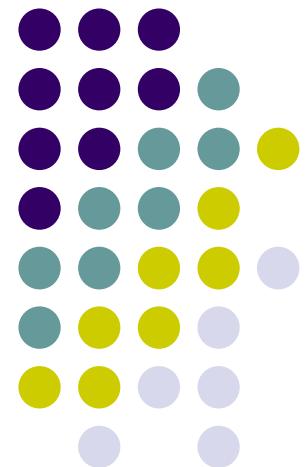


Digital Image Processing (CS/ECE 545)

Lecture 9: Color Images (Part 2) & Introduction to Spectral Techniques (Fourier Transform, DFT, DCT)

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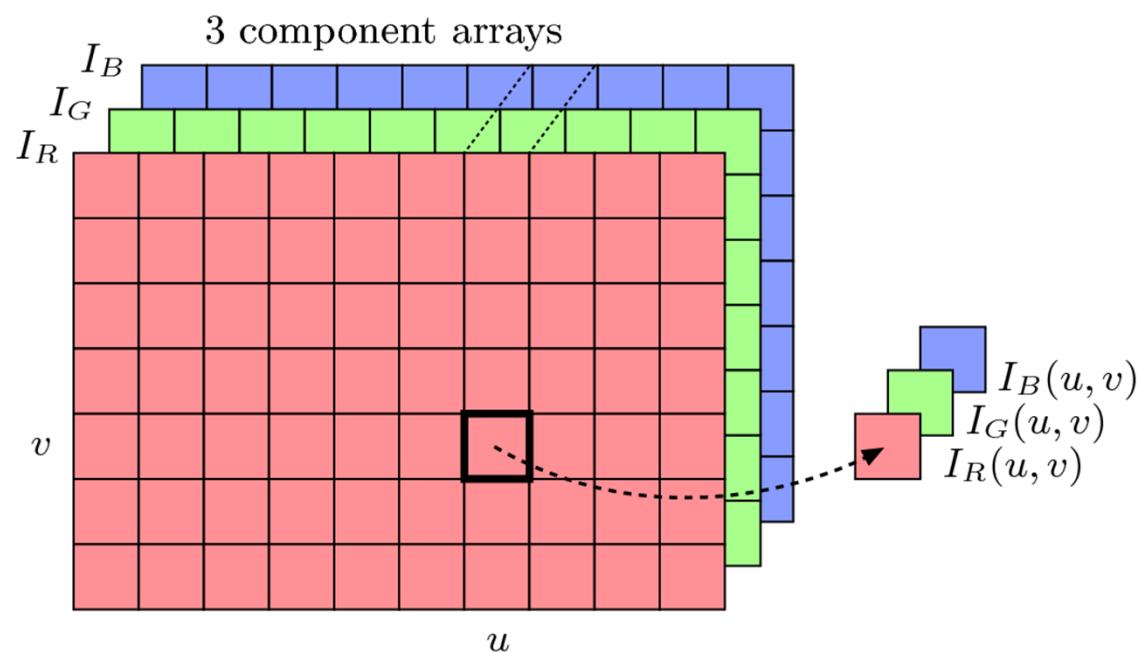
Organization of Color Images

- **True color:** Uses all colors in color space
- **Indexed color:** Uses only some colors
 - Which subset of colors to use? Depends on application
- True color:
 - used in applications that contain many colors with subtle differences
 - E.g. digital photography or photorealistic rendering
- Two main ways to organize true color
 - Component ordering
 - Packed ordering



True Color: Component Ordering

- Colors in 3 separate arrays of similar length
- Retrieve same location (u,v) in each R, G and B array

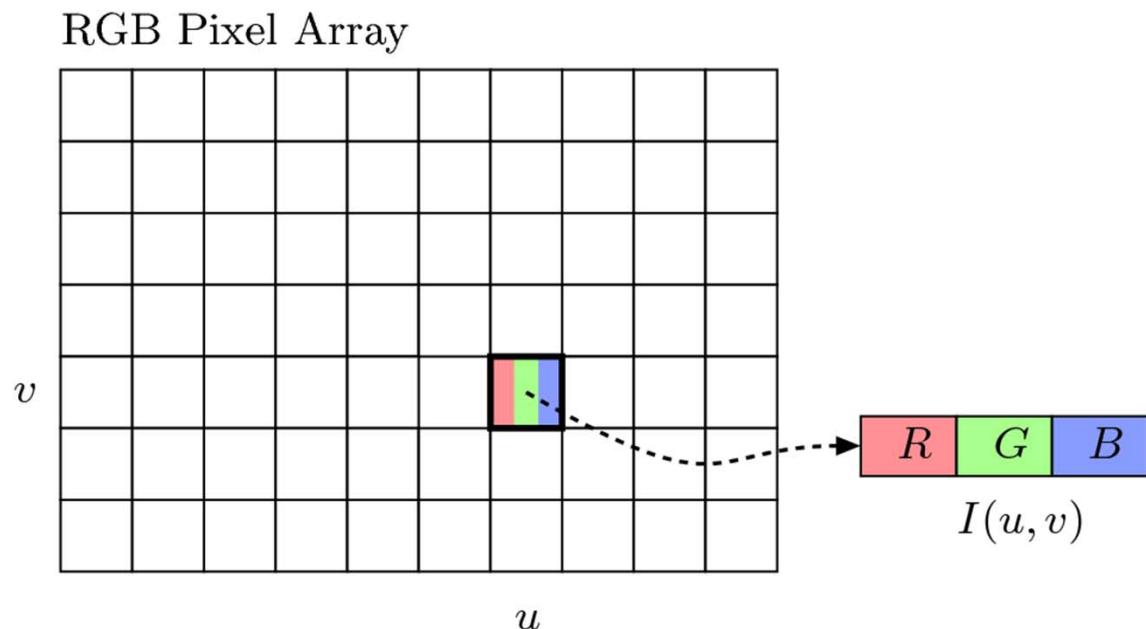


$$\begin{pmatrix} R \\ G \\ B \end{pmatrix} \leftarrow \begin{pmatrix} I_R(u, v) \\ I_G(u, v) \\ I_B(u, v) \end{pmatrix}$$



True Color: Packed Ordering

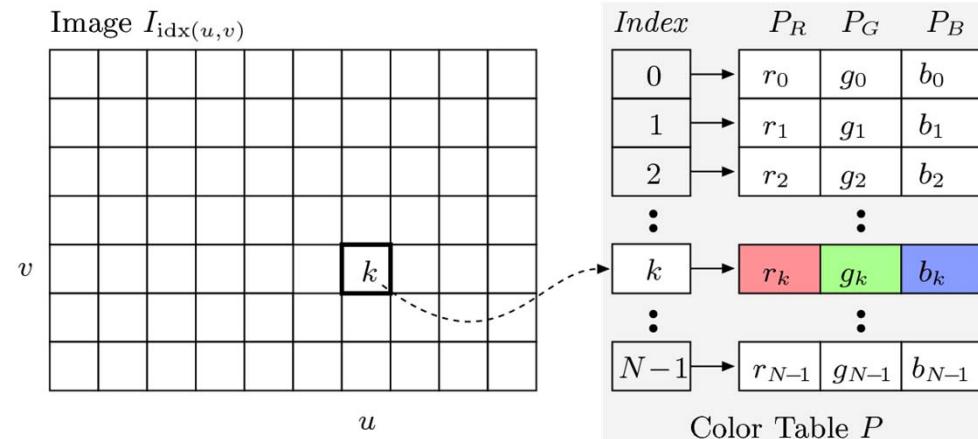
- Component (RGB) values representing a pixel's color is packed together into single element





Indexed Images

- Permit only limited number of distinct colors ($N = 2$ to 256)
- Used in illustrations or graphics containing large regions with same color
- Instead of intensity values, image contains indices into color table or palette
- Palette saved as part of image
- Converting from true color to indexed color requires quantization





Color Images in ImageJ

- ImageJ supports 2 types of color images
 - RGB full-color images (24-bit “RGB color”),
 - packed order
 - Supports TIFF, BMP, JPEG, PNG and RAW file formats
 - Indexed images (“8-bit color”)
 - Up to 256 colors max (8 bits)
 - Supports GIF, PNG, BMP and TIFF (uncompressed) file formats
- See section 12.1.2 of Burger & Burge



Color Image Conversion in ImageJ

- Methods for converting between different types of color and grayscale image objects
- **Note:** if `doScaling` is `true`, pixel values scaled to maximum range of new image

```
ImageProcessor convertToByte(boolean doScaling)
    Converts to an 8-bit grayscale image (ByteProcessor).

ImageProcessor convertToShort(boolean doScaling)
    Converts to a 16-bit grayscale image (ShortProcessor).

ImageProcessor convertToFloat()
    Converts to a 32-bit floating-point image (FloatProcessor).

ImageProcessor convertToRGB()
    Converts to a 32-bit RGB color image (ColorProcessor).
```



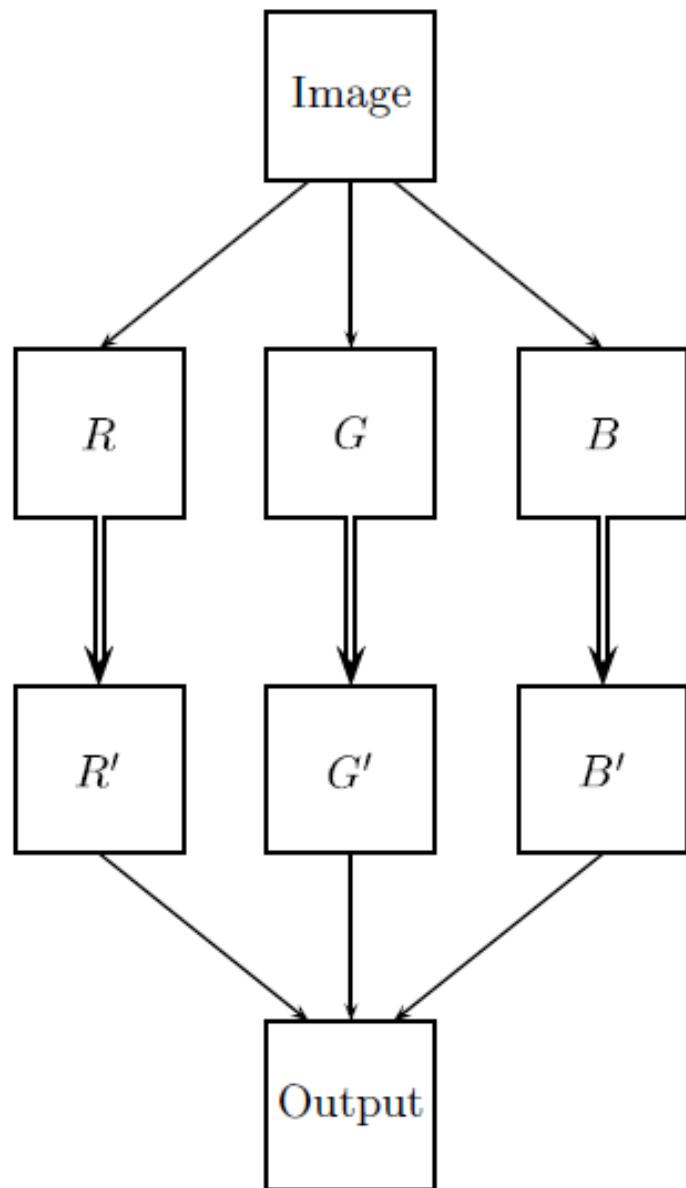
Conversion to ImagePlus Objects

- Do not create new image. Just modify original ImagePlus object

```
ImageConverter(ImagePlus ipl)
    Instantiates an ImageConverter object for the image ipl.

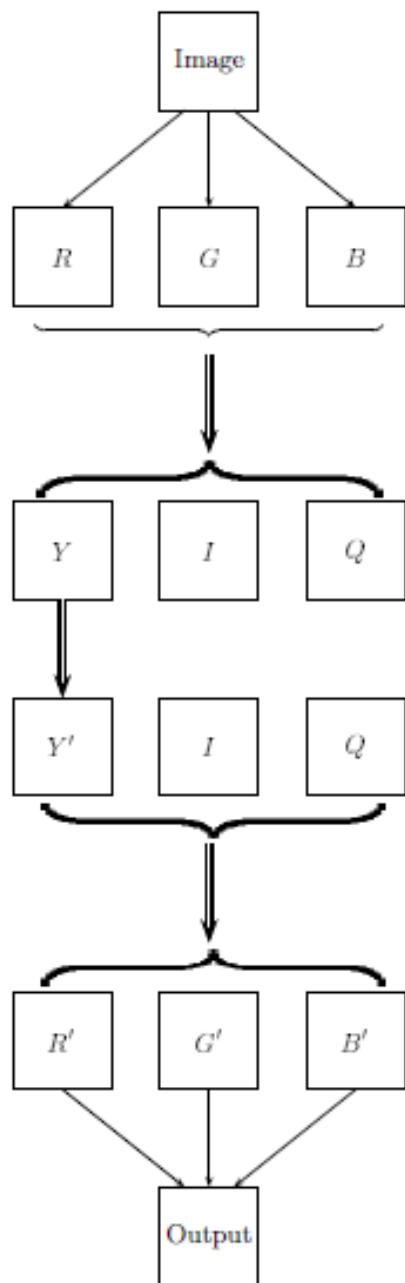
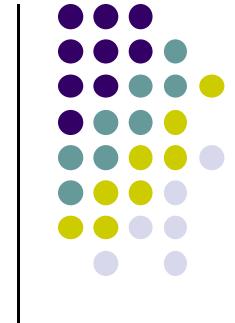
---


void convertToGray8()
    Converts ipl to an 8-bit grayscale image.
void convertToGray16()
    Converts ipl to a 16-bit grayscale image.
void convertToGray32()
    Converts ipl to a 32-bit grayscale image (float).
void convertToRGB()
    Converts ipl to an RGB color image.
void convertRGBtoIndexedColor(int nColors)
    Converts the RGB true color image ipl to an indexed image with
    8-bit index values and nColors colors, performing color quanti-
    zation.
void convertToHSB()
    Converts ipl to a color image using the HSB color space (see
    Sec. 12.2.3).
void convertHSBtoRGB()
    Converts an HSB color space image ipl to an RGB color image.
```



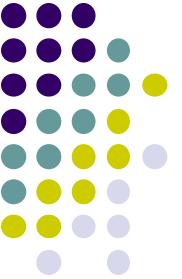
General Strategies for Processing Color Images

- **Strategy 1:** Process each RGB matrix separately



General Strategies for Processing Color Images

- **Strategy 2:** Compute luminance (weighted average of RGB), process intensity matrix



RGB to HSV Conversion

- Define the following values

$$C_{\text{high}} = \max(R, G, B), \quad C_{\text{low}} = \min(R, G, B), \quad \text{and}$$

$$C_{\text{rng}} = C_{\text{high}} - C_{\text{low}}.$$

- Find **saturation** of RGB color components ($C_{\text{max}}=255$)

$$S_{\text{HSV}} = \begin{cases} \frac{C_{\text{rng}}}{C_{\text{high}}} & \text{for } C_{\text{high}} > 0 \\ 0 & \text{otherwise} \end{cases}$$

- And luminance value

$$V_{\text{HSV}} = \frac{C_{\text{high}}}{C_{\text{max}}}$$



RGB to HSV Conversion

- Normalize each component using

$$R' = \frac{C_{\text{high}} - R}{C_{\text{rng}}} \quad G' = \frac{C_{\text{high}} - G}{C_{\text{rng}}} \quad B' = \frac{C_{\text{high}} - B}{C_{\text{rng}}}$$

- Calculate preliminary hue value H' as

$$H' = \begin{cases} B' - G' & \text{if } R = C_{\text{high}} \\ R' - B' + 2 & \text{if } G = C_{\text{high}} \\ G' - R' + 4 & \text{if } B = C_{\text{high}} \end{cases}$$

- Finally, obtain final hue value by normalizing to interval [0,1]

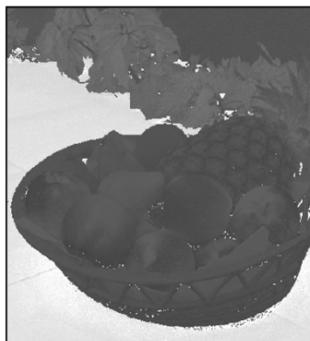
$$H_{\text{HSV}} = \frac{1}{6} \cdot \begin{cases} (H' + 6) & \text{for } H' < 0 \\ H' & \text{otherwise} \end{cases}$$



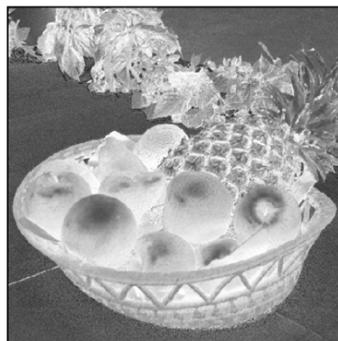
Example: RGB to HSV Conversion



Original RGB
image



H_{HSV}



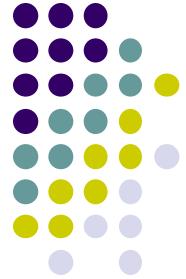
S_{HSV}



V_{HSV}

HSV values
in grayscale

RGB to HSV Conversion Java Code



```
1 static float[] RGBtoHSV (int R, int G, int B, float[] HSV) {
2     // R, G, B ∈ [0, 255]
3     float H = 0, S = 0, V = 0;
4     float cMax = 255.0f;
5     int cHi = Math.max(R,Math.max(G,B)); // highest color value
6     int cLo = Math.min(R,Math.min(G,B)); // lowest color value
7     int cRng = cHi - cLo;           // color range
8
9     // compute value V
10    V = cHi / cMax;
11
12    // compute saturation S
13    if (cHi > 0)
14        S = (float) cRng / cHi;
15
16    // compute hue H
17    if (cRng > 0) { // hue is defined only for color pixels
18        float rr = (float)(cHi - R) / cRng;
19        float gg = (float)(cHi - G) / cRng;
20        float bb = (float)(cHi - B) / cRng;
21        float hh;
22        if (R == cHi)                      // R is highest color value
23            hh = bb - gg;
24        else if (G == cHi)                // G is highest color value
25            hh = rr - bb + 2.0f;
26        else                            // B is highest color value
27            hh = gg - rr + 4.0f;
28        if (hh < 0)
29            hh= hh + 6;
30        H = hh / 6;
31    }
32
33    if (HSV == null) // create a new HSV array if needed
34        HSV = new float[3];
35    HSV[0] = H; HSV[1] = S; HSV[2] = V;
36    return HSV;
37 }
```



HSV to RGB Conversion

- To convert HSV tuple with each component in $[0,1]$ range into RGB, first calculate

$$H' = (6 \cdot H_{\text{HSV}}) \bmod 6$$

- Then compute the following intermediate values

$$\begin{aligned} c_1 &= \lfloor H' \rfloor, & x &= (1 - S_{\text{HSV}}) \cdot V_{\text{HSV}}, \\ c_2 &= H' - c_1, & y &= (1 - (S_{\text{HSV}} \cdot c_1)) \cdot V_{\text{HSV}}, \\ & & z &= (1 - (S_{\text{HSV}} \cdot (1 - c_1))) \cdot V_{\text{HSV}}. \end{aligned}$$

where $v = V_{\text{HSV}}$

- Normalized RGB values (in range $[0,1]$) are calculated as

$$(R', G', B') = \begin{cases} (v, z, x) & \text{if } c_1 = 0 \\ (y, v, x) & \text{if } c_1 = 1 \\ (x, v, z) & \text{if } c_1 = 2 \\ (x, y, v) & \text{if } c_1 = 3 \\ (z, x, v) & \text{if } c_1 = 4 \\ (v, x, y) & \text{if } c_1 = 5. \end{cases}$$



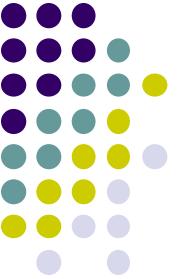
HSV to RGB Conversion

- RGB Components can be scaled to whole numbers in range [0,255] as

$$R = \min(\text{round}(255 \cdot R'), 255),$$

$$G = \min(\text{round}(255 \cdot G'), 255),$$

$$B = \min(\text{round}(255 \cdot B'), 255).$$



HSV to RGB Code

```
1  public static int HSVtoRGB (float h, float s, float v) {  
2      // h, s, v ∈ [0, 1]  
3      float r = 0, g = 0, b = 0;  
4      float hh = (6 * h) % 6;           //  $h' \leftarrow (6 \cdot h) \bmod 6$   
5      int c1 = (int) hh;                //  $c_1 \leftarrow \lfloor h' \rfloor$   
6      float c2 = hh - c1;  
7      float x = (1 - s) * v;  
8      float y = (1 - (s * c2)) * v;  
9      float z = (1 - (s * (1 - c2))) * v;  
10     switch (c1) {  
11         case 0: r = v; g = z; b = x; break;  
12         case 1: r = y; g = v; b = x; break;  
13         case 2: r = x; g = v; b = z; break;  
14         case 3: r = x; g = y; b = v; break;  
15         case 4: r = z; g = x; b = v; break;  
16         case 5: r = v; g = x; b = y; break;  
17     }  
18     int R = Math.min((int)(r * 255), 255);  
19     int G = Math.min((int)(g * 255), 255); // Eqn. (12.19)  
20     int B = Math.min((int)(b * 255), 255);  
21     // create int-packed RGB-color:  
22     int rgb = ((R & 0xff) << 16) | ((G & 0xff) < 8) | B & 0xff;  
23     return rgb;  
24 }
```



RGB to HLS Conversion

- Compute Hue same way as for HSV model

$$H_{\text{HLS}} = H_{\text{HSV}}$$

- Then compute the other 2 values as:

$$L_{\text{HLS}} = \frac{(C_{\text{high}} + C_{\text{low}})/255}{2}$$

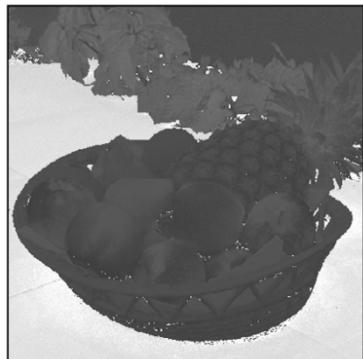
$$S_{\text{HLS}} = \begin{cases} 0 & \text{for } L_{\text{HLS}} = 0 \\ 0.5 \cdot \frac{C_{\text{rng}}/255}{L_{\text{HLS}}} & \text{for } 0 < L_{\text{HLS}} \leq 0.5 \\ 0.5 \cdot \frac{C_{\text{rng}}/255}{1-L_{\text{HLS}}} & \text{for } 0.5 < L_{\text{HLS}} < 1 \\ 0 & \text{for } L_{\text{HLS}} = 1. \end{cases}$$



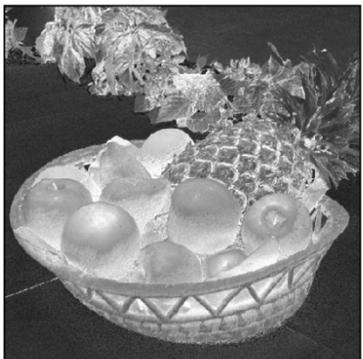
Example RGB to HLS Conversion



Original RGB
image



H_{HLS}



S_{HLS}



L_{HLS}

HLS values
in grayscale



RGB to HLS Conversion Code

```
1 static float[] RGBtoHLS (float R, float G, float B) {
2     // R, G, B assumed to be in [0, 1]
3     float cHi = Math.max(R,Math.max(G,B)); // highest color value
4     float cLo = Math.min(R,Math.min(G,B)); // lowest color value
5     float cRng = cHi - cLo;           // color range
6
7     // compute luminance L
8     float L = (cHi + cLo)/2;
9
10    // compute saturation S
11    float S = 0;
12    if (0 < L && L < 1) {
13        float d = (L <= 0.5f) ? L : (1 - L);
14        S = 0.5f * cRng / d;
15    }
16
17    // compute hue H
18    float H=0;
19    if (cHi > 0 && cRng > 0) {      // a color pixel
20        float rr = (float)(cHi - R) / cRng;
21        float gg = (float)(cHi - G) / cRng;
22        float bb = (float)(cHi - B) / cRng;
23        float hh;
24        if (R == cHi)                  // R is highest color value
25            hh = bb - gg;
26        else if (G == cHi)           // G is highest color value
27            hh = rr - bb + 2.0f;
28        else                         // B is highest color value
29            hh = gg - rr + 4.0f;
30
31        if (hh < 0)
32            hh= hh + 6;
33        H = hh / 6;
34    }
35
36    return new float[] {H,L,S};
37 }
```



HLS to RGB Conversion

- Assuming H, L and S in [0,1] range

$$(R', G', B') = \begin{cases} (0, 0, 0) & \text{for } L_{\text{HLS}} = 0 \\ (1, 1, 1) & \text{for } L_{\text{HLS}} = 1 \end{cases}$$

- Otherwise, calculate

$$H' = (6 \cdot H_{\text{HLS}}) \bmod 6$$

- Then calculate the values

$$\begin{aligned} c_1 &= \lfloor H' \rfloor \\ c_2 &= H' - c_1 \end{aligned}$$

$$d = \begin{cases} S_{\text{HLS}} \cdot L_{\text{HLS}} & \text{for } L_{\text{HLS}} \leq 0.5 \\ S_{\text{HLS}} \cdot (1 - L_{\text{HLS}}) & \text{for } L_{\text{HLS}} > 0.5 \end{cases}$$

$$w = L_{\text{HLS}} + d$$

$$y = w - (w - x) \cdot c_2$$

$$x = L_{\text{HLS}} - d$$

$$z = x + (w - x) \cdot c_2.$$

(12.25)



HLS to RGB Conversion

- Assignment of RGB values is done as follows

$$(R', G', B') = \begin{cases} (w, z, x) & \text{if } c_1 = 0 \\ (y, w, x) & \text{if } c_1 = 1 \\ (x, w, z) & \text{if } c_1 = 2 \\ (x, y, w) & \text{if } c_1 = 3 \\ (z, x, w) & \text{if } c_1 = 4 \\ (w, x, y) & \text{if } c_1 = 5 \end{cases}$$



HLS to RGB Code

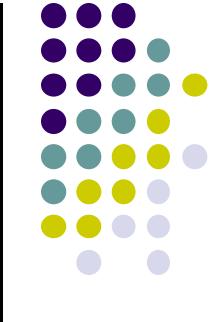
```
1  static float[] HLStoRGB (float H, float L, float S) {
2      // H, L, S assumed to be in [0, 1]
3      float R = 0, G = 0, B = 0;
4
5      if (L <= 0)          // black
6          R = G = B = 0;
7      else if (L >= 1)    // white
8          R = G = B = 1;
9      else {
10         float hh = (6 * H) % 6;
11         int c1 = (int) hh;
12         float c2 = hh - c1;
13         float d = (L <= 0.5f) ? (S * L) : (S * (1 - L));
14         float w = L + d;
15         float x = L - d;
16         float y = w - (w - x) * c2;
17         float z = x + (w - x) * c2;
18         switch (c1) {
19             case 0: R=w; G=z; B=x; break;
20             case 1: R=y; G=w; B=x; break;
21             case 2: R=x; G=w; B=z; break;
22             case 3: R=x; G=y; B=w; break;
23             case 4: R=z; G=x; B=w; break;
24             case 5: R=w; G=x; B=y; break;
25         }
26     }
27     return new float[] {R,G,B};
28 }
```



TV Color Spaces – YUV, YIQ, YC_bC_r

- YUV, YIQ: color encoding for analog NTSC and PAL
- YC_bC_r : Digital TV encoding
- Key common ideas:
 - Separate luminance component Y from 2 chroma components
 - Instead of encoding colors, encode color differences between components (maintains compatibility with black and white TV)

YUV



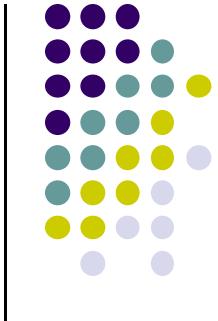
- Basis for color encoding in analog TV in north america (NTSC) and Europe (PAL)
- Y components computed from RGB components as

$$Y = 0.299 \cdot R + 0.587 \cdot G + 0.114 \cdot B$$

- UV components computed as:

$$U = 0.492 \cdot (B - Y) \quad \text{and} \quad V = 0.877 \cdot (R - Y)$$

YUV



- Entire transformation from RGB to YUV

$$\begin{pmatrix} Y \\ U \\ V \end{pmatrix} = \begin{pmatrix} 0.299 & 0.587 & 0.114 \\ -0.147 & -0.289 & 0.436 \\ 0.615 & -0.515 & -0.100 \end{pmatrix} \cdot \begin{pmatrix} R \\ G \\ B \end{pmatrix}$$

- Invert matrix above to transform from YUV back to RGB

$$\begin{pmatrix} R \\ G \\ B \end{pmatrix} = \begin{pmatrix} 1.000 & 0.000 & 1.140 \\ 1.000 & -0.395 & -0.581 \\ 1.000 & 2.032 & 0.000 \end{pmatrix} \cdot \begin{pmatrix} Y \\ U \\ V \end{pmatrix}$$



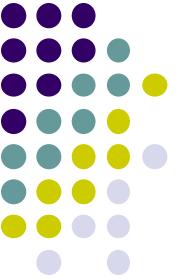
YIQ

- Original NTSC used variant of YUV called YIQ
- Y component is same as in YUV
- Both U and V color vectors rotated and mirrored so that

$$\begin{pmatrix} I \\ Q \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} \cos \beta & \sin \beta \\ -\sin \beta & \cos \beta \end{pmatrix} \cdot \begin{pmatrix} U \\ V \end{pmatrix}$$

2D rotation
matrix

where $\beta = 0.576$ (33 degrees)



YC_bC_r

- Internationally standardized variant of YUV
- Used for digital TV and image compression (e.g. JPEG)
- Y , C_b , C_r components calculated as

$$Y = w_R \cdot R + (1 - w_B - w_R) \cdot G + w_B \cdot B$$

$$C_b = \frac{0.5}{1 - w_B} \cdot (B - Y)$$

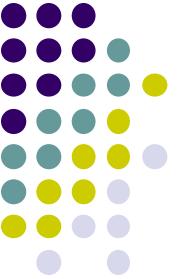
$$C_r = \frac{0.5}{1 - w_R} \cdot (R - Y)$$

- Inverse transform from YC_bC_r to RGB

$$R = Y + \frac{1 - w_R}{0.5} \cdot C_r$$

$$G = Y - \frac{w_B \cdot (1 - w_B) \cdot C_b - w_R \cdot (1 - w_R) \cdot C_r}{0.5 \cdot (1 - w_B - w_R)}$$

$$B = Y + \frac{1 - w_B}{0.5} \cdot C_b$$



YC_bC_r

- ITU recommendation BT.601 specifies values:

$$w_R = 0.299, \quad w_B = 0.114, \quad w_G = 1 - w_B - w_R = 0.587$$

- Thus the transformation

$$\begin{pmatrix} Y \\ C_b \\ C_r \end{pmatrix} = \begin{pmatrix} 0.299 & 0.587 & 0.114 \\ -0.169 & -0.331 & 0.500 \\ 0.500 & -0.419 & -0.081 \end{pmatrix} \cdot \begin{pmatrix} R \\ G \\ B \end{pmatrix}$$

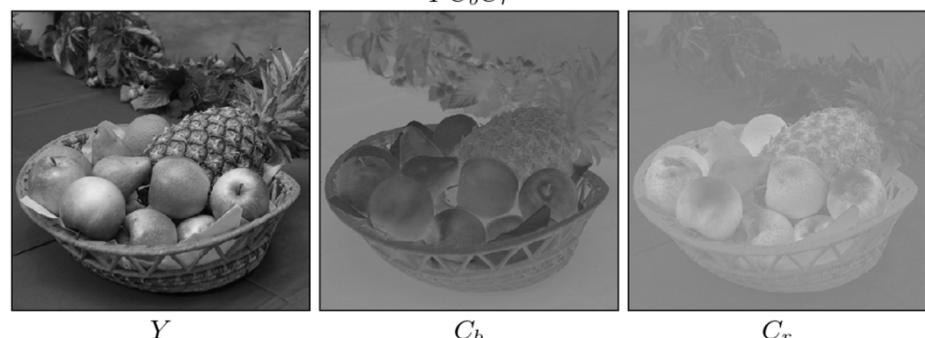
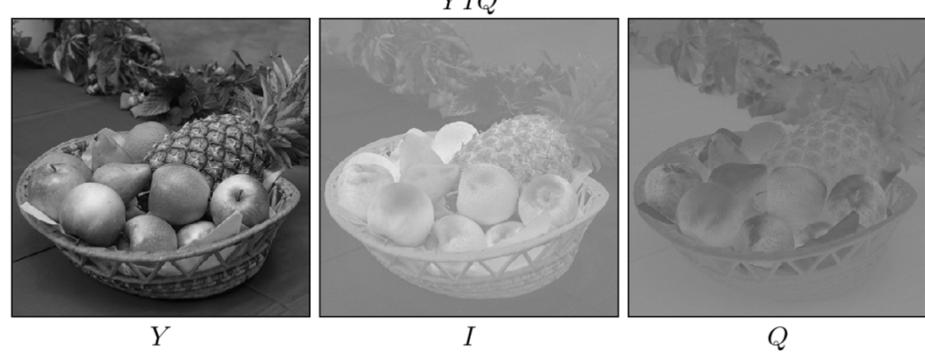
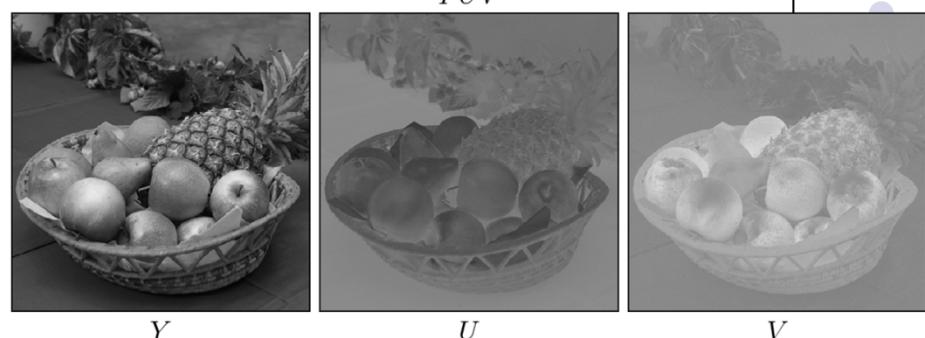
- And the inverse transformation becomes

$$\begin{pmatrix} R \\ G \\ B \end{pmatrix} = \begin{pmatrix} 1.000 & 0.000 & 1.403 \\ 1.000 & -0.344 & -0.714 \\ 1.000 & 1.773 & 0.000 \end{pmatrix} \cdot \begin{pmatrix} Y \\ C_b \\ C_r \end{pmatrix}$$



Comparing YUV, YIQ and YC_bC_r

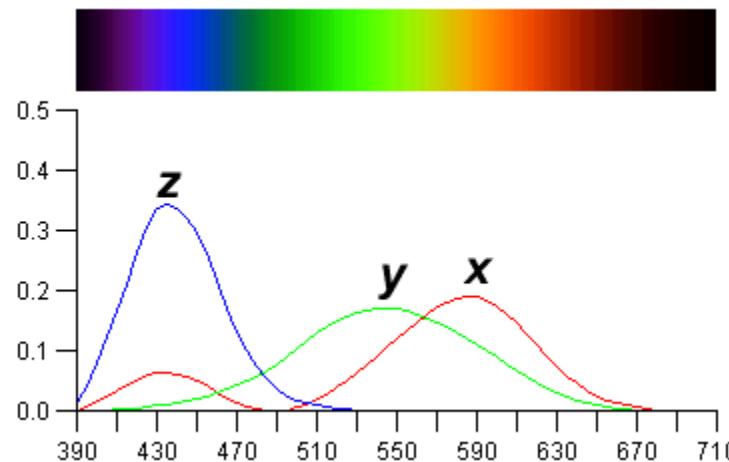
- Y values are identical in all 3 color spaces





CIE Color Space

- *CIE* (Commission Internationale d'Eclairage) came up with 3 hypothetical lights X, Y, and Z with these spectra:



Note that:

$$X \sim R$$

$$Y \sim G$$

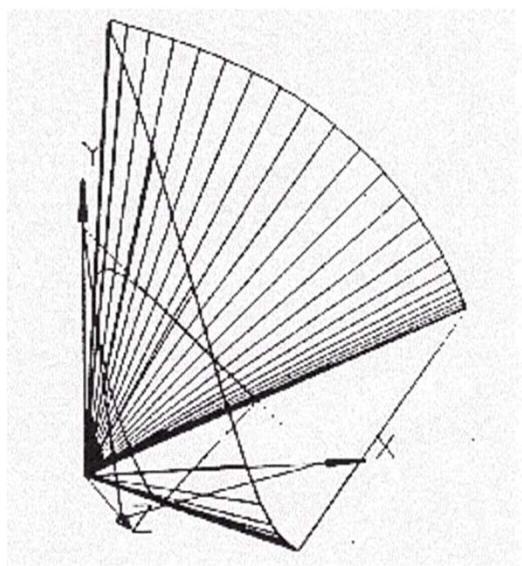
$$Z \sim B$$

- **Idea:** any wavelength λ can be matched perceptually by *positive* combinations of X,Y,Z
- CIE created table of XYZ values for all *visible* colors

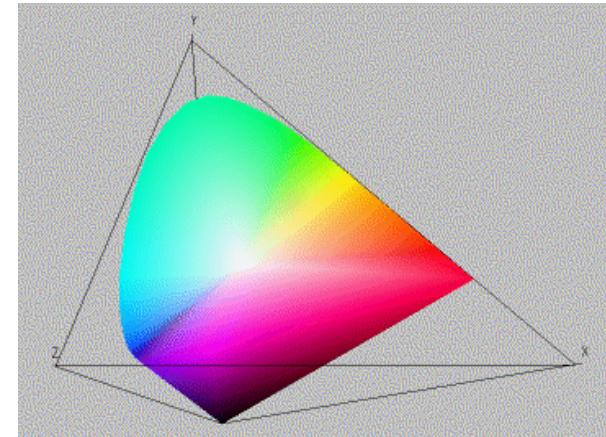


CIE Color Space

- The *gamut* of all colors perceivable is thus a three-dimensional shape in X,Y,Z
- Color = $X'X + Y'Y + Z'Z$

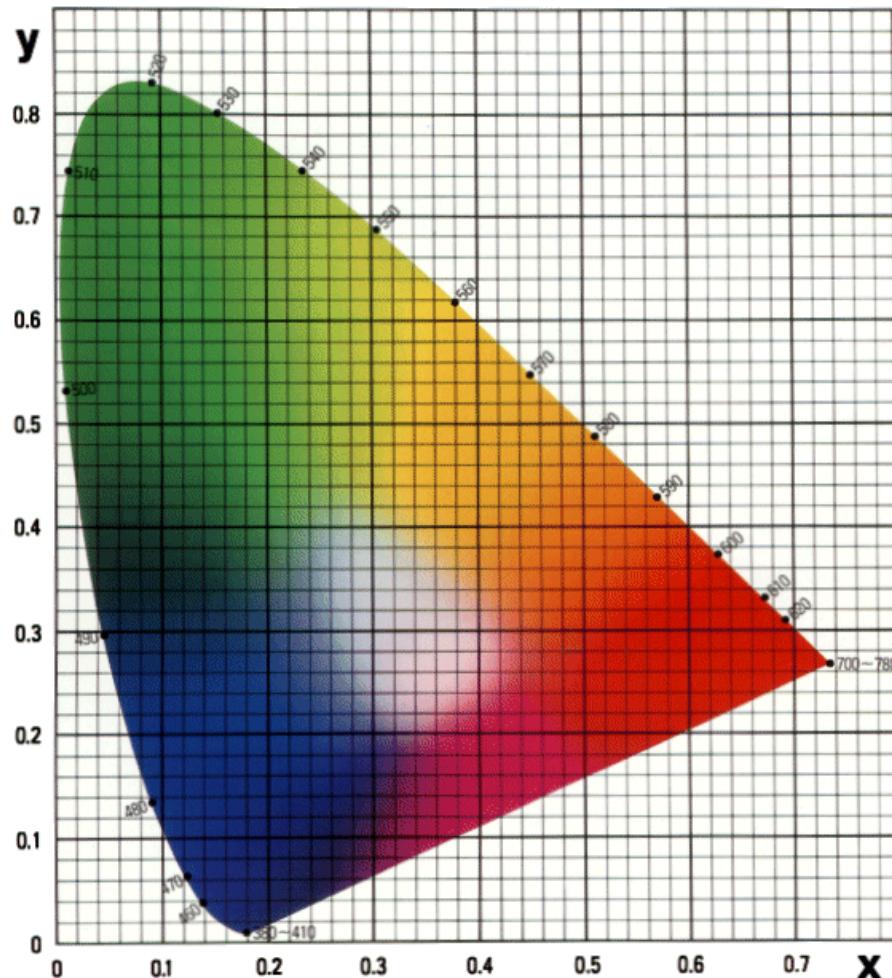


**Human
Perceptual
Gamut**





CIE Chromaticity Diagram (1931)



- For simplicity, we often project to the 2D plane
- Also normalize

$$x + y + z = 1$$

$$x = \frac{X}{X + Y + Z} \quad y = \frac{Y}{X + Y + Z} \quad z = \frac{Z}{X + Y + Z}$$

- Note: Inside horseshoe visible, outside invisible to eye

Note: Look up x, y
Calculate z as $1 - x - y$



Standard Illuminants

- Central goal of CIE chart is the quantitative measurement of colors in physical reality
- CIE specifies some standard illuminants for many **real** and **hypothetical** light sources
- Specified by spectral radiant power distribution and correlated color temperature
- **D50:** natural direct sunlight
- **D65:** Indirect daylight, overcast sky

| Pt. | Temp. | X | Y | Z | x | y |
|------------|---------|----------|----------|----------|--------|--------|
| D50 | 5000° K | 0.964296 | 1.000000 | 0.825105 | 0.3457 | 0.3585 |
| D65 | 6500° K | 0.950456 | 1.000000 | 1.088754 | 0.3127 | 0.3290 |
| E | 5400° K | 1 | 1 | 1 | 1/3 | 1/3 |



CIE uses

- Find complementary colors:
 - equal linear distances from white in opposite directions
- Measure hue and saturation:
 - Extend line from color to white till it cuts horseshoe (hue)
 - Saturation is ratio of distances color-to-white/hue-to-white
- Define and compare device color gamut (color ranges)
- **Problem:** not perceptually uniform:
 - Same amount of changes in different directions generate perceived difference that are not equal
 - CIE LUV, $L^*a^*b^*$ - uniform



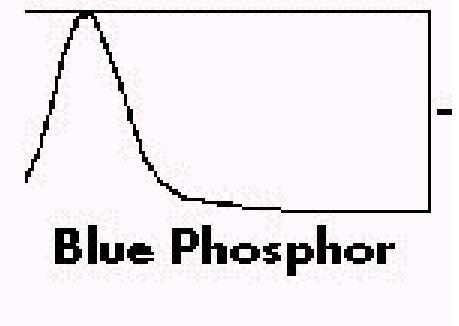
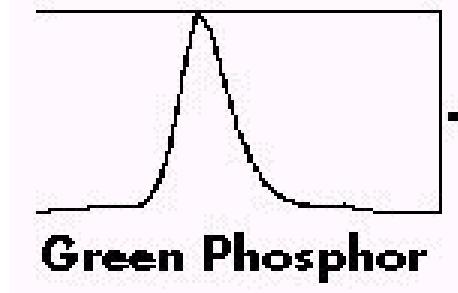
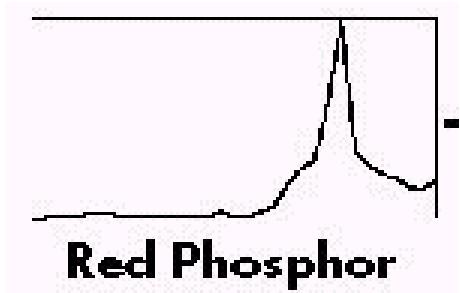
CIE L*a*b*

- Main goal was to make changes in this space linear with respect to human perception
- Now popular in high-quality photographic applications
- Used in Adobe Photoshop as standard for converting between different color spaces
- Components:
 - Luminosity **L**
 - Color components **a*** and **b*** which specify color hue and saturation along green-red and blue-yellow axes
- All 3 components are measured relative to reference white
- Non-linear correction function (like gamma correction) applied

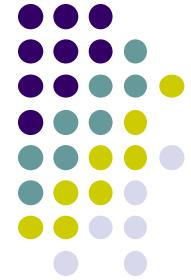


Device Color Gamuts

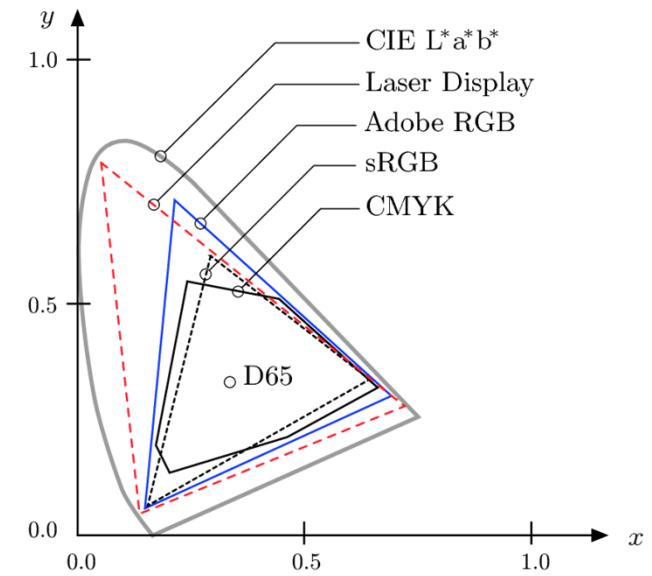
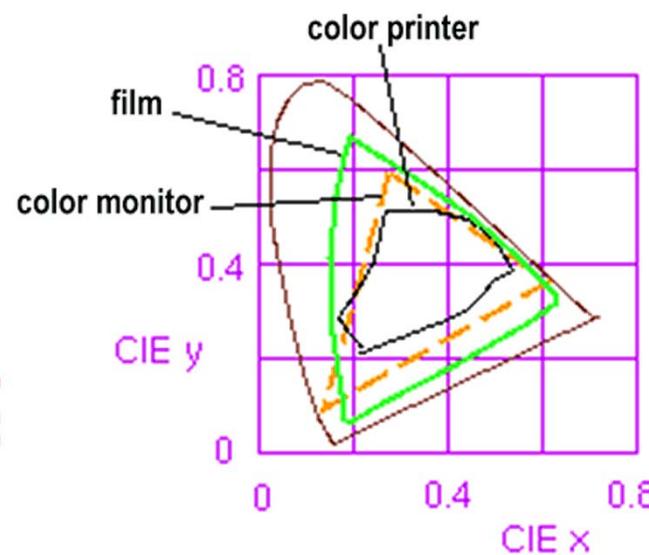
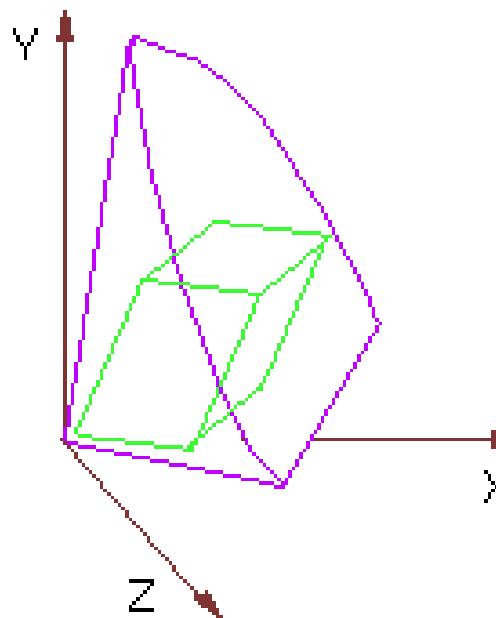
- Since X, Y, and Z are hypothetical light sources, no real device can produce the entire gamut of perceivable color
- Depends on physical means of producing color on device
- Example: R,G,B phosphors on CRT monitor

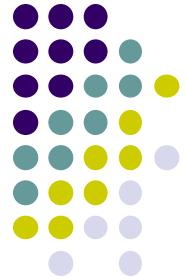


Device Color Gamuts



- The RGB color cube sits within CIE color space
- We can use the CIE chromaticity diagram to compare the gamuts of various devices
- E.g. compare color printer and monitor color gamuts





Transformation CIE XYZ to L*a*b*

- Current ISO Standard 13655 conversion

$$L^* = 116 \cdot Y' - 16$$

$$a^* = 500 \cdot (X' - Y')$$

$$b^* = 200 \cdot (Y' - Z')$$

where

$$X' = f_1\left(\frac{X}{X_{\text{ref}}}\right) \quad Y' = f_1\left(\frac{Y}{Y_{\text{ref}}}\right) \quad Z' = f_1\left(\frac{Z}{Z_{\text{ref}}}\right)$$

$$f_1(c) = \begin{cases} c^{\frac{1}{3}} & \text{for } c > 0.008856 \\ 7.787 \cdot c + \frac{16}{116} & \text{for } c \leq 0.008856 \end{cases}$$

- Usually, standard illuminant D65 is specified as reference $(X_{\text{ref}}, Y_{\text{ref}}, Z_{\text{ref}})$
- Possible values of a^* and b^* are in range [-127, +127]



Transformation L*a*b* to CIE XYZ

- Reverse transformation from L*a*b* space to XYZ is

$$X = X_{\text{ref}} \cdot f_2\left(\frac{a^*}{500} + Y'\right)$$

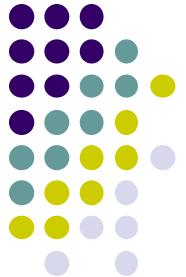
$$Y = Y_{\text{ref}} \cdot f_2(Y')$$

$$Z = Z_{\text{ref}} \cdot f_2\left(Y' - \frac{b^*}{200}\right)$$

where

$$Y' = \frac{L^* + 16}{116}$$

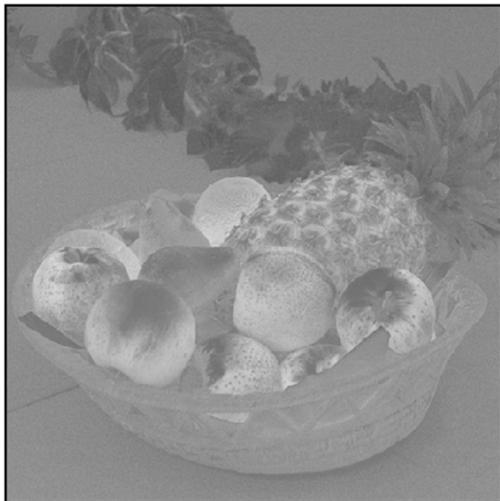
$$f_2(c) = \begin{cases} c^3 & \text{for } c^3 > 0.008856 \\ \frac{c - 16/116}{7.787} & \text{for } c^3 \leq 0.008856 \end{cases}$$



Example of L*a*b* Components



L^*



a^*



b^*



Code for XYZ to L*a*b* and L*a*b* to XYZ Conversion

```
23 // XYZ→CIELab: returns D65-related L*a*b values
24 // from D50-related XYZ values:
25 public float[] fromCIEXYZ(float[] XYZ50) {
26     float[] XYZ65 = catD50toD65.apply(XYZ50);
27     double xx = f1(XYZ65[0] / Xref);
28     double yy = f1(XYZ65[1] / Yref);
29     double zz = f1(XYZ65[2] / Zref);
30
31     float L = (float)(116 * yy - 16);
32     float a = (float)(500 * (xx - yy));
33     float b = (float)(200 * (yy - zz));
34     return new float[] {L, a, b};
35 }
36
37 // CIELab→XYZ: returns D50-related XYZ values
38 // from D65-related L*a*b* values:
39 public float[] toCIEXYZ(float[] Lab) {
40     double yy = (Lab[0] + 16) / 116;
41     float X65 = (float)(Xref * f2(Lab[1] / 500 + yy));
42     float Y65 = (float)(Yref * f2(yy));
43     float Z65 = (float)(Zref * f2(yy - Lab[2] / 200));
44     float[] XYZ65 = new float[] {X65, Y65, Z65};
45     return catD65toD50.apply(XYZ65);
46 }
```



Measuring Color Differences

- Due to its uniformity with respect to human perception, differences between colors in L*a*b* color space can be determined as **euclidean distance**

$$\begin{aligned}\text{ColorDist}_{\text{Lab}}(\mathbf{C}_1, \mathbf{C}_2) &= \|\mathbf{C}_1 - \mathbf{C}_2\| \\ &= \sqrt{(L_1^* - L_2^*)^2 + (a_1^* - a_2^*)^2 + (b_1^* - b_2^*)^2}\end{aligned}$$



sRGB

- For many computer display-oriented applications, use of CIE color space may be too cumbersome
- sRGB
 - developed by Hewlett Packard and Microsoft
 - has relatively small gamut compared to L*a*b*
 - Its colors can be reproduced by most computer monitors
 - De Facto standard for digital cameras
- Several image formats (EXIF, PNG) based on sRGB



Transformation CIE XYZ to sRGB

- First compute linear RGB values as

$$\begin{pmatrix} R \\ G \\ B \end{pmatrix} = M_{\text{RGB}} \begin{pmatrix} X \\ Y \\ Z \end{pmatrix}$$

Where

$$M_{\text{RGB}} = \begin{pmatrix} 3.240479 & -1.537150 & -0.498535 \\ -0.969256 & 1.875992 & 0.041556 \\ 0.055648 & -0.204043 & 1.057311 \end{pmatrix}$$

- Next gamma correct linear RGB values

$$R' = f_\gamma(R) \quad G' = f_\gamma(G) \quad B' = f_\gamma(B)$$

$$f_\gamma(c) = \begin{cases} 1.055 \cdot c^{\frac{1}{2.4}} - 0.055 & \text{for } c > 0.0031308 \\ 12.92 \cdot c & \text{for } c \leq 0.0031308 \end{cases}$$



Transformation sRGB to CIE XYZ

- First linearize R' G' B' values as

$$R = f_{\gamma}^{-1}(R') \quad G = f_{\gamma}^{-1}(G') \quad B = f_{\gamma}^{-1}(B')$$

With

$$f_{\gamma}^{-1}(c') = \begin{cases} \left(\frac{c'+0.055}{1.055}\right)^{2.4} & \text{for } c' > 0.03928 \\ \frac{c'}{12.92} & \text{for } c' \leq 0.03928 \end{cases}$$

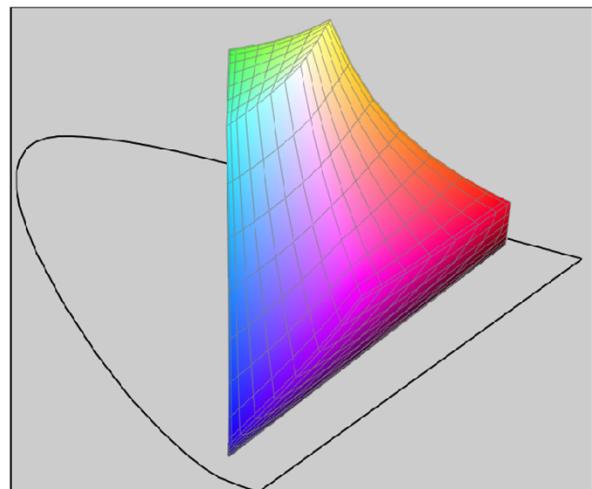
- Linearized RGB then transformed to XYZ as

$$\begin{pmatrix} X \\ Y \\ Z \end{pmatrix} = M_{\text{RGB}}^{-1} \begin{pmatrix} R \\ G \\ B \end{pmatrix} \quad M_{\text{RGB}}^{-1} = \begin{pmatrix} 0.412453 & 0.357580 & 0.180423 \\ 0.212671 & 0.715160 & 0.072169 \\ 0.019334 & 0.119193 & 0.950227 \end{pmatrix}$$



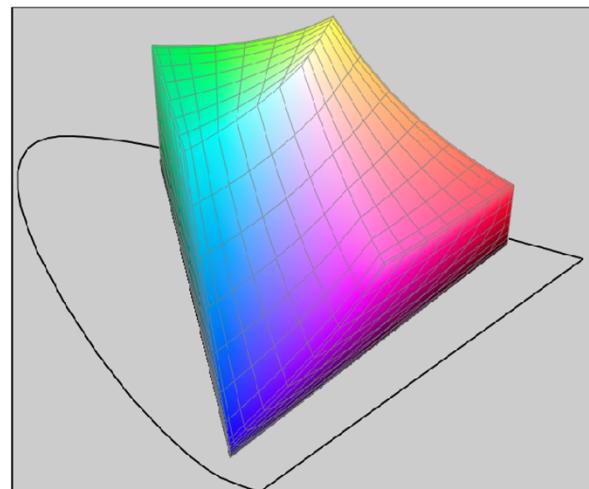
Adobe RGB

- Small gamut limited to colors reproducible by computer monitors is a weakness of sRGB
- Creates problems in areas such as printing
- Adobe RGB similar to sRGB but with much larger gamut



(a)

sRGB gamut



(b)

Adobe RGB gamut



Chromatic Adaptation

- Human eye adapts to make color of object same under different lighting conditions
- E.g. Paper appears white in bright daylight and under fluorescent light
- CIE color system allows colors to be specified relative to white point, called **relative colorimetry**
- If 2 colors specified relative to different white points, they can be related to each other using **chromatic adaptation transformation (CAT)**



XYZ Scaling

- Simplest chromatic adaptation method is XYZ scaling
- Basically, color coordinates multiplied by ratios of corresponding white point coordinates

$$X_2 = X_1 \cdot \frac{X_{W2}}{X_{W1}} \quad Y_2 = Y_1 \cdot \frac{Y_{W2}}{Y_{W1}} \quad Z_2 = Z_1 \cdot \frac{Z_{W2}}{Z_{W1}}$$

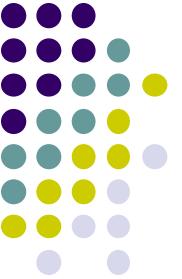
- For example to convert colors from system based on white point $\mathbf{W}_1 = \mathbf{D65}$ to system relative to $\mathbf{W}_2 = \mathbf{D50}$

$$X_{50} = X_{65} \cdot \frac{X_{\mathbf{D50}}}{X_{\mathbf{D65}}} = X_{65} \cdot \frac{0.964296}{0.950456} = X_{65} \cdot 1.01456 ,$$

$$Y_{50} = Y_{65} \cdot \frac{Y_{\mathbf{D50}}}{Y_{\mathbf{D65}}} = Y_{65} \cdot \frac{1.000000}{1.000000} = Y_{65} ,$$

$$Z_{50} = Z_{65} \cdot \frac{Z_{\mathbf{D50}}}{Z_{\mathbf{D65}}} = Z_{65} \cdot \frac{0.825105}{1.088754} = Z_{65} \cdot 0.757843$$

- Another alternative is **Bradford adaptation**



Colorimetric Support in Java

- sRGB is standard color space in Java
- Components of color objects and RGB color images are color corrected



Statistics of Color Images

- **Task:** Determine how many unique colors in a given image
- **Approach 1:** Create histogram, count frequency of each color
 - Not efficient since for 24-bit image, there are $2^{24} = 16,777,216$ colors
- **Approach 2:** Put pixels in array, then sort
 - Similar colors next to each other
 - We can then count the number of **transitions between neighboring colors**
 - Much more efficient than histogram approach if many repeated colors



Counting Colors in RGB Image

```
1 import ij.process.ColorProcessor;
2 import java.util.Arrays;
3
4 public class ColorStatistics {
5
6     static int countColors (ColorProcessor cp) {
7         // duplicate pixel array and sort
8         int[] pixels = ((int[]) cp.getPixels()).clone(); ←
9         Arrays.sort(pixels);
10
11        int k = 1; // image contains at least one color
12        for (int i = 0; i < pixels.length-1; i++) {
13            if (pixels[i] != pixels[i+1])
14                k = k + 1; ←
15        }
16        return k;
17    }
18
19 } // end of class ColorStatistics
```

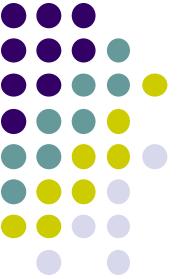
Create copy of 1D RGB array,
Then sort

Count transitions between
contiguous color blocks



Color Histograms

- When applied to object of type **ColorProcessor**, built-in ImageJ method **getHistogram()**, simply counts intensity of corresponding gray values
- **Another alternative:** compute individual intensity histograms of 3 color channels
 - **Downside:** does not give information about actual colors in image
- **A good alternative:** 2D color histograms

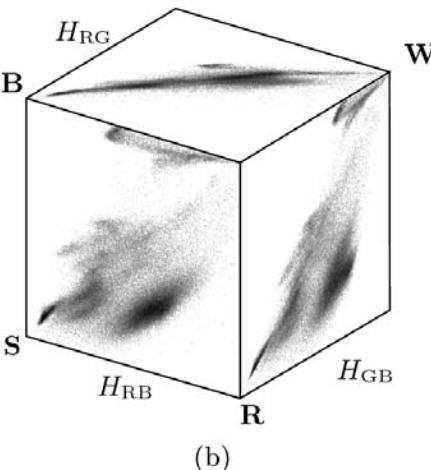
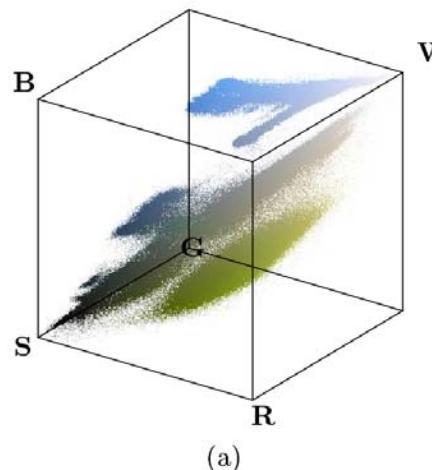


2D Color Histograms

- Define:

$$H_{RG}(r, g) \leftarrow \text{number of pixels with } I_{RGB}(u, v) = (r, g, *)$$
$$H_{RB}(r, b) \leftarrow \text{number of pixels with } I_{RGB}(u, v) = (r, *, b)$$
$$H_{GB}(g, b) \leftarrow \text{number of pixels with } I_{RGB}(u, v) = (*, g, b)$$

- **Note:** * denotes arbitrary component value
- Resulting 2D histograms are independent of original image size, easily visualized





Method for computing 2D Histogram

```
1 static int[][] get2dHistogram
2             (ColorProcessor cp, int c1, int c2) ←
3 // c1, c2: R = 0, G = 1, B = 2
4 int[] RGB = new int[3];
5 int[][] H = new int[256][256]; // histogram array H[c1][c2]
6
7 for (int v = 0; v < cp.getHeight(); v++) {
8     for (int u = 0; u < cp.getWidth(); u++) {
9         cp.getPixel(u, v, RGB);
10        int i = RGB[c1];
11        int j = RGB[c2];
12        // increment corresponding histogram cell
13        H[j][i]++; // i runs horizontal, j runs vertical
14    }
15 }
16 return H;
17 }
```

Color components
(Histogram axes)
Specified by c1 and c2

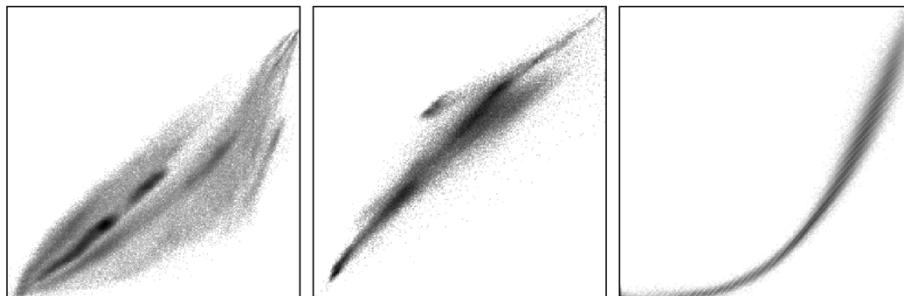
Color distribution H
returned in 2D array



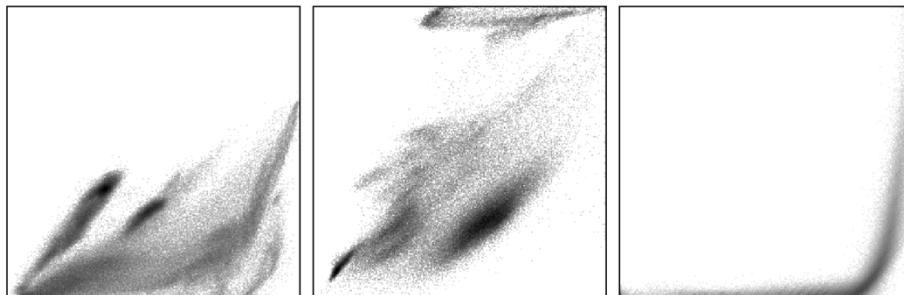
Original Images



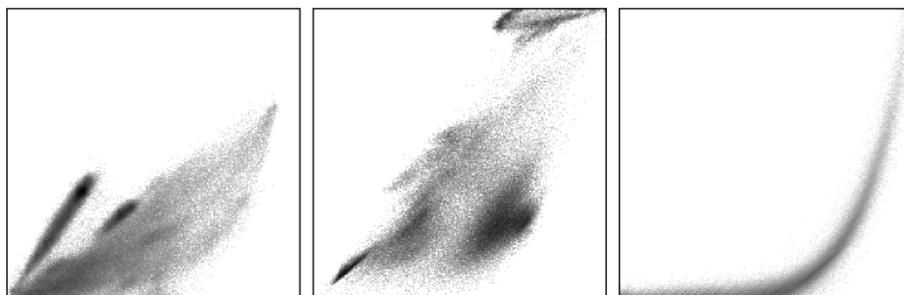
Red-Green Histograms ($R \rightarrow, G \uparrow$)



Red-Blue Histograms ($R \rightarrow, B \uparrow$)



Green-Blue Histograms ($G \rightarrow, B \uparrow$)

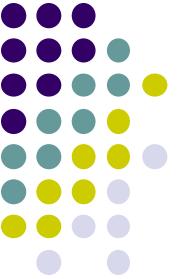


Example: Combined Color Histogram



Color Quantization

- True color can be quite large in actual description
- Sometimes need to reduce size
- **Examples:**
 - Convert 24-bit TIFF to 8-bit TIFF
 - Take a true-color description from database and convert to web image format
- Replace true-color with “best match” from smaller subset
- Quantization algorithms:
 - Uniform quantization
 - Popularity algorithm
 - Median-cut algorithm
 - Octree algorithm



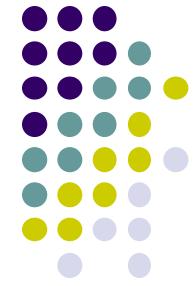
Scalar Color Quantization

- Convert each component of each original RGB value independently from range $[0, \dots, m-1]$ to $[0, \dots, n-1]$

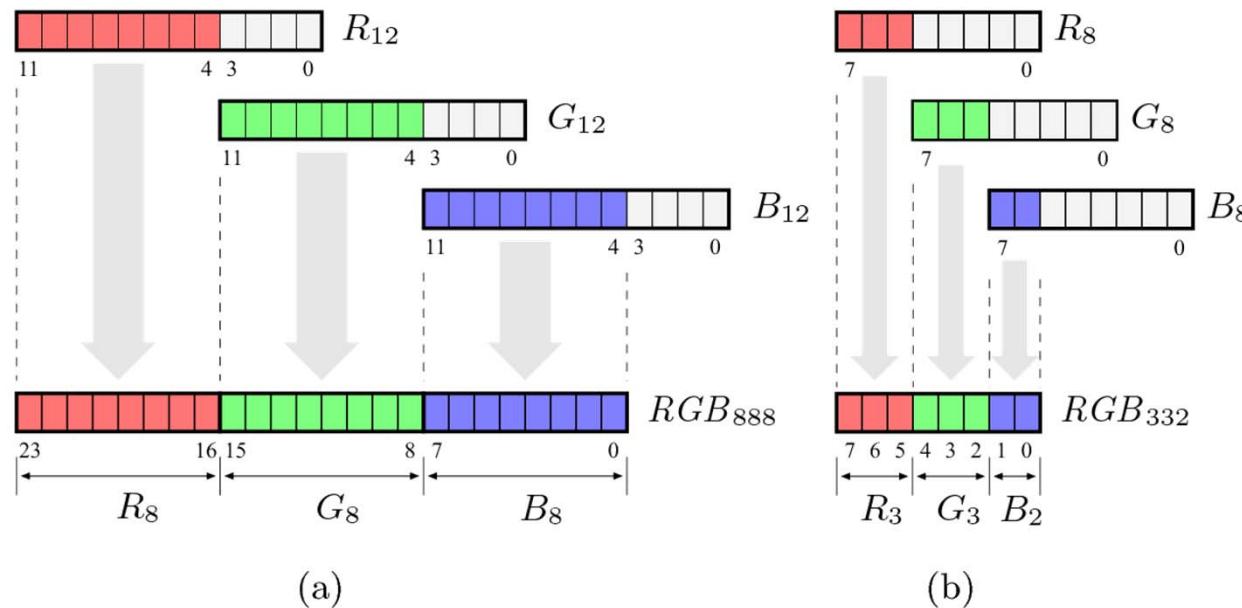
$$c'_i \leftarrow \left\lfloor c_i \cdot \frac{n}{m} \right\rfloor$$

- Example:** Convert color image with 3x12-bit components ($m=4096$) to RGB image with 3x8-bit components ($n=256$)
 - Multiply each component in orginal color by $n/m = 256/4096 = 1/16$
 - Result is then truncated
- Sometimes m and n not same for all components
- E.g. 3:3:2 packing = 3 bits for red, 3 bits for green and 2 bits for blue

Scalar Quantization

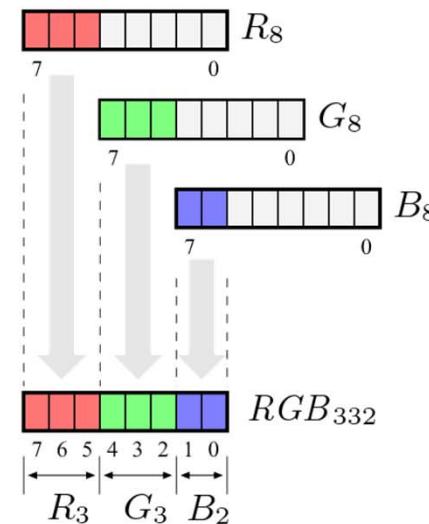


**Quantization
of 3x12-bit to
3x8-bit colors**



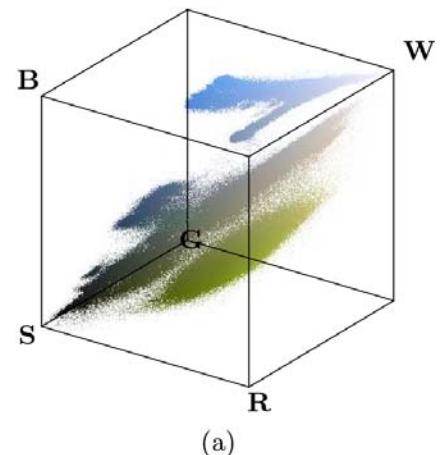
(a)

**Quantization
of 3x8-bit to
3:3:2-packed
8-bit colors**

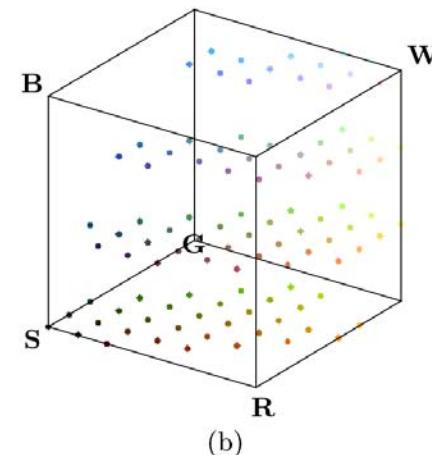


(b)

**Distribution of 226,321
colors before scalar
3:3:2 quantization**



(a)



**256 colors after scalar
3:3:2 quantization**



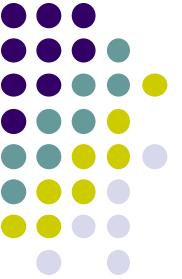
Vector Quantization

- Does not treat individual components separately
- Each color of pixel treated as single entity
- **Goal:**
 1. To find set of n representative color vectors
 2. Replace each original color by one of the new color vectors
- n is usually pre-determined
- Resulting deviation should be minimal
- Turns out to be an expensive global optimization problem
- Following methods thus calculate local optima
 - Populousity algorithm
 - Median-cut algorithm



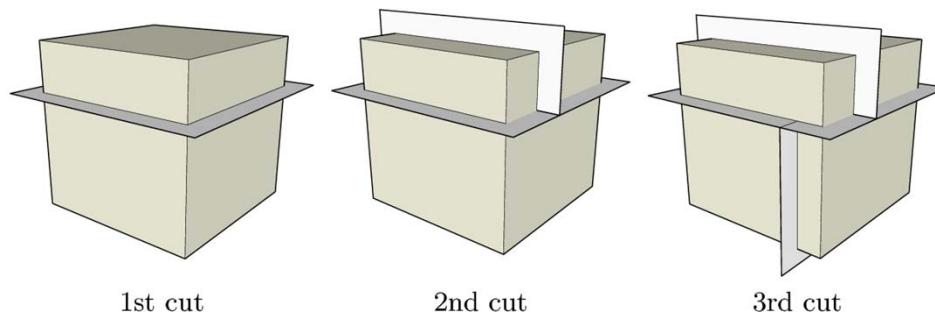
Popularity Algorithm

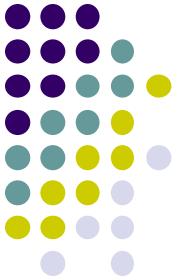
- Selects n most frequently occurring colors in image as representative set of color vectors
- General algorithm:
 - Sort image colors into array,
 - Populate histogram as before
 - pick n most frequently occurring colors as representative set
 - For each original color, replace with closest color in representative set
Note: closest color also shortest distance in color space
- Algorithm performs well as long as colors not scattered a lot



Median-Cut Algorithm

- Considered classical method for color quantization
- Implemented in many applications and in ImageJ
- Algorithm:
 - Compute color histogram of original image
 - Recursively divide RGB color space till number of boxes equal to desired number of representative colors is reached
 - At each step of recursion, box with most pixels is split at median of the longest of its 3 axes so that half pixels left in each subbox
 - In the last step, the mean color of all pixels in each subbox is computed and used as the representative color (each contained pixel is replaced by this mean)





```

1: MEDIANCUT( $I, K_{\max}$ )
   I: color image,  $K_{\max}$ : max. number of quantized colors
   Returns a new quantized image with at most  $K_{\max}$  colors.
2:    $\mathcal{C}_R \leftarrow \text{FINDREPRESENTATIVECOLORS}(I, K_{\max})$ 
3:   return QUANTIZEIMAGE( $I, \mathcal{C}_R$ )


---

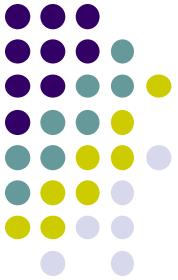

4: FINDREPRESENTATIVECOLORS( $I, K_{\max}$ )
5:   Determine  $\mathcal{C} = \{c_1, c_2, \dots, c_K\}$ , the set of  $K$  distinct colors in  $I$ ,
   where each color instance  $c_i$  is a tuple  $\langle \text{red}, \text{grn}, \text{blu}, \text{cnt} \rangle$  consisting
   of the RGB color components ( $\text{red}, \text{grn}, \text{blu}$ ) and the number
   of pixels ( $\text{cnt}$ ) for that particular color.
6:   if  $|\mathcal{C}| \leq K_{\max}$  then
7:      $\mathcal{C}_R \leftarrow \mathcal{C}$ .
8:   else
9:     Create a color box  $b_0$  at level 0 that contains all image colors  $\mathcal{C}$ 
10:    and make it the initial element in the set of color boxes  $\mathcal{B}$ :
11:     $b_0 \leftarrow \text{CREATECOLORBOX}(\mathcal{C}, 0)$                                  $\triangleright$  see Alg. 12.2
12:     $\mathcal{B} \leftarrow \{b_0\}$                                                $\triangleright$  initial set of color boxes
13:     $k \leftarrow 1$ 
14:     $done \leftarrow \text{false}$ 
15:    while  $k < N_{\max}$  and not  $done$  do
16:       $b \leftarrow \text{FINDBOXTOSPLIT}(\mathcal{B})$                                  $\triangleright$  see Alg. 12.2
17:      if  $b \neq \text{nil}$  then
18:         $\langle b_1, b_2 \rangle \leftarrow \text{SPLITBOX}(b)$                                  $\triangleright$  see Alg. 12.2
19:         $\mathcal{B} \leftarrow \mathcal{B} - \{b\}$                                                $\triangleright$  remove  $b$  from  $\mathcal{B}$ 
20:         $\mathcal{B} \leftarrow \mathcal{B} \cup \{b_1, b_2\}$                                  $\triangleright$  insert  $b_1, b_2$  into  $\mathcal{B}$ 
21:         $k \leftarrow k + 1$ 
22:      else                                               $\triangleright$  no more boxes to split
23:         $done \leftarrow \text{true}$ 
24:      Determine the average color inside each color box in set  $\mathcal{B}$ :
25:       $\mathcal{C}_R \leftarrow \{c_j = \text{AVERAGECOLORS}(b_j) \mid b_j \in \mathcal{B}\}$        $\triangleright$  see Alg. 12.3
26:      return  $\mathcal{C}_R$ .


---


27: QUANTIZEIMAGE( $I, \mathcal{C}_R$ )
   Returns a new image with color pixels from  $I$  replaced by their closest
   representative colors in  $\mathcal{C}_R$ :
28:   Create a new image  $I'$  the same size as  $I$ .
29:   for all  $(u, v)$  do
30:     Find the color  $c \in \mathcal{C}_R$  that is “closest” to  $I(u, v)$  (e.g., using the
       Euclidean distance in RGB space).
31:      $I'(u, v) \leftarrow c$ 
32:   return  $I'$ .

```

Median-Cut Algorithm Part 1 of 3



```

1: CREATECOLORBOX( $\mathcal{C}, m$ )
    Creates and returns a new color box containing the colors  $\mathcal{C}$ . A color
    box  $b$  is a tuple  $\langle \text{colors}, \text{level}, \text{rmin}, \text{rmax}, \text{gmin}, \text{gmax}, \text{bmin}, \text{bmax} \rangle$ ,
    where  $\text{colors}$  is the set of image colors represented by the box,  $\text{level}$ 
    denotes the split-level, and  $\text{rmin}, \dots, \text{bmax}$  describe the color bound-
    aries of the box in RGB space.
2: Find the RGB extrema of all colors in this box:
   
$$\left. \begin{array}{l} r_{\min} \leftarrow \min \text{red}(c) \\ r_{\max} \leftarrow \max \text{red}(c) \\ g_{\min} \leftarrow \min \text{grn}(c) \\ g_{\max} \leftarrow \max \text{grn}(c) \\ b_{\min} \leftarrow \min \text{blu}(c) \\ b_{\max} \leftarrow \max \text{blu}(c) \end{array} \right\} \text{for all colors } c \in \mathcal{C}$$

3: Create a new color box  $b$ :
    $b \leftarrow \langle \mathcal{C}, m, r_{\min}, r_{\max}, g_{\min}, g_{\max}, b_{\min}, b_{\max} \rangle$ 
4: return  $b$ .

```

```

5: FINDBOXTOSPLIT( $\mathcal{B}$ )
    Searches the set of boxes  $\mathcal{B}$  for a box to split and returns this box,
    or  $\text{nil}$  if no splittable box can be found.

    Let  $\mathcal{B}_s$  be the set of all color boxes that can be split (i.e., contain at
    least 2 different colors):
6:  $\mathcal{B}_s \leftarrow \{ b \mid b \in \mathcal{B} \wedge |\text{colors}(b)| \geq 2 \}$ 
7: if  $\mathcal{B}_s = \{\}$  then ▷ no splittable box was found
8:     return  $\text{nil}$ .
9: else
10:    Select a box  $b_x \in \mathcal{B}_s$ , such that  $\text{level}(b_x)$  is a minimum.
11:    return  $b_x$ .

```

```

12: SPLITBOX( $b$ )
    Splits the color box  $b$  at the median plane perpendicular to its longest
    dimension and returns a pair of new color boxes.

13:  $m \leftarrow \text{level}(b)$ 
14:  $d \leftarrow \text{FINDMAXBOXDIMENSION}(b)$  ▷ see Alg. 12.3
15:  $\mathcal{C} \leftarrow \text{colors}(b)$ 
16: From all color samples in  $\mathcal{C}$  determine  $x_{\text{med}}$  as the median of the
    color distribution along dimension  $d$ .
17: Partition the set  $\mathcal{C}$  into two disjoint sets  $\mathcal{C}_1$  and  $\mathcal{C}_2$  by splitting at
     $x_{\text{med}}$  along dimension  $d$ .
18:  $b_1 \leftarrow \text{CREATECOLORBOX}(\mathcal{C}_1, m + 1)$ 
19:  $b_2 \leftarrow \text{CREATECOLORBOX}(\mathcal{C}_2, m + 1)$ 
20: return  $\langle b_1, b_2 \rangle$ .

```

Median-Cut Algorithm Part 2 of 3



```

1: AVERAGECOLORS( $b$ )
    Returns the average color  $c_{\text{avg}}$  for the pixels represented by the color
    box  $b$ .
2:  $\mathcal{C} \leftarrow \text{colors}(b)$ 
3:  $n \leftarrow 0, r_{\text{sum}} \leftarrow 0, g_{\text{sum}} \leftarrow 0, b_{\text{sum}} \leftarrow 0$ 
4: for all  $c \in \mathcal{C}$  do
5:      $k \leftarrow \text{cnt}(c)$ 
6:      $n \leftarrow n + k$ 
7:      $r_{\text{sum}} \leftarrow r_{\text{sum}} + k \cdot \text{red}(c)$ 
8:      $g_{\text{sum}} \leftarrow g_{\text{sum}} + k \cdot \text{grn}(c)$ 
9:      $b_{\text{sum}} \leftarrow b_{\text{sum}} + k \cdot \text{blu}(c)$ 
10:     $r_{\text{avg}} \leftarrow \frac{1}{n} \cdot r_{\text{sum}}, g_{\text{avg}} \leftarrow \frac{1}{n} \cdot g_{\text{sum}}, b_{\text{avg}} \leftarrow \frac{1}{n} \cdot b_{\text{sum}}$ 
11:     $c_{\text{avg}} \leftarrow \langle r_{\text{avg}}, g_{\text{avg}}, b_{\text{avg}} \rangle$ 
12:    return  $c_{\text{avg}}$ .
```

```

13: FINDMAXBOXDIMENSION( $b$ )
    Returns the largest dimension of the color box  $b$  (i.e., Red, Green, or
    Blue).
14:  $\text{size}_r = \text{rmax}(b) - \text{rmin}(b)$ 
15:  $\text{size}_g = \text{gmax}(b) - \text{gmin}(b)$ 
16:  $\text{size}_b = \text{bmax}(b) - \text{bmin}(b)$ 
17:  $\text{size}_{\text{max}} = \max(\text{size}_r, \text{size}_g, \text{size}_b)$ 
18: if  $\text{size}_{\text{max}} = \text{size}_r$  then
19:     return Red.
20: else if  $\text{size}_{\text{max}} = \text{size}_g$  then
21:     return Green.
22: else
23:     return Blue.
```

Median-Cut Algorithm Part 3 of 3

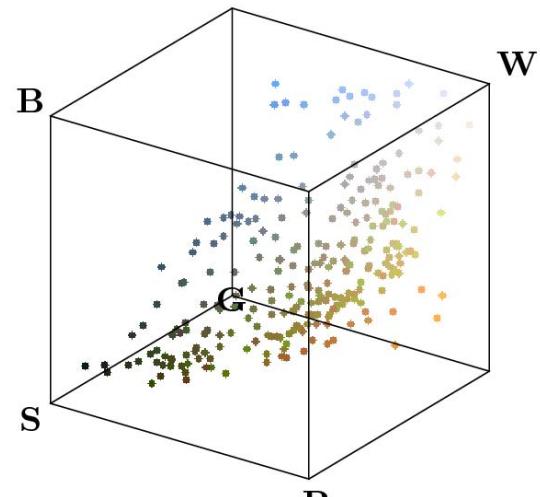


Octree & Other Quantization Algorithms

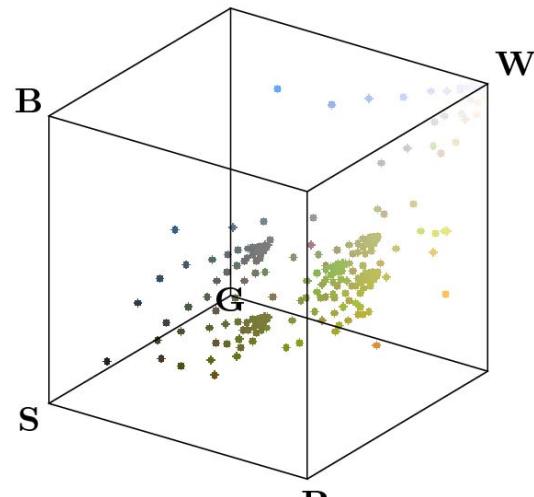
- Octree:
 - Similar to median cut
 - Hierarchical structure: each cube may be split into **8 subcubes**
- **Other approaches:**
 - Use 10% of pixels that are randomly selected as representative
 - Statistical and clustering methods. E.g. k-means



Color Distribution after Median Cut



(a)



(b)

**Color distribution
after reducing original
226,321 colors to 256
using **median cut****

**Color distribution
after reducing original
226,321 colors to 256
using **octree****

Comparison of Quantization Errors

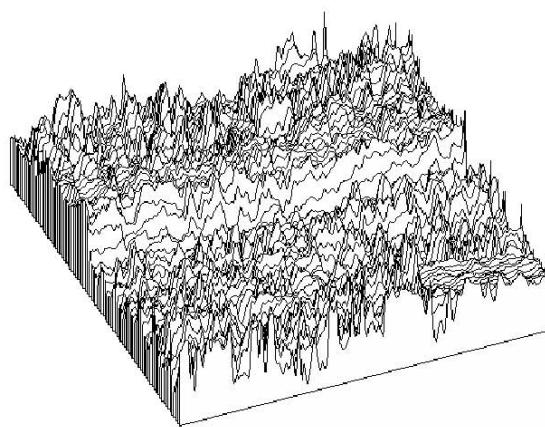


Original
Image



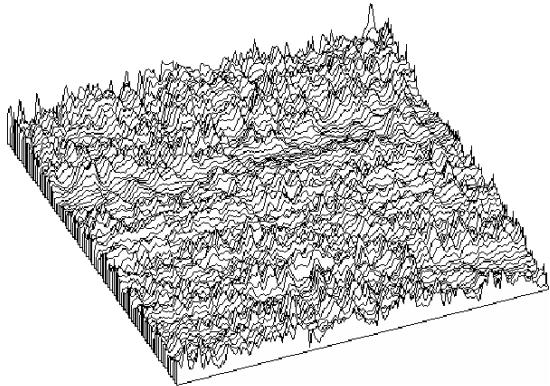
(a) Detail

Distance between
original and
quantized color
for scalar 3:3:2
packing



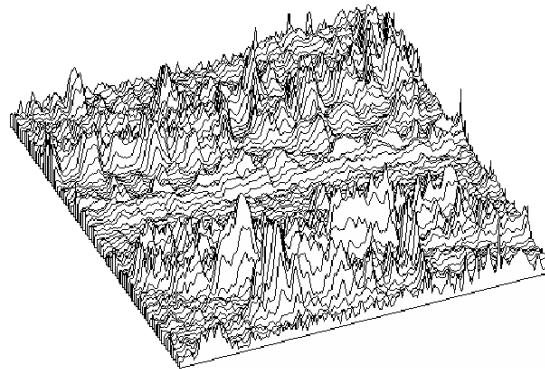
(b) 3:3:2

Median Cut



(c) Median-Cut

Octree



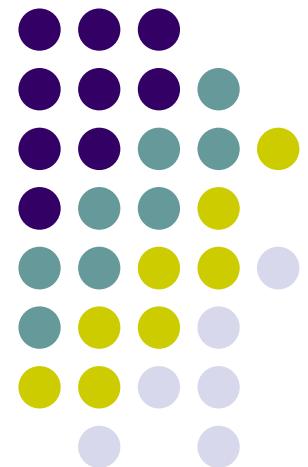
(d) Octree

Digital Image Processing (CS/ECE 545)

Lecture 9: Color Images (Part 2) & Introduction to Spectral Techniques (Fourier Transform, DFT, DCT)

Prof Emmanuel Agu

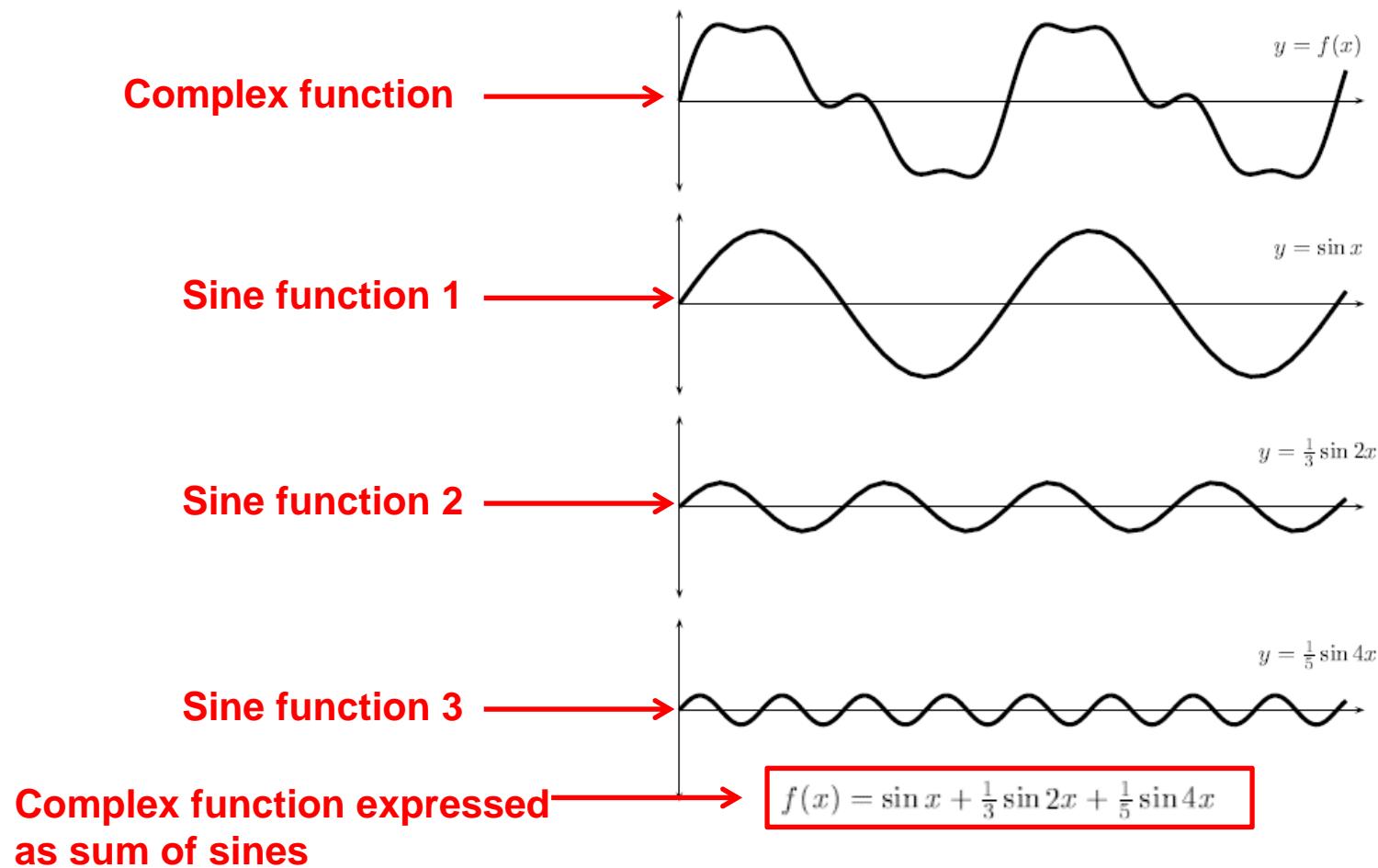
*Computer Science Dept.
Worcester Polytechnic Institute (WPI)*





Fourier Transform

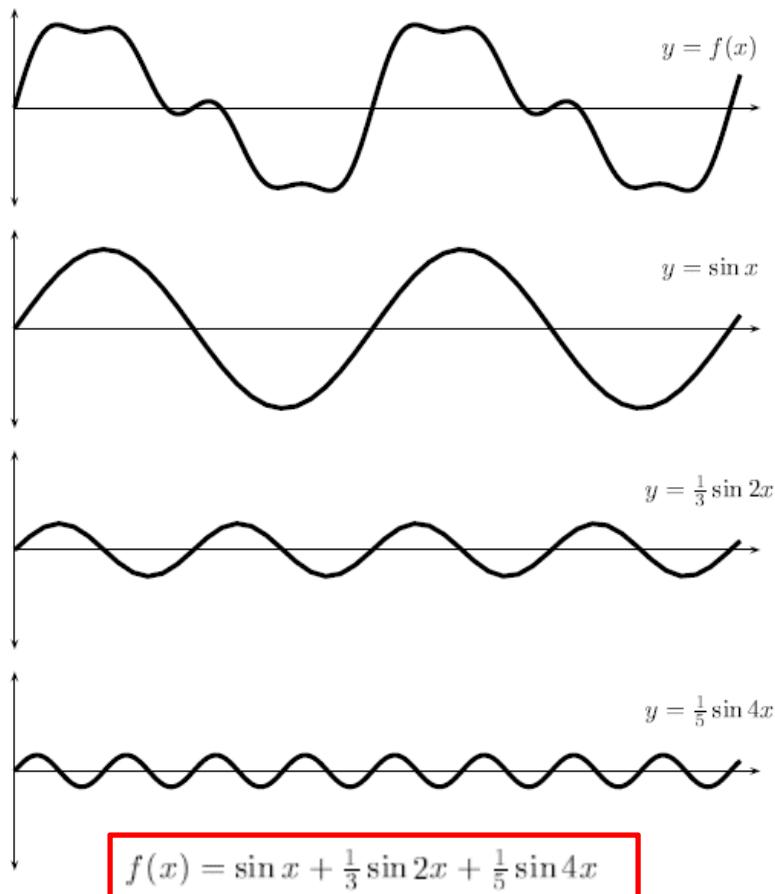
- **Main idea:** Any periodic function can be decomposed into a summation of sines and cosines





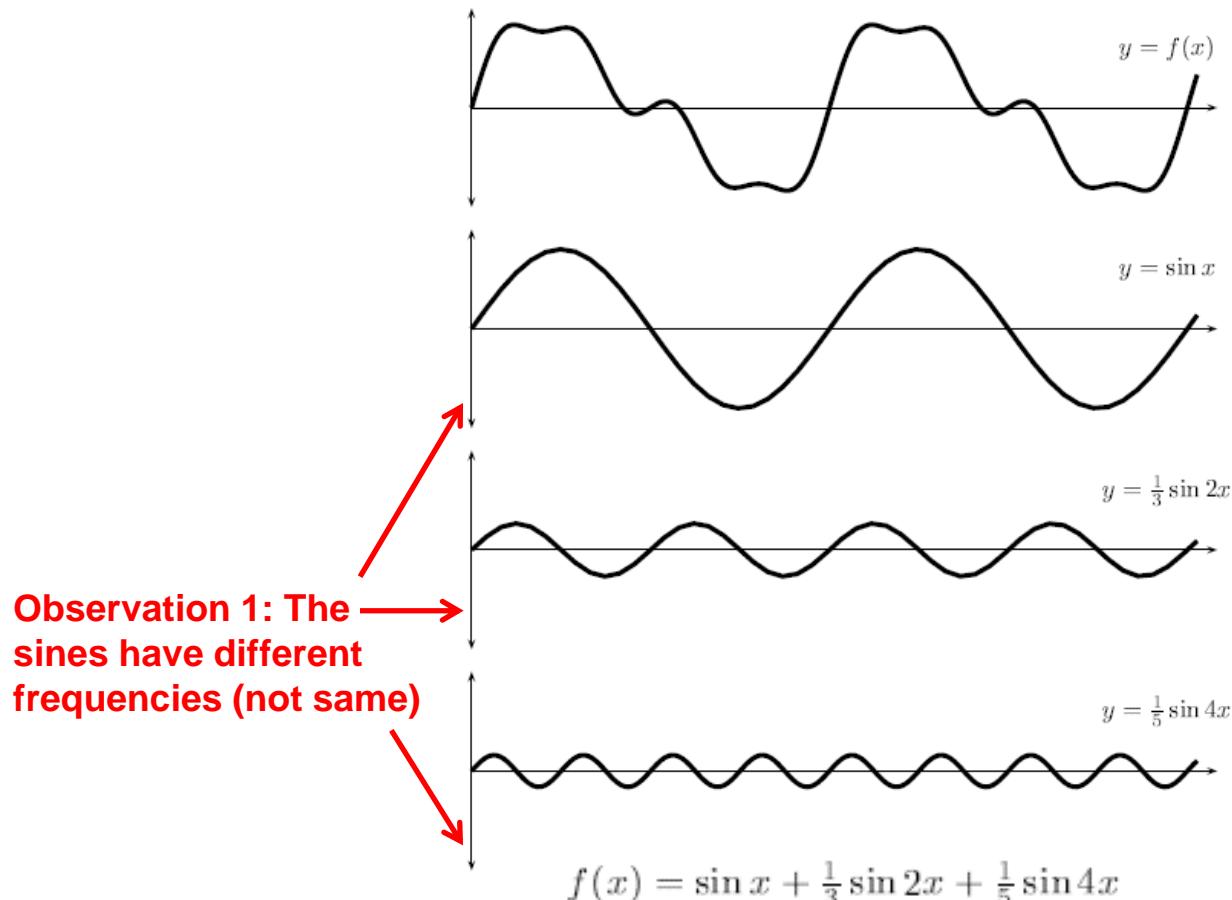
Fourier Transform: Why?

- Mathematically easier to analyze effects of transmission medium, noise, etc on simple sine functions, then add to get effect on complex signal





Fourier Transform: Some Observations



Observation 1: The sines have different frequencies (not same)

Observation 2: Frequencies of sines are multiples of each other (called harmonics)

Frequency = 1x

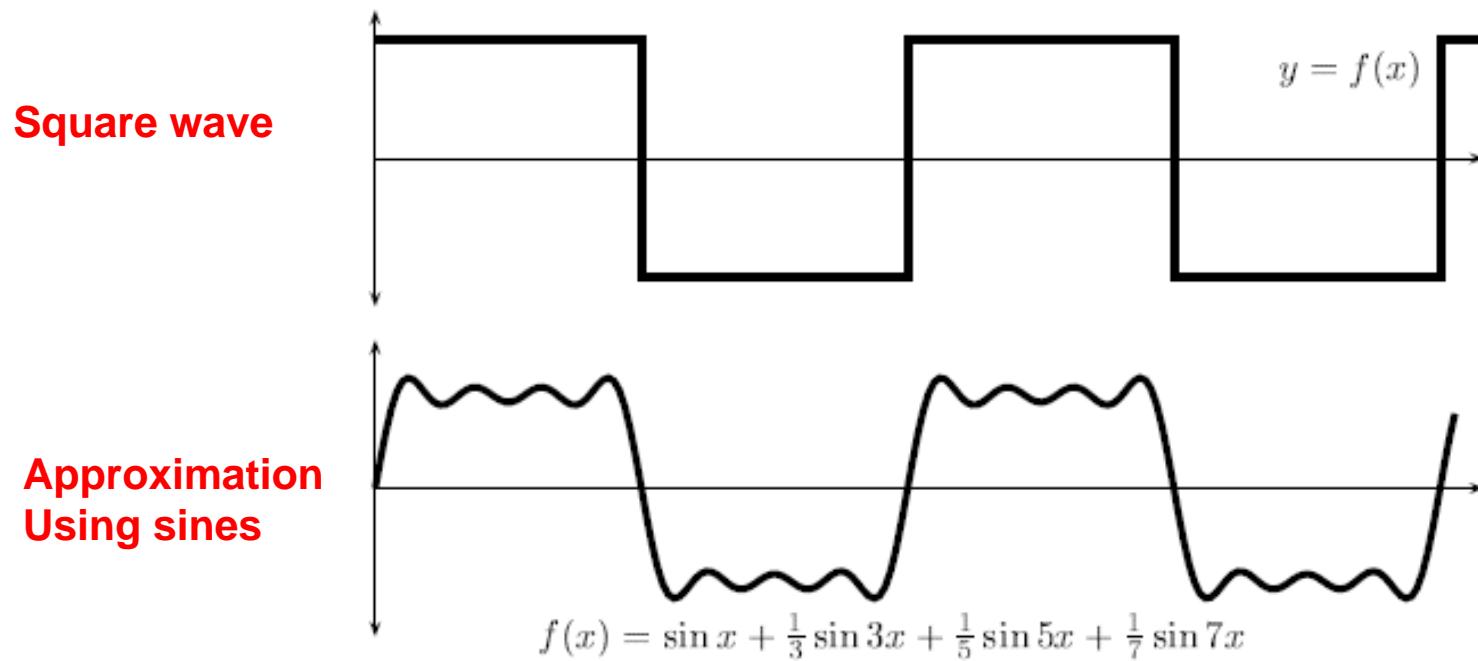
Frequency = 2x

Frequency = 4x

Observation 3: Different amounts of different sines added together (e.g. 1/3, 1/5, etc)



Fourier Transform: Another Example



**Observation 4: The sine terms go to infinity.
The more sines we add, the closer the
approximation of the original.**



Who is Fourier?

- French mathematician and physicist
- Lived 1768 - 1830





Spectral Techniques

- Technique for representation and analysis of signals in frequency domain including audio, images, video
- How to decompose signal into summation of a series of sine and cosine functions (also called harmonic functions)
- Spectral techniques can improve efficiency of image processing
- Some image processing effects, concepts, techniques easier in frequency domain
- Includes **fourier transform, discrete fourier transform and discrete cosine transform**



Sine and Cosine Functions: A Review

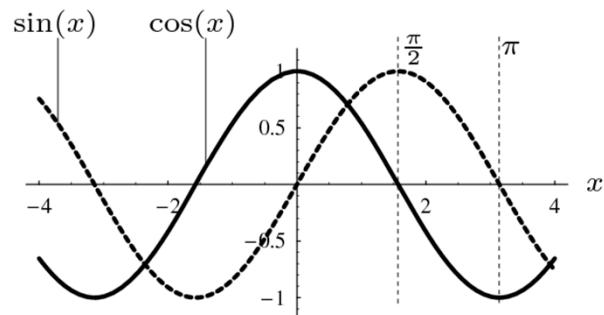
- Cosine function

$$f(x) = \cos(x)$$

- A function is periodic if

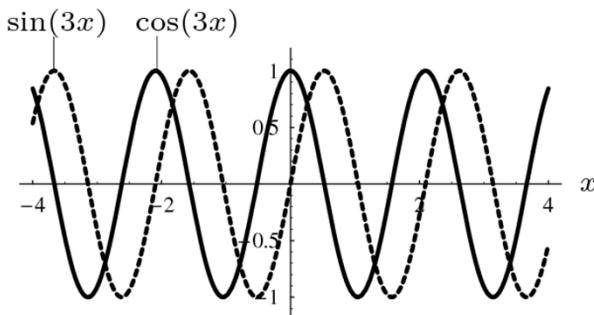
$$\cos(x) = \cos(x + 2\pi) = \cos(x + 4\pi) = \dots = \cos(x + k2\pi)$$

- Sines and cosines at different frequencies



(a)

Frequency = 1x



(b)

Frequency = 3x



Sines and Cosines: A Review

- Relationship between period T , frequency f and angular velocity ω

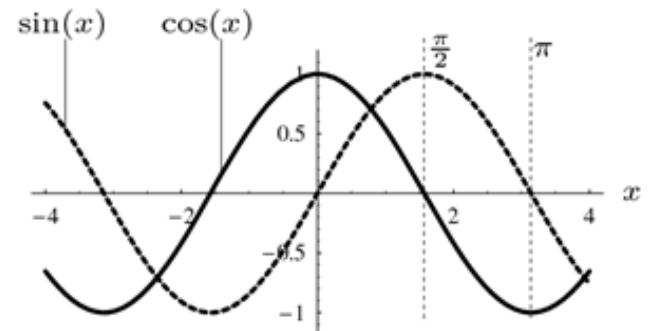
$$f = \frac{1}{T} = \frac{\omega}{2\pi} \quad \text{or} \quad \omega = 2\pi f$$

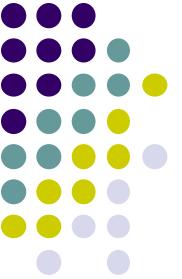
- Shifting phase of a cosine function

$$\cos(x) \rightarrow \cos(x - \varphi)$$

- Sine = cos shifted to right by 90 degrees

$$\sin(\omega x) = \cos\left(\omega x - \frac{\pi}{2}\right)$$





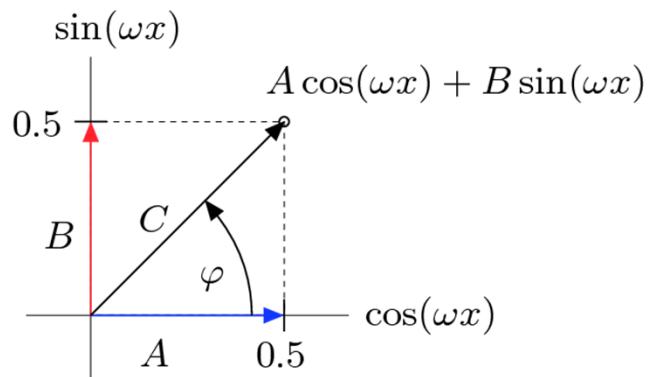
Sines and Cosines: A Review

- Adding a sine and cosine with same frequencies but arbitrary amplitudes A and B creates another sinusoid

$$A \cdot \cos(\omega x) + B \cdot \sin(\omega x) = C \cdot \cos(\omega x - \varphi)$$

- Amplitude and phase angle of C are

$$C = \sqrt{A^2 + B^2} \quad \text{and} \quad \varphi = \tan^{-1}\left(\frac{B}{A}\right)$$





Sines and Cosines: A Review

- Euler's complex number notation

$$z = e^{i\theta} = \cos(\theta) + i \cdot \sin(\theta)$$

- Easy to combine sines and cosines of same frequency

$$e^{i\theta} = e^{i\omega x} = \cos(\omega x) + i \cdot \sin(\omega x)$$



Fourier Series of Periodic Functions

- (Almost) any periodic function $g(x)$ with fundamental frequency ω_0 can be described as a sum of sinusoids

$$g(x) = \sum_{k=0}^{\infty} [A_k \cos(k\omega_0 x) + B_k \sin(k\omega_0 x)]$$

Infinite sum of Cosines Sines

- This infinite sum is called a **Fourier Series**
- Summed sines and cosines are multiples of the fundamental frequency (harmonics)
- A_k and B_k called **Fourier coefficients**
 - Not known initially but derived from original function $g(x)$ during Fourier analysis



Fourier Integral

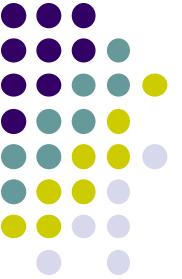
- For non-periodic functions similar ideas yield the **Fourier Integral** (integration of densely packed sines and cosines)

$$g(x) = \int_0^{\infty} A_{\omega} \cos(\omega x) + B_{\omega} \sin(\omega x) \, d\omega$$

where coefficients can be found as

$$A_{\omega} = A(\omega) = \frac{1}{\pi} \int_{-\infty}^{\infty} g(x) \cdot \cos(\omega x) \, dx$$

$$B_{\omega} = B(\omega) = \frac{1}{\pi} \int_{-\infty}^{\infty} g(x) \cdot \sin(\omega x) \, dx$$



Fourier Transform

- **Fourier Transform:** Transition of function $g(x)$ to its Fourier spectrum $G(\omega)$

$$\begin{aligned} G(\omega) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cdot [\cos(\omega x) - i \cdot \sin(\omega x)] dx \\ &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cdot e^{-i\omega x} dx. \end{aligned}$$

- **Inverse Fourier Transform:** Reconstruction of original function $g(x)$ from its Fourier spectrum $G(\omega)$

$$\begin{aligned} g(x) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} G(\omega) \cdot [\cos(\omega x) + i \cdot \sin(\omega x)] d\omega \\ &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} G(\omega) \cdot e^{i\omega x} d\omega. \end{aligned}$$



References

- Wilhelm Burger and Mark J. Burge, Digital Image Processing, Springer, 2008
- University of Utah, CS 4640: Image Processing Basics, Spring 2012
- Rutgers University, CS 334, Introduction to Imaging and Multimedia, Fall 2012
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- Computer Graphics Using OpenGL 2nd edition by F.S Hill Jr, chapter 12