view_frames Result Recorded at time: 1584732474.178 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1584732474.178 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1584732474.178 sec old) Buffer length: 0.000 sec Link0 Broadcaster: /robot_state_publisher Average rate: 10.211 Hz Most recent transform: 1584732474.090 (0.087 sec old) Buffer length: 4.799 sec Link1 Broadcaster: /robot_state_publisher Average rate: 10.211 Hz Most recent transform: 1584732474.090 (0.087 sec old) Buffer length: 4.799 sec Link2 Broadcaster: /robot_state_publisher Average rate: 10.211 Hz Most recent transform: 1584732474.090 (0.087 sec old) Buffer length: 4.799 sec Link3 Broadcaster: /robot_state_publisher Average rate: 10.211 Hz Most recent transform: 1584732474.090 (0.087 sec old) Buffer length: 4.799 sec Link4 Broadcaster: /robot_state_publisher Average rate: 10.211 Hz Most recent transform: 1584732474.090 (0.087 sec old) Buffer length: 4.799 sec Link5 Broadcaster: /robot_state_publisher Average rate: 10.211 Hz Most recent transform: 1584732474.090 (0.087 sec old) Buffer length: 4.799 sec EE Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1584732474.178 sec old) Buffer length: 0.000 sec

Connector