .debug_abbrev   000000ad 00000000 00000000 00000177 2**0
    CONTENTS, READONLY, DEBUGGING
 5 .debug_loc      00000058 00000000 00000000 00000224 2**0
    CONTENTS, READONLY, DEBUGGING
 6 .debug_aranges  00000020 00000000 00000000 0000027c 2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
 7 .debug_line     0000006a 00000000 00000000 0000029c 2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
 8 .debug_str      000000bf 00000000 00000000 00000306 2**0
    CONTENTS, READONLY, DEBUGGING
 9 .comment        00000012 00000000 00000000 000003c5 2**0
    CONTENTS, READONLY
10 .ARM.attributes 00000033 00000000 00000000 000003d7 2**0
    CONTENTS, READONLY
11 .debug_frame    00000044 00000000 00000000 0000040c 2**2
    CONTENTS, RELOC, READONLY, DEBUGGING
```

startup.o

```
$ arm-none-eabi-objdump.exe -h startup.o

startup.o:      file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
 0 .text          000000b4 00000000 00000000 00000034 2**2
    CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE
 1 .data          00000000 00000000 00000000 000000e8 2**0
    CONTENTS, ALLOC, LOAD, DATA
 2 .bss           00000400 00000000 00000000 000000e8 2**2
    ALLOC
 3 .vectors        00000010 00000000 00000000 000000e8 2**2
    CONTENTS, ALLOC, LOAD, RELOC, READONLY, DATA
 4 .debug_info     00000183 00000000 00000000 000000f8 2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
 5 .debug_abbrev   000000c8 00000000 00000000 0000027b 2**0
    CONTENTS, READONLY, DEBUGGING
 6 .debug_loc      00000064 00000000 00000000 00000343 2**0
    CONTENTS, READONLY, DEBUGGING
 7 .debug_aranges  00000020 00000000 00000000 000003a7 2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
 8 .debug_line     0000006c 00000000 00000000 000003c7 2**0
    CONTENTS, RELOC, READONLY, DEBUGGING
 9 .debug_str      0000015d 00000000 00000000 00000433 2**0
    CONTENTS, READONLY, DEBUGGING
10 .comment        00000012 00000000 00000000 00000590 2**0
    CONTENTS, READONLY
11 .ARM.attributes 00000033 00000000 00000000 000005a2 2**0
    CONTENTS, READONLY
12 .debug_frame    0000004c 00000000 00000000 000005d8 2**2
    CONTENTS, RELOC, READONLY, DEBUGGING
```

Project.elf

```
$ arm-none-eabi-objdump.exe -h Project1_Pressure_Controller.elf
Project1_Pressure_Controller.elf:      file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
  0 .text          000003b8  08000000  08000000  00008000  2**2
    CONTENTS, ALLOC, LOAD, READONLY, CODE
  1 .data          00000004  20000000  080003b8  00010000  2**2
    CONTENTS, ALLOC, LOAD, DATA
  2 .bss           00000417  20000004  080003bc  00010004  2**2
    ALLOC
  3 .debug_info     000005f8  00000000  00000000  00010004  2**0
    CONTENTS, READONLY, DEBUGGING
  4 .debug_abbrev   000003ee  00000000  00000000  000105fc  2**0
    CONTENTS, READONLY, DEBUGGING
  5 .debug_loc      000002f0  00000000  00000000  000109ea  2**0
    CONTENTS, READONLY, DEBUGGING
  6 .debug_aranges  000000c0  00000000  00000000  00010cda  2**0
    CONTENTS, READONLY, DEBUGGING
  7 .debug_line     000002c2  00000000  00000000  00010d9a  2**0
    CONTENTS, READONLY, DEBUGGING
  8 .debug_str      000002a4  00000000  00000000  0001105c  2**0
    CONTENTS, READONLY, DEBUGGING
  9 .comment        00000011  00000000  00000000  00011300  2**0
    CONTENTS, READONLY
10 .ARM.attributes 00000033  00000000  00000000  00011311  2**0
    CONTENTS, READONLY
11 .debug_frame     00000210  00000000  00000000  00011344  2**2
    CONTENTS, READONLY, DEBUGGING
```