

Two Functional MDD's for the Price of One - Part 2

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Symphony - Modeling Language for Non-Linear Optimization

- Models linear and non-linear optimization problems
- Simple declarative language
- Support for bounded parameters and constraint programming
- Generates performance oriented c code
- Solver Agnostic (plug into your solver of choice)

Vectors and dimension

- In Symphony, everything is vector.
- Vectors
 - ▶ Dimension (Shape): can be scalar, 1D, 2D, 3D, ...
 - ★ Scalar is just a single number
 - ★ 1D(n) variable is an array of n number, useful for problems in signal processing, sound processing, ..
 - ★ 2D($m \times n$) variable is a 2D array of $m \times n$ numbers, useful for problems in image processing, ...
 - ★ 3D($m \times n \times p$) variable is a 3D array of $m \times n \times p$ numbers, useful for problems in topology, image processing with voxels, ...
 - ▶ Numtype: can be real (R) or complex (C)
- We can manipulate vectors like adding, multiplying, doing inner product, ... to form new vectors (expressions).

Forming An Expression

- $(+), (-), (*), (/)$ Add/Subtract/Multiply/Divide (point-wise) two vectors having same shape and same numtype
- $(*.)$ Scale a vector with a scalar (if they form a vector space in Mathematics, i.e, real number can scale anything, but complex can only scale complex)
- $(<.>)$ Inner product (dot product) of two vectors
- $(^)$ Power a vector with an integer
- Piecewise:

```
1  case x:
2      x <= 0    -> -x
3      otherwise -> x
4
```

- `sumElements`, `norm2square`, `normHuber`

Structure

A valid symphony problem consists of:

- Variables
- Objective function
- Constants (optional)
- Constraints (optional)

Variable Declaration

- Variables are declared in a **variable** block
- For example:

```
1  variables :  
2      x[100][100] = 10  
3      y[20][20][20]  
4      a, b = 2, c  
5
```

- Assignment denotes an initial value
- Unassigned variables will be randomly initialized with a number between (0,1)

Objective Function

- Declared in a **minimize** block
- For example:

```
1  minimize:  
2      (x - y)^2  
3
```

- Must evaluate to a scalar (one dimensional value)

Constant Declarations

- Declared in a **constants** block
- For example:

```
1  constants :  
2      m = 2  
3      delta = 10, sigma = 15  
4      mask[100][100] = Pattern(FIRST_ROW_1)  
5
```

- Unlike variables, constants must be assigned, and are not optimized over
- Multi-dimensional constants can be assigned using the Pattern function, which takes the following macros as input

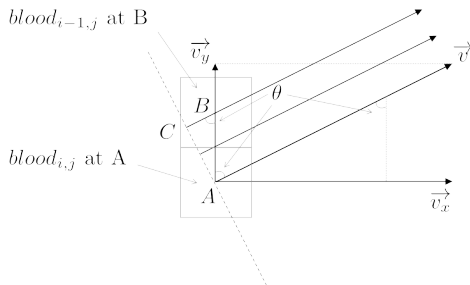
```
1  FIRST_COLUMN_0, FIRST_COLUMN_1, LAST_ROW_0  
2  LAST_ROW_1, LAST_COLUMN_0, LAST_COLUMN_1 ...  
3
```

Local Variables

- Sometimes your expression can become too convoluted, declare local variables using a **let** block
- For example:

```
1  let :
2    regularizerX = norm2square x
3    regularizerY = norm2square y
4    regularizer = regularizerX + regularizerY
5
6  minimize:
7    norm2square (x - y) + regularizer
8
```

Sample Problem 1 - Velocity Problem



- MRI imaging problem dealing with blood flow
- Given vector field of blood flow: can we find how long each blood cell has been there?
- Do this by minimizing the **flow** over time (hence an optimization problem!)

Velocity Problem - Model Derivation

$$\Rightarrow t_{i-1,j} - t_{i,j} = \frac{CB}{|\vec{v}|} = \frac{AB \cos \theta}{\sqrt{v_x^2 + v_y^2}} = \frac{1 \frac{v_y}{\sqrt{v_x^2 + v_y^2}}}{\sqrt{v_x^2 + v_y^2}} = \frac{v_y}{v_x^2 + v_y^2} \quad (1)$$

$$\Rightarrow (t_{i-1,j} - t_{i,j})(v_x^2 + v_y^2) = v_y \quad (2)$$

$$\Leftrightarrow \Delta t_y (v_x^2 + v_y^2) = v_y \quad (3)$$

Velocity Problem - Optimization Model

$$\min_t \sum_{\text{pixels}} (\Delta t_x (v_x^2 + v_y^2) - v_x) * v_x^2)^2 \\ + \sum_{\text{pixels}} (\Delta t_y ((v_x^2 + x_y^2) - x_y) * x_y^2)^2$$

$v_{(x,y)}$ velocity in x,y direction

$t_{(x,y)}$ time in x,y direction

Variable Bounds

- Variable bounds are put in a **constraints** block
- For example:

```
1  constants :  
2      yUpperBound = 5  
3  constraints :  
4      x >= 10  
5      y <= yUpperBound  
6
```

- Bounds must be assigned to a value or constant (not an expression)

File Storage

- Values for variables or constants can be loaded from text files or HDF5 datasets
- For example:

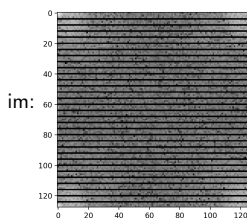
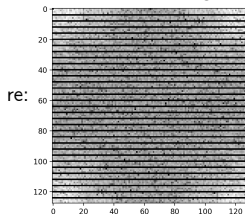
```
1  constants :  
2      b[10][10] = File("b.txt")  
3  variables :  
4      real[128][128] = Dataset("dataset.hd5", "real")  
5      imag[128][128] = Dataset("dataset.hd5", "imag")  
6
```

HDF5 - Hierarchical Data Format

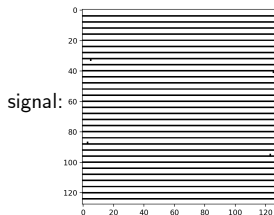
- Designed to store and organize large amounts of data
- Capable of storing multiple labeled datasets in a single file
- Great library [h5py](#) for python, capable of generating data straight from numpy arrays

Brain Problem - 1

Data: real part (re) and imag part (im) of image's k-space received by the MRI.
Black spots are where the signal is lost.

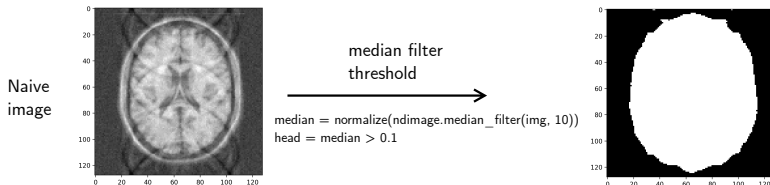


Apply a threshold: $\text{signal} = \text{abs}(\text{re}) > 0.5$ to get a matrix of where the signal is received.
 $\text{signal}[i][j] = 1$ if there is signal in this spot, 0 otherwise



Brain Problem - 2

Naively reconstruct the image by taking inverse FFT, we get the naive image.



Determine the box
constraint

x_{lb} and x_{ub}

- Inside head: $\text{pixel} \geq 0$
- Outside head: $-4 \leq \text{pixel} \leq 4$

Multi-Coil MRI

$$\min_{\rho} \sum_{i=0}^{\text{\#coils}} ||FT(P)) - m_i||^2 \\ + \lambda(||\delta_x(\rho)||^2 + ||\delta_y(\rho)||^2)$$

ρ = True Image

S_i = Coil Sensitivity

m_i = K-Space measurement

λ = scaling

Constraints

- Declared in a **constraints** block (just like variable bounds)
- For example:

```
1  constraints :  
2      x <.> x >= 0  
3
```

- Expression must be on LHS and must evaluate to scalar (one-dimensional value)
- **Note:** limits your choice of supported solvers

Logistics Problem

- In most logistic problems we want to Maximize the benefits or Minimize the costs.
- This table is for defining the revenue of sending products from factories to companies.

	Company1	Company2
Factory1	1.75	2.25
Factory2	2.00	2.50

- the below table shows the demand of companies. Also the capacity of each factory for producing is 60000.

	Company1	Company2
Factory1	x_{11}	x_{12}
Factory2	x_{21}	x_{22}
	23000	30000

Logistics Problem

- we want to Maximize the revenue.

$$Max f(x) = Min - f(x)$$

- So we will have:

$$Min - ((c_{11} * x_{11}) + (c_{12} * x_{12}) + (c_{21} * x_{21}) + (c_{22} * x_{22}))$$

subject to:

$$x_{11} \geq 0, x_{12} \geq 0, x_{21} \geq 0, x_{22} \geq 0$$

$$x_{11} + x_{21} \geq \text{DemandCompany1}$$

$$x_{12} + x_{22} \geq \text{DemandCompany2}$$

$$x_{11} + x_{12} \leq \text{CapacityFactory1}$$

$$x_{21} + x_{22} \leq \text{CapacityFactory2}$$

Logistics Problem

variables here are the the products which are sent from each factory to each company.

$$\text{CapacityFactory1} = 600000$$

$$\text{CapacityFactory2} = 600000$$

$$\text{DemandCompany1} = 30000$$

$$\text{DemandCompany2} = 23000$$

$$c_{11} \rightarrow \text{revenue of } x_{11} = 1.75$$

$$c_{12} \rightarrow \text{revenue of } x_{12} = 2.25$$

$$c_{21} \rightarrow \text{revenue of } x_{21} = 2$$

$$c_{22} \rightarrow \text{revenue of } x_{22} = 2.50$$